

01_TwiBot_20_dimensionality

August 19, 2023

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[1]: import pandas as pd
import matplotlib.pyplot as plt
import itertools
```

1 Dimension and compression vs model performance

1.1 TwiBot-20

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[2]: dataset_nam = "twibot"

y_test = pd.read_excel(f"./dimensionality_input/{dataset_nam}/results/ytest.
↳xlsx"
                        ).drop(columns=["Unnamed: 0", "index"], errors="ignore")

results = pd.read_csv(f"./dimensionality_input/{dataset_nam}/results/
↳results_aggregated.csv",
                      index_col = 0)
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[3]: # UMAP: only seed 0 for readability

a = results["embedding_type"].unique().tolist()
a.remove("graph_features")
a.remove("all_embeddings")
a

for model, metric, embedding_type, compression_name in list(
    itertools.product(results["model"].unique(),
                      #["acc", "f1", "mcc", "auc"],
                      ["f1"],
                      a,
                      results["compression_name"].unique())):

    if compression_name == "no_compression":
        pass
    else:
        print(f"----- \n {model}, {metric}, {embedding_type},
↳{compression_name}")
```

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temp = results[results["compression_name"].isin(["no_compression",
compression_name])]
temp = temp[(temp["embedding_type"] == embedding_type) & (temp["model"]
compression_name == model)]
if compression_name == "umap":
    temp = temp[(temp["seed"] == 0) | (temp["seed"].isna())]

temp2 = temp.sort_values(by="original_dim_number", ascending=True)

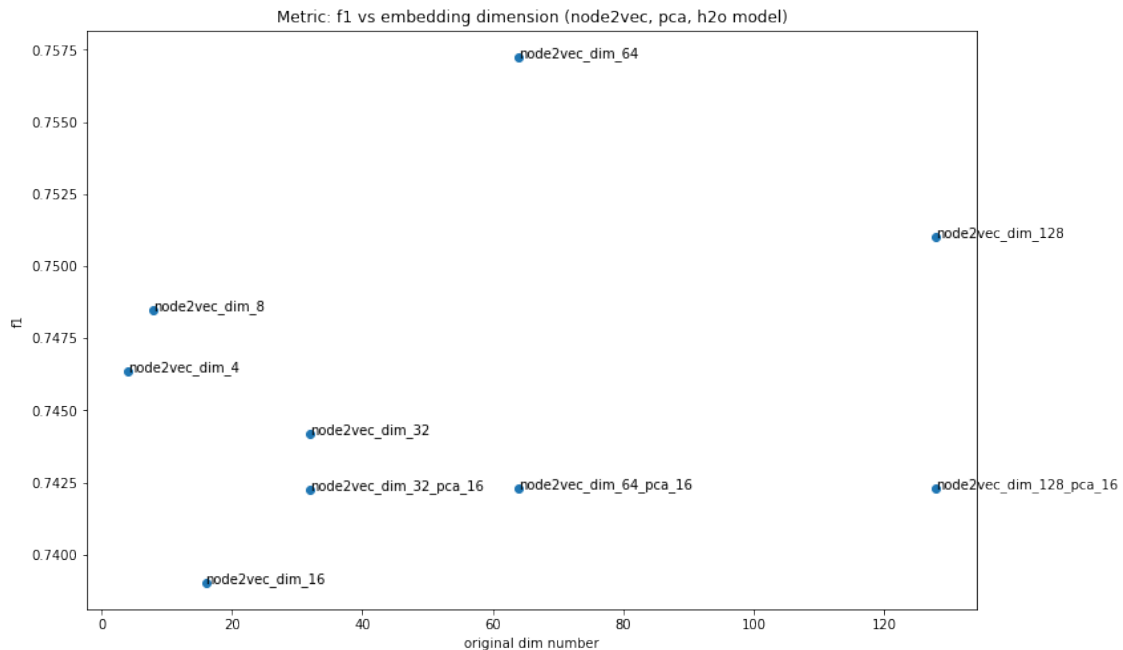
fig, ax = plt.subplots(figsize=(12,8))
plt.scatter(temp2["original_dim_number"], temp2[metric], label =
compression_name temp2["embedding_name"])
plt.title(f"Metric: {metric} vs embedding dimension ({embedding_type},
compression_name {compression_name}, {model} model)")
plt.xlabel("original dim number")
plt.ylabel(metric)

for index in range(len(temp2["original_dim_number"])):
    ax.text(temp2["original_dim_number"].iloc[index],
            temp2[metric].iloc[index],
            temp2["embedding_name"].iloc[index], size=10)

