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A new method for finding an initial solution for the transportation problem

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Overview

- Transportation problem
 - Definition
 - Solving
- Previous methods
 - Explanation
 - weaknesses
- Proposed method
 - Explanation
 - Examples
- Comparing
 - Runtime Comparing
 - Implementation
 - Results and tables
- Conclusion
- Future works
- References

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Definition

Transportation problem

- ❑ one of the well-known and useful models in linear optimization
- ❑ Has many applications in determining how to optimally transport goods, require a very large number of constraints and variables
- ❑ Solving with simplex method may require an exorbitant computational effort
- ❑ Special solving method

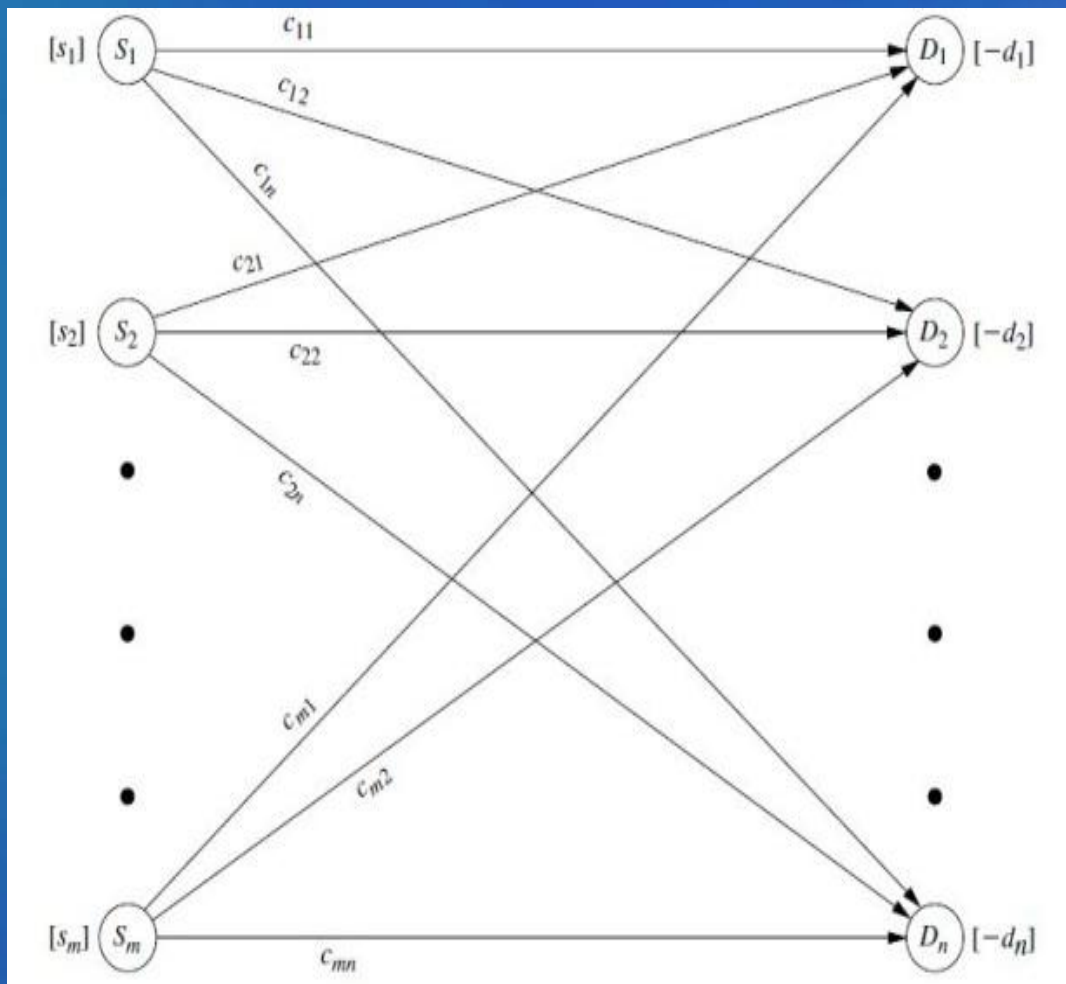
Definition

Transportation problem

$$\min \sum_{j=1}^n \sum_{i=1}^m c_{ij} x_{ij}$$

Subject to: $\sum_{j=1}^n x_{ij} = s_i$

$$\sum_{i=1}^m x_{ij} = d_j$$



Definition

Parameter table for transportation problem

	Cost per Unit Distributed				Supply
	Destination				
	1	2	...	n	
1	c_{11}	c_{12}	...	c_{1n}	s_1
2	c_{21}	c_{22}	...	c_{2n}	s_2
\vdots				\vdots
m	c_{m1}	c_{m2}	...	c_{mn}	s_m
Demand	d_1	d_2	...	d_n	

