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1 Basic

1.1 .vimrc

```
syn on
se ai nu ru cul mouse=a
se cin et ts=4 sw=4 sts=4
so $VIMRUNTIME/mswin.vim
colo desert
se gfn=Monospace\ 14
```

1.2 Misc

```
#include <random>
mt19937 rng(0x5EED);
int randint(int lb, int ub)
{ return uniform_int_distribution<int>(lb, ub)(rng); }

#define SECS (clock() / CLOCKS_PER_SEC)

struct KeyHasher {
    size_t operator()(const Key& k) const {
        return k.first + k.second * 100000;
    }
};
typedef unordered_map<Key,int,KeyHasher> map_t;
```

1.3 python-related

```
from fractions import Fraction
from decimal import Decimal, getcontext
getcontext().prec = 250 # set precision

itwo = Decimal(0.5)
two = Decimal(2)

N = 200
def angle(cosT):
    """given cos(theta) in decimal return theta"""
    for i in range(N):
        cosT = ((cosT + 1) / two) ** itwo
        sinT = (1 - cosT * cosT) ** itwo
        return sinT * (2 ** N)
pi = angle(Decimal(-1))
```

2 flow

2.1 ISAP

```
#define SZ(c) ((int)(c).size())
struct Maxflow {
    static const int MAXV = 20010;
    static const int INF = 1000000;
    struct Edge {
        int v, c, r;
        Edge(int _v, int _c, int _r):
            v(_v), c(_c), r(_r) {}
    };
    int s, t;
    vector<Edge> G[MAXV*2];
    int iter[MAXV*2], d[MAXV*2], gap[MAXV*2], tot;
    void init(int x) {
        tot = x+2;
        s = x+1, t = x+2;
        for(int i = 0; i <= tot; i++) {
            G[i].clear();
            iter[i] = d[i] = gap[i] = 0;
        }
    }
    void addEdge(int u, int v, int c) {
        G[u].push_back(Edge(v, c, SZ(G[v])));
        G[v].push_back(Edge(u, 0, SZ(G[u]) - 1));
    }
};
```

2.2 MinCostFlow

```

    }
}
if(mom[t] == -1) break ;
int df = INFF;
for(int u = t; u != s; u = mom[u])
    df = min(df, g[mom[u]][id[u]].cap);
for(int u = t; u != s; u = mom[u]){
    Edge &e = g[mom[u]][id[u]];
    e.cap -= df;
    g[e.v][e.rev].cap += df;
}
mxf += df;
mnc += df*d[t];
}
return mnc;
}
} flow;

```

2.3 Dinic

2.4 Kuhn Munkres

```
struct KM{
// Maximum Bipartite Weighted Matching (Perfect Match)
static const int MXN = 650;
static const int INF = 2147483647; // LL
int n,match[MXN],vx[MXN],vy[MXN];
```

```

int edge[MXN][MXN],lx[MXN],ly[MXN],slack[MXN];
// **** LL
void init(int _n){
    n = _n;
    for(int i=0; i<n; i++) for(int j=0; j<n; j++)
        edge[i][j] = 0;
}
void addEdge(int x, int y, int w) // LL
{ edge[x][y] = w; }
bool DFS(int x){
    vx[x] = 1;
    for (int y=0; y<n; y++){
        if (vy[y]) continue;
        if (lx[x]+ly[y] > edge[x][y]){
            slack[y]=min(slack[y], lx[x]+ly[y]-edge[x][y]);
        } else {
            vy[y] = 1;
            if (match[y] == -1 || DFS(match[y]))
                { match[y] = x; return true; }
        }
    }
    return false;
}
int solve(){
    fill(match,match+n,-1);
    fill(lx,lx+n,-INF); fill(ly,ly+n,0);
    for (int i=0; i<n; i++)
        for (int j=0; j<n; j++)
            lx[i] = max(lx[i], edge[i][j]);
    for (int i=0; i<n; i++){
        fill(slack,slack+n,INF);
        while (true){
            fill(vx,vx+n,0); fill(vy,vy+n,0);
            if ( DFS(i) ) break;
            int d = INF; // long long
            for (int j=0; j<n; j++)
                if (!vy[j]) d = min(d, slack[j]);
            for (int j=0; j<n; j++){
                if (vx[j]) lx[j] -= d;
                if (vy[j]) ly[j] += d;
                else slack[j] -= d;
            }
        }
    }
    int res=0;
    for (int i=0; i<n; i++)
        res += edge[match[i]][i];
    return res;
}
}graph;

```

2.5 DMST

```

/*
 * Edmond's algorithm for Directed MST
 * runs in O(VE)
 */
const int MAXV = 10010;
const int MAXE = 10010;
const int INF = 2147483647;
struct Edge{
    int u, v, c;
    Edge(int x=0, int y=0, int z=0) : u(x), v(y), c(z){}
};
int V, E, root;
Edge edges[MAXE];
inline int newV(){ return ++ V; }
inline void addEdge(int u, int v, int c)
{ edges[++E] = Edge(u, v, c); }
bool con[MAXV];
int mnInW[MAXV], prv[MAXV], cyc[MAXV], vis[MAXV];
inline int DMST(){
    fill(con, con+V+1, 0);
    int r1 = 0, r2 = 0;
    while(1){
        fill(mnInW, mnInW+V+1, INF);
        fill(prv, prv+V+1, -1);
        REP(i, 1, E){
            int u=edges[i].u, v=edges[i].v, c=edges[i].c;
            if(u != v && v != root && c < mnInW[v])

```

```

                mnInW[v] = c, prv[v] = u;
            }
        }
        fill(vis, vis+V+1, -1);
        fill(cyc, cyc+V+1, -1);
        r1 = 0;
        bool jf = 0;
        REP(i, 1, V){
            if(con[i]) continue;
            if(prv[i] == -1 && i != root) return -1;
            if(prv[i] > 0) r1 += mnInW[i];
            int s;
            for(s = i; s != -1 && vis[s] == -1; s = prv[s])
                vis[s] = i;
            if(s > 0 && vis[s] == i){
                // get a cycle
                jf = 1; int v = s;
                do{
                    cyc[v] = s, con[v] = 1;
                    r2 += mnInW[v]; v = prv[v];
                }while(v != s);
                con[s] = 0;
            }
        }
        if(!jf) break;
        REP(i, 1, E){
            int &u = edges[i].u;
            int &v = edges[i].v;
            if(cyc[v] > 0) edges[i].c -= mnInW[edges[i].v];
            if(cyc[u] > 0) edges[i].u = cyc[edges[i].u];
            if(cyc[v] > 0) edges[i].v = cyc[edges[i].v];
            if(u == v) edges[i--] = edges[E--];
        }
        return r1+r2;
    }
}

```

2.6 SW min-cut

```

// global min cut
struct SW{ // O(V^3)
    static const int MXN = 514;
    int n,vst[MXN],del[MXN];
    int edge[MXN][MXN],wei[MXN];
    void init(int _n){
        n = _n; FZ(edge); FZ(del);
    }
    void addEdge(int u, int v, int w){
        edge[u][v] += w; edge[v][u] += w;
    }
    void search(int &s, int &t){
        FZ(vst); FZ(wei);
        s = t = -1;
        while (true){
            int mx=-1, cur=0;
            for (int i=0; i<n; i++)
                if (!del[i] && !vst[i] && mx<wei[i])
                    cur = i, mx = wei[i];
            if (mx == -1) break;
            vst[cur] = 1;
            s = t; t = cur;
            for (int i=0; i<n; i++)
                if (!vst[i] && !del[i]) wei[i] += edge[cur][i];
        }
    }
    int solve(){
        int res = 2147483647;
        for (int i=0,x,y; i<n-1; i++){
            search(x,y);
            res = min(res,wei[y]);
            del[y] = 1;
            for (int j=0; j<n; j++)
                edge[x][j] = (edge[j][x] += edge[y][j]);
        }
        return res;
    }
}graph;

```

2.7 Max Cost Circulation

```

struct MaxCostCirc {
    static const int MAXN = 33;
    int n , m;
    struct Edge { int v , w , c , r; };
    vector<Edge> g[ MAXN ];
    int dis[ MAXN ] , prv[ MAXN ] , prve[ MAXN ];
    bool vis[ MAXN ];
    int ans;
    void init( int _n , int _m ) : n(_n), m(_m) {}
    void adde( int u , int v , int w , int c ) {
        g[ u ].push_back( { v , w , c , SZ( g[ v ] ) } );
        g[ v ].push_back( { u , -w , 0 , SZ( g[ u ] )-1 } );
    }
    bool poscyc() {
        fill( dis , dis+n+1 , 0 );
        fill( prv , prv+n+1 , 0 );
        fill( vis , vis+n+1 , 0 );
        int tmp = -1;
        FOR( t , n+1 ) {
            REP( i , 1 , n ) {
                FOR( j , SZ( g[ i ] ) ) {
                    Edge& e = g[ i ][ j ];
                    if( e.c && dis[ e.v ] < dis[ i ]+e.w ) {
                        dis[ e.v ] = dis[ i ]+e.w;
                        prv[ e.v ] = i;
                        prve[ e.v ] = j;
                        if( t == n ) {
                            tmp = i;
                            break;
                        }
                    }
                }
            }
        }
        if( tmp == -1 ) return 0;
        int cur = tmp;
        while( !vis[ cur ] ) {
            vis[ cur ] = 1;
            cur = prv[ cur ];
        }
        int now = cur , cost = 0 , df = 100000;
        do{
            Edge &e = g[ prv[ now ] ][ prve[ now ] ];
            df = min( df , e.c );
            cost += e.w;
            now = prv[ now ];
        }while( now != cur );
        ans += df*cost; now = cur;
        do{
            Edge &e = g[ prv[ now ] ][ prve[ now ] ];
            Edge &re = g[ now ][ e.r ];
            e.c -= df;
            re.c += df;
            now = prv[ now ];
        }while( now != cur );
        return 1;
    }
} circ;

```

2.8 Gusfield

```

#define SOURCE 0
#define SINK 1
const unsigned int inf=4000000000u;
int n,deg[MAXN],adj[MAXN][MAXN]; //n,deg,adj,cap
unsigned int res[MAXN][MAXN],cap[MAXN][MAXN];
int nei[MAXN],gdeg[MAXN],gadj[MAXN][MAXN];
unsigned int gres[MAXN][MAXN];
unsigned int cut[MAXN][MAXN];
unsigned int cutarr[MAXN*MAXN];
int cutn,ql,qr,que[MAXN],pred[MAXN];
unsigned int aug[MAXN];
bool cutset[MAXN];
int visited[MAXN],visid=0;
inline void augment(int src,int sink) {
    int v=sink; unsigned a=aug[sink];
    while(v!=src) {
        res[pred[v]][v]-=a;
        res[v][pred[v]]+=a;
        v=pred[v];
    }
}
inline bool bfs(int src,int sink) {

```

```

    int i,v,u; ++visid;
    ql=qr=0; que[qr++]=src;
    visited[src]=visid; aug[src]=inf;
    while(ql<qr) {
        v=que[ql++];
        for(i=0;i<deg[v];i++) {
            u=adj[v][i];
            if(visited[u]==visid||res[v][u]==0) continue;
            visited[u]=visid; pred[u]=v;
            aug[u]=min(aug[v],res[v][u]);
            que[qr++]=u;
            if(u==sink) return 1;
        }
    }
    return 0;
}
void dfs_src(int v) {
    int i,u;
    visited[v]=visid;
    cutset[v]=SOURCE;
    for(i=0;i<deg[v];i++) {
        u=adj[v][i];
        if(visited[u]<visid&&res[v][u]) dfs_src(u);
    }
}
inline unsigned int maxflow(int src,int sink) {
    int i,j;
    unsigned int f=0;
    for(i=0;i<n;i++) {
        for(j=0;j<deg[i];j++) res[i][adj[i][j]]=cap[i][adj[i][j]];
        cutset[i]=SINK;
    }
    while(bfs(src,sink)) {
        augment(src,sink);
        f+=aug[sink];
    }
    ++visid;
    dfs_src(src);
    return f;
}
inline void gusfield() {
    int i,j;
    unsigned int f;
    for(i=0;i<n;i++) { nei[i]=0; gdeg[i]=0; }
    for(i=1;i<n;i++) {
        f=maxflow(i,nei[i]);
        gres[i][nei[i]]=gres[nei[i]][i]=f;
        gadj[i][gdeg[i]++]=nei[i];
        gadj[nei[i]][gdeg[nei[i]]++]=i;
        for(j=i+1;j<n;j++)
            if(nei[j]==nei[i]&&cutset[j]==SOURCE) nei[j]=i;
    }
}
void dfs(int v,int pred,int src,unsigned int cur) {
    int i,u;
    cut[src][v]=cur;
    for(i=0;i<gdeg[v];i++) {
        u=gadj[v][i];
        if(u==pred) continue;
        dfs(u,v,src,min(cur,gres[v][u]));
    }
}
inline void find_all_cuts() {
    int i;
    cutn=0; gusfield();
    for(i=0;i<n;i++) dfs(i,-1,i,inf);
}

```

2.9 Max flow with lower/upper bound

```

// Max flow with lower/upper bound on edges
// source = 1 , sink = n
int in[ N ] , out[ N ];
int l[ M ] , r[ M ] , a[ M ] , b[ M ];
int solve() {
    flow.init( n );
    for( int i = 0 ; i < m ; i ++ ) {
        in[ r[ i ] ] += a[ i ];
        out[ l[ i ] ] += a[ i ];
    }
}

```

```

    flow.addEdge( l[ i ] , r[ i ] , b[ i ] - a[ i ] );
    // flow from l[i] to r[i] must in [a[i], b[i]]
}
int nd = 0;
for( int i = 1 ; i <= n ; i ++ ){
    if( in[ i ] < out[ i ] ){
        flow.addEdge( i , flow.t , out[ i ] - in[ i ] );
        nd += out[ i ] - in[ i ];
    }
    if( out[ i ] < in[ i ] )
        flow.addEdge( flow.s , i , in[ i ] - out[ i ] );
}
// original sink to source
flow.addEdge( n , 1 , INF );
if( flow.maxflow() != nd )
    // no solution
    return -1;
int ans = flow.G[ 1 ].back().c; // source to sink
flow.G[ 1 ].back().c = flow.G[ n ].back().c = 0;
// take out super source and super sink
for( size_t i = 0 ; i < flow.G[ flow.s ].size() ; i
    ++ ){
    flow.G[ flow.s ][ i ].c = 0;
    Edge &e = flow.G[ flow.s ][ i ];
    flow.G[ e.v ][ e.r ].c = 0;
}
for( size_t i = 0 ; i < flow.G[ flow.t ].size() ; i
    ++ ){
    flow.G[ flow.t ][ i ].c = 0;
    Edge &e = flow.G[ flow.t ][ i ];
    flow.G[ e.v ][ e.r ].c = 0;
}
flow.addEdge( flow.s , 1 , INF );
flow.addEdge( n , flow.t , INF );
flow.reset();
return ans + flow.maxflow();
}

```

2.10 Flow Method

Maximize $c^T x$ subject to $Ax \leq b$, $x \geq 0$;
 with the corresponding symmetric dual problem,
 Minimize $b^T y$ subject to $A^T y \geq c$, $y \geq 0$.

Maximize $c^T x$ subject to $Ax \leq b$;
 with the corresponding asymmetric dual problem,
 Minimize $b^T y$ subject to $A^T y = c$, $y \geq 0$.

General Graph:

IMax Ind. SetI + IMin Vertex CoverI = IVI

IMax Ind. Edge SetI + IMin Edge CoverI = IVI

Bipartite Graph:

IMax Ind. SetI = IMin Edge CoverI

IMax Ind. Edge SetI = IMin Vertex CoverI

To reconstruct the minimum vertex cover, dfs from each unmatched vertex on the left side **and** with unused edges only. Equivalently, dfs from source with unused edges only **and** without visiting sink. Then, a vertex is chosen iff. it is on the left side **and** without visited **or** on the right side **and** visited through dfs.

Maximum density subgraph ($\sum\{W_e\} + \sum\{W_v\}$) / IVI

Binary search on answer:

For a fixed D, construct a Max flow model as follow:

Let S be Sum of all weight(**or** inf)

1. from source to each node with cap = S

2. For each (u,v,w) in E, (u->v, cap=w), (v->u, cap=w)

3. For each node v, from v to sink with cap = S + 2 * D - deg[v] - 2 * (W of v)

where deg[v] = \sum weight of edge associated with v

If maxflow < S * IVI, D is an answer.

Requiring subgraph: all vertex can be reached from source with edge whose cap > 0.

