

2.06. Prove  $\oint d\vec{r} \times \vec{B} = \int \int_S (\hat{n} \times \vec{\nabla}) \times \vec{B} dS$ .

Consider a vector  $\vec{A} = \vec{B} \times \vec{C}$ , where  $\vec{C}$  is a constant vector.  
Then by Stoke's theorem applied to the vector field  $\vec{A}$ :

$$\int \int_S \underbrace{[\vec{\nabla} \times (\vec{B} \times \vec{C})]}_{\vec{\nabla} \times \vec{A}} \cdot d\vec{S} = \oint_C \underbrace{(\vec{B} \times \vec{C})}_{\vec{A}} \cdot d\vec{r}$$

$$\text{Use identity: } \vec{\nabla} \times (\vec{B} \times \vec{C}) = (\vec{C} \cdot \vec{\nabla}) \vec{B} - \vec{C} (\vec{\nabla} \cdot \vec{B}) \\ - (\vec{B} \cdot \vec{\nabla}) \vec{C} + \vec{B} (\vec{\nabla} \cdot \vec{C}) \quad \left( \begin{array}{l} \text{Prove} \\ \text{Take home} \end{array} \right)$$

Since  $\vec{C}$  is a constant vector, 3rd and 4th terms of the above vanish.

$$\Rightarrow \int \int_S [\vec{\nabla} \times (\vec{B} \times \vec{C})] \cdot d\vec{S} \\ = \int \int_S [(\vec{C} \cdot \vec{\nabla}) \vec{B} - \vec{C} (\vec{\nabla} \cdot \vec{B})] \cdot \underbrace{d\vec{S}}_{\hat{n} dS} \\ = \int \int_S [(\vec{C} \cdot \vec{\nabla}) \vec{B} - \vec{C} (\vec{\nabla} \cdot \vec{B})] \cdot \hat{n} dS$$

Now, consider  $[(\vec{C} \cdot \vec{\nabla}) \vec{B}] \cdot \vec{D}$

$$= D_j C_i \partial_i B_j = C_i \partial_i (D_j B_j) - B_j C_i \partial_i D_j$$

$$= \vec{C} \cdot [\vec{\nabla} (\vec{D} \cdot \vec{B})] - \vec{B} \cdot [(\vec{C} \cdot \vec{\nabla}) \vec{D}]$$

Choose  $\vec{D} = \hat{n}$

$$\Rightarrow [(\vec{C} \cdot \vec{\nabla}) \vec{B} - \vec{C} (\vec{\nabla} \cdot \vec{B})] \cdot \hat{n}$$

$$= \vec{C} \cdot [\vec{\nabla} (\hat{n} \cdot \vec{B})] - \vec{B} \cdot [(\vec{C} \cdot \vec{\nabla}) \hat{n}] - \vec{C} \cdot [\hat{n} (\vec{\nabla} \cdot \vec{B})]$$

(By using above identity)

$$= \vec{C} \cdot [\vec{\nabla} (\vec{B} \cdot \hat{n}) - \hat{n} (\vec{\nabla} \cdot \vec{B})] - \vec{B} \cdot [(\vec{C} \cdot \vec{\nabla}) \hat{n}]$$

Next,  $[(\vec{D} \times \vec{\nabla}) \times \vec{B}]_i$

$$= \epsilon_{ijk} (\vec{D} \times \vec{\nabla})_j B_k = \epsilon_{ijk} \epsilon_{jlm} D_l \partial_m B_k$$

$$= \underbrace{\epsilon_{jki} \epsilon_{jlm}}_{\delta_{kl} \delta_{im} - \delta_{km} \delta_{il}} D_l \partial_m B_k = D_k \partial_i B_k - D_i \partial_k B_k$$

$$= \partial_i (D_k B_k) - B_k \partial_i D_k - D_i (\vec{\nabla} \cdot \vec{B})$$

$$= \partial_i (\vec{D} \cdot \vec{B}) - D_i (\vec{\nabla} \cdot \vec{B}) - \vec{B} \cdot (\partial_i \vec{D})$$

$$= [\vec{\nabla} (\vec{D} \cdot \vec{B})]_i - [\vec{D} (\vec{\nabla} \cdot \vec{B})]_i - \vec{B} \cdot (\partial_i \vec{D})$$

$$\therefore \vec{c} \cdot [(\vec{D} \times \vec{v}) \times \vec{B}]$$

$$= c_i [(\vec{D} \times \vec{v}) \times \vec{B}]_i$$

$$= \vec{c} \cdot [\vec{v} (\vec{D} \cdot \vec{B}) - \vec{D} (\vec{v} \cdot \vec{B})] - \vec{B} \cdot (c_i \partial_i \vec{D})$$

$$= \vec{c} \cdot [\vec{v} (\vec{D} \cdot \vec{B}) - \vec{D} (\vec{v} \cdot \vec{B})] - \vec{B} \cdot [(\vec{c} \cdot \vec{\nabla}) \vec{D}]$$

So, for  $\vec{D} = \hat{n}$ , the above yields

$$\vec{c} \cdot [(\hat{n} \times \vec{v}) \times \vec{B}] = [(\vec{c} \cdot \vec{v}) \vec{B} - \vec{c} (\vec{v} \cdot \vec{B})] \cdot \hat{n}$$

(Give this as take home assignment)

Therefore we have,

$$\iint_S [\vec{v} \times (\vec{B} \times \vec{c})] \cdot d\vec{S} = \iint_S \vec{c} \cdot [(\hat{n} \times \vec{v}) \times \vec{B}] dS$$

$$= \vec{c} \cdot \iint_S [(\hat{n} \times \vec{v}) \times \vec{B}] dS$$

(As  $\vec{c}$  is a constant vector)

On the other hand

$$\oint_C (\vec{B} \times \vec{c}) \cdot d\vec{r} = \oint_C \vec{c} \cdot (d\vec{r} \times \vec{B})$$

$$= \vec{c} \cdot \oint_C d\vec{r} \times \vec{B}$$

Now since  $\vec{C}$  is completely arbitrary, equating the above two one obtains,

$$\oint_S [(\hat{n} \times \vec{\nabla}) \times \vec{B}] dS = \oint_C d\vec{r} \times \vec{B}.$$