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Solving the transportation problem

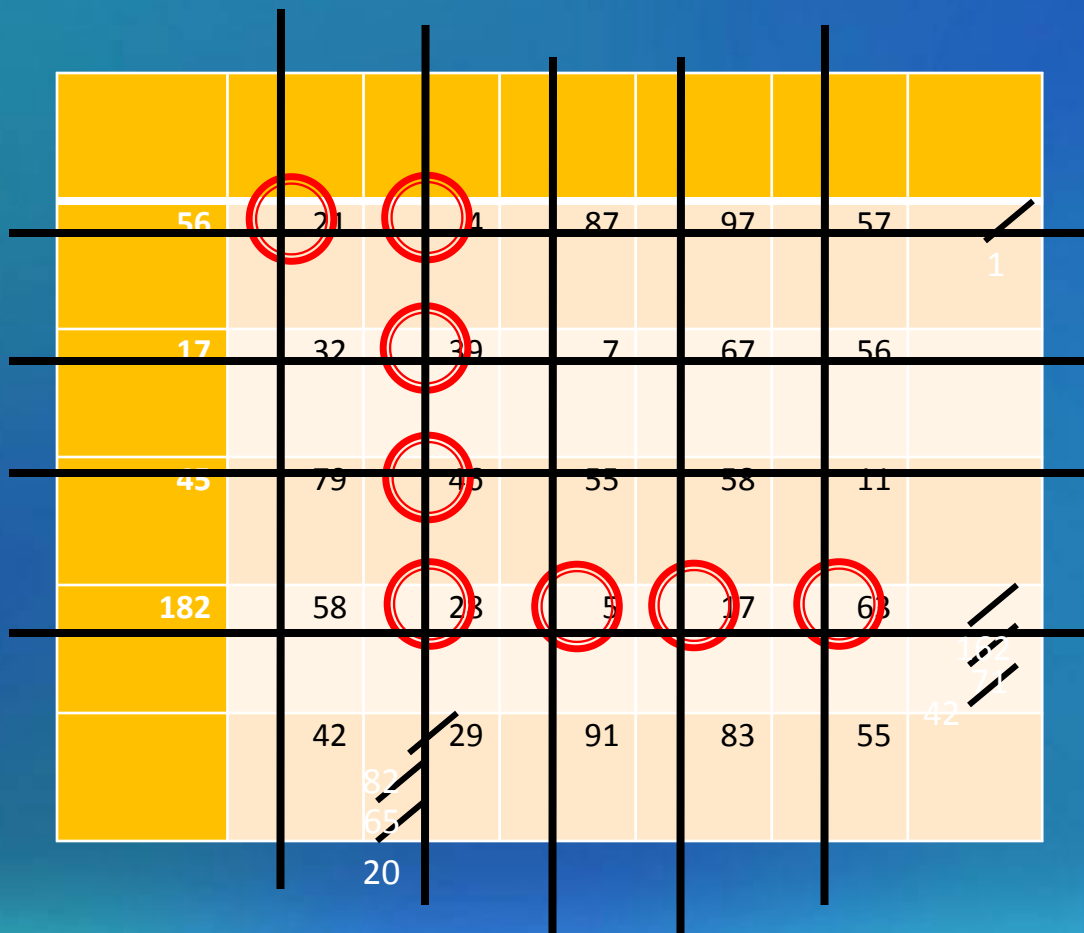
- **goal**
 - ☐ Find the optimal answer to satisfy the conditions with minimum cost
 - ☐ Select $n+m-1$ (or less) edges for transportation
- **Solving method**
 - ☐ Find an initial feasible solution
 - ☐ Run the iterative algorithm to improve the answer and finally find the optimal solution
- **Importance of initial solution**
 - ☐ Finding a better initial solution results in an impressive decrease in the number of iterations to reach the optimal solution in the main algorithm

This paper aims to introducing a novel method, to find an appropriate initial solution for the transportation problem

