

Name	Survival
Identifier	UCXXXX
Source	CH
Lead	CH
Description	The robot is pursuing a mission that is permanent in time (e.g. patrol) and has to recharge itself appropriatedly so as to keep achieving the objectives of the mission
Functional Focus	robustness
Rationale	
Implementation	Physical
Actors	Mobile robot, human operator, environmental entities
Status	Proposed
Priority	High
Basic flow of Events	-
Preconditions	i) Base robotic platform operational. ii) Location of the charging points
Postconditions	
Extends *	
Includes *	Identification
Constraints*	
Assumptions *	
Alternate Flow of Events *	
Change history *	2009-01-13 created CH
Open issues *	doubtable formulation, is this a UC?
<i>ASLab projects</i>	ICEA: UC0101 (ICEAsim)
<i>Free slots *</i>	