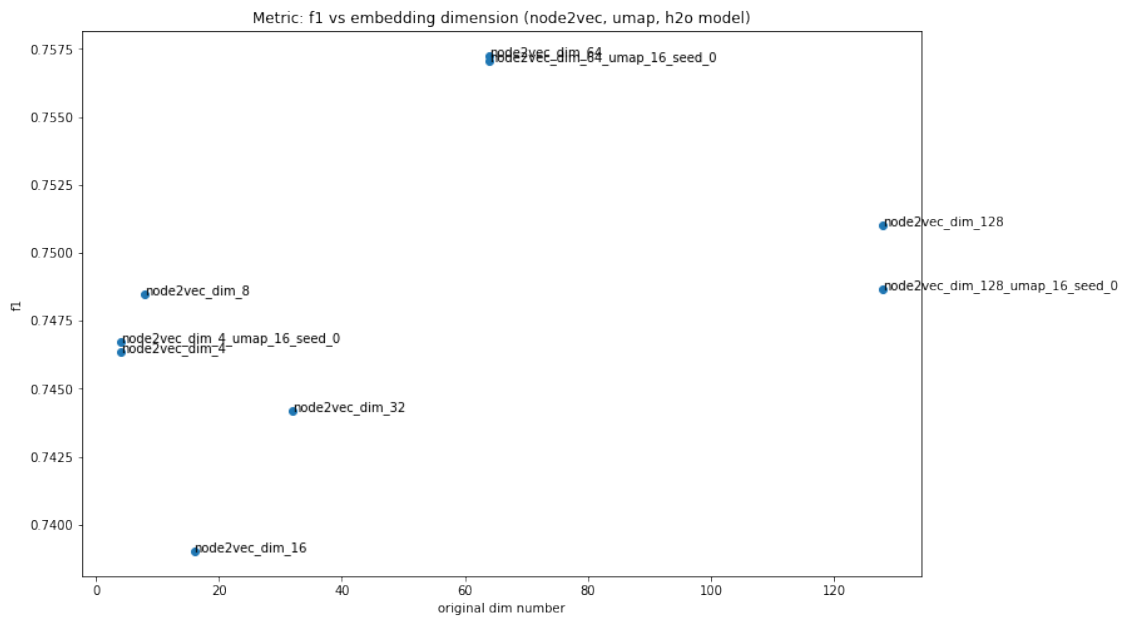
plt.show()

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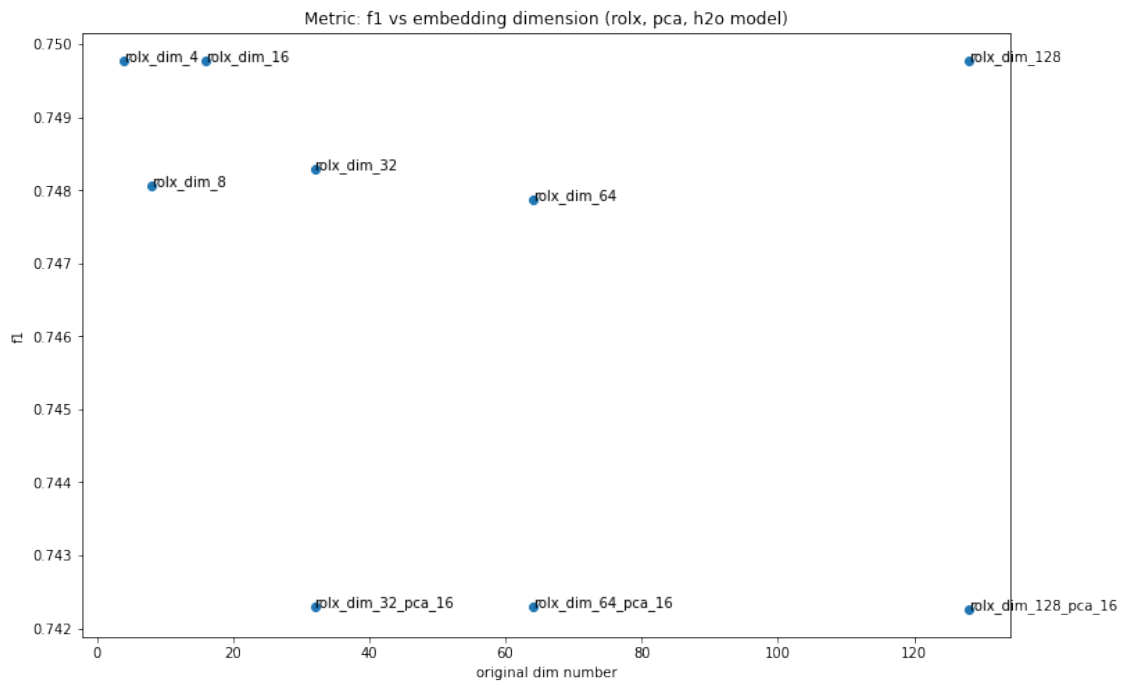
h2o, f1, node2vec, pca