3 Math

3.1 FFT

```

// const int MAXN = 262144;
// (must be 2^k)
// before any usage, run pre_fft() first
typedef long double ld;
typedef complex<ld> cplx;
const ld PI = acos(-1);
const cplx I(0, 1);
cplx omega[MAXN+1];
void pre_fft(){
    for(int i=0; i<=MAXN; i++)
        omega[i] = exp(i * 2 * PI / MAXN * I);
}
// n must be 2^k
void fft(int n, cplx a[], bool inv=false){
    int basic = MAXN / n;
    int theta = basic;
    for (int m = n; m >= 2; m >= 1) {
        int mh = m >> 1;
        for (int i = 0; i < mh; i++) {
            cplx w = omega[inv ? MAXN-(i*theta%MAXN)
                : i*theta%MAXN];
            for (int j = i; j < n; j += m) {
                int k = j + mh;
                cplx x = a[j] - a[k];
                a[j] += a[k];
                a[k] = w * x;
            }
        }
        theta = (theta * 2) % MAXN;
    }
    int i = 0;
    for (int j = 1; j < n - 1; j++) {
        for (int k = n >> 1; k > (i ^= k); k >= 1);
        if (j < i) swap(a[i], a[j]);
    }
    if(inv) for (i = 0; i < n; i++) a[i] /= n;
}

```

3.2 NTT

```

/* p=a*2^k+1
p          a      k      root
998244353  119    23      3
2013265921 15     27     31
2061584302081 15    37      7
2748779069441 5     39      3
1945555039024054273 27 56    5 */
template<LL P, LL root, int MAXN>
struct NTT{
    static LL bigmod(LL a, LL b) {
        LL res = 1;
        for (LL bs = a; b; b >= 1, bs = (bs * bs) % P)
            if(b&1) res=(res*bs)%P;
        return res;
    }
    static LL inv(LL a, LL b) {
        if(a==1)return 1;
        return (((LL)(a-inv(b%a,a))*b+1)/a)%b;
    }
    LL omega[MAXN+1];
    NTT() {
        omega[0] = 1;
        LL r = bigmod(root, (P-1)/MAXN);
        for (int i=1; i<=MAXN; i++)
            omega[i] = (omega[i-1]*r)%P;
    }
    void tran(int n, LL a[], bool inv_ntt=false){//n=2^k
        int basic = MAXN / n , theta = basic;
        for (int m = n; m >= 2; m >= 1) {
            int mh = m >> 1;
            for (int i = 0; i < mh; i++) {
                LL w = omega[i*theta%MAXN];
                for (int j = i; j < n; j += m) {
                    int k = j + mh;

```

```

        LL x = a[j] - a[k];
        if (x < 0) x += P;
        a[j] += a[k];
        if (a[j] > P) a[j] -= P;
        a[k] = (w * x) % P;
    }
}
theta = (theta * 2) % MAXN;
}
int i = 0;
for (int j = 1; j < n - 1; j++) {
    for (int k = n >> 1; k > (i ^ k); k >= 1);
    if (j < i) swap(a[i], a[j]);
}
if (inv_ntt) {
    LL ni = inv(n,P);
    reverse(a+1, a+n);
    for (i = 0; i < n; i++)
        a[i] = (a[i] * ni) % P;
}
};
const LL P=2013265921,root=31;
const int MAXN=4194304;
NTT<P, root, MAXN> ntt;

```

3.3 Fast Walsh Transform

```

/* xor convolution:
* x = (x0,x1) , y = (y0,y1)
* z = ( x0y0 + x1y1 , x0y1 + x1y0 )
* =>
* x' = ( x0+x1 , x0-x1 ) , y' = ( y0+y1 , y0-y1 )
* z' = ( ( x0+x1 )( y0+y1 ) , ( x0-x1 )( y0-y1 ) )
* z = (1/2) * z''
* or convolution:
* x = (x0, x0+x1), inv = (x0, x1-x0) w/o final div
* and convolution:
* x = (x0+x1, x1), inv = (x0-x1, x1) w/o final div */
typedef long long LL;
const int MAXN = (1<<20)+10;
const LL MOD = 1e9+7;
inline LL pw( LL x , LL k ) {
    LL res = 1;
    for( LL bs = x ; k ; k >= 1, bs = (bs * bs)%MOD )
        if( k&1 ) res = ( res * bs ) % MOD;
    return res;
}
inline LL inv( LL x ) {
    return pw( x , MOD-2 );
}
inline void fwt( LL x[ MAXN ] , int N , bool inv=0 ) {
    for( int d = 1 ; d < N ; d <= 1 ) {
        int d2 = d<<1;
        for( int s = 0 ; s < N ; s += d2 )
            for( int i = s , j = s+d ; i < s+d ; i++, j++ ) {
                LL ta = x[ i ] , tb = x[ j ];
                x[ i ] = ta+tb;
                x[ j ] = ta-tb;
                if( x[ i ] >= MOD ) x[ i ] -= MOD;
                if( x[ j ] < 0 ) x[ j ] += MOD;
            }
    }
    if( inv )
        for( int i = 0 ; i < N ; i++ ) {
            x[ i ] *= inv( N );
            x[ i ] %= MOD;
        }
}

```

3.4 Poly operator

```

struct PolyOp {
#define FOR(i, c) for (int i = 0; i < (c); ++i)
    NTT<P, root, MAXN> ntt;
    static int nxt2k(int x) {
        int i = 1; for (; i < x; i <= 1); return i;
    }
}

```

```

void Mul(int n, LL a[], int m, LL b[], LL c[]) {
    static LL aa[MAXN], bb[MAXN];
    int N = nxt2k(n+m);
    copy(a, a+n, aa); fill(aa+n, aa+N, 0);
    copy(b, b+m, bb); fill(bb+m, bb+N, 0);
    ntt(N, aa); ntt(N, bb);
    FOR(i, N) c[i] = aa[i] * bb[i] % P;
    ntt(N, c, 1);
}
void Inv(int n, LL a[], LL b[]) {
    // ab = aa^-1 = 1 mod x^(n/2)
    // (b - a^-1)^2 = 0 mod x^n
    // bb - a^-2 + 2 ba^-1 = 0
    // bba - a^-1 + 2b = 0
    // bba + 2b = a^-1
    static LL tmp[MAXN];
    if (n == 1) {b[0] = ntt.inv(a[0], P); return;}
    Inv((n+1)/2, a, b);
    int N = nxt2k(n*2);
    copy(a, a+n, tmp);
    fill(tmp+n, tmp+N, 0);
    fill(b+n, b+N, 0);
    ntt(N, tmp); ntt(N, b);
    FOR(i, N) {
        LL t1 = (2 - b[i] * tmp[i]) % P;
        if (t1 < 0) t1 += P;
        b[i] = b[i] * t1 % P;
    }
    ntt(N, b, 1);
    fill(b+n, b+N, 0);
}
void Div(int n, LL a[], int m, LL b[], LL d[], LL r
    []) {
    // Ra = Rb * Rd mod x^(n-m+1)
    // Rd = Ra * Rb^-1 mod
    static LL aa[MAXN], bb[MAXN], ta[MAXN], tb[MAXN];
    if (n < m) {copy(a, a+n, r); fill(r+n, r+m, 0);
        return;}
    // d: n-1 - (m-1) = n-m (n-m+1 terms)
    copy(a, a+n, aa); copy(b, b+m, bb);
    reverse(aa, aa+n); reverse(bb, bb+m);
    Inv(n-m+1, bb, tb);
    Mul(n-m+1, ta, n-m+1, tb, d);
    fill(d+n-m+1, d+n, 0); reverse(d, d+n-m+1);
    // r: m-1 - 1 = m-2 (m-1 terms)
    Mul(m, b, n-m+1, d, ta);
    FOR(i, n) { r[i] = a[i] - ta[i]; if (r[i] < 0) r[i]
        += P; }
}
void dx(int n, LL a[], LL b[]) { REP(i, 1, n-1) b[i]
    -1] = i * a[i] % P; }
void Sx(int n, LL a[], LL b[]) {
    b[0] = 0;
    FOR(i, n) b[i+1] = a[i] * ntt.iv[i+1] % P;
}
void Ln(int n, LL a[], LL b[]) {
    // Integral a' a^-1 dx
    static LL a1[MAXN], a2[MAXN], b1[MAXN];
    int N = nxt2k(n*2);
    dx(n, a, a1); Inv(n, a, a2);
    Mul(n-1, a1, n, a2, b1);
    Sx(n+n-1-1, b1, b);
    fill(b+n, b+N, 0);
}
void Exp(int n, LL a[], LL b[]) {
    // Newton method to solve g(a(x)) = ln b(x) - a(x)
    // = 0
    // b' = b - g(b(x)) / g'(b(x))
    // b' = b (1 - lnb + a)
    static LL lnb[MAXN], c[MAXN], tmp[MAXN];
    assert(a[0] == 0); // dont know exp(a[0]) mod P
    if (n == 1) {b[0] = 1; return;}
    Exp((n+1)/2, a, b);
    fill(b+(n+1)/2, b+n, 0);
    Ln(n, b, lnb);
    fill(c, c+n, 0); c[0] = 1;
    FOR(i, n) {
        c[i] += a[i] - lnb[i];
        if (c[i] < 0) c[i] += P;
        if (c[i] >= P) c[i] -= P;
    }
    Mul(n, b, n, c, tmp);
}

```



```

    copy(tmp, tmp+n, b);
}
} polyop;

```

3.5 Miller Rabin

```

// n < 4,759,123,141      3 : 2, 7, 61
// n < 1,122,004,669,633 4 : 2, 13, 23, 1662803
// n < 3,474,749,660,383 6 : pirmes <= 13
// n < 2^64              7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
// Make sure testing integer is in range [2, n-2] if
// you want to use magic.
// wiInt over flow. use __int128
bool witness(Int a, Int n, Int u, int t){
    if(!a) return 0;
    Int x=mypow(a,u,n);
    for(int i=0; i<t; i++){
        Int nx=mul(x,x,n);
        if(nx==1&&x!=1&&x!=n-1) return 1;
        x=nx;
    }
    return x!=1;
}
bool miller_rabin(Int n, int s=100) {
    // iterate s times of witness on n
    // return 1 if prime, 0 otherwise
    if(n<2) return 0;
    if(!(n&1)) return n == 2;
    Int u=n-1; int t=0;
    // n-1 = u*2^t
    while(!(u&1)) u>>=1, t++;
    while(s--){
        Int a=randInt()%(n-1)+1;
        if(witness(a,n,u,t)) return 0;
    }
    return 1;
}

```

3.6 Simplex

```

const int MAXN = 111;
const int MAXM = 111;
const double eps = 1E-10;
double a[MAXN][MAXM], b[MAXN], c[MAXM], d[MAXN][MAXM];
double x[MAXM];
int ix[MAXN + MAXM]; // !!! array all indexed from 0
// max{cx} subject to {Ax<=b, x>=0}
// n: constraints, m: vars !!!
// x[] is the optimal solution vector
// usage :
// value = simplex(a, b, c, N, M);
double simplex(double a[MAXN][MAXM], double b[MAXN],
               double c[MAXM], int n, int m){
    ++m;
    int r = n, s = m - 1;
    memset(d, 0, sizeof(d));
    for (int i = 0; i < n + m; ++i) ix[i] = i;
    for (int i = 0; i < n; ++i) {
        for (int j = 0; j < m - 1; ++j) d[i][j] = -a[i][j];
        d[i][m - 1] = 1;
        d[i][m] = b[i];
        if (d[r][m] > d[i][m]) r = i;
    }
    for (int j = 0; j < m - 1; ++j) d[n][j] = c[j];
    d[n + 1][m - 1] = -1;
    for (double dd;; ) {
        if (r < n) {
            int t = ix[s]; ix[s] = ix[r + m]; ix[r + m] = t;
            d[r][s] = 1.0 / d[r][s];
            for (int j = 0; j <= m; ++j)
                if (j != s) d[r][j] *= -d[r][s];
            for (int i = 0; i <= n + 1; ++i) if (i != r) {
                for (int j = 0; j <= m; ++j) if (j != s)
                    d[i][j] += d[r][j] * d[i][s];
                d[i][s] *= d[r][s];
            }
        }
    }
}

```

```

r = -1; s = -1;
for (int j = 0; j < m; ++j)
    if (s < 0 || ix[s] > ix[j]) {
        if (d[n + 1][j] > eps ||
            (d[n + 1][j] > -eps && d[n][j] > eps))
            s = j;
    }
if (s < 0) break;
for (int i = 0; i < n; ++i) if (d[i][s] < -eps) {
    if (r < 0 ||
        (dd = d[r][m] / d[r][s] - d[i][m] / d[i][s])
        < -eps ||
        (dd < eps && ix[r + m] > ix[i + m]))
        r = i;
}
if (r < 0) return -1; // not bounded
}
if (d[n + 1][m] < -eps) return -1; // not executable
double ans = 0;
for (int i = 0; i < m; i++) x[i] = 0;
for (int i = m; i < n + m; ++i) { // the missing
    enumerated x[i] = 0
    if (ix[i] < m - 1) {
        ans += d[i - m][m] * c[ix[i]];
        x[ix[i]] = d[i - m][m];
    }
}
return ans;
}

```

3.7 Faulhaber

```

/* faulhaber' s formula -
 * cal power sum formula of all p=1~k in O(k^2) */
#define MAXK 2500
const int mod = 1000000007;
int b[MAXK]; // bernoulli number
int inv[MAXK+1]; // inverse
int cm[MAXK+1][MAXK+1]; // combinactories
int co[MAXK][MAXK+2]; // coefficient of x^j when p=i
inline int getinv(int x) {
    int a=x, b=mod, a0=1, a1=0, b0=0, b1=1;
    while(b) {
        int q,t;
        q=a/b; t=b; b=a-b*q; a=t;
        t=b0; b0=a0-b0*q; a0=t;
        t=b1; b1=a1-b1*q; a1=t;
    }
    return a0<0?a0+mod:a0;
}
inline void pre() {
    /* combinational */
    for (int i=0; i<=MAXK; i++) {
        cm[i][0]=cm[i][i]=1;
        for (int j=1; j<i; j++)
            cm[i][j]=add(cm[i-1][j-1], cm[i-1][j]);
    }
    /* inverse */
    for (int i=1; i<=MAXK; i++) inv[i]=getinv(i);
    /* bernoulli */
    b[0]=1; b[1]=getinv(2); // with b[1] = 1/2
    for (int i=2; i<=MAXK; i++) {
        if (i&1) { b[i]=0; continue; }
        b[i]=1;
        for (int j=0; j<i; j++)
            b[i]=sub(b[i], mul(cm[i][j], mul(b[j], inv[i-j+1])));
    }
    /* faulhaber */
    // sigma_x=1~n {x^p} =
    // 1/(p+1) * sigma_j=0~p {C(p+1,j)*B_j*n^(p-j+1)}
    for (int i=1; i<=MAXK; i++) {
        co[i][0]=0;
        for (int j=0; j<=i; j++)
            co[i][i-j+1]=mul(inv[i+1], mul(cm[i+1][j], b[j]));
    }
}
/* sample usage: return f(n,p) = sigma_x=1~n (x^p) */
inline int solve(int n, int p) {
}

```

```

int sol=0,m=n;
for(int i=1;i<=p+1;i++) {
    sol=add(sol,mul(co[p][i],m));
    m = mul(m, n);
}
return sol;
}

```

3.8 Chinese Remainder

```

LL solve(LL x1, LL m1, LL x2, LL m2) {
    LL g = __gcd(m1, m2);
    if((x2 - x1) % g) return -1; // no sol
    m1 /= g; m2 /= g;
    pair<LL,LL> p = gcd(m1, m2);
    LL lcm = m1 * m2 * g;
    LL res = p.first * (x2 - x1) * m1 + x1;
    return (res % lcm + lcm) % lcm;
}

```

3.9 Pollard Rho

```

// does not work when n is prime
LL f(LL x, LL mod){ return add(mul(x,x,mod),1,mod); }
LL pollard_rho(LL n) {
    if(!(n&1)) return 2;
    while(true){
        LL y=2, x=rand()%(n-1)+1, res=1;
        for(int sz=2; res==1; sz*=2) {
            for(int i=0; i<sz && res<=1; i++) {
                x = f(x, n);
                res = __gcd(abs(x-y), n);
            }
            y = x;
        }
        if (res!=0 && res!=n) return res;
    }
}

```

3.10 ax+by=gcd

```

PII gcd(LL a, LL b){
    if(b == 0) return {1, 0};
    PII q = gcd(b, a % b);
    return {q.second, q.first - q.second * (a / b)};
}

```

3.11 Discrete sqrt

```

void calcH(int &t, int &h, const int p) {
    int tmp=p-1; for(t=0;(tmp&1)==0;tmp/=2) t++; h=tmp;
}
// solve equation x^2 mod p = a
bool solve(int a, int p, int &x, int &y) {
    if(p == 2) { x = y = 1; return true; }
    int p2 = p / 2, tmp = mypow(a, p2, p);
    if (tmp == p - 1) return false;
    if ((p + 1) % 4 == 0) {
        x=mypow(a,(p+1)/4,p); y=p-x; return true;
    } else {
        int t, h, b, pb; calcH(t, h, p);
        if (t >= 2) {
            do {b = rand() % (p - 2) + 2;
                while (mypow(b, p / 2, p) != p - 1);
                pb = mypow(b, h, p);
            } while (1);
            int s = mypow(a, h / 2, p);
            for (int step = 2; step <= t; step++) {
                int ss = (((LL)(s * s) % p) * a) % p;
                for(int i=0;i<t-step;i++) ss=mul(ss,ss,p);
                if (ss + 1 == p) s = (s * pb) % p;
                pb = ((LL)pb * pb) % p;
            } x = ((LL)s * a) % p; y = p - x;
        } return true;
    }
}