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Previous methods

Northwest corner method

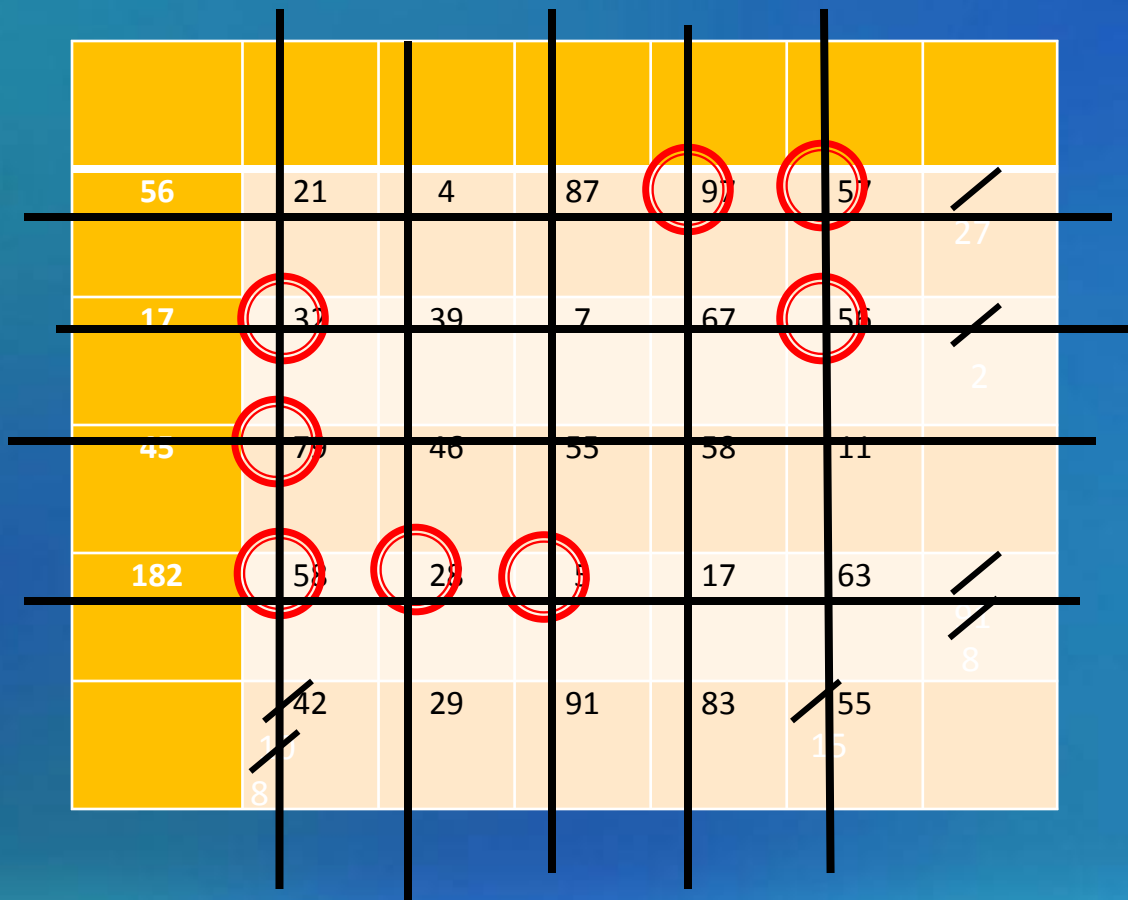


- Begin by selecting x_{11}
- if x_{ij} was the last basic variable selected, then next select $x_{i,j+1}$ if source i has any supply remaining. Otherwise, next select $x_{i+1,j}$.

$$57 \cdot 55 + 97 \cdot 1 + 67 \cdot 17 + 38 \cdot 45 + 5 \cdot 91 + 28 \cdot 29 + 58 \cdot 42 = 9748$$

Previous methods

Least Cost Method



select the cheapest edge and transfer as much as possible

Total cost:

$$\begin{aligned}
 &4 \cdot 29 + 5 \cdot 91 + 11 \cdot 45 + 17 \cdot 83 \\
 &+ 21 \cdot 27 + 32 \cdot 15 + 56 \cdot 2 + \\
 &63 \cdot 8 \\
 &= 4140
 \end{aligned}$$

Previous methods

Vogel's method

- Calculate the difference between the smallest and next-to-the-smallest unit cost c_{ij} still remaining in every rows or columns.
- In that row or column having the *largest difference*, select the variable having the *smallest remaining unit cost*.