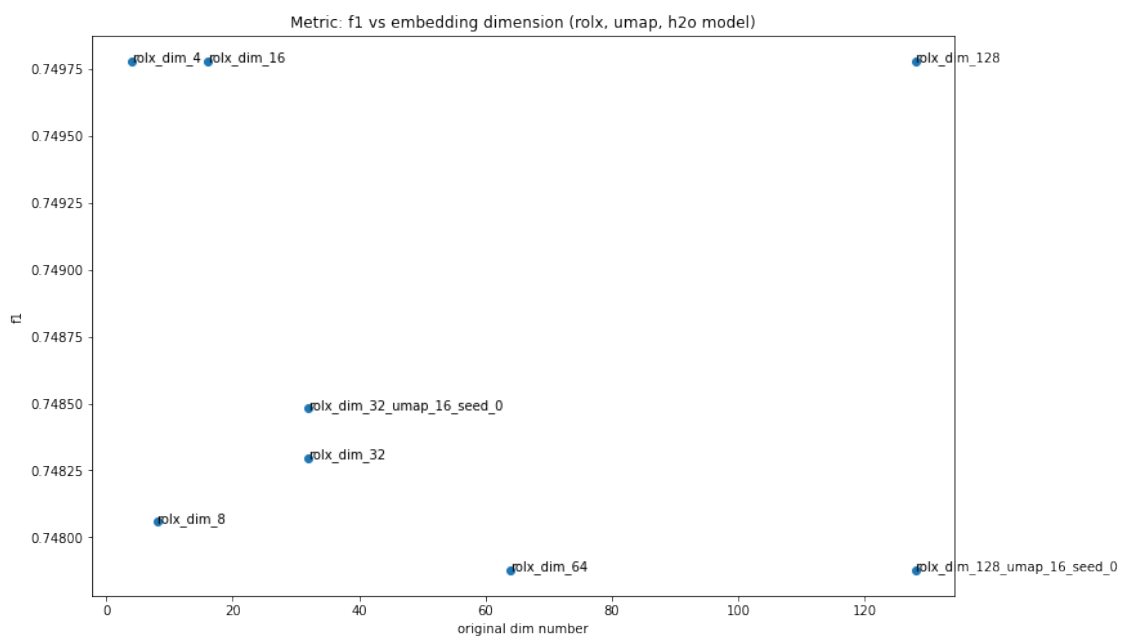
h2o, f1, node2vec, umap



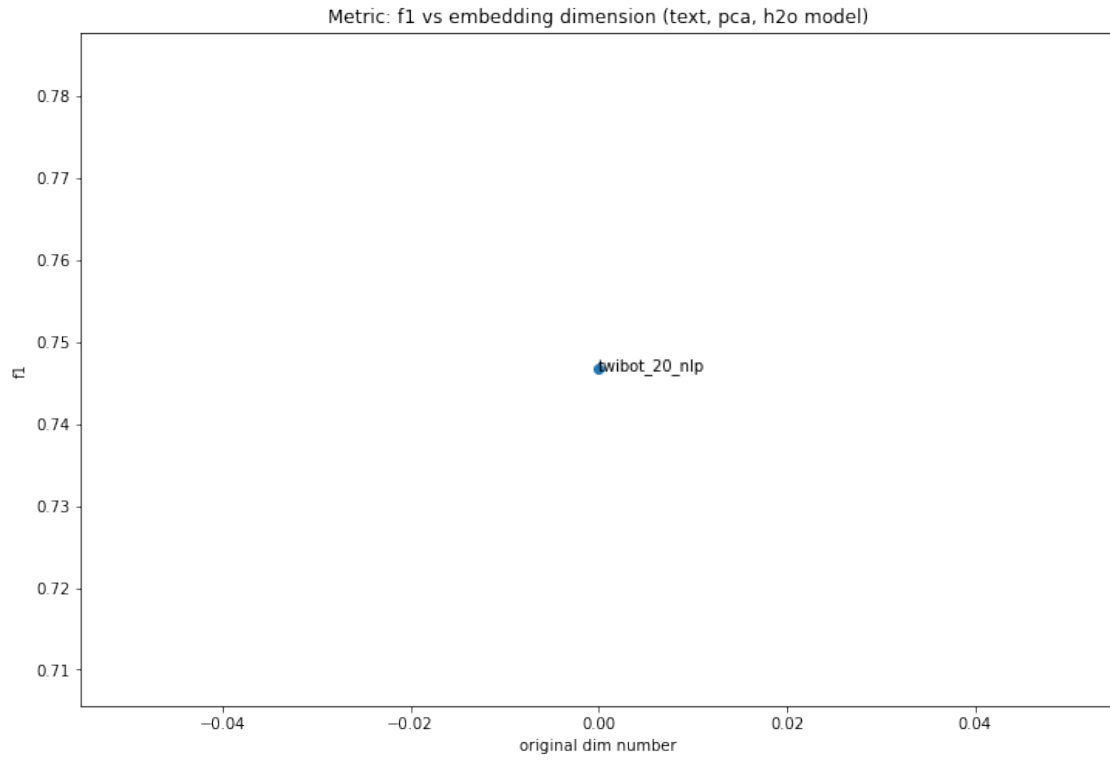
h2o, f1, rolx, pca