```

3.12 SchreierSims

```

// time: O(n^2 lg^3 |G| + t n lg |G|)
// mem : O(n^2 lg |G| + tn)
// t : number of generator
namespace SchreierSimsAlgorithm{
    typedef vector<int> Permu;
    Permu inv( const Permu& p ){
        Permu ret( p.size() );
        for( int i = 0; i < (int)p.size(); i ++ )
            ret[ p[ i ] ] = i;
        return ret;
    }
    Permu operator*( const Permu& a, const Permu& b ){
        Permu ret( a.size() );
        for( int i = 0; i < (int)a.size(); i ++ )
            ret[ i ] = b[ a[ i ] ];
        return ret;
    }
    typedef vector<Permu> Bucket;
    typedef vector<int> Table;
    typedef pair<int,int> pii;
    int n, m;
    vector<Bucket> bkts, bktsInv;
    vector<Table> lookup;
    int fastFilter( const Permu &g, bool addToG = 1 ){
        n = bkts.size();
        Permu p;
        for( int i = 0; i < n; i ++ ){
            int res = lookup[ i ][ p[ i ] ];
            if( res == -1 ){
                if( addToG ){
                    bkts[ i ].push_back( p );
                    bktsInv[ i ].push_back( inv( p ) );
                    lookup[ i ][ p[ i ] ] = (int)bkts[i].size()-1;
                }
                return i;
            }
            p = p * bktsInv[i][res];
        }
        return -1;
    }
    long long calcTotalSize(){
        long long ret = 1;
        for( int i = 0; i < n; i ++ )
            ret *= bkts[i].size();
        return ret;
    }
    bool inGroup( const Permu &g ){
        return fastFilter( g, false ) == -1;
    }
    void solve( const Bucket &gen, int _n ){
        n = _n, m = gen.size(); // m perm[0..n-1]
        //clear all
        bkts.clear();
        bktsInv.clear();
        lookup.clear();
        for(int i = 0; i < n; i ++ ){
            lookup[i].resize(n);
            fill(lookup[i].begin(), lookup[i].end(), -1);
        }
        Permu id( n );
        for(int i = 0; i < n; i ++ ) id[i] = i;
        for(int i = 0; i < n; i ++ ){
            bkts[i].push_back(id);
            bktsInv[i].push_back(id);
            lookup[i][i] = 0;
        }
        for(int i = 0; i < m; i ++ )
            fastFilter( gen[i] );
        queue< pair<pii,pii> > toUpd;
        for(int i = 0; i < n; i ++ )
            for(int j = i; j < n; j ++ )
                for(int k = 0; k < (int)bkts[i].size(); k ++ )
                    for(int l = 0; l < (int)bkts[j].size(); l ++ )
                        toUpd.push( {pii(i,k), pii(j,l)} );
        while( !toUpd.empty() ){
            pii a = toUpd.front().first;
            pii b = toUpd.front().second;
            toUpd.pop();
        }
    }
}

```



```

    int res = fastFilter(bkts[a.first][a.second] *
                        bkts[b.first][b.second]);
    if(res == -1) continue;
    pii newPair(res, (int)bkts[res].size() - 1);
    for(int i = 0; i < n; i++){
        for(int j = 0; j < (int)bkts[i].size(); ++j){
            if(i <= res)
                toUpd.push(make_pair(pii(i, j), newPair));
            if(res <= i)
                toUpd.push(make_pair(newPair, pii(i, j)));
        }
    }
}

```

3.13 Romberg

```

// Estimates the definite integral of
// \int_a^b f(x) dx
template<class T>
double romberg( T& f, double a, double b, double eps=1e-8){
    vector<double> t; double h=b-a, last, curr; int k=1, i=1;
    t.push_back(h*(f(a)+f(b))/2);
    do{ last=t.back(); curr=0; double x=a+h/2;
        for(int j=0; j<k; j++) curr+=f(x), x+=h;
        curr=(t[0] + h*curr)/2; double k1=4.0/3.0, k2
            =1.0/3.0;
        for(int j=0; j<i; j++){ double temp=k1*curr-k2*t[j];
            t[j]=curr; curr=temp; k2/=4*k1-k2; k1=k2+1;
        } t.push_back(curr); k*=2; h/=2; i++;
    }while( fabs(last-curr) > eps);
    return t.back();
}

```

3.14 Prefix Inverse

```

void solve( int m ){
    inv[ 1 ] = 1;
    for( int i = 2 ; i < m ; i ++ )
        inv[ i ] = ((LL)(m - m / i) * inv[m % i]) % m;
}

```

3.15 Roots of Polynomial

```

const double eps = 1e-12;
const double inf = 1e+12;
double a[ 10 ], x[ 10 ];
int n;
int sign( double x ){return (x < -eps)?(-1):(x>eps);}
double f(double a[], int n, double x){
    double tmp=1, sum=0;
    for(int i=0; i<=n; i++){
        sum=sum+a[i]*tmp; tmp=tmp*x;
    }
    return sum;
}
double binary(double l, double r, double a[], int n){
    int sl=sign(f(a, n, l)), sr=sign(f(a, n, r));
    if(sl==0) return l; if(sr==0) return r;
    if(sl*sr>0) return inf;
    while(r-l>eps){
        double mid=(l+r)/2;
        int ss=sign(f(a, n, mid));
        if(ss==0) return mid;
        if(ss*sl>0) l=mid; else r=mid;
    }
    return l;
}
void solve(int n, double a[], double x[], int &nx){
    if(n==1){ x[1]=-a[0]/a[1]; nx=1; return; }
    double da[10], dx[10]; int ndx;
    for(int i=n; i>=1; i--) da[i-1]=a[i]*i;
    solve(n-1, da, dx, ndx);
    nx=0;
    if(ndx==0){
        double tmp=binary(-inf, inf, a, n);

```

```

        if (tmp<inf) x[++nx]=tmp;
        return;
    }
    double tmp;
    tmp=binary(-inf, dx[1], a, n);
    if(tmp<inf) x[++nx]=tmp;
    for(int i=1; i<=ndx-1; i++){
        tmp=binary(dx[i], dx[i+1], a, n);
        if(tmp<inf) x[++nx]=tmp;
    }
    tmp=binary(dx[ndx], inf, a, n);
    if(tmp<inf) x[++nx]=tmp;
}
int main() {
    scanf("%d", &n);
    for(int i=n; i>=0; i--) scanf("%lf", &a[i]);
    int nx;
    solve(n, a, x, nx);
    for(int i=1; i<=nx; i++) printf("%.6f\n", x[i]);
}

```

3.16 Result

- Lucas' Theorem :
For $n, m \in \mathbb{Z}^*$ and prime P , $C(m, n) \bmod P = \prod C(m_i, n_i)$ where m_i is the i -th digit of m in base P .
- Stirling Numbers(permutation $|P| = n$ with k cycles):
 $S(n, k) = \text{coefficient of } x^k \text{ in } \Pi_{i=0}^{n-1} (x+i)$
- Stirling Numbers(Partition n elements into k non-empty set):
 $S(n, k) = \frac{1}{k!} \sum_{j=0}^k (-1)^{k-j} \binom{k}{j} j^n$
- Pick' s Theorem : $A = i + b/2 - 1$
- Kirchhoff's theorem :
 $A_{ii} = \deg(i), A_{ij} = (i, j) \in E ? -1 : 0$, Deleting any one row, one column, and cal the $\det(A)$
- Burnside Lemma: $|X/G| = \frac{1}{|G|} \sum_{g \in G} |X^g|$
- Polya theorem: $|Y^x/G| = \frac{1}{|G|} \sum_{g \in G} m^{c(g)}$
 $m = |Y|$: num of colors, $c(g)$: num of cycle

4 Geometry

4.1 Intersection of 2 lines

```

Pt LLIntersect(Line a, Line b) {
    Pt p1 = a.s, p2 = a.e, q1 = b.s, q2 = b.e;
    double f1 = (p2-p1)^(q1-p1), f2 = (p2-p1)^(p1-q2), f;
    if(dcmp(f=f1+f2) == 0)
        return dcmp(f1)?Pt(NAN, NAN):Pt(INFINITY, INFINITY);
    return q1*(f2/f) + q2*(f1/f);
}

```

4.2 halfPlaneIntersection

```

bool onleft(Line L, Pt p) {
    return dcmp(L.v^(p-L.s)) > 0;
}
// assume that Lines intersect
vector<Pt> HPI(vector<Line>& L) {
    sort(L.begin(), L.end());
    int n = L.size(), fir, las;
    Pt *p = new Pt[n];
    Line *q = new Line[n];
    q[fir=las=0] = L[0];
    for(int i = 1; i < n; i++) {
        while(fir < las && !onleft(L[i], p[las-1])) las--;
        while(fir < las && !onleft(L[i], p[fir])) fir++;
        q[++las] = L[i];
        if(dcmp(q[las].v^q[las-1].v) == 0) {
            las--;
            if(onleft(q[las], L[i].s)) q[las] = L[i];
        }
    }
}

```

```

    if(fir < las) p[las-1] = LLIntersect(q[las-1], q[
        las]);
}
while(fir < las && !onleft(q[fir], p[las-1])) las--;
if(las-fir <= 1) return {};
p[las] = LLIntersect(q[las], q[fir]);
int m = 0;
vector<Pt> ans(las-fir+1);
for(int i = fir ; i <= las ; i++) ans[m++] = p[i];
return ans;
}

```

4.3 Intersection of 2 segments

```

bool onseg(Pt p, Line L) {
    Pt x = L.s-p, y = L.e-p;
    return dcmp(x^y) == 0 && dcmp(x*y) <= 0; //inseg:dcmp
        (x*y)<0
}
// assume a.s != a.e != b.s != b.e
Pt SSIntersect(Line a, Line b) {
    Pt p = LLIntersect(a, b);
    if(isinf(p.x) && (onseg(a.s,b) || onseg(a.e,b) ||
        onseg(b.s, a) || onseg(b.e, a))) return p; //
        parallel
    if(isfinite(p.x) && onseg(p, a) && onseg(p, b))
        return p; //not parallel
    return {NAN,NAN};
}

```

4.4 Intersection of circle and segment

```

bool Inter( const Pt& p1 , const Pt& p2 , Circle& cc ){
    Pt dp = p2 - p1;
    double a = dp * dp;
    double b = 2 * ( dp * ( p1 - cc.o ) );
    double c = cc.o * cc.o + p1 * p1 - 2 * ( cc.o * p1 )
        - cc.R * cc.R;
    double bb4ac = b * b - 4 * a * c;
    return !( fabs( a ) < eps or bb4ac < 0 );
}

```

4.5 Intersection of polygon and circle

```

Pt ORI , info[ N ];
D r; int n;
// Divides into multiple triangle, and sum up
// oriented area
D area2(Pt pa, Pt pb){
    if( norm(pa) < norm(pb) ) swap(pa, pb);
    if( norm(pb) < eps ) return 0;
    D S, h, theta;
    D a = norm( pb ), b = norm( pa ), c = norm(pb - pa);
    D cosB = (pb * (pb - pa)) / a / c, B = acos(cosB);
    D cosC = (pa * pb) / a / b, C = acos(cosC);
    if(a > r){
        S = (C/2)*r*r;
        h = a*b*sin(C)/c;
        if (h < r && B < PI/2) S -= (acos(h/r)*r*r - h*sqrt
            (r*r-h*h));
    }else if(b > r){
        theta = PI - B - asin(sin(B)/r*a);
        S = .5*a*r*sin(theta) + (C-theta)/2*r*r;
    }else S = .5*sin(C)*a*b;
    return S;
}
D area() {
    D S = 0;
    for(int i = 0; i < n; ++i)
        S += abs( area2(info[i], info[i + 1])) * sign( det(
            info[i], info[i + 1]));
    return fabs(S);
}

```

4.6 Intersection of 2 circles

4.7 Circle cover

```

#define N 1021
struct CircleCover{
    int C; Circ c[ N ];
    bool g[ N ][ N ], overlap[ N ][ N ];
    // Area[i] : area covered by at least i circles
    D Area[ N ];
    void init( int _C ){ C = _C; }
    bool CCinter( Circ& a , Circ& b , Pt& p1 , Pt& p2 ){
        Pt o1 = a.o , o2 = b.o;
        D r1 = a.R , r2 = b.R;
        if( norm( o1 - o2 ) > r1 + r2 ) return {};
        if( norm( o1 - o2 ) < max(r1, r2) - min(r1, r2) )
            return {};
        D d2 = ( o1 - o2 ) * ( o1 - o2 );
        D d = sqrt(d2);
        if( d > r1 + r2 ) return false;
        Pt u=(o1+o2)*0.5 + (o1-o2)*((r2*r2-r1*r1)/(2*d2));
        D A=sqrt((r1+r2+d)*(r1-r2+d)*(r1+r2-d)*(-r1+r2+d));
        Pt v=Pt( o1.Y-o2.Y , -o1.X + o2.X ) * A / (2*d2);
        p1 = u + v; p2 = u - v;
        return true;
    }
    struct Teve {
        Pt p; D ang; int add;
        Teve() {}
        Teve(Pt _a, D _b, int _c):p(_a), ang(_b), add(_c){}
        bool operator<(const Teve &a)const
            {return ang < a.ang;}
    }eve[ N * 2 ];
    // strict: x = 0, otherwise x = -1
    bool disjuct( Circ& a, Circ &b, int x )
    {return sign( norm( a.o - b.o ) - a.R - b.R ) > x;}
    bool contain( Circ& a, Circ &b, int x )
    {return sign( a.R - b.R - norm( a.o - b.o ) ) > x;}
    bool contain(int i, int j){
        /* c[j] is non-strictly in c[i]. */
        return (sign(c[i].R - c[j].R) > 0 ||
            (sign(c[i].R - c[j].R) == 0 && i < j) ) &&
            contain(c[i], c[j], -1);
    }
    void solve(){
        for( int i = 0 ; i <= C + 1 ; i ++ )
            Area[ i ] = 0;
        for( int i = 0 ; i < C ; i ++ )
            for( int j = 0 ; j < C ; j ++ )
                overlap[i][j] = contain(i, j);
        for( int i = 0 ; i < C ; i ++ )
            for( int j = 0 ; j < C ; j ++ )
                g[i][j] = !(overlap[i][j] || overlap[j][i] ||
                    disjuct(c[i], c[j], -1));
        for( int i = 0 ; i < C ; i ++ ){
            int E = 0, cnt = 1;
            for( int j = 0 ; j < C ; j ++ )
                if( j != i && overlap[j][i] )
                    cnt ++;
            for( int j = 0 ; j < C ; j ++ )
                if( i != j && g[i][j] ){
                    Pt aa, bb;
                    CCinter(c[i], c[j], aa, bb);
                    D A=atan2(aa.Y - c[i].o.Y, aa.X - c[i].o.X);
                    D B=atan2(bb.Y - c[i].o.Y, bb.X - c[i].o.X);
                    eve[E ++] = Teve(bb, B, 1);
                    eve[E ++] = Teve(aa, A, -1);
                    if(B > A) cnt ++;
                }
            if( E == 0 ) Area[ cnt ] += pi * c[i].R * c[i].R;
            else{
                sort( eve , eve + E );
                eve[E] = eve[0];
                for( int j = 0 ; j < E ; j ++ ){
                    cnt += eve[j].add;
                    Area[cnt] += (eve[j].p ^ eve[j + 1].p) * .5;
                    D theta = eve[j + 1].ang - eve[j].ang;
                    if( theta < 0 ) theta += 2. * pi;
                    Area[cnt] +=
                        (theta - sin(theta)) * c[i].R*c[i].R * .5;
                }
            }
        }
    }
}

```

```

    }
  }
};

```

4.8 Intersection of segments set

```

struct event{
    Pt pt;int t,a,b; //sort by greater<pt.x>
    event(Pt &pt,int t,int a,int b=-1):pt(pt),t(t),a(a),b
        (b){}
};
vector<Line> LA; //must be filled
double cx=-1e9;
struct cmp{
    bool operator()(int a,int b){
        return LA[a].eval(cx)<LA[b].eval(cx);
    } //line.eval(x)=s.y+(e.y-s.y)*(x-s.x)/(e.x-s.x)
};
#define FI first
#define SE second
#define DEL(it) pq.erase(it->SE),it->SE=NULL;
#define UPD(cit,nit) \
Line A=LA[cit->FI],B=LA[nit->FI];\
if(cit->SE!=NULL) DEL(cit)\
Pt tmp=LLIntersect(A,B);\
if(!isnan(tmp.x)&&tmp.x>=cur.pt.x)\
cit->SE=pq.push({tmp,2,cit->FI,nit->FI});
#define INSF if(it!=s.begin()){UPD(prev(it),it)}
#define INSB if(next(it)!=s.end()){UPD(it,next(it))}
vector<Pt> AllPairLLIntersect(){
    __gnu_pbds::priority_queue<event> pq;
    map<int,__gnu_pbds::priority_queue<event>::
        point_iterator,cmp> s;
    for(int i=0;i<LA.size();i++){ //s.x < e.x
        pq.push({LA[i].s,0,i}),pq.push({LA[i].e,1,i});
    }
    vector<Pt> res;
    while(!pq.empty()){
        event cur=pq.top();pq.pop(); //cur.pt.x>=cx-eps
        cx=cur.pt.x-eps;
        if(cur.t==0){
            auto it=s.insert({cur.a,NULL}).FI;
            INSF;INSB;
        }
        else if(cur.t==1){
            auto it=s.lower_bound(cur.a); //it->FI==cur.a
            if(it->SE!=NULL) pq.erase(it->SE);
            s.erase(it++);
            if(it!=s.begin()&&it!=s.end()){UPD(prev(it),it)}
            else if(it!=s.begin()&&(--it)->SE!=NULL)DEL(it);
        }
        else{
            auto it=s.lower_bound(cur.a); //it->FI==cur.a
            res.push_back(cur.pt); //next(it)->FI==cur.b
            s.erase(it++);
            if(it->SE!=NULL) pq.erase(it->SE);
            s.erase(it++);
            cx+=eps*2;
            it=s.insert(it,{cur.a,NULL});INSB;
            it=s.insert(it,{cur.b,NULL});INSF;
        } //next(it)->FI==cur.a
        cx=cur.pt.x;
    }
    return res;
}

