Matlab protocol and thoughts

Introduction

- \bullet dataformat
- What data is needed
- What stuctur should the data be sent with what, when, how

Uart matlab

Identifcer	Value
Position T	1
Position B	2
Velocity T	3
Velocity B	4
PWM T	5
PWM B	6
Ref T	7
Ref B	8
РТ	9
ΡВ	10
ΙT	11
IΒ	12
DΤ	13
DВ	14

Table 1: Table to test captions and labels

0.1 Sources

fejl, postion, hastighed, homingsensor, fejl fra pid, contorl singal, ref signal og outputtet.