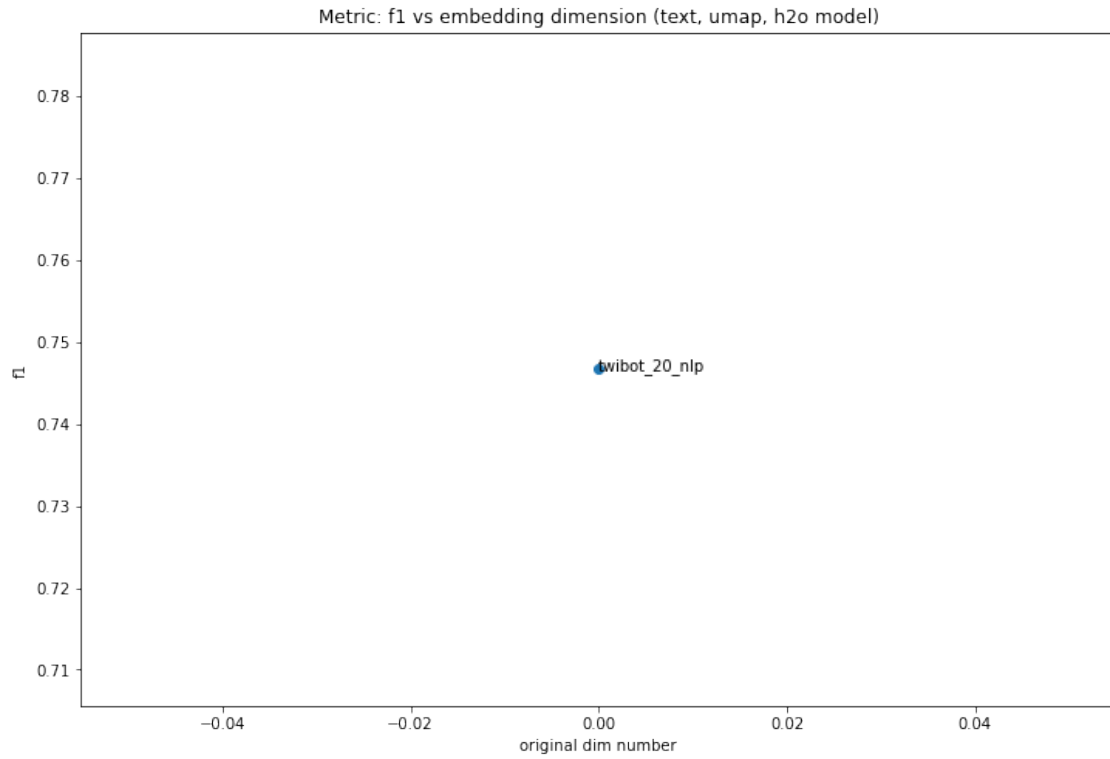
h2o, f1, rolx, umap



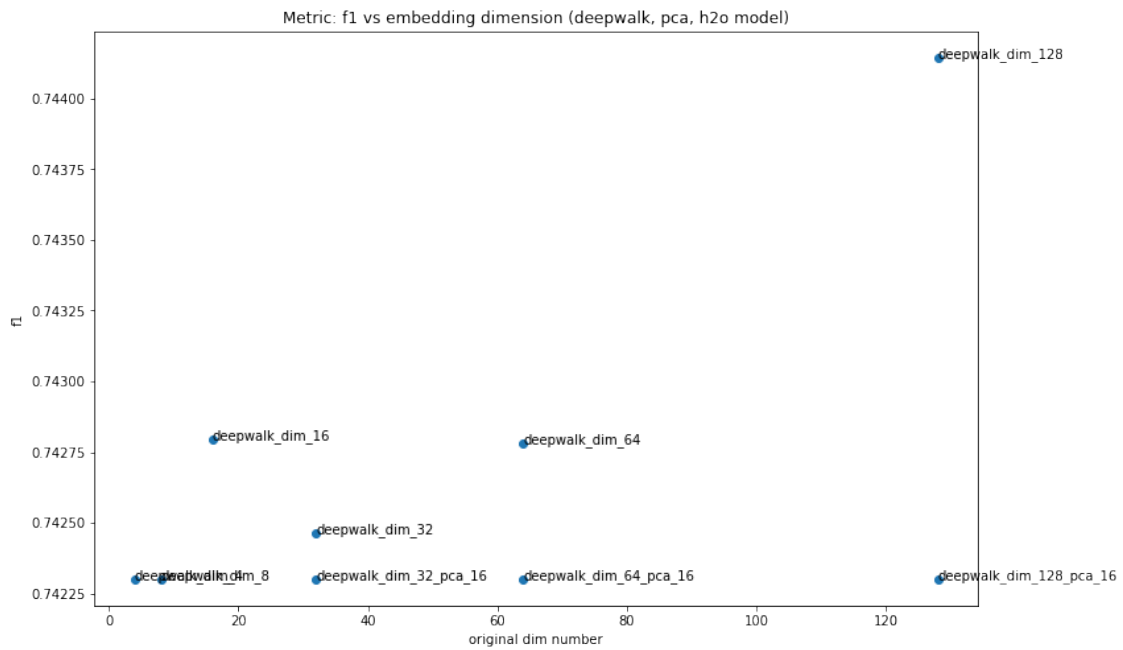
h2o, f1, text, pca



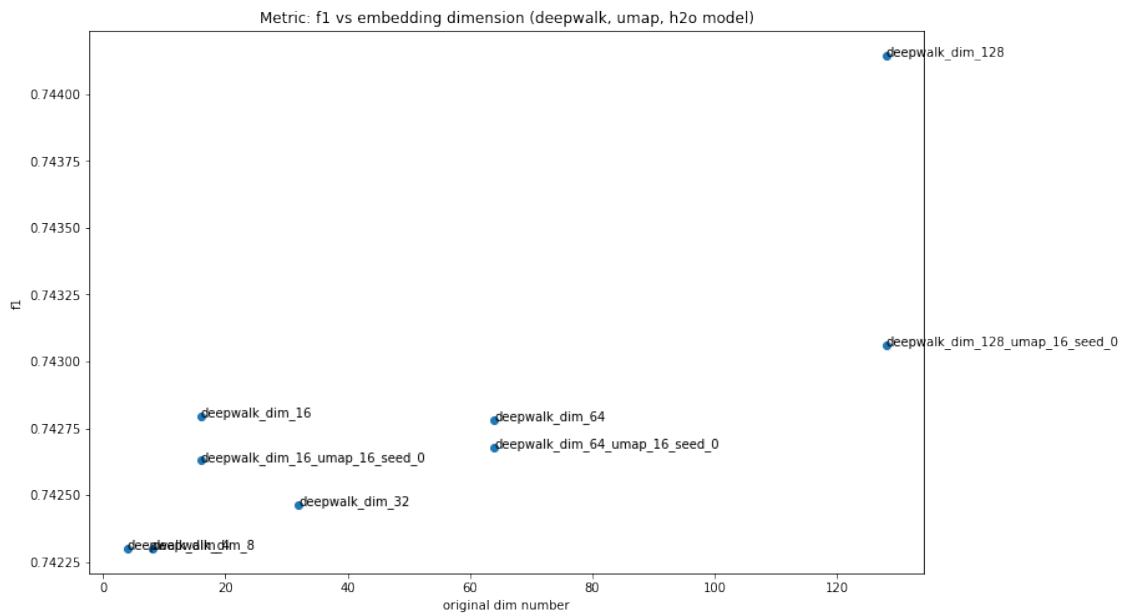