```

4.9 Convex Hull trick

```

/* Given a convexhull, answer queries in O(\lg N)
CH should not contain identical points, the area should
be > 0, min pair(x, y) should be listed first */
double det( const Pt& p1 , const Pt& p2 )
{ return p1.X * p2.Y - p1.Y * p2.X; }
struct Conv{
    int n;
    vector<Pt> a;
    vector<Pt> upper, lower;

```

```

Conv(vector<Pt> _a) : a(_a){
    n = a.size();
    int ptr = 0;
    for(int i=1; i<n; ++i) if (a[ptr] < a[i]) ptr = i;
    for(int i=0; i<=ptr; ++i) lower.push_back(a[i]);
    for(int i=ptr; i<n; ++i) upper.push_back(a[i]);
    upper.push_back(a[0]);
}
int sign( LL x ){ // fixed when changed to double
    return x < 0 ? -1 : x > 0; }
pair<LL,int> get_tang(vector<Pt> &conv, Pt vec){
    int l = 0, r = (int)conv.size() - 2;
    for( ; l + 1 < r; ){
        int mid = (l + r) / 2;
        if(sign(det(conv[mid+1]-conv[mid],vec))>0)r=mid;
        else l = mid;
    }
    return max(make_pair(det(vec, conv[r]), r),
        make_pair(det(vec, conv[0]), 0));
}
void upd_tang(const Pt &p, int id, int &i0, int &i1){
    if(det(a[i0] - p, a[id] - p) > 0) i0 = id;
    if(det(a[i1] - p, a[id] - p) < 0) i1 = id;
}
void bi_search(int l, int r, Pt p, int &i0, int &i1){
    if(l == r) return;
    upd_tang(p, l % n, i0, i1);
    int sl=sign(det(a[l % n] - p, a[(l + 1) % n] - p));
    for( ; l + 1 < r; ){
        int mid = (l + r) / 2;
        int smid=sign(det(a[mid%n]-p, a[(mid+1)%n]-p));
        if (smid == sl) l = mid;
        else r = mid;
    }
    upd_tang(p, r % n, i0, i1);
}
int bi_search(Pt u, Pt v, int l, int r) {
    int sl = sign(det(v - u, a[l % n] - u));
    for( ; l + 1 < r; ){
        int mid = (l + r) / 2;
        int smid = sign(det(v - u, a[mid % n] - u));
        if (smid == sl) l = mid;
        else r = mid;
    }
    return l % n;
}
// 1. whether a given point is inside the CH
bool contain(Pt p) {
    if (p.X < lower[0].X || p.X > lower.back().X)
        return 0;
    int id = lower_bound(lower.begin(), lower.end(), Pt
        (p.X, -INF)) - lower.begin();
    if (lower[id].X == p.X) {
        if (lower[id].Y > p.Y) return 0;
    }else if(det(lower[id-1]-p,lower[id]-p)<0)return 0;
    id = lower_bound(upper.begin(), upper.end(), Pt(p.X
        , INF), greater<Pt>()) - upper.begin();
    if (upper[id].X == p.X) {
        if (upper[id].Y < p.Y) return 0;
    }else if(det(upper[id-1]-p,upper[id]-p)<0)return 0;
    return 1;
}
// 2. Find 2 tang pts on CH of a given outside point
// return true with i0, i1 as index of tangent points
// return false if inside CH
bool get_tang(Pt p, int &i0, int &i1) {
    if (contain(p)) return false;
    i0 = i1 = 0;
    int id = lower_bound(lower.begin(), lower.end(), p)
        - lower.begin();
    bi_search(0, id, p, i0, i1);
    bi_search(id, (int)lower.size(), p, i0, i1);
    id = lower_bound(upper.begin(), upper.end(), p,
        greater<Pt>()) - upper.begin();
    bi_search((int)lower.size() - 1, (int)lower.size()
        - 1 + id, p, i0, i1);
    bi_search((int)lower.size() - 1 + id, (int)lower.
        size() - 1 + (int)upper.size(), p, i0, i1);
    return true;
}
// 3. Find tangent points of a given vector
// ret the idx of vertex has max cross value with vec

```

```

int get_tang(Pt vec){
    pair<LL, int> ret = get_tang(upper, vec);
    ret.second = (ret.second+(int)lower.size()-1)%n;
    ret = max(ret, get_tang(lower, vec));
    return ret.second;
}
// 4. Find intersection point of a given line
// return 1 and intersection is on edge (i, next(i))
// return 0 if no strictly intersection
bool get_intersection(Pt u, Pt v, int &i0, int &i1){
    int p0 = get_tang(u - v), p1 = get_tang(v - u);
    if(sign(det(v-u, a[p0]-u))*sign(det(v-u, a[p1]-u))<0){
        if(p0 > p1) swap(p0, p1);
        i0 = bi_search(u, v, p0, p1);
        i1 = bi_search(u, v, p1, p0 + n);
        return 1;
    }
    return 0;
}
};

```

4.10 Tangent line of two circles

```

vector<Line> go( const Cir& c1 , const Cir& c2 , int
    sign1 ){
    // sign1 = 1 for outer tang, -1 for inter tang
    vector<Line> ret;
    double d_sq = norm2( c1.0 - c2.0 );
    if( d_sq < eps ) return ret;
    double d = sqrt( d_sq );
    Pt v = ( c2.0 - c1.0 ) / d;
    double c = ( c1.R - sign1 * c2.R ) / d;
    if( c * c > 1 ) return ret;
    double h = sqrt( max( 0.0 , 1.0 - c * c ) );
    for( int sign2 = 1 ; sign2 >= -1 ; sign2 -= 2 ){
        Pt n = { v.X * c - sign2 * h * v.Y ,
            v.Y * c + sign2 * h * v.X };
        Pt p1 = c1.0 + n * c1.R;
        Pt p2 = c2.0 + n * ( c2.R * sign1 );
        if( fabs( p1.X - p2.X ) < eps and
            fabs( p1.Y - p2.Y ) < eps )
            p2 = p1 + perp( c2.0 - c1.0 );
        ret.push_back( { p1 , p2 } );
    }
    return ret;
}

```

4.11 KD Tree

```

const int MXN=100005;
const int MXK=10;
struct KDTree{
    struct Nd{
        LL x[MXK];
        int id;
        Nd *l,*r;
    }tree[MXN],*root;
    int n,k;
    LL dis(LL a,LL b){return (a-b)*(a-b);}
    LL dis(LL a[MXK],LL b[MXK]){
        LL ret=0;
        for(int i=0;i<k;i++) ret+=dis(a[i],b[i]);
        return ret;
    }
    void init(vector<vector<LL>> &ip,int _n,int _k){
        n=_n,k=_k;
        for(int i=0;i<n;i++){
            tree[i].id=i;
            copy(ip[i].begin(),ip[i].end(),tree[i].x);
        }
        root=build(0,n-1,0);
    }
    Nd* build(int l,int r,int d){
        if(l>r) return NULL;
        if(d==k) d=0;
        int m=(l+r)>>1;
        nth_element(tree+l,tree+m,tree+r+1,[&](const Nd &a,
            const Nd &b){return a.x[d]<b.x[d];});

```

```

        tree[m].l=build(l,m-1,d+1);
        tree[m].r=build(m+1,r,d+1);
        return tree+m;
    }
    LL pt[MXK],cd[MXK],sd,md;
    int mID;
    void nearest(Nd *r,int d){
        if(!r||sd>=md) return;
        if(d==k) d=0;
        LL td=dis(r->x,pt);
        if(td<md) md=td,mID=r->id;
        LL old=cd[d];
        nearest(pt[d]<r->x[d]?r->l:r->r,d+1);
        cd[d]=dis(r->x[d],pt[d]),sd+=cd[d]-old;
        nearest(pt[d]<r->x[d]?r->r:r->l,d+1);
        sd-=cd[d]-old,cd[d]=old;
    }
    pair<LL,int> query(vector<LL> &_pt,LL _md=1LL<<57){
        mID=-1,md=_md;
        copy(_pt.begin(),_pt.end(),pt);
        nearest(root,0);
        return {md,mID};
    }
}tree;

```

4.12 Poly Union

```

struct PY{
    int n; Pt pt[5]; double area;
    Pt& operator[](const int x){ return pt[x]; }
    void init(){ //n,pt[0~n-1] must be filled
        area=pt[n-1]^pt[0];
        for(int i=0;i<n-1;i++) area+=pt[i]^pt[i+1];
        if((area/=2)<0)reverse(pt,pt+n),area=-area;
    }
};
PY py[500];
pair<double,int> c[5000];
inline double segP(Pt &p,Pt &p1,Pt &p2){
    if(dcmp(p1.x-p2.x)==0) return (p.y-p1.y)/(p2.y-p1.y);
    return (p.x-p1.x)/(p2.x-p1.x);
}
double polyUnion(int n){ //py[0~n-1] must be filled
    int i,j,ii,jj,ta,tb,r,d;
    double z,w,s,sum,tc,td;
    for(i=0;i<n;i++) py[i][py[i].n]=py[i][0];
    sum=0;
    for(i=0;i<n;i++){
        for(ii=0;ii<py[i].n;ii++){
            r=0;
            c[r++]=make_pair(0.0,0);
            c[r++]=make_pair(1.0,0);
            for(j=0;j<n;j++){
                if(i==j) continue;
                for(jj=0;jj<py[j].n;jj++){
                    ta=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj]))
                        ;
                    tb=dcmp(tri(py[i][ii],py[i][ii+1],py[j][jj+1]))
                        +1));
                    if(ta==0 && tb==0){
                        if((py[j][jj+1]-py[j][jj])*(py[i][ii+1]-py[i][ii])>0 && j<i){
                            c[r++]=make_pair(segP(py[j][jj],py[i][ii],py[i][ii+1]),1);
                            c[r++]=make_pair(segP(py[j][jj+1],py[i][ii],py[i][ii+1]),-1);
                        }
                    }
                    else if(ta>0 && tb<0){
                        tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
                        td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
                        c[r++]=make_pair(tc/(tc-td),1);
                    }
                    else if(ta<0 && tb>0){
                        tc=tri(py[j][jj],py[j][jj+1],py[i][ii]);
                        td=tri(py[j][jj],py[j][jj+1],py[i][ii+1]);
                        c[r++]=make_pair(tc/(tc-td),-1);
                    }
                }
            }
        }
    }
    sort(c,c+r);
    z=min(max(c[0].first,0.0),1.0);

```

```

    d=c[0].second; s=0;
    for(j=1;j<r;j++){
        w=min(max(c[j].first,0.0),1.0);
        if(!d) s=w-z;
        d+=c[j].second; z=w;
    }
    sum+=(py[i][ii]^py[i][ii+1])*s;
}
}
return sum/2;
}

```

```

// insert s
hull.insert(s);
}
void insert(LD m,LD c) { insert(Seg(m,c)); }
LD query(LD x) { // return y @ given x
    set<Seg>::iterator it =
        hull.lower_bound(Seg(0.0,0.0,x,1));
    return it->evaly(x);
}
};

```

4.13 Lower Concave Hull

```

/****
    maintain a "concave hull" that support the following
    1. insertion of a line
    2. query of height(y) on specific x on the hull
****/
/* set as needed */
typedef long double LD;
const LD eps=1e-9;
const LD inf=1e19;
class Seg {
public:
    LD m,c,x1,x2; // y=mx+c
    bool flag;
    Seg(
        LD _m,LD _c,LD _x1=-inf,LD _x2=inf,bool _flag=0)
        :m(_m),c(_c),x1(_x1),x2(_x2),flag(_flag) {}
    LD evaly(LD x) const { return m*x+c; }
    const bool operator<(LD x) const{return x2-eps<x;}
    const bool operator<(const Seg &b) const {
        if(flag||b.flag) return *this<b.x1;
        return m+eps<b.m;
    }
};
class LowerConcaveHull { // maintain a hull like: \_/_/
public:
    set<Seg> hull;
    /* functions */
    LD xintersection(Seg a,Seg b)
    { return (a.c-b.c)/(b.m-a.m); }
    inline set<Seg>::iterator replace(set<Seg> &
        hull,set<Seg>::iterator it,Seg s) {
        hull.erase(it);
        return hull.insert(s).first;
    }
    void insert(Seg s) {
        // insert a line and update hull
        set<Seg>::iterator it=hull.find(s);
        // check for same slope
        if(it!=hull.end()) {
            if(it->c+eps>=s.c) return;
            hull.erase(it);
        }
        // check if below whole hull
        it=hull.lower_bound(s);
        if(it!=hull.end())&&
            s.evaly(it->x1)<=it->evaly(it->x1)+eps) return;
        // update right hull
        while(it!=hull.end()) {
            LD x=xintersection(s,*it);
            if(x>=it->x2-eps) hull.erase(it++);
            else {
                s.x2=x;
                it=replace(hull,it,Seg(it->m,it->c,x,it->x2));
                break;
            }
        }
        // update left hull
        while(it!=hull.begin()) {
            LD x=xintersection(s,*(--it));
            if(x<=it->x1+eps) hull.erase(it++);
            else {
                s.x1=x;
                it=replace(hull,it,Seg(it->m,it->c,it->x1,x));
                break;
            }
        }
    }
};

```

4.14 Delaunay Triangulation

```

/* Delaunay Triangulation:
    Given a sets of points on 2D plane, find a
    triangulation such that no points will strictly
    inside circumcircle of any triangle.

    find : return a triangle contain given point
    add_point : add a point into triangulation

    A Triangle is in triangulation iff. its has_chd is 0.
    Region of triangle u: iterate each u.edge[i].tri,
    each points are u.p[(i+1)%3], u.p[(i+2)%3]

    calculation involves O(|V|^6) */
const int N = 100000 + 5;
const type inf = 2e3;
type eps = 1e-6; // 0 when integer
type sqr(type x) { return x*x; }
// return p4 is in circumcircle of tri(p1,p2,p3)
bool in_cc(const Pt& p1, const Pt& p2, const Pt& p3,
    const Pt& p4){
    type u11 = p1.X - p4.X; type u12 = p1.Y - p4.Y;
    type u21 = p2.X - p4.X; type u22 = p2.Y - p4.Y;
    type u31 = p3.X - p4.X; type u32 = p3.Y - p4.Y;
    type u13 = sqr(p1.X)-sqr(p4.X)+sqr(p1.Y)-sqr(p4.Y);
    type u23 = sqr(p2.X)-sqr(p4.X)+sqr(p2.Y)-sqr(p4.Y);
    type u33 = sqr(p3.X)-sqr(p4.X)+sqr(p3.Y)-sqr(p4.Y);
    type det = -u13*u22*u31 + u12*u23*u31 + u13*u21*u32
        -u11*u23*u32 - u12*u21*u33 + u11*u22*u33;
    return det > eps;
}
type side(const Pt& a, const Pt& b, const Pt& p)
{ return (b - a) ^ (p - a); }
typedef int SdRef;
struct Tri;
typedef Tri* TriRef;
struct Edge {
    TriRef tri; SdRef side;
    Edge():tri(0), side(0){}
    Edge(TriRef _tri, SdRef _side):tri(_tri), side(_side)
    {}
};
struct Tri {
    Pt p[3];
    Edge edge[3];
    TriRef chd[3];
    Tri() {}
    Tri(const Pt& p0, const Pt& p1, const Pt& p2) {
        p[0] = p0; p[1] = p1; p[2] = p2;
        chd[0] = chd[1] = chd[2] = 0;
    }
    bool has_chd() const { return chd[0] != 0; }
    int num_chd() const {
        return chd[0] == 0 ? 0
            : chd[1] == 0 ? 1
            : chd[2] == 0 ? 2 : 3;
    }
    bool contains(Pt const& q) const {
        for( int i = 0 ; i < 3 ; i ++ )
            if( side(p[i], p[(i + 1) % 3] , q) < -eps )
                return false;
        return true;
    }
} pool[ N * 10 ], *tris;
void edge( Edge a, Edge b ){
    if(a.tri) a.tri->edge[a.side] = b;
    if(b.tri) b.tri->edge[b.side] = a;
}