56	21	4	87	97	37			
							14	
17	32	39	77	67	56			
45	74	46	55	58	11			
182	53	23	3	17	63			
							10	
	42	29	91	83	55			
	10		74	15				

21-4 = 17
32-7 = 25
46-11 = 35
17-5 = 12

21-4 = 17
32-7 = 25
17-5 = 12

21-4 = 17
32-7 = 25
28-5 = 12

32-21 = 11
28-4 = 24
7-5 = 2
58-17 = 41
56-11 = 45

32-21 = 11
28-4 = 24
7-5 = 2
67-17 = 50
57-56 = 1

21-4 = 17
28-5 = 12

21-4 = 17
58-28 = 30

57-4 = 53
63-28 = 35

58-21 = 37
28-4 = 24
87-5 = 82
63-57 = 6

58-21 = 37
28-4 = 24
63-57 = 6

28-4 = 24
63-57 = 6

63-28 = 35

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weaknesses

- ❑ ***Northwest corner*** method choose the edges, independent of their costs
- ❑ ***Least Cost Method*** choose the minimum cost available, a greedy algorithm, but our choice in one iteration may force bad choices in the next iterations
- ❑ ***Vogel's method*** calculate a penalty to considering bad choices in the future, but only considering one level penalty, not enough to make a good choice.

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Proposed method

Target : better greedy choice in each iteration

Definition:

- **Effective number of a source node (Ens_i)** is an approximation of the number of destination nodes which will transfer with the i_{th} source in next iterations.

$$ENs_i = \max\left\{ \left\lceil \frac{Csi}{Cst} * Nd \right\rceil, 2 \right\}$$

Csi : remaining capacity of i_{th} node

Cst : total remaining capacity of all sources

Nd : number of remaining destination

- **Effective number of a destination node (End_j)** defines similarly for the destinations.

$$ENd_j = \max\left\{ \left\lceil \frac{Cdj}{Cdt} * Ns \right\rceil, 2 \right\}$$

Proposed method

Effective value of a source node (EVs_i) is a approximation of the total penalty cost we will pay if we do not choose the lowest edge of i_{th} source.

$$EVs_i = \frac{P[1]*(ENs_i-1)+P[2]*(ENs_i-2)+\dots+P[ENs_i-1]*(1)}{\left(\frac{ENs_i(ENs_i-1)}{2}\right)} - P[0]$$

array $pn[]$ is increasing order of ENs_i reaming cheapest edges of the i_{th} source node.

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17		2	56	21	4	87	3	97	57	17
										29
10		2	17	32	39	7	2	67	56	10
										15
35		2	45	79	46	55	58	11		
22.5		4	182	58	28	5	17	63	22	30
	10			42	29	91	83	55		
				21						
	2			2	2	2	2	2		
	2			2	2					
	2			11	24	2	41	45		
	1			24	11					

$$ENs_4 = \max\left\{\left\lceil \frac{182}{300} * 5 \right\rceil, 2\right\} = 4$$

$$EV_{s_4} = \frac{17 * (3) + 28 * (2) + 58 * (1)}{(6)} - 5 = 22.5$$

$$EV_{d_1} = \frac{56}{(1)} - 11 = 45$$

$$EN_{d_1} = \max\left\{\left\lceil \frac{55}{300} * 4 \right\rceil, 2\right\} = 2$$

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comparing

Properties of proposing method

- ❑ by using the *effective number*, estimating the number of next transitions of each node
- ❑ by calculating *effective value* choosing a better greedy choice in each iteration which will provide better initial solutions
- ❑ We can implement this method by $O(n^2)$ in time complexity, like Vogel's method.