h2o, f1, text, umap



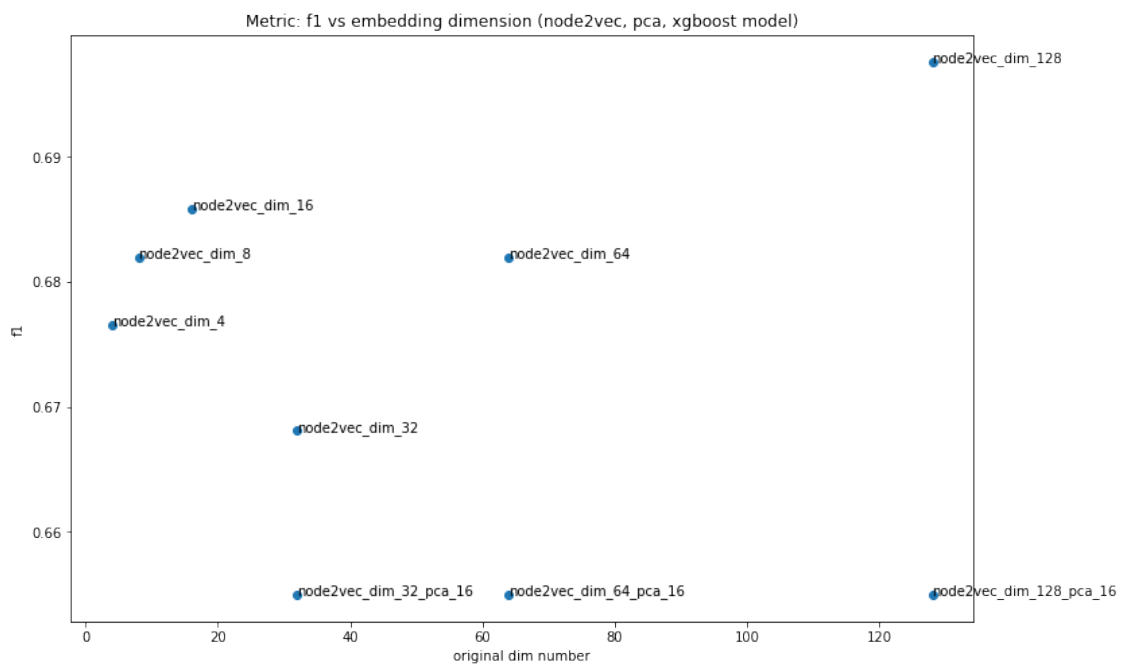
h2o, f1, deepwalk, pca



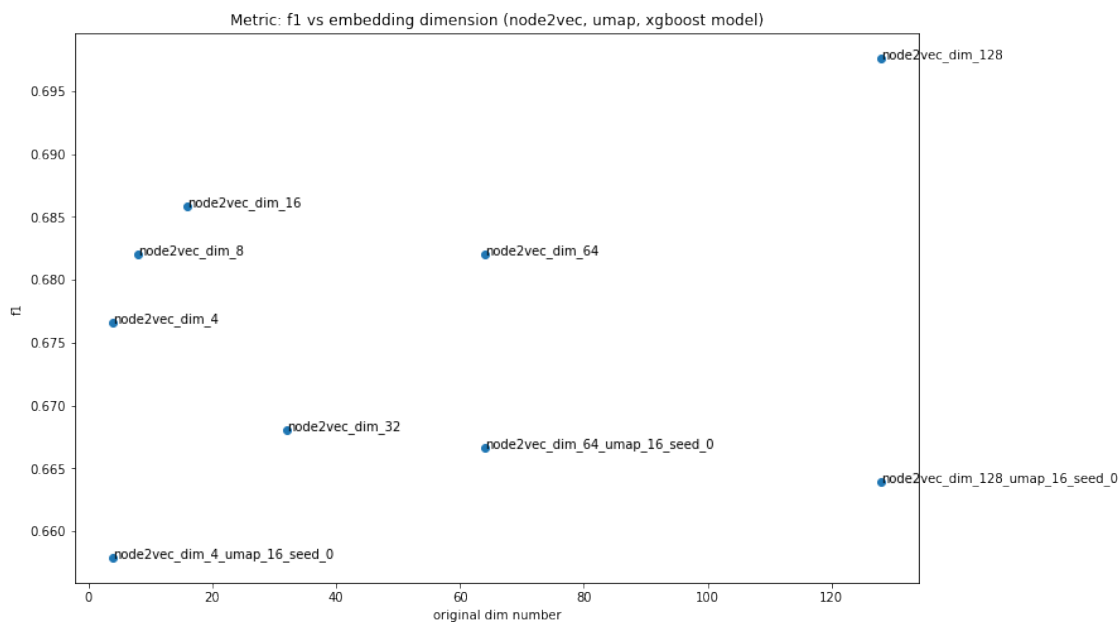
h2o, f1, deepwalk, umap