```



```

struct Trig { // Triangulation
    Trig(){
        the_root = // Tri should at least contain all
                    points
                    new(tris++)Tri(Pt(-inf,-inf),Pt(+inf+inf,-inf),Pt
                    (-inf,+inf+inf));
    }
    TriRef find(Pt p){const{ return find(the_root,p); }
    void add_point(const Pt& p){ add_point(find(the_root,
        p),p); }
    TriRef the_root;
    static TriRef find(TriRef root, const Pt& p) {
        while( true ){
            if( !root->has_chd() )
                return root;
            for( int i = 0; i < 3 && root->chd[i] ; ++i )
                if (root->chd[i]->contains(p)) {
                    root = root->chd[i];
                    break;
                }
        }
        assert( false ); // "point not found"
    }
    void add_point(TriRef root, Pt const& p) {
        TriRef tab,tbc,tca;
        /* split it into three triangles */
        tab=new(tris++) Tri(root->p[0],root->p[1],p);
        tbc=new(tris++) Tri(root->p[1],root->p[2],p);
        tca=new(tris++) Tri(root->p[2],root->p[0],p);
        edge(Edge(tab,0), Edge(tbc,1));
        edge(Edge(tbc,0), Edge(tca,1));
        edge(Edge(tca,0), Edge(tab,1));
        edge(Edge(tab,2), root->edge[2]);
        edge(Edge(tbc,2), root->edge[0]);
        edge(Edge(tca,2), root->edge[1]);
        root->chd[0] = tab;
        root->chd[1] = tbc;
        root->chd[2] = tca;
        flip(tab,2);
        flip(tbc,2);
        flip(tca,2);
    }
    void flip(TriRef tri, SdRef pi) {
        TriRef trj = tri->edge[pi].tri;
        int pj = tri->edge[pi].side;
        if (!trj) return;
        if (!in_cc(tri->p[0],tri->p[1],tri->p[2],trj->p[pj]
            )) return;
        /* flip edge between tri,trj */
        TriRef trk = new(tris++) Tri(tri->p[(pi+1)%3], trj
            ->p[pj], tri->p[pi]);
        TriRef trl = new(tris++) Tri(trj->p[(pj+1)%3], tri
            ->p[pi], trj->p[pj]);
        edge(Edge(trk,0), Edge(trl,0));
        edge(Edge(trk,1), tri->edge[(pi+2)%3]);
        edge(Edge(trk,2), trj->edge[(pj+1)%3]);
        edge(Edge(trl,1), trj->edge[(pj+2)%3]);
        edge(Edge(trl,2), tri->edge[(pi+1)%3]);
        tri->chd[0]=trk; tri->chd[1]=trl; tri->chd[2]=0;
        trj->chd[0]=trk; trj->chd[1]=trl; trj->chd[2]=0;
        flip(trk,1); flip(trk,2);
        flip(trl,1); flip(trl,2);
    }
};
vector<TriRef> triang;
set<TriRef> vst;
void go( TriRef now ){
    if( vst.find( now ) != vst.end() )
        return;
    vst.insert( now );
    if( !now->has_chd() ){
        triang.push_back( now );
        return;
    }
    for( int i = 0 ; i < now->num_chd() ; i ++ )
        go( now->chd[ i ] );
}
void build( int n , Pt* ps ){
    tris = pool;
    random_shuffle(ps, ps + n);
    Trig tri;
    for(int i = 0; i < n; ++ i)

```

```

        tri.add_point(ps[i]);
        go( tri.the_root );
    }
}

```

4.15 Min Enclosing Circle

```

struct Mec{
    // return pair of center and r
    static const int N = 101010;
    int n;
    Pt p[ N ], cen;
    double r2;
    void init( int _n , Pt _p[] ){
        n = _n;
        memcpy( p , _p , sizeof(Pt) * n );
    }
    double sqr(double a){ return a*a; }
    Pt center(Pt p0, Pt p1, Pt p2) {
        Pt a = p1-p0;
        Pt b = p2-p0;
        double c1=norm2( a ) * 0.5;
        double c2=norm2( b ) * 0.5;
        double d = a ^ b;
        double x = p0.X + (c1 * b.Y - c2 * a.Y) / d;
        double y = p0.Y + (a.X * c2 - b.X * c1) / d;
        return Pt(x,y);
    }
    pair<Pt,double> solve(){
        random_shuffle(p,p+n);
        r2=0;
        for (int i=0; i<n; i++){
            if (norm2(cen-p[i]) <= r2) continue;
            cen = p[i];
            r2 = 0;
            for (int j=0; j<i; j++){
                if (norm2(cen-p[j]) <= r2) continue;
                cen=Pt((p[i].X+p[j].X)/2,(p[i].Y+p[j].Y)/2);
                r2 = norm2(cen-p[j]);
                for (int k=0; k<j; k++){
                    if (norm2(cen-p[k]) <= r2) continue;
                    cen = center(p[i],p[j],p[k]);
                    r2 = norm2(cen-p[k]);
                }
            }
            return {cen,sqrt(r2)};
        }
    }
} mec;

```

4.16 Minkowski sum

```

vector<Pt> minkowski(vector<Pt> p, vector<Pt> q){
    int n = p.size() , m = q.size();
    Pt c = Pt(0, 0);
    for( int i = 0; i < m; i ++ ) c = c + q[i];
    c = c / m;
    for( int i = 0; i < m; i ++ ) q[i] = q[i] - c;
    int cur = -1;
    for( int i = 0; i < m; i ++ )
        if( (q[i] ^ (p[0] - p[n-1])) > -eps)
            if( cur == -1 || (q[i] ^ (p[0] - p[n-1])) >
                (q[cur] ^ (p[0] - p[n-1])) )
                cur = i;
    vector<Pt> h;
    p.push_back(p[0]);
    for( int i = 0; i < n; i ++ )
        while( true ){
            h.push_back(p[i] + q[cur]);
            int nxt = (cur + 1 == m ? 0 : cur + 1);
            if((q[cur] ^ (p[i+1] - p[i])) < -eps) cur = nxt;
            else if( (q[nxt] ^ (p[i+1] - p[i])) >
                (q[cur] ^ (p[i+1] - p[i])) ) cur = nxt;
            else break;
        }
    for(auto &&i : h) i = i + c;
    return convex_hull(h);
}

```


4.17 Min dist on Cuboid

```
typedef LL T;
T r;
void turn(T i, T j, T x, T y, T z,
          T x0, T y0, T L, T W, T H) {
    if (z==0) { T R = x*x+y*y; if (R<r) r=R; return; }
    if(i>=0 && i< 2) turn(i+1, j, x0+L+z, y, x0+L-x,
                        x0+L, y0, H, W, L);
    if(j>=0 && j< 2) turn(i, j+1, x, y0+W+z, y0+W-y,
                        x0, y0+W, L, H, W);
    if(i<=0 && i>-2) turn(i-1, j, x0-z, y, x-x0,
                        x0-H, y0, H, W, L);
    if(j<=0 && j>-2) turn(i, j-1, x, y0-z, y-y0,
                        x0, y0-H, L, H, W);
}
T solve(T L, T W, T H,
        T x1, T y1, T z1, T x2, T y2, T z2){
    if( z1!=0 && z1!=H ){
        if( y1==0 || y1==W )
            swap(y1,z1), swap(y2,z2), swap(W,H);
    }else swap(x1,z1), swap(x2,z2), swap(L,H);
    if (z1==H) z1=0, z2=H-z2;
    r=INF; turn(0,0,x2-x1,y2-y1,z2,-x1,-y1,L,W,H);
    return r;
}
```

4.18 Heart of Triangle

```
Pt inCenter( Pt &A, Pt &B, Pt &C) { // 内心
    double a = norm(B-C), b = norm(C-A), c = norm(A-B);
    return (A * a + B * b + C * c) / (a + b + c);
}
Pt circumCenter( Pt &a, Pt &b, Pt &c) { // 外心
    Pt bb = b - a, cc = c - a;
    double db=norm2(bb), dc=norm2(cc), d=2*(bb ^ cc);
    return a-Pt(bb.Y*dc-cc.Y*db, cc.X*db-bb.X*dc) / d;
}
Pt othroCenter( Pt &a, Pt &b, Pt &c) { // 垂心
    Pt ba = b - a, ca = c - a, bc = b - c;
    double Y = ba.Y * ca.Y * bc.Y,
           A = ca.X * ba.Y - ba.X * ca.Y,
           x0= (Y+ca.X*ba.Y*b.X-ba.X*ca.Y*c.X) / A,
           y0= -ba.X * (x0 - c.X) / ba.Y + ca.Y;
    return Pt(x0, y0);
}
```

5 Graph

5.1 HeavyLightDecomp

```
#define REP(i, s, e) for(int i = (s); i <= (e); i++)
#define REPD(i, s, e) for(int i = (s); i >= (e); i--)
const int MAXN = 100010;
const int LOG = 19;
struct HLD{
    int n;
    vector<int> g[MAXN];
    int sz[MAXN], dep[MAXN];
    int ts, tid[MAXN], tdi[MAXN], tl[MAXN], tr[MAXN];
    // ts : timestamp, useless after yutruli
    // tid[ u ] : pos. of node u in the seq.
    // tdi[ i ] : node at pos i of the seq.
    // tl , tr[ u ] : subtree interval in the seq. of node u
    int prt[MAXN][LOG], head[MAXN];
    // head[ u ] : head of the chain contains u
    void dfsz(int u, int p){
        dep[u] = dep[p] + 1;
        prt[u][0] = p; sz[u] = 1; head[u] = u;
        for(int& v:g[u]) if(v != p){
            dep[v] = dep[u] + 1;
            dfsz(v, u);
            sz[u] += sz[v];
        }
    }
```

```
void dfs1(int u){
    ts++;
    tid[u] = tl[u] = tr[u] = ts;
    tdi[tid[u]] = u;
    sort(ALL(g[u]),
         [&](int a, int b){return sz[a] > sz[b];});
    bool flag = 1;
    for(int& v:g[u]) if(v != prt[u][0]){
        if(flag) head[v] = head[u], flag = 0;
        dfs1(v);
        tr[u] = tr[v];
    }
}
inline int lca(int a, int b){
    if(dep[a] > dep[b]) swap(a, b);
    int diff = dep[b] - dep[a];
    REPD(k, LOG-1, 0) if(diff & (1<<k)){
        b = prt[b][k];
    }
    if(a == b) return a;
    REPD(k, LOG-1, 0) if(prt[a][k] != prt[b][k]){
        a = prt[a][k]; b = prt[b][k];
    }
    return prt[a][0];
}
void init( int _n ){
    n = _n; REP( i , 1 , n ) g[ i ].clear();
}
void addEdge( int u , int v ){
    g[ u ].push_back( v );
    g[ v ].push_back( u );
}
void yutruli(){
    dfsz(1, 0);
    ts = 0;
    dfs1(1);
    REP(k, 1, LOG-1) REP(i, 1, n)
        prt[i][k] = prt[prt[i][k-1]][k-1];
}
vector< PII > getPath( int u , int v ){
    vector< PII > res;
    while( tid[ u ] < tid[ head[ v ] ] ){
        res.push_back( PII(tid[ head[ v ] ], tid[ v ]) );
        v = prt[ head[ v ] ][ 0 ];
    }
    res.push_back( PII( tid[ u ], tid[ v ] ) );
    reverse( ALL( res ) );
    return res;
}
/* res : list of intervals from u to v
 * u must be ancestor of v
 * usage :
 * vector< PII >& path = tree.getPath( u , v )
 * for( PII tp : path ) {
 *     int l , r; tie( l , r ) = tp;
 *     upd( l , r );
 *     uu = tree.tdi[ l ], vv = tree.tdi[ r ];
 *     uu ~> vv is a heavy path on tree
 * }
 */
} tree;
```

5.2 DominatorTree

```
const int MAXN = 100010;
struct DominatorTree{
    #define REP(i,s,e) for(int i=(s);i<=(e);i++)
    #define REPD(i,s,e) for(int i=(s);i>=(e);i--)
    int n , m , s;
    vector< int > g[ MAXN ], pred[ MAXN ];
    vector< int > cov[ MAXN ];
    int dfn[ MAXN ], nfd[ MAXN ], ts;
    int par[ MAXN ];
    int sdom[ MAXN ], idom[ MAXN ];
    int mom[ MAXN ], mn[ MAXN ];
    inline bool cmp( int u , int v )
    { return dfn[ u ] < dfn[ v ]; }
    int eval( int u ){
        if( mom[ u ] == u ) return u;
```

```

    int res = eval( mom[ u ] );
    if( cmp( sdom[ mn[ mom[ u ] ] ] , sdom[ mn[ u ] ] ) )
        mn[ u ] = mn[ mom[ u ] ];
    return mom[ u ] = res;
}
void init( int _n , int _m , int _s ){
    ts = 0; n = _n; m = _m; s = _s;
    REP( i , 1 , n ) g[ i ].clear(), pred[ i ].clear();
}
void addEdge( int u , int v ){
    g[ u ].push_back( v );
    pred[ v ].push_back( u );
}
void dfs( int u ){
    ts++;
    dfn[ u ] = ts;
    nfd[ ts ] = u;
    for( int v : g[ u ] ) if( dfn[ v ] == 0 ){
        par[ v ] = u;
        dfs( v );
    }
}
void build(){
    REP( i , 1 , n ){
        dfn[ i ] = nfd[ i ] = 0;
        cov[ i ].clear();
        mom[ i ] = mn[ i ] = sdom[ i ] = i;
    }
    dfs( s );
    REPD( i , n , 2 ){
        int u = nfd[ i ];
        if( u == 0 ) continue;
        for( int v : pred[ u ] ) if( dfn[ v ] ){
            eval( v );
            if( cmp( sdom[ mn[ v ] ] , sdom[ u ] ) )
                sdom[ u ] = sdom[ mn[ v ] ];
        }
        cov[ sdom[ u ] ].push_back( u );
        mom[ u ] = par[ u ];
        for( int w : cov[ par[ u ] ] ){
            eval( w );
            if( cmp( sdom[ mn[ w ] ] , par[ u ] ) )
                idom[ w ] = mn[ w ];
            else idom[ w ] = par[ u ];
        }
        cov[ par[ u ] ].clear();
    }
    REP( i , 2 , n ){
        int u = nfd[ i ];
        if( u == 0 ) continue;
        if( idom[ u ] != sdom[ u ] )
            idom[ u ] = idom[ idom[ u ] ];
    }
}
} domT;

```

5.3 MaxClique

```

#define N 111
struct MaxClique{ // 0-base
    typedef bitset< N > Int;
    Int linkto[ N ] , v[ N ];
    int n;
    void init( int _n ){
        n = _n;
        for( int i = 0 ; i < n ; i ++ ){
            linkto[ i ].reset();
            v[ i ].reset();
        }
    }
    void addEdge( int a , int b ){
        v[ a ][ b ] = v[ b ][ a ] = 1;
    }
    int popcount( const Int& val )
    { return val.count(); }
    int lowbit( const Int& val )
    { return val._Find_first(); }
    int ans , stk[ N ];
    int id[ N ] , di[ N ] , deg[ N ];
    Int cans;

```

```

    void maxclique( int elem_num , Int candi ){
        if( elem_num > ans ){
            ans = elem_num;
            cans.reset();
            for( int i = 0 ; i < elem_num ; i ++ )
                cans[ id[ stk[ i ] ] ] = 1;
        }
        int potential = elem_num + popcount( candi );
        if( potential <= ans ) return;
        int pivot = lowbit( candi );
        Int smaller_candi = candi & (~linkto[pivot]);
        while( smaller_candi.count() && potential > ans ){
            int next = lowbit( smaller_candi );
            candi[next] = !candi[next];
            smaller_candi[ next ] = !smaller_candi[ next ];
            potential --;
            if( next == pivot || (smaller_candi & linkto[next]
                ).count() ){
                stk[ elem_num ] = next;
                maxclique( elem_num + 1 , candi & linkto[next] );
            }
        }
    }
    int solve(){
        for( int i = 0 ; i < n ; i ++ ){
            id[ i ] = i;
            deg[ i ] = v[ i ].count();
        }
        sort( id , id + n , [&]( int id1 , int id2 ){
            return deg[id1] > deg[id2]; } );
        for( int i = 0 ; i < n ; i ++ )
            di[ id[ i ] ] = i;
        for( int i = 0 ; i < n ; i ++ )
            for( int j = 0 ; j < n ; j ++ )
                if( v[ i ][ j ] )
                    linkto[ di[ i ] ][ di[ j ] ] = 1;
        Int cand; cand.reset();
        for( int i = 0 ; i < n ; i ++ )
            cand[ i ] = 1;
        ans = 1;
        cans.reset(); cans[ 0 ] = 1;
        maxclique( 0 , cand );
        return ans;
    }
} solver;

```

5.4 Strongly Connected Component

```

void dfs( int i ){
    V[i] = low[i] = ++ts, stk[top++] = i, instk[i] = 1;
    for( auto x : E[i] ){
        if( !V[x] ) dfs( x ), low[i] = min( low[i] , low[x] );
        else if( instk[x] ) low[i] = min( low[i] , V[x] );
    }
    if( V[i] == low[i] ){
        int j;
        do{ j = stk[--top], instk[j] = 0, scc[j] = i; } while( j != i );
    }
}