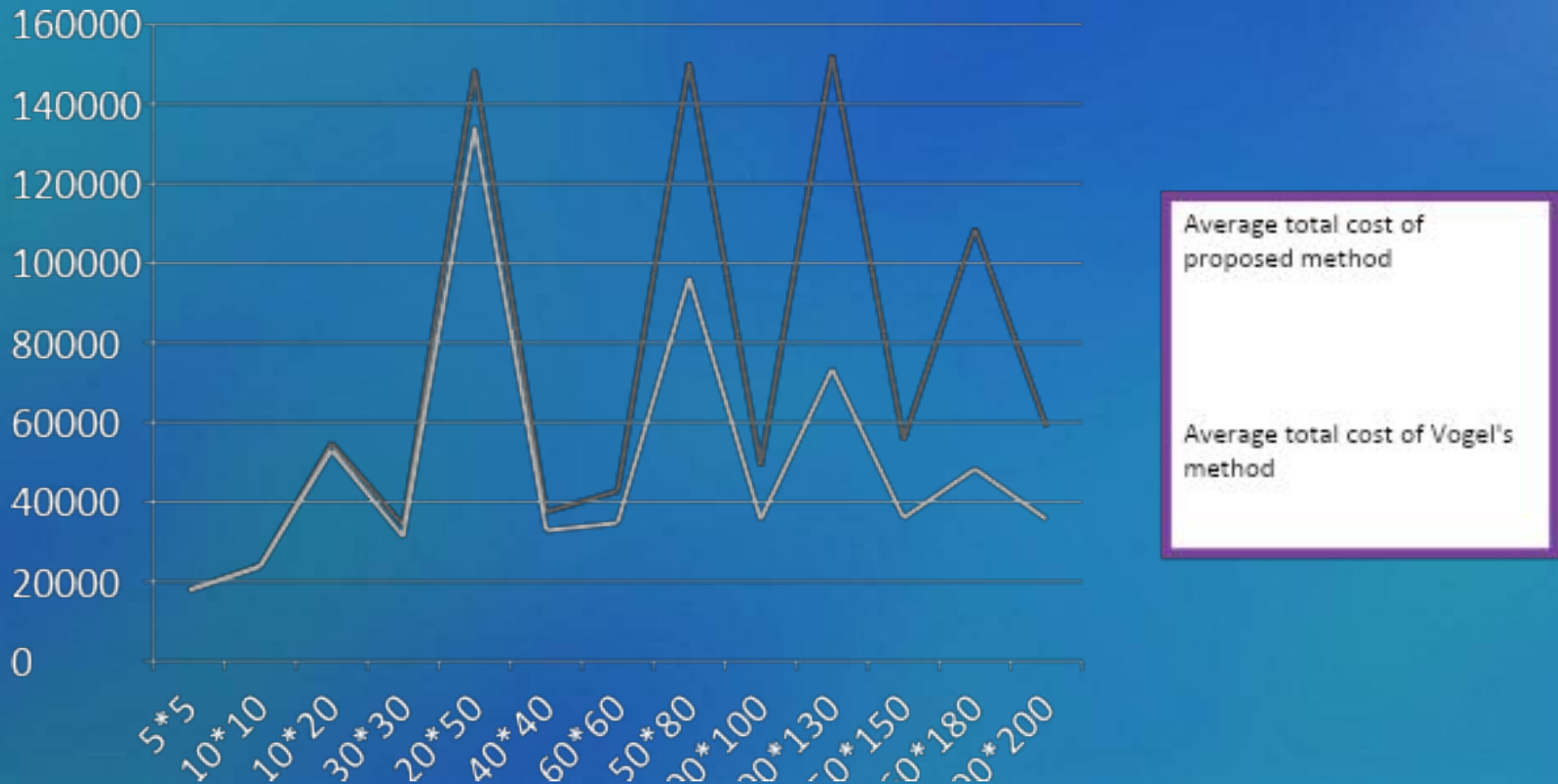
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implementation

- ❑ We compared our method and Vogel's method using 13 different size problems.
- ❑ For each problem instance, 1000 balanced transportation problem was implemented and solved using both method.
- ❑ Comparison criteria
 - average of total cost of the solution
 - Number of the better answers in each size of the problem