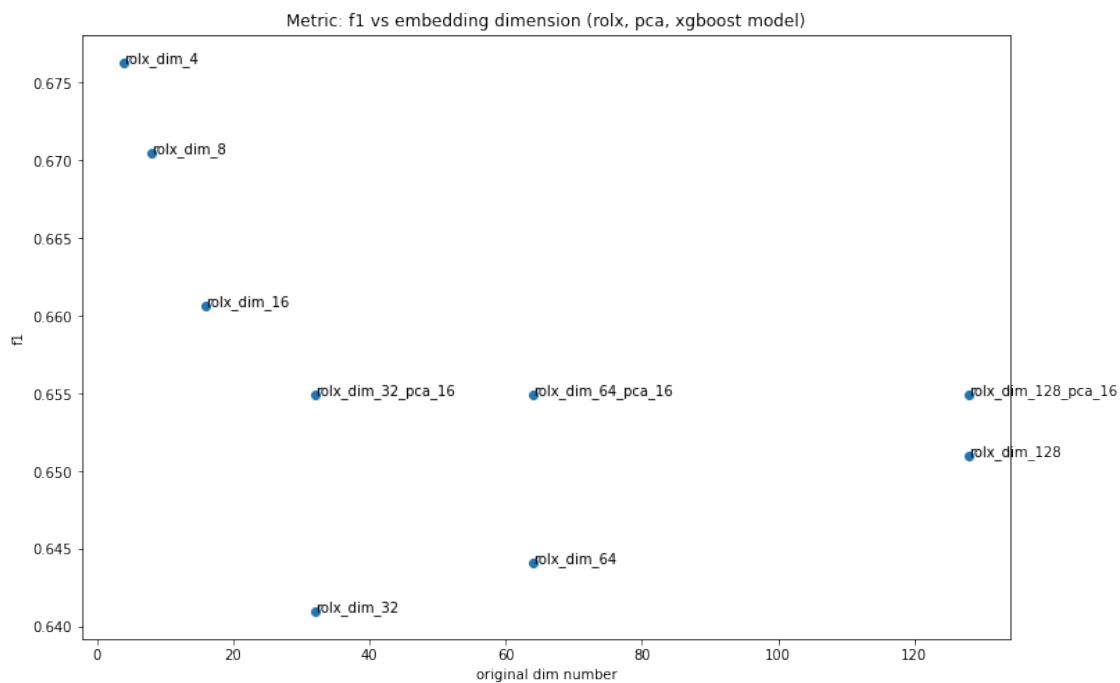
xgboost, f1, node2vec, pca



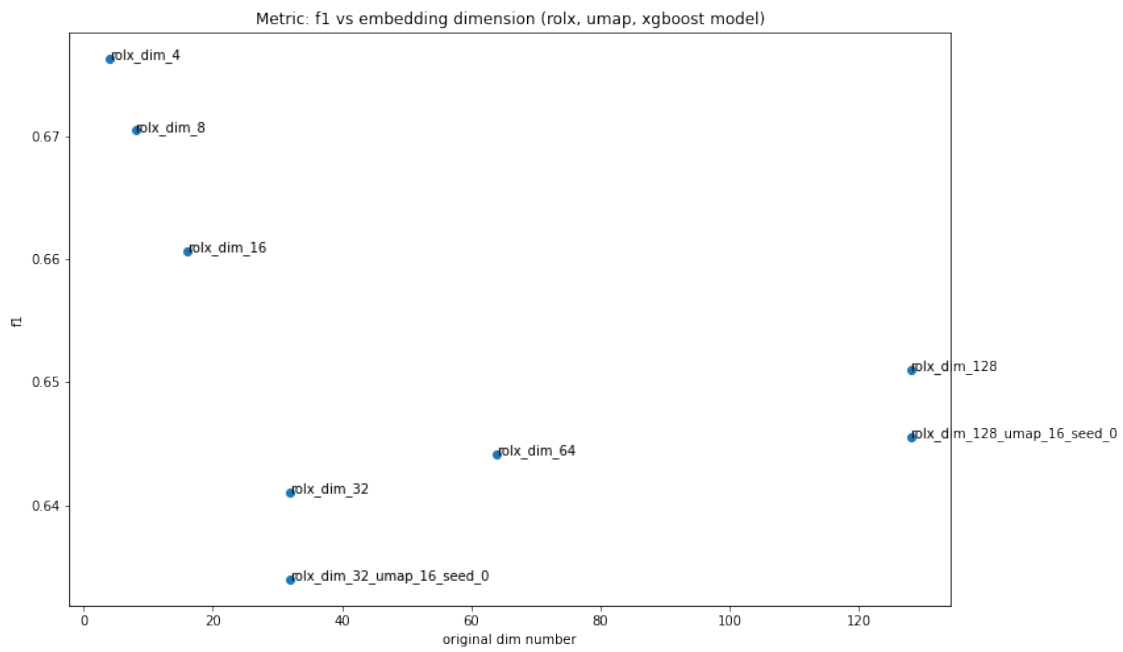
xgboost, f1, node2vec, umap