```

5.5 Dynamic MST

```

/* Dynamic MST O( Q lg^2 Q )
(qx[i], qy[i]) -> chg weight of edge No. qx[i] to qy[i]
delete an edge: (i, \infty)
add an edge: change from \infty to specific value
*/
const int SZ = M + 3 * MXQ;
int a[ N ], *tz;
int find( int xx ){
    int root = xx; while( a[root] ) root = a[root];
    int next; while( (next = a[xx]) ){ a[xx] = root; xx = next; }
    return root;
}
bool cmp( int aa , int bb ){ return tz[aa] < tz[bb]; }
int kx[ N ], ky[ N ], kt , vd[ N ], id[ M ], app[ M ];
bool extra[ M ];

```

```

void solve(int *qx,int *qy,int Q,int n,int *x,int *y,
int *z,int m1,long long ans){
    if(Q==1){
        for(int i=1;i<=n;i++) a[i]=0;
        z[ qx[0] ]=qy[0]; tz = z;
        for(int i=0;i<m1;i++) id[i]=i;
        sort(id,id+m1,cmp); int ri,rj;
        for(int i=0;i<m1;i++){
            ri=find(x[id[i]]); rj=find(y[id[i]]);
            if(ri!=rj){ ans+=z[id[i]]; a[ri]=rj; }
        }
        printf("%lld\n",ans);
        return;
    }
    int ri,rj;
    //contract
    kt=0;
    for(int i=1;i<=n;i++) a[i]=0;
    for(int i=0;i<Q;i++){
        ri=find(x[qx[i]]); rj=find(y[qx[i]]); if(ri!=rj) a[ri]=rj;
    }
    int tm=0;
    for(int i=0;i<m1;i++) extra[i]=true;
    for(int i=0;i<Q;i++) extra[ qx[i] ]=false;
    for(int i=0;i<m1;i++) if(extra[i]) id[tm++]=i;
    tz=z; sort(id,id+tm,cmp);
    for(int i=0;i<tm;i++){
        ri=find(x[id[i]]); rj=find(y[id[i]]);
        if(ri!=rj){
            a[ri]=rj; ans += z[id[i]];
            kx[kt]=x[id[i]]; ky[kt]=y[id[i]]; kt++;
        }
    }
    for(int i=1;i<=n;i++) a[i]=0;
    for(int i=0;i<kt;i++) a[ find(kx[i]) ]=find(ky[i]);
    int n2=0;
    for(int i=1;i<=n;i++) if(a[i]==0)
        vd[i]++;n2;
    for(int i=1;i<=n;i++) if(a[i])
        vd[i]=vd[find(i)];
    int m2=0, *Nx=x+m1, *Ny=y+m1, *Nz=z+m1;
    for(int i=0;i<m1;i++) app[i]=-1;
    for(int i=0;i<Q;i++) if(app[qx[i]]==-1){
        Nx[m2]=vd[ x[ qx[i] ] ]; Ny[m2]=vd[ y[ qx[i] ] ];
        Nz[m2]=z[ qx[i] ];
        app[qx[i]]=m2; m2++;
    }
    for(int i=0;i<Q;i++){ z[ qx[i] ]=qy[i]; qx[i]=app[qx[i]]; }
    for(int i=1;i<=n2;i++) a[i]=0;
    for(int i=0;i<tm;i++){
        ri=find(vd[ x[id[i]] ]); rj=find(vd[ y[id[i]] ]);
        if(ri!=rj){
            a[ri]=rj; Nx[m2]=vd[ x[id[i]] ];
            Ny[m2]=vd[ y[id[i]] ]; Nz[m2]=z[id[i]]; m2++;
        }
    }
    int mid=Q/2;
    solve(qx,qy,mid,n2,Nx,Ny,Nz,m2,ans);
    solve(qx+mid,qy+mid,Q-mid,n2,Nx,Ny,Nz,m2,ans);
}
int x[SZ],y[SZ],z[SZ],qx[MXQ],qy[MXQ],n,m,Q;
void init(){
    scanf("%d%d",&n,&m);
    for(int i=0;i<m;i++) scanf("%d%d%d",x+i,y+i,z+i);
    scanf("%d",&Q);
    for(int i=0;i<Q;i++){ scanf("%d%d",qx+i,qy+i); qx[i]--; }
}
void work(){ if(Q) solve(qx,qy,Q,n,x,y,z,m,0); }
int main(){init(); work(); }

```

5.6 Maximum General graph Matching

```

const int N = 514, E = (2e5) * 2;
struct Graph{
    int to[E],bro[E],head[N],e;
    int lnk[N],vis[N],stp,n;
    void init( int _n ){

```

```

        stp = 0; e = 1; n = _n;
        for( int i = 1 ; i <= n ; i ++ )
            lnk[i] = vis[i] = 0;
    }
    void add_edge(int u,int v){
        to[e]=v,bro[e]=head[u],head[u]=e++;
        to[e]=u,bro[e]=head[v],head[v]=e++;
    }
    bool dfs(int x){
        vis[x]=stp;
        for(int i=head[x];i;i=bro[i]){
            int v=to[i];
            if(!lnk[v]){
                lnk[x]=v,lnk[v]=x;
                return true;
            }else if(vis[lnk[v]]<stp){
                int w=lnk[v];
                lnk[x]=v,lnk[v]=x,lnk[w]=0;
                if(dfs(w)){
                    return true;
                }
                lnk[w]=v,lnk[v]=w,lnk[x]=0;
            }
        }
        return false;
    }
    int solve(){
        int ans = 0;
        for(int i=1;i<=n;i++)
            if(!lnk[i]){
                stp++; ans += dfs(i);
            }
        return ans;
    }
} graph;

```

5.7 Minimum General Weighted Matching

```

struct Graph {
    // Minimum General Weighted Matching (Perfect Match)
    static const int MXN = 105;
    int n, edge[MXN][MXN];
    int match[MXN],dis[MXN],onstk[MXN];
    vector<int> stk;
    void init(int _n) {
        n = _n;
        for( int i = 0 ; i < n ; i ++ )
            for( int j = 0 ; j < n ; j ++ )
                edge[ i ][ j ] = 0;
    }
    void add_edge(int u, int v, int w)
    { edge[u][v] = edge[v][u] = w; }
    bool SPFA(int u){
        if (onstk[u]) return true;
        stk.PB(u);
        onstk[u] = 1;
        for (int v=0; v<n; v++){
            if (u != v && match[u] != v && !onstk[v]){
                int m = match[v];
                if (dis[m] > dis[u] - edge[v][m] + edge[u][v]){
                    dis[m] = dis[u] - edge[v][m] + edge[u][v];
                    onstk[v] = 1;
                    stk.PB(v);
                    if (SPFA(m)) return true;
                    stk.pop_back();
                    onstk[v] = 0;
                }
            }
        }
        onstk[u] = 0;
        stk.pop_back();
        return false;
    }
    int solve() {
        // find a match
        for (int i=0; i<n; i+=2){
            match[i] = i+1;
            match[i+1] = i;
        }
        while (true){

```

```

    int found = 0;
    for( int i = 0 ; i < n ; i ++ )
        onstk[ i ] = dis[ i ] = 0;
    for (int i=0; i<n; i++){
        stk.clear();
        if (!onstk[i] && SPFA(i)){
            found = 1;
            while (SZ(stk)>=2){
                int u = stk.back(); stk.pop_back();
                int v = stk.back(); stk.pop_back();
                match[u] = v;
                match[v] = u;
            }
        }
    }
    if (!found) break;
}
int ret = 0;
for (int i=0; i<n; i++)
    ret += edge[i][match[i]];
ret /= 2;
return ret;
}
}graph;

```

5.8 Maximum General Weighted Matching

```

struct WeightGraph {
    static const int INF = INT_MAX;
    static const int N = 514;
    struct edge{
        int u,v,w; edge(){}
        edge(int ui,int vi,int wi)
            :u(ui),v(vi),w(wi){}
    };
    int n,n_x;
    edge g[N*2][N*2];
    int lab[N*2];
    int match[N*2],slack[N*2],st[N*2],pa[N*2];
    int flo_from[N*2][N+1],S[N*2],vis[N*2];
    vector<int> flo[N*2];
    queue<int> q;
    int e_delta(const edge &e){
        return lab[e.u]+lab[e.v]-g[e.u][e.v].w*2;
    }
    void update_slack(int u,int x){
        if(!slack[x]||e_delta(g[u][x])<e_delta(g[slack[x]][x]))slack[x]=u;
    }
    void set_slack(int x){
        slack[x]=0;
        for(int u=1;u<=n;++u)
            if(g[u][x].w>0&&st[u]!=x&&S[st[u]]==0)
                update_slack(u,x);
    }
    void q_push(int x){
        if(x<=n)q.push(x);
        else for(size_t i=0;i<flo[x].size();i++)
            q_push(flo[x][i]);
    }
    void set_st(int x,int b){
        st[x]=b;
        if(x>n)for(size_t i=0;i<flo[x].size();++i)
            set_st(flo[x][i],b);
    }
    int get_pr(int b,int xr){
        int pr=find(flo[b].begin(),flo[b].end(),xr)-flo[b].begin();
        if(pr%2==1){
            reverse(flo[b].begin()+1,flo[b].end());
            return (int)flo[b].size()-pr;
        }else return pr;
    }
    void set_match(int u,int v){
        match[u]=g[u][v].v;
        if(u<=n) return;
        edge e=g[u][v];
        int xr=flo_from[u][e.u],pr=get_pr(u,xr);
        for(int i=0;i<pr;++i)set_match(flo[u][i],flo[u][i+1]);
    }

```

```

    set_match(xr,v);
    rotate(flo[u].begin(),flo[u].begin()+pr,flo[u].end());
}
void augment(int u,int v){
    for(;;){
        int xnv=st[match[u]];
        set_match(u,v);
        if(!xnv)return;
        set_match(xnv,st[pa[xnv]]);
        u=st[pa[xnv]],v=xnv;
    }
}
int get_lca(int u,int v){
    static int t=0;
    for(++t;u||v;swap(u,v)){
        if(u==0)continue;
        if(vis[u]==t)return u;
        vis[u]=t;
        u=st[match[u]];
        if(u)u=st[pa[u]];
    }
    return 0;
}
void add_blossom(int u,int lca,int v){
    int b=n+1;
    while(b<=n_x&&st[b])++b;
    if(b>n_x)++n_x;
    lab[b]=0,S[b]=0;
    match[b]=match[lca];
    flo[b].clear();
    flo[b].push_back(lca);
    for(int x=u,y;x!=lca;x=st[pa[y]])
        flo[b].push_back(x),flo[b].push_back(y=st[match[x]]),q_push(y);
    reverse(flo[b].begin()+1,flo[b].end());
    for(int x=v,y;x!=lca;x=st[pa[y]])
        flo[b].push_back(x),flo[b].push_back(y=st[match[x]]),q_push(y);
    set_st(b,b);
    for(int x=1;x<=n_x;++x)g[b][x].w=g[x][b].w=0;
    for(int x=1;x<=n;++x)flo_from[b][x]=0;
    for(size_t i=0;i<flo[b].size();++i){
        int xs=flo[b][i];
        for(int x=1;x<=n_x;++x)
            if(g[b][x].w==0||e_delta(g[xs][x])<e_delta(g[b][x]))
                g[b][x]=g[xs][x],g[x][b]=g[x][xs];
        for(int x=1;x<=n;++x)
            if(flo_from[xs][x])flo_from[b][x]=xs;
    }
    set_slack(b);
}
void expand_blossom(int b){
    for(size_t i=0;i<flo[b].size();++i)
        set_st(flo[b][i],flo[b][i]);
    int xr=flo_from[b][g[b][pa[b]].u],pr=get_pr(b,xr);
    for(int i=0;i<pr;i+=2){
        int xs=flo[b][i],xns=flo[b][i+1];
        pa[xs]=g[xns][xs].u;
        S[xs]=1,S[xns]=0;
        slack[xs]=0,set_slack(xns);
        q_push(xns);
    }
    S[xr]=1,pa[xr]=pa[b];
    for(size_t i=pr+1;i<flo[b].size();++i){
        int xs=flo[b][i];
        S[xs]=-1,set_slack(xs);
    }
    st[b]=0;
}
bool on_found_edge(const edge &e){
    int u=st[e.u],v=st[e.v];
    if(S[v]==-1){
        pa[v]=e.u,S[v]=1;
        int nu=st[match[v]];
        slack[v]=slack[nu]=0;
        S[nu]=0,q_push(nu);
    }else if(S[v]==0){
        int lca=get_lca(u,v);
        if(!lca)return augment(u,v),augment(v,u),true;
        else add_blossom(u,lca,v);
    }
}

```

```

    }
    return false;
}
bool matching(){
    memset(S+1,-1,sizeof(int)*n_x);
    memset(slack+1,0,sizeof(int)*n_x);
    q=queue<int>();
    for(int x=1;x<=n_x;++x)
        if(st[x]==x&&!match[x])pa[x]=0,S[x]=0,q_push(x);
    if(q.empty())return false;
    for(;;){
        while(q.size()){
            int u=q.front();q.pop();
            if(S[st[u]]==1)continue;
            for(int v=1;v<=n;v++){
                if(g[u][v].w>0&&st[u]!=st[v]){
                    if(e_delta(g[u][v])==0){
                        if(on_found_edge(g[u][v]))return true;
                    }else update_slack(u,st[v]);
                }
            }
        }
        int d=INF;
        for(int b=n+1;b<=n_x;++b)
            if(st[b]==b&&S[b]==1)d=min(d,lab[b]/2);
        for(int x=1;x<=n_x;++x)
            if(st[x]==x&&slack[x]){
                if(S[x]==-1)d=min(d,e_delta(g[slack[x]][x]));
                else if(S[x]==0)d=min(d,e_delta(g[slack[x]][x])/2);
            }
        for(int u=1;u<=n;++u){
            if(S[st[u]]==0){
                if(lab[u]<=d)return 0;
                lab[u]-=d;
            }else if(S[st[u]]==1)lab[u]+=d;
        }
        for(int b=n+1;b<=n_x;++b)
            if(st[b]==b){
                if(S[st[b]]==0)lab[b]+=d*2;
                else if(S[st[b]]==1)lab[b]-=d*2;
            }
        q=queue<int>();
        for(int x=1;x<=n_x;++x)
            if(st[x]==x&&slack[x]&&st[slack[x]]!=x&&e_delta(g[slack[x]][x])==0)
                if(on_found_edge(g[slack[x]][x]))return true;
        for(int b=n+1;b<=n_x;++b)
            if(st[b]==b&&S[b]==1&&lab[b]==0)expand_blossom(b);
    }
    return false;
}
pair<long long,int> solve(){
    memset(match+1,0,sizeof(int)*n);
    n_x=n;
    int n_matches=0;
    long long tot_weight=0;
    for(int u=0;u<=n;++u)st[u]=u,flo[u].clear();
    int w_max=0;
    for(int u=1;u<=n;++u)
        for(int v=1;v<=n;v++){
            flo_from[u][v]=(u==v?0);
            w_max=max(w_max,g[u][v].w);
        }
    for(int u=1;u<=n;++u)lab[u]=w_max;
    while(matching())n_matches++;
    for(int u=1;u<=n;++u)
        if(match[u]&&match[u]<u)
            tot_weight+=g[u][match[u]].w;
    return make_pair(tot_weight,n_matches);
}
void add_edge( int ui , int vi , int wi ){
    g[ui][vi].w = g[vi][ui].w = wi;
}
void init( int _n ){
    n = _n;
    for(int u=1;u<=n;++u)
        for(int v=1;v<=n;v++)
            g[u][v]=edge(u,v,0);
}
} graph;

```

5.9 Minimum Steiner Tree

```

// Minimum Steiner Tree
//  $O(V 3^T + V^2 2^T)$ 
struct SteinerTree{
#define V 33
#define T 8
#define INF 1023456789
    int n , dst[V][V] , dp[1<<T][V] , tdst[V];
    void init( int _n ){
        n = _n;
        for( int i = 0 ; i < n ; i ++ ){
            for( int j = 0 ; j < n ; j ++ )
                dst[ i ][ j ] = INF;
            dst[ i ][ i ] = 0;
        }
    }
    void add_edge( int ui , int vi , int wi ){
        dst[ ui ][ vi ] = min( dst[ ui ][ vi ] , wi );
        dst[ vi ][ ui ] = min( dst[ vi ][ ui ] , wi );
    }
    void shortest_path(){
        for( int k = 0 ; k < n ; k ++ )
            for( int i = 0 ; i < n ; i ++ )
                for( int j = 0 ; j < n ; j ++ )
                    dst[ i ][ j ] = min( dst[ i ][ j ] ,
                        dst[ i ][ k ] + dst[ k ][ j ] );
    }
    int solve( const vector<int>& ter ){
        int t = (int)ter.size();
        for( int i = 0 ; i < ( 1 << t ) ; i ++ )
            for( int j = 0 ; j < n ; j ++ )
                dp[ i ][ j ] = INF;
        for( int i = 0 ; i < n ; i ++ )
            dp[ 0 ][ i ] = 0;
        for( int msk = 1 ; msk < ( 1 << t ) ; msk ++ ){
            if( msk == ( msk & (-msk) ) ){
                int who = __lg( msk );
                for( int i = 0 ; i < n ; i ++ )
                    dp[ msk ][ i ] = dst[ ter[ who ] ][ i ];
                continue;
            }
            for( int i = 0 ; i < n ; i ++ )
                for( int submsk = ( msk - 1 ) & msk ; submsk ;
                    submsk = ( submsk - 1 ) & msk )
                    dp[ msk ][ i ] = min( dp[ msk ][ i ] ,
                        dp[ submsk ][ i ] +
                        dp[ msk ^ submsk ][ i ] );
            for( int i = 0 ; i < n ; i ++ ){
                tdst[ i ] = INF;
                for( int j = 0 ; j < n ; j ++ )
                    tdst[ i ] = min( tdst[ i ] ,
                        dp[ msk ][ j ] + dst[ j ][ i ] );
            }
            for( int i = 0 ; i < n ; i ++ )
                dp[ msk ][ i ] = tdst[ i ];
        }
        int ans = INF;
        for( int i = 0 ; i < n ; i ++ )
            ans = min( ans , dp[ ( 1 << t ) - 1 ][ i ] );
        return ans;
    }
} solver;

