

**Minimum Variance Estimate.** Ignoring any large time trend in the light curve, we can write any realization as

$$\mathbf{y} = \mathbf{s} + \mathbf{n} \quad (1)$$

and define

$$\mathbf{S} \equiv \langle \mathbf{s}\mathbf{s}^T \rangle, \mathbf{N} \equiv \langle \mathbf{n}\mathbf{n}^T \rangle, \mathbf{S}_* \equiv \langle (s_*)\mathbf{s} \rangle \quad (2)$$

We then have the minimum variance estimate (MVE)  $\hat{s}_*$  for  $s_*$  as

$$\hat{s}_* = \mathbf{S}_*^T [\mathbf{S} + \mathbf{N}]^{-1} \mathbf{y} \quad (3)$$

with the variance of  $s_*$  about  $\hat{s}_*$  as

$$\langle (s_* - \hat{s}_*)^2 \rangle = \langle s_*^2 \rangle - \mathbf{S}_*^T [\mathbf{S} + \mathbf{N}]^{-1} \mathbf{S}_* \quad (4)$$

**Unconstrained Realizations of the Underlying Process.** Given the symmetric, positive-definite covariance matrix  $\mathbf{C} \equiv \mathbf{S} + \mathbf{N}$ , generating a random realization is straightforward.

- Cholesky decompose  $\mathbf{C} = \mathbf{M}\mathbf{M}^T$ , where  $\mathbf{M}$  is the lower triangular matrix.
- Generate  $\mathbf{r} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$
- Compute  $\mathbf{x} = \mathbf{M}\mathbf{r}$  so that  $\langle \mathbf{x}\mathbf{x}^T \rangle = \langle \mathbf{M}\mathbf{r}(\mathbf{M}\mathbf{r})^T \rangle = \langle \mathbf{M}\mathbf{r}\mathbf{r}^T\mathbf{M}^T \rangle = \mathbf{C}$

**Predictive Distribution from the Observed Light Curve.** Given  $\mathbf{C}$  and the observed light curve vector  $\mathbf{y}$ , we can compute Equation (3) and (4) by

- Cholesky decompose  $\mathbf{C} = \mathbf{M}\mathbf{M}^T$ , where  $\mathbf{M}$  is the lower.
- Solve  $\mathbf{M}\mathbf{A} = \mathbf{y}$  for  $\mathbf{A}$  and then  $\mathbf{M}^T\alpha = \mathbf{A}$  for  $\alpha$ , so that  $\mathbf{C}\alpha = (\mathbf{M}\mathbf{M}^T)\alpha = \mathbf{y}$ , thus  $\alpha = \mathbf{C}^{-1}\mathbf{y}$ .
- $\hat{s}_* = \mathbf{S}_*^T\alpha$  is the MVE.
- Solve  $\mathbf{M}\mathbf{v} = \mathbf{S}_*$  for  $\mathbf{v}$
- $\langle (s_* - \hat{s}_*)^2 \rangle = \langle s_*^2 \rangle - \mathbf{v}^T\mathbf{v}$ , given  $\mathbf{S}_*^T\mathbf{C}^{-1}\mathbf{S}_* = \mathbf{S}_*^T(\mathbf{M}^T)^{-1}\mathbf{M}^{-1}\mathbf{S}_* = \mathbf{v}^T\mathbf{v}$

**Constrained Realizations of the Underlying Process by Observed Light Curves.** A typical realization constrained by the data at unmeasured epoch can be produced as  $s_*$  by

$$s_* = u_* + \hat{s}_* \quad (5)$$

where  $u_*$  is a Gaussian process with zero mean and correlation matrix  $\mathbf{Q}$

$$\mathbf{Q} = [\mathbf{S}^{-1} + \mathbf{N}^{-1}]^{-1} = \mathbf{S}[\mathbf{S} + \mathbf{N}]^{-1}\mathbf{N} = \mathbf{N}[\mathbf{S} + \mathbf{N}]^{-1}\mathbf{S} \quad (6)$$

$u_*$  can be generated using the same way as in the unconstrained prediction case using the Cholesky decomposition of  $\mathbf{Q}$ .

## References

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<sup>1</sup>Written in Oct 20, 2011