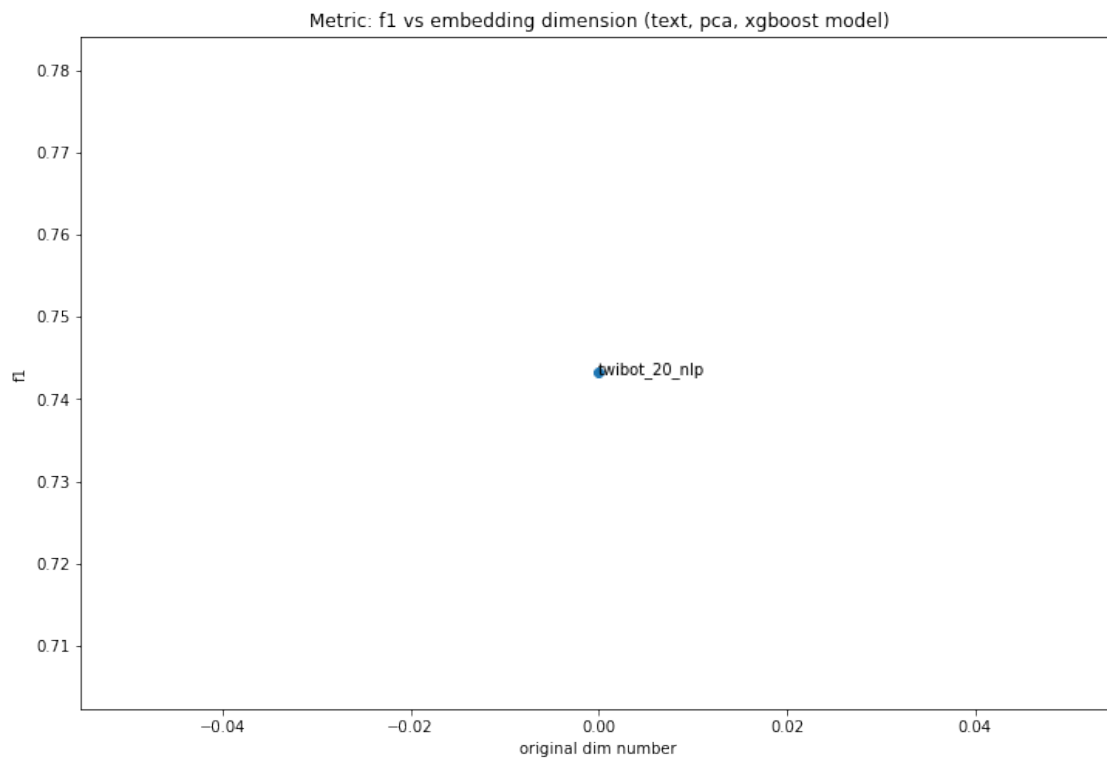
xgboost, f1, rolx, pca



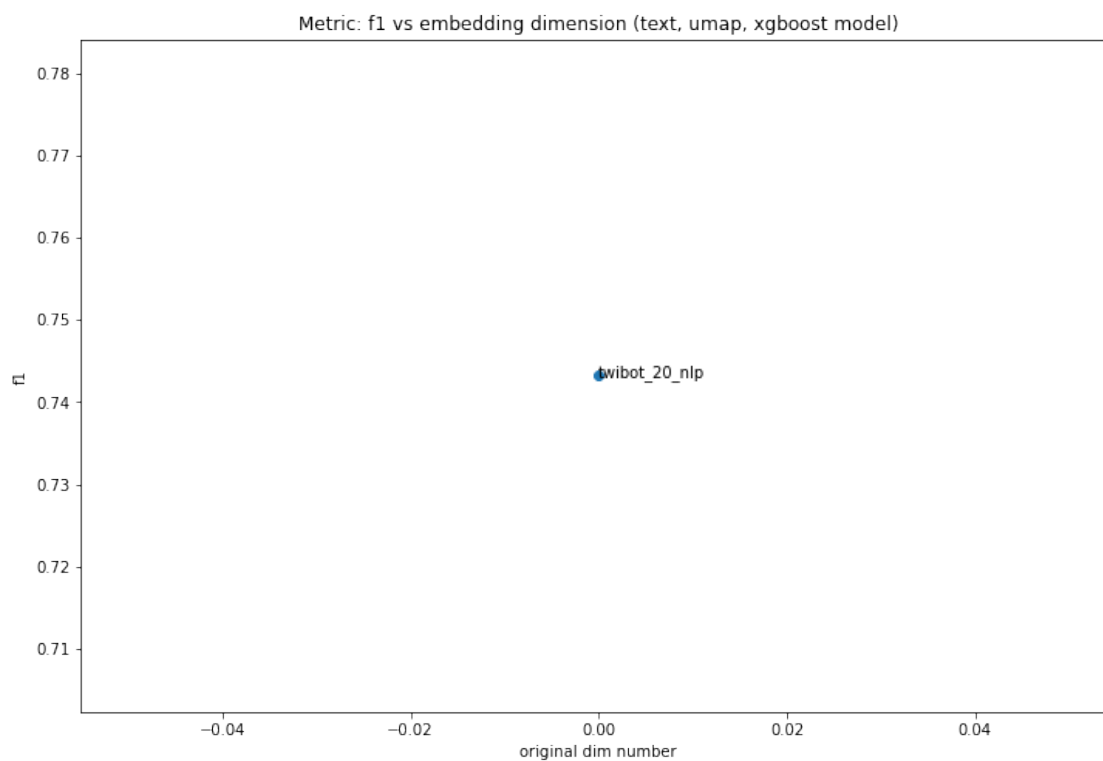
xgboost, f1, rolx, umap