```

5.10 BCC based on vertex

```

struct BccVertex {
    int n,nScc,step,dfn[MXN],low[MXN];
    vector<int> E[MXN],sccv[MXN];
    int top,stk[MXN];
    void init(int _n) {
        n = _n; nScc = step = 0;
        for (int i=0; i<n; i++) E[i].clear();
    }
    void addEdge(int u, int v)
    { E[u].PB(v); E[v].PB(u); }
    void DFS(int u, int f) {
        dfn[u] = low[u] = step++;
        stk[top++] = u;
    }

```

```

for (auto v:E[u]) {
    if (v == f) continue;
    if (dfn[v] == -1) {
        DFS(v,u);
        low[u] = min(low[u], low[v]);
        if (low[v] >= dfn[u]) {
            int z;
            sccv[nScc].clear();
            do {
                z = stk[--top];
                sccv[nScc].PB(z);
            } while (z != v);
            sccv[nScc++].PB(u);
        }
    } else
        low[u] = min(low[u], dfn[v]);
}
}
vector<vector<int>> solve() {
    vector<vector<int>> res;
    for (int i=0; i<n; i++)
        dfn[i] = low[i] = -1;
    for (int i=0; i<n; i++)
        if (dfn[i] == -1) {
            top = 0;
            DFS(i,i);
        }
    REP(i,nScc) res.PB(sccv[i]);
    return res;
}
}graph;

```

5.11 Min Mean Cycle

```

/* minimum mean cycle O(VE) */
struct MMC{
#define E 101010
#define V 1021
#define inf 1e9
#define eps 1e-6
    struct Edge { int v,u; double c; };
    int n, m, prv[V][V], prve[V][V], vst[V];
    Edge e[E];
    vector<int> edgeID, cycle, rho;
    double d[V][V];
    void init( int _n )
    { n = _n; m = 0; }
    // WARNING: TYPE matters
    void addEdge( int vi , int ui , double ci )
    { e[ m ++ ] = { vi , ui , ci }; }
    void bellman_ford() {
        for(int i=0; i<n; i++) d[0][i]=0;
        for(int i=0; i<n; i++) {
            fill(d[i+1], d[i+1]+n, inf);
            for(int j=0; j<m; j++) {
                int v = e[j].v, u = e[j].u;
                if(d[i][v]<inf && d[i+1][u]>d[i][v]+e[j].c) {
                    d[i+1][u] = d[i][v]+e[j].c;
                    prv[i+1][u] = v;
                    prve[i+1][u] = j;
                }
            }
        }
    }
    double solve(){
        // returns inf if no cycle, mmc otherwise
        double mmc=inf;
        int st = -1;
        bellman_ford();
        for(int i=0; i<n; i++) {
            double avg=-inf;
            for(int k=0; k<n; k++) {
                if(d[n][i]<inf-eps) avg=max(avg,(d[n][i]-d[k][i])/(n-k));
                else avg=max(avg,inf);
            }
            if (avg < mmc) tie(mmc, st) = tie(avg, i);
        }
        FZ(vst); edgeID.clear(); cycle.clear(); rho.clear();
    }
};

```

```

for (int i=n; !vst[st]; st=prv[i--][st]) {
    vst[st]++;
    edgeID.PB(prve[i][st]);
    rho.PB(st);
}
while (vst[st] != 2) {
    int v = rho.back(); rho.pop_back();
    cycle.PB(v);
    vst[v]++;
}
reverse(ALL(edgeID));
edgeID.resize(SZ(cycle));
return mmc;
}
} mmc;

```

5.12 Directed Graph Min Cost Cycle

```

// works in O(N M)
#define INF 100000000000000LL
#define N 5010
#define M 200010
struct edge{
    int to; LL w;
    edge(int a=0, LL b=0): to(a), w(b){}
};
struct node{
    LL d; int u, next;
    node(LL a=0, int b=0, int c=0): d(a), u(b), next(c){}
}b[M];
struct DirectedGraphMinCycle{
    vector<edge> g[N], grev[N];
    LL dp[N][N], p[N], d[N], mu;
    bool inq[N];
    int n, bn, bsz, hd[N];
    void b_insert(LL d, int u){
        int i = d/mu;
        if(i >= bn) return;
        b[++bsz] = node(d, u, hd[i]);
        hd[i] = bsz;
    }
    void init( int _n ){
        n = _n;
        for( int i = 1 ; i <= n ; i ++ )
            g[ i ].clear();
    }
    void addEdge( int ai , int bi , LL ci )
    { g[ai].push_back(edge(bi,ci)); }
    LL solve(){
        fill(dp[0], dp[0]+n+1, 0);
        for(int i=1; i<=n; i++){
            fill(dp[i]+1, dp[i]+n+1, INF);
            for(int j=1; j<=n; j++) if(dp[i-1][j] < INF){
                for(int k=0; k<(int)g[j].size(); k++){
                    dp[i][g[j][k].to] =min(dp[i][g[j][k].to],
                                            dp[i-1][j]+g[j][k].w);
                }
            }
        }
        mu=INF; LL bunbo=1;
        for(int i=1; i<=n; i++) if(dp[n][i] < INF){
            LL a=-INF, b=1;
            for(int j=0; j<=n-1; j++) if(dp[j][i] < INF){
                if(a*(n-j) < b*(dp[n][i]-dp[j][i])){
                    a = dp[n][i]-dp[j][i];
                    b = n-j;
                }
            }
            if(mu*b > bunbo*a)
                mu = a, bunbo = b;
        }
        if(mu < 0) return -1; // negative cycle
        if(mu == INF) return INF; // no cycle
        if(mu == 0) return 0;
        for(int i=1; i<=n; i++){
            for(int j=0; j<(int)g[i].size(); j++)
                g[i][j].w *= bunbo;
            memset(p, 0, sizeof(p));
            queue<int> q;
            for(int i=1; i<=n; i++){
                q.push(i);
            }
        }
    }
};

```



```

    inq[i] = true;
}
while(!q.empty()){
    int i=q.front(); q.pop(); inq[i]=false;
    for(int j=0; j<(int)g[i].size(); j++){
        if(p[g[i][j].to] > p[i]+g[i][j].w-mu){
            p[g[i][j].to] = p[i]+g[i][j].w-mu;
            if(!inq[g[i][j].to]){
                q.push(g[i][j].to);
                inq[g[i][j].to] = true;
            }
        }
    }
}
for(int i=1; i<=n; i++) grev[i].clear();
for(int i=1; i<=n; i++){
    for(int j=0; j<(int)g[i].size(); j++){
        g[i][j].w += p[i]-p[g[i][j].to];
        grev[g[i][j].to].push_back(edge(i, g[i][j].w));
    }
}
LL mlldc = n*mu;
for(int i=1; i<=n; i++){
    bn=mlldc/mu, bsz=0;
    memset(hd, 0, sizeof(hd));
    fill(d+i+1, d+n+1, INF);
    b_insert(d[i]=0, i);
    for(int j=0; j<=bn-1; j++) for(int k=hd[j]; k; k=
        b[k].next){
        int u = b[k].u;
        LL du = b[k].d;
        if(du > d[u]) continue;
        for(int l=0; l<(int)g[u].size(); l++) if(g[u][l]
            .to > i){
            if(d[g[u][l].to] > du + g[u][l].w){
                d[g[u][l].to] = du + g[u][l].w;
                b_insert(d[g[u][l].to], g[u][l].to);
            }
        }
    }
    for(int j=0; j<(int)grev[i].size(); j++) if(grev[
        i][j].to > i)
        mlldc=min(mlldc,d[grev[i][j].to] + grev[i][j].w);
}
return mlldc / bunbo;
}
} graph;

```

5.13 K-th Shortest Path

```

// time: O(|E| \lg |E| + |V| \lg |V| + K)
// memory: O(|E| \lg |E| + |V|)
struct KSP{ // 1-base
    struct nd{
        int u, v, d;
        nd(int ui = 0, int vi = 0, int di = INF)
        { u = ui; v = vi; d = di; }
    };
    struct heap{
        nd* edge; int dep; heap* chd[4];
    };
    static int cmp(heap* a, heap* b)
    { return a->edge->d > b->edge->d; }
    struct node{
        int v; LL d; heap* H; nd* E;
        node(){
            node(LL _d, int _v, nd* _E)
            { d = _d; v = _v; E = _E; }
            node(heap* _H, LL _d)
            { H = _H; d = _d; }
            friend bool operator<(node a, node b)
            { return a.d > b.d; }
        };
        int n, k, s, t, dst[ N ];
        nd *nxt[ N ];
        vector<nd*> g[ N ], rg[ N ];
        heap *nullNd, *head[ N ];
        void init( int _n, int _k, int _s, int _t ){
            n = _n; k = _k; s = _s; t = _t;
            for( int i = 1; i <= n; i ++ ){
                g[ i ].clear(); rg[ i ].clear();

```

```

                nxt[ i ] = head[ i ] = NULL;
                dst[ i ] = -1;
            }
        }
        void addEdge( int ui, int vi, int di ){
            nd* e = new nd(ui, vi, di);
            g[ ui ].push_back( e );
            rg[ vi ].push_back( e );
        }
        queue<int> dfsQ;
        void dijkstra(){
            while(dfsQ.size()) dfsQ.pop();
            priority_queue<node> Q;
            Q.push(node(0, t, NULL));
            while (!Q.empty()){
                node p = Q.top(); Q.pop();
                if(dst[p.v] != -1) continue;
                dst[ p.v ] = p.d;
                nxt[ p.v ] = p.E;
                dfsQ.push( p.v );
                for(auto e: rg[ p.v ])
                    Q.push(node(p.d + e->d, e->u, e));
            }
        }
        heap* merge(heap* curNd, heap* newNd){
            if(curNd == nullNd) return newNd;
            heap* root = new heap;
            memcpy(root, curNd, sizeof(heap));
            if(newNd->edge->d < curNd->edge->d){
                root->edge = newNd->edge;
                root->chd[2] = newNd->chd[2];
                root->chd[3] = newNd->chd[3];
                newNd->edge = curNd->edge;
                newNd->chd[2] = curNd->chd[2];
                newNd->chd[3] = curNd->chd[3];
            }
            if(root->chd[0]->dep < root->chd[1]->dep)
                root->chd[0] = merge(root->chd[0], newNd);
            else
                root->chd[1] = merge(root->chd[1], newNd);
            root->dep = max(root->chd[0]->dep, root->chd[1]->
                dep) + 1;
            return root;
        }
        vector<heap*> V;
        void build(){
            nullNd = new heap;
            nullNd->dep = 0;
            nullNd->edge = new nd;
            fill(nullNd->chd, nullNd->chd+4, nullNd);
            while(not dfsQ.empty()){
                int u = dfsQ.front(); dfsQ.pop();
                if(!nxt[ u ]) head[ u ] = nullNd;
                else head[ u ] = head[nxt[ u ]->v];
                V.clear();
                for( auto&& e : g[ u ] ){
                    int v = e->v;
                    if( dst[ v ] == -1 ) continue;
                    e->d += dst[ v ] - dst[ u ];
                    if( nxt[ u ] != e ){
                        heap* p = new heap;
                        fill(p->chd, p->chd+4, nullNd);
                        p->dep = 1;
                        p->edge = e;
                        V.push_back(p);
                    }
                }
                if(V.empty()) continue;
                make_heap(V.begin(), V.end(), cmp);
                #define L(X) ((X<<1)+1)
                #define R(X) ((X<<1)+2)
                for( size_t i = 0; i < V.size(); i ++ ){
                    if(L(i) < V.size()) V[i]->chd[2] = V[L(i)];
                    else V[i]->chd[2]=nullNd;
                    if(R(i) < V.size()) V[i]->chd[3] = V[R(i)];
                    else V[i]->chd[3]=nullNd;
                }
                head[u] = merge(head[u], V.front());
            }
        }
        vector<LL> ans;
        void first_KC(){

```

```

ans.clear();
priority_queue<node> Q;
if( dst[ s ] == -1 ) return;
ans.push_back( dst[ s ] );
if( head[s] != nullNd )
    Q.push(node(head[s], dst[s]+head[s]->edge->d));
for( int _ = 1 ; _ < k and not Q.empty() ; _ ++ ){
    node p = Q.top(), q; Q.pop();
    ans.push_back( p.d );
    if(head[ p.H->edge->v ] != nullNd){
        q.H = head[ p.H->edge->v ];
        q.d = p.d + q.H->edge->d;
        Q.push(q);
    }
    for( int i = 0 ; i < 4 ; i ++ )
        if( p.H->chd[ i ] != nullNd ){
            q.H = p.H->chd[ i ];
            q.d = p.d - p.H->edge->d + p.H->chd[ i ]->
                edge->d;
            Q.push( q );
        }
}
}
void solve(){
    dijkstra();
    build();
    first_K();
}
} solver;

```

6 String

6.1 PalTree

```

const int MXN = 1000010;
struct PalT{
    int nxt[MXN][26], fail[MXN], len[MXN], cnt[MXN], num[MXN];
    int tot, lst, n;
    char s[MXN] = {-1};
    int newNode(int l, int f){
        len[tot] = l, fail[tot] = f, cnt[tot] = num[tot] = 0;
        memset(nxt[tot], 0, sizeof(nxt[tot]));
        return tot++;
    }
    int get_fail(int x){
        while(s[n-len[x]-1] != s[n]) x = fail[x];
        return x;
    }
    void push(){
        int c = s[n] - 'a', np = get_fail(lst);
        if(! (lst = nxt[np][c])){
            lst = newNode(len[np] + 2, get_fail(fail[np]))[c];
            nxt[np][c] = lst;
            num[lst] = num[fail[lst]] + 1;
        }
        ++cnt[lst];
    }
    void init(const char *_s){
        tot = lst = n = 0;
        newNode(0, 1), newNode(-1, 0);
        for(; *_s; ++_s) s[n++] = *_s, ++n, push();
        for(int i = tot - 1; i > 1; i--) cnt[fail[i]] += cnt[i];
    }
} palT;

```

6.2 SAIS

```

const int N = 300010;
struct SA{
#define REP(i,n) for ( int i=0; i<int(n); i++ )
#define REP1(i,a,b) for ( int i=(a); i<=int(b); i++ )
    bool _t[N*2];
    int _s[N*2], _sa[N*2], _c[N*2], x[N], _p[N], _q[N*2],
        hei[N], r[N];

```

```

int operator [] (int i){ return _sa[i]; }
void build(int *s, int n, int m){
    memcpy(_s, s, sizeof(int) * n);
    sais(_s, _sa, _p, _q, _t, _c, n, m);
    mkhei(n);
}
void mkhei(int n){
    REP(i,n) r[_sa[i]] = i;
    hei[0] = 0;
    REP(i,n) if(r[i]) {
        int ans = i > 0 ? max(hei[r[i-1]] - 1, 0) : 0;
        while(_s[i+ans] == _s[_sa[r[i]-1]+ans]) ans++;
        hei[r[i]] = ans;
    }
}
void sais(int *s, int *sa, int *p, int *q, bool *t,
    int *c, int n, int z){
    bool uniq = t[n-1] = true, neq;
    int nn = 0, nmzx = -1, *nsa = sa + n, *ns = s + n,
        lst = -1;
#define MS0(x,n) memset((x),0,n*sizeof(*(x)))
#define MAGIC(XD) MS0(sa, n); \
    memcpy(x, c, sizeof(int) * z); \
    XD; \
    memcpy(x + 1, c, sizeof(int) * (z - 1)); \
    REP(i,n) if(sa[i] && !t[sa[i]-1]) sa[x[s[sa[i]-1]]++] =
        sa[i]-1; \
    memcpy(x, c, sizeof(int) * z); \
    for(int i = n - 1; i >= 0; i--) if(sa[i] && t[sa[i]-1])
        sa[--x[s[sa[i]-1]]] = sa[i]-1;
    MS0(c, z);
    REP(i,n) uniq &= ++c[s[i]] < 2;
    REP(i,z-1) c[i+1] += c[i];
    if (uniq) { REP(i,n) sa[--c[s[i]]] = i; return; }
    for(int i = n - 2; i >= 0; i--) t[i] = (s[i] == s[i
        + 1] ? t[i+1] : s[i] < s[i+1]);
    MAGIC(REP1(i,1,n-1) if(t[i] && !t[i-1]) sa[--x[s[i
        ]]] = p[q[i] = nn++] = i);
    REP(i, n) if (sa[i] && t[sa[i]] && !t[sa[i]-1]) {
        neq = lst < 0 || memcmp(s+sa[i], s+lst, (p[q[sa[i]]+1]-sa
            [i])*sizeof(int));
        ns[q[lst=sa[i]]] = nmzx + neq;
    }
    sais(ns, nsa, p + nn, q + n, t + n, c + z, nn, nmzx
        + 1);
    MAGIC(for(int i = nn - 1; i >= 0; i--) sa[--x[s[p[
        nsa[i]]]]] = p[nsa[i]]);
}
} sa;
int H[N], SA[N], RA[N];
void suffix_array(int* ip, int len) {
    // should padding a zero in the back
    // ip is int array, len is array length
    // ip[0..n-1] != 0, and ip[len] = 0
    ip[len++] = 0;
    sa.build(ip, len, 128);
    memcpy(H, sa.hei+1, len<<2);
    memcpy(SA, sa._sa+1, len<<2);
    for(int i=0; i<len; i++) RA[i] = sa.r[i]-1;
    // resulting height, sa array \in [0,len)
}