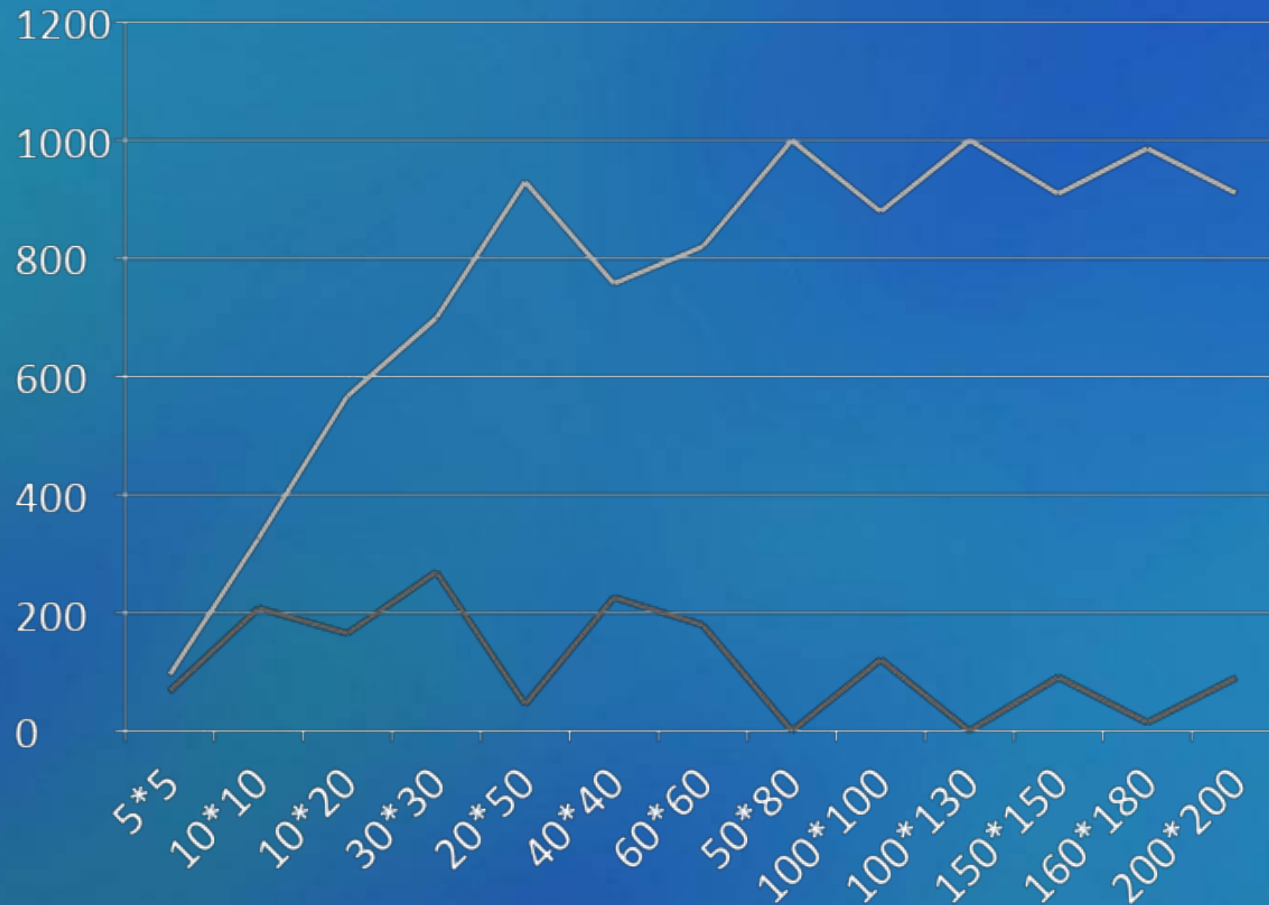
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Experimental results



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Experimental results



Number of better answers of
proposed method

Number of better answers of
Vogel's method

Experimental results

Size of problem	Num of vogel 's better answers	Num of proposed method 's better answers	Num of equal answers
5*5	67	95	838
10*10	208	326	466
10*20	165	567	268
30*30	269	699	32
20*50	45	930	25
40*40	226	757	17
60*60	179	820	1
50*80	0	1000	0
100*100	121	879	0
150*130	0	1000	0
150*150	91	909	0
160*180	14	986	0
200*200	90	910	0

Size of problem	Avg cost vogel 's answer	Avg cost our answer
5*5	17836	17777
10*10	24052	23735
10*20	54814	53066
30*30	34213	31213
20*50	148577	134252
40*40	37486	32814
60*60	42730	34708
50*80	150351	96446
100*100	49125	35550
150*130	152166	73396
150*150	55631	35984
160*180	108752	48316
200*200	58805	35651

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conclusion

- ❑ This paper aims to introducing a novel method, to find an initial solution for transportation problem
- ❑ The proposed method, according to the remaining capacity of each node and calculating an estimation number of next transitions of the node, will reach better answer through making a better choice in each iteration
- ❑ The implementation also shows the prospering performance of this method

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Future works

- ❑ Focus on the main algorithm in order to reduce the number of iterations to solve the problem.
- ❑ Define a new formula for effective number and effective value .
- ❑ Take beneficiary of distributed and parallel systems to implement the algorithm.

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