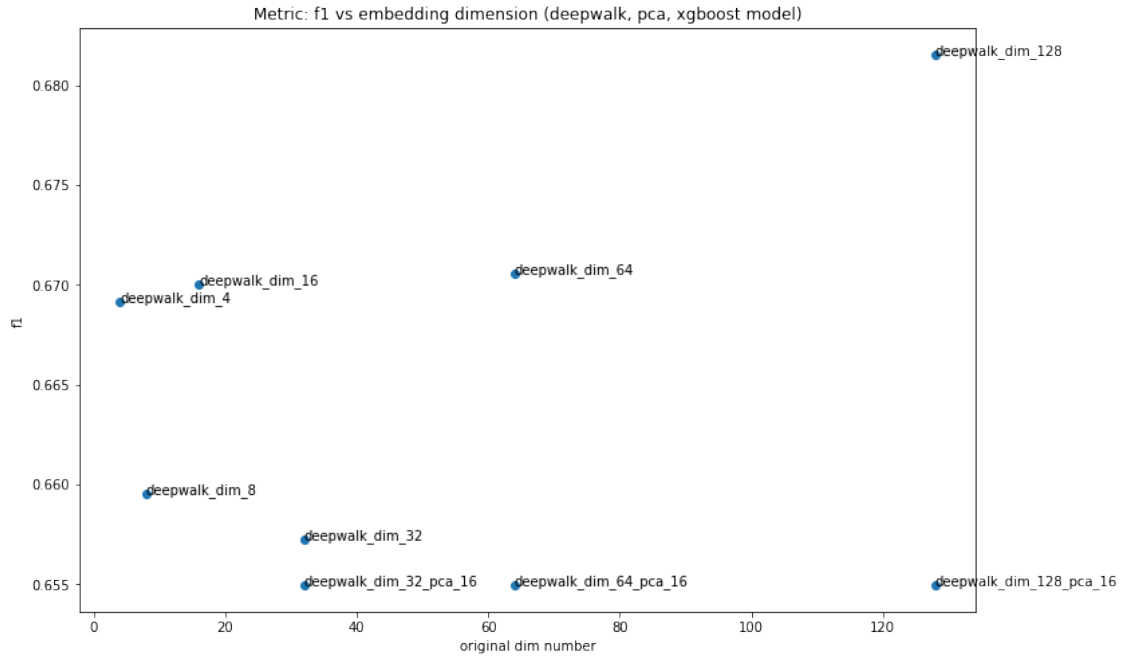
xgboost, f1, text, pca



xgboost, f1, text, umap



xgboost, f1, deepwalk, pca



xgboost, f1, deepwalk, umap