```

6.3 SuffixAutomata

```

const int MAXM = 1000010;
struct SAM{
    int tot, root, lst, mom[MAXM], mx[MAXM];
    int acc[MAXM], nxt[MAXM][33];
    int newNode(){
        int res = ++tot;
        fill(nxt[res], nxt[res]+33, 0);
        mom[res] = mx[res] = acc[res] = 0;
        return res;
    }
    void init(){
        tot = 0;
        root = newNode();
        mom[root] = 0, mx[root] = 0;
        lst = root;
    }
}

```

```

void push(int c){
    int p = lst;
    int np = newNode();
    mx[np] = mx[p]+1;
    for(; p && nxt[p][c] == 0; p = mom[p])
        nxt[p][c] = np;
    if(p == 0) mom[np] = root;
    else{
        int q = nxt[p][c];
        if(mx[p]+1 == mx[q]) mom[np] = q;
        else{
            int nq = newNode();
            mx[nq] = mx[p]+1;
            for(int i = 0; i < 33; i++)
                nxt[nq][i] = nxt[q][i];
            mom[nq] = mom[q];
            mom[q] = nq;
            mom[np] = nq;
            for(; p && nxt[p][c] == q; p = mom[p])
                nxt[p][c] = nq;
        }
    }
    lst = np;
}
void push(char *str){
    for(int i = 0; str[i]; i++)
        push(str[i]-'a'+1);
}
} sam;

```

6.4 Aho-Corasick

```

struct ACautomata{
    struct Node{
        int cnt;
        Node *go[26], *fail, *dic;
        Node(){
            cnt = 0; fail = 0; dic = 0;
            memset(go, 0, sizeof(go));
        }
    } pool[1048576], *root;
    int nMem;
    Node* new_Node(){
        pool[nMem] = Node();
        return &pool[nMem++];
    }
    void init() { nMem = 0; root = new_Node(); }
    void add(const string &str) { insert(root, str, 0); }
    void insert(Node *cur, const string &str, int pos){
        for(int i=pos; i<str.size(); i++){
            if(!cur->go[str[i]-'a'])
                cur->go[str[i]-'a'] = new_Node();
            cur=cur->go[str[i]-'a'];
        }
        cur->cnt++;
    }
    void make_fail(){
        queue<Node*> que;
        que.push(root);
        while (!que.empty()){
            Node* fr=que.front(); que.pop();
            for (int i=0; i<26; i++){
                if (fr->go[i]){
                    Node *ptr = fr->fail;
                    while (ptr && !ptr->go[i]) ptr = ptr->fail;
                    fr->go[i]->fail=ptr=(ptr?ptr->go[i]:root);
                    fr->go[i]->dic=(ptr->cnt?ptr:ptr->dic);
                    que.push(fr->go[i]);
                }
            }
        }
    }
} AC;

```

6.5 Z Value

```

void z_value(const char *s, int len, int *z){
    z[0]=len;
    for(int i=1, l=0, r=0; i<len; i++){
        z[i]=i<r?(i-l+z[i-l]<z[l]?z[i-l]:r-i):0;
        while(i+z[i]<len&&s[i+z[i]]==s[z[i]]) ++z[i];
    }
}

```

```

        if(i+z[i]>r) l=i, r=i+z[i];
    }
}

```

6.6 BWT

```

struct BurrowsWheeler{
#define SIGMA 26
#define BASE 'a'
    vector<int> v[ SIGMA ];
    void BWT(char* ori, char* res){
        // make ori -> ori + ori
        // then build suffix array
    }
    void iBWT(char* ori, char* res){
        for( int i = 0 ; i < SIGMA ; i ++ )
            v[ i ].clear();
        int len = strlen( ori );
        for( int i = 0 ; i < len ; i ++ )
            v[ ori[i] - BASE ].push_back( i );
        vector<int> a;
        for( int i = 0 , ptr = 0 ; i < SIGMA ; i ++ )
            for( auto j : v[ i ] ){
                a.push_back( j );
                ori[ ptr ++ ] = BASE + i;
            }
        for( int i = 0 , ptr = 0 ; i < len ; i ++ ){
            res[ i ] = ori[ a[ ptr ] ];
            ptr = a[ ptr ];
        }
        res[ len ] = 0;
    }
} bwt;

```

6.7 ZValue Palindrome

```

void z_value_pal(char *s, int len, int *z){
    len=(len<<1)+1;
    for(int i=len-1; i>=0; i--){
        s[i]=i&1?s[i>>1]:'@';
        z[0]=1;
        for(int i=1, l=0, r=0; i<len; i++){
            z[i]=i<r?min(z[l+l-i], r-i):1;
            while(i-z[i]>=0&&i+z[i]<len&&s[i-z[i]]==s[i+z[i]])
                ++z[i];
            if(i+z[i]>r) l=i, r=i+z[i];
        }
    }
}

```

6.8 Smallest Rotation

```

string mcp(string s){
    int n = s.length();
    s += s;
    int i=0, j=1;
    while (i<n && j<n){
        int k = 0;
        while (k < n && s[i+k] == s[j+k]) k++;
        if (s[i+k] <= s[j+k]) j += k+1;
        else i += k+1;
        if (i == j) j++;
    }
    int ans = i < n ? i : j;
    return s.substr(ans, n);
}

```

6.9 Cyclic LCS

```

#define L 0
#define LU 1
#define U 2
const int mov[3][2]={0,-1, -1,-1, -1,0};
int al, bl;

```

```

char a[MAXL*2], b[MAXL*2]; // 0-indexed
int dp[MAXL*2][MAXL];
char pred[MAXL*2][MAXL];
inline int lcs_length(int r) {
    int i=r+al, j=bl, l=0;
    while(i>r) {
        char dir=pred[i][j];
        if(dir==LU) l++;
        i+=mov[dir][0];
        j+=mov[dir][1];
    }
    return l;
}
inline void reroot(int r) { // r = new base row
    int i=r, j=1;
    while(j<=bl&&pred[i][j]!=LU) j++;
    if(j>bl) return;
    pred[i][j]=L;
    while(i<2*al&&j<=bl) {
        if(pred[i+1][j]==U) {
            i++;
            pred[i][j]=L;
        } else if(j<bl&&pred[i+1][j+1]==LU) {
            i++;
            j++;
            pred[i][j]=L;
        } else {
            j++;
        }
    }
}
int cyclic_lcs() {
    // a, b, al, bl should be properly filled
    // note: a WILL be altered in process
    // -- concatenated after itself
    char tmp[MAXL];
    if(al>bl) {
        swap(al, bl);
        strcpy(tmp, a);
        strcpy(a, b);
        strcpy(b, tmp);
    }
    strcpy(tmp, a);
    strcat(a, tmp);
    // basic lcs
    for(int i=0; i<=2*al; i++) {
        dp[i][0]=0;
        pred[i][0]=U;
    }
    for(int j=0; j<=bl; j++) {
        dp[0][j]=0;
        pred[0][j]=L;
    }
    for(int i=1; i<=2*al; i++) {
        for(int j=1; j<=bl; j++) {
            if(a[i-1]==b[j-1]) dp[i][j]=dp[i-1][j-1]+1;
            else dp[i][j]=max(dp[i-1][j], dp[i][j-1]);
            if(dp[i][j-1]==dp[i][j]) pred[i][j]=L;
            else if(a[i-1]==b[j-1]) pred[i][j]=LU;
            else pred[i][j]=U;
        }
    }
    // do cyclic lcs
    int clcs=0;
    for(int i=0; i<al; i++) {
        clcs=max(clcs, lcs_length(i));
        reroot(i+1);
    }
    // recover a
    a[al]='\0';
    return clcs;
}

```

7 Data Structure

7.1 Link-Cut Tree

```
const int MEM = 100005;
```

```

struct Splay {
    static Splay nil, mem[MEM], *pmem;
    Splay *ch[2], *f;
    int val, rev, size;
    Splay(int _val=-1) : val(_val), rev(0), size(1) {
        f = ch[0] = ch[1] = &nil;
    }
    bool isr() {
        return f->ch[0] != this && f->ch[1] != this;
    }
    int dir() {
        return f->ch[0] == this ? 0 : 1;
    }
    void setCh(Splay *c, int d) {
        ch[d] = c;
        if(c != &nil) c->f = this;
        pull();
    }
    void push() {
        if(!rev) return;
        swap(ch[0], ch[1]);
        if(ch[0] != &nil) ch[0]->rev ^= 1;
        if(ch[1] != &nil) ch[1]->rev ^= 1;
        rev=0;
    }
    void pull() {
        size = ch[0]->size + ch[1]->size + 1;
        if(ch[0] != &nil) ch[0]->f = this;
        if(ch[1] != &nil) ch[1]->f = this;
    }
} Splay::nil, Splay::mem[MEM], *Splay::pmem=Splay::mem;
Splay *nil = &Splay::nil;
void rotate(Splay *x) {
    Splay *p = x->f;
    int d = x->dir();
    if(!p->isr()) p->f->setCh(x, p->dir());
    else x->f = p->f;
    p->setCh(x->ch[!d], d);
    x->setCh(p, !d);
}
vector<Splay*> splayVec;
void splay(Splay *x) {
    splayVec.clear();
    for(Splay *q=x; q=q->f) {
        splayVec.push_back(q);
        if(q->isr()) break;
    }
    reverse(begin(splayVec), end(splayVec));
    for(auto it : splayVec) it->push();
    while(!x->isr()) {
        if(x->f->isr()) rotate(x);
        else if(x->dir()==x->f->dir())
            rotate(x->f), rotate(x);
        else rotate(x), rotate(x);
    }
}
int id(Splay *x) { return x - Splay::mem + 1; }
Splay* access(Splay *x) {
    Splay *q = nil;
    for(; x!=nil; x=x->f) {
        splay(x);
        x->setCh(q, 1);
        q = x;
    }
    return q;
}
void chroot(Splay *x) {
    access(x), splay(x);
    x->rev ^= 1;
}
void link(Splay *x, Splay *y) {
    chroot(y);
    y->f=x;
}
void cut_p(Splay *y) {
    access(y), splay(y);
    y->ch[0] = y->ch[0]->f = nil;
}
void cut(Splay *x, Splay *y) {
    chroot(x);
    cut_p(y);
}
Splay* get_root(Splay *x) {
    x=access(x);
    for(; x->ch[0] != nil; x = x->ch[0])

```

```

    x->push();
    splay(x);
    return x;
}
bool conn(Splay *x, Splay *y) {
    x = get_root(x), y = get_root(y);
    return x == y;
}
Splay* lca(Splay *x, Splay *y) {
    access(x);
    return access(y);
}
/* query(Splay *x, Splay *y){
    setroot(y), x=access(x);
    return x->size;
}*/
/* query(Splay *x, Splay *y){
    Splay *p=lca(x,y);
    return p->val+p->ch[1]->size+(x!=p?x->size:0);
}*/

```

7.2 Black Magic

```

#include <bits/extc++.h>
using namespace __gnu_pbds;
typedef tree<int, null_type, less<int>, rb_tree_tag,
    tree_order_statistics_node_update> set_t;
#include <ext/pb_ds/assoc_container.hpp>
typedef cc_hash_table<int, int> umap_t;
typedef priority_queue<int> heap;
#include <ext/rope>
using namespace __gnu_cxx;
int main(){
    // Insert some entries into s.
    set_t s; s.insert(12); s.insert(505);
    // The order of the keys should be: 12, 505.
    assert(*s.find_by_order(0) == 12);
    assert(*s.find_by_order(3) == 505);
    // The order of the keys should be: 12, 505.
    assert(s.order_of_key(12) == 0);
    assert(s.order_of_key(505) == 1);
    // Erase an entry.
    s.erase(12);
    // The order of the keys should be: 505.
    assert(*s.find_by_order(0) == 505);
    // The order of the keys should be: 505.
    assert(s.order_of_key(505) == 0);

    heap h1, h2; h1.join( h2 );

    rope<char> r[ 2 ];
    r[ 1 ] = r[ 0 ]; // persistenet
    string t = "abc";
    r[ 1 ].insert( 0, t.c_str() );
    r[ 1 ].erase( 1, 1 );
    cout << r[ 1 ].substr( 0, 2 );
}

```

8 Others

8.1 Find max tangent(x,y is increasing)

```

const int MAXN = 100010;
Pt sum[MAXN], pnt[MAXN], ans, calc;
inline bool cross(Pt a, Pt b, Pt c){
    return (c.y-a.y)*(c.x-b.x) > (c.x-a.x)*(c.y-b.y);
} //pt[0]=(0,0); pt[i]=(i, pt[i-1].y+dy[i-1]), i=1~n; dx>=1
double find_max_tan(int n, int l, LL dy[]){
    int np, st, ed, now;
    sum[0].x = sum[0].y = np = st = ed = 0;
    for (int i = 1, v; i <= n; i++){
        sum[i].x = i, sum[i].y = sum[i-1].y + dy[i-1];
        ans.x = now = 1, ans.y = -1;
        for (int i = 0; i <= n - l; i++){
            while(np > 1 && cross(pnt[np-2], pnt[np-1], sum[i]))
                np--;

```

```

            if (np < now && np != 0) now = np;
            pnt[np++] = sum[i];
            while(now < np && !cross(pnt[now-1], pnt[now], sum[i+1]))
                now++;
            calc = sum[i + l] - pnt[now - 1];
            if (ans.y * calc.x < ans.x * calc.y)
                ans = calc, st = pnt[now - 1].x, ed = i + l;
        }
    }
    return (double)(sum[ed].y - sum[st].y) / (sum[ed].x - sum[st].x);
}

```

8.2 Exact Cover Set

```

// given n*m 0-1 matrix
// find a set of rows s.t.
// for each column, there's exactly one 1
#define N 1024 //row
#define M 1024 //column
#define NM ((N+2)*(M+2))
char A[N][M]; //n*m 0-1 matrix
bool used[N]; //answer: the row used
int id[N][M];
int L[NM], R[NM], D[NM], U[NM], C[NM], S[NM], ROW[NM];
void remove(int c){
    L[R[c]] = L[c]; R[L[c]] = R[c];
    for( int i = D[c]; i != c; i = D[i] )
        for( int j = R[i]; j != i; j = R[j] ){
            U[D[j]] = U[j]; D[U[j]] = D[j]; S[C[j]]--;
        }
}
void resume(int c){
    for( int i = D[c]; i != c; i = D[i] )
        for( int j = L[i]; j != i; j = L[j] ){
            U[D[j]] = D[U[j]] = j; S[C[j]]++;
        }
    L[R[c]] = R[L[c]] = c;
}
bool dfs(){
    if(R[0] == 0) return 1;
    int md = 1000000000, c;
    for( int i = R[0]; i != 0; i = R[i] )
        if(S[i] < md){ md = S[i]; c = i; }
    if(md == 0) return 0;
    remove(c);
    for( int i = D[c]; i != c; i = D[i] ){
        used[ROW[i]] = 1;
        for( int j = R[i]; j != i; j = R[j] ) remove(C[j]);
        if(dfs()) return 1;
        for( int j = L[i]; j != i; j = L[j] ) resume(C[j]);
        used[ROW[i]] = 0;
    }
    resume(c);
    return 0;
}
bool exact_cover(int n, int m){
    for( int i = 0; i <= m; i++ ){
        R[i] = i + 1; L[i] = i - 1; U[i] = D[i] = i;
        S[i] = 0; C[i] = i;
    }
    R[m] = 0; L[0] = m;
    int t = m + 1;
    for( int i = 0; i < n; i++ ){
        int k = -1;
        for( int j = 0; j < m; j++ ){
            if(!A[i][j]) continue;
            if(k == -1) L[t] = R[t] = t;
            else{ L[t] = k; R[t] = R[k]; }
            k = t; D[t] = j + 1; U[t] = U[j + 1];
            L[R[t]] = R[L[t]] = U[D[t]] = D[U[t]] = t;
            C[t] = j + 1; S[C[t]]++; ROW[t] = i; id[i][j] = t++;
        }
    }
    for( int i = 0; i < n; i++ ) used[i] = 0;
    return dfs();
}

```