



SysML v2

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Acknowledgments – contains material from Ed Seidewitz

Agenda – SysML v2

1. **Motivation, history, packages**
2. Selected packages – structure
3. Selected packages - actions
4. Selected packages – calculations & constraints
5. Tools

SysML v2 – History and Timeline

SysML v2 – next generation systems modeling language addressing SysML v1 limitations

RFP: December 2017

Work on SysML v1 continues in parallel, v1.7 adopted 2022

SysML v2 Submission Team formed in December 2017

Grew to 200+ members from 80+ organizations

March 2024, Finalize Specifications, Establish Revision Task Forces

Mid 2024, Publish Formal Specifications

Motivation

Problems of UML heritage

- Only small evolutions in UML
- No standardized diagram exchange format
- XML format does not work well with git => Plant UML might become de-facto standard
- UML complexity

⇒ Towards a new language with ***standardized textual format*** and automatically generated diagrams

- Meta model in KerML (Kernel Modeling Language), OMG standard (07/2023)
<https://www.omg.org/spec/KerML> (400 pages)

Naming

- Objective: more consistent naming
 - “**definition**” for reusable items
 - “**usage**” for references and context-dependent specifications

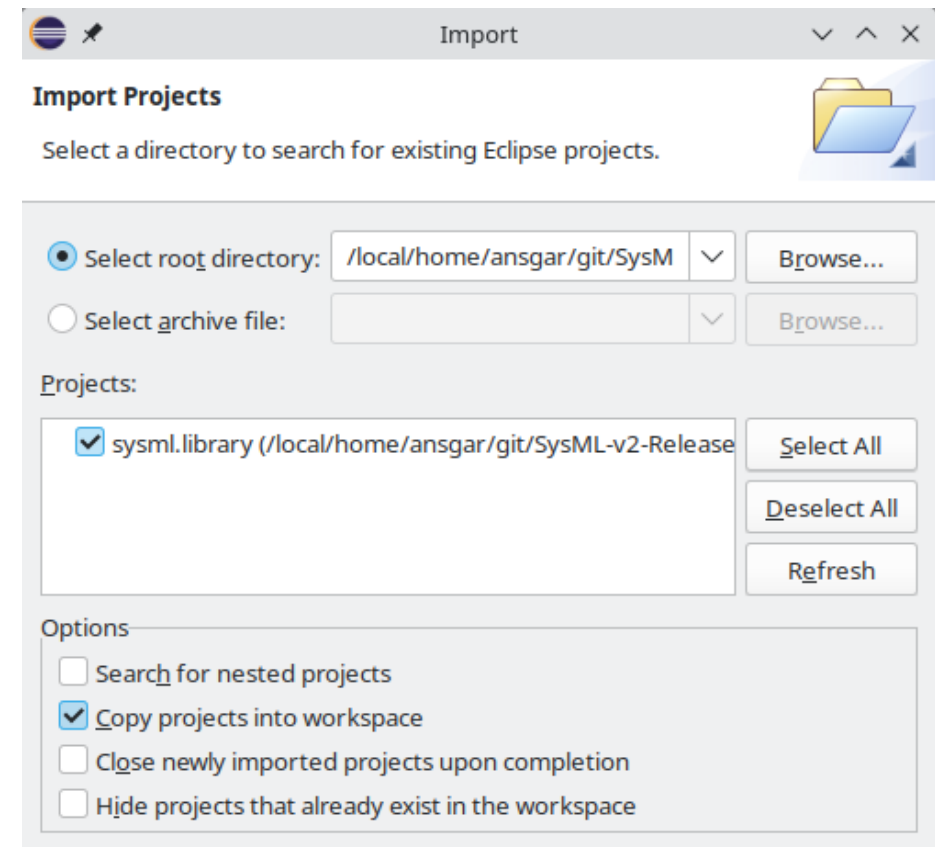
⇒ Naming is (sometimes) quite different from SysML v1 and UML
- Example: connection definition and connection (in a couple of slides)

Tools

- Eclipse-based reference implementation
 - Ed Seidewitz (Model-driven solutions)
 - <https://github.com/Systems-Modeling/SysML-v2-Release/tree/master>
- SysOn – Collaboration OBEO & CEA
 - Web-based (fronted/backend)
 - <https://doc.mbse-syson.org/>
- SysIDE for VS code
 - <https://github.com/sensmetry/sysml-2ls>

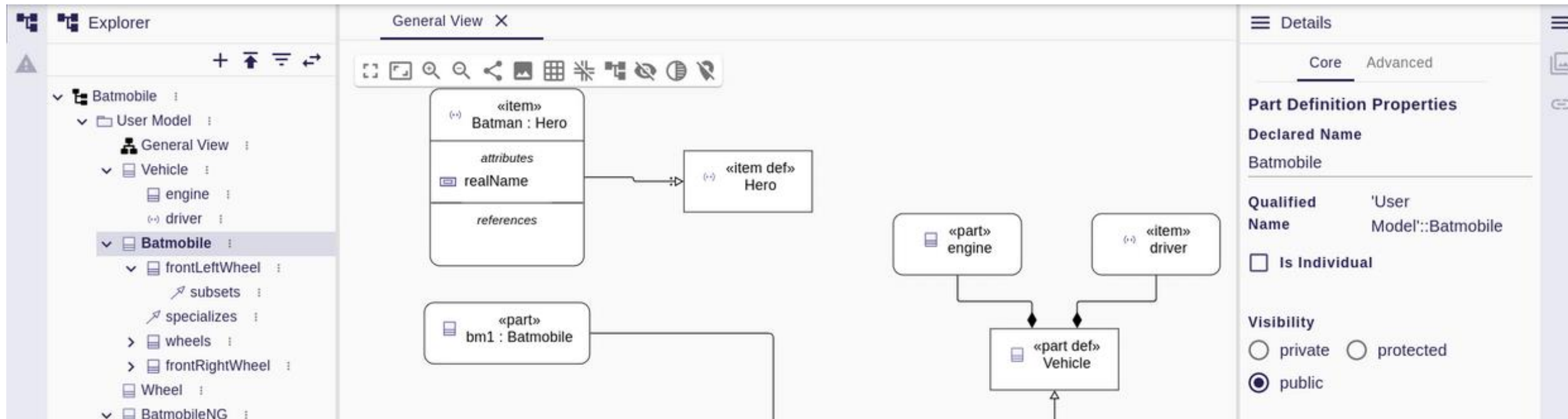
Installation instructions – Reference implementation

- We will mainly use the reference implementation (but you can install all three)
- Get an eclipse-modeling tools 2024-12 from here:
 - <https://www.eclipse.org/downloads/packages/>
 - Help > Install New Software > Add > archive
“install/eclipse/org.omg.sysml.site.zip”
 - Import sysml.library via “Import > General >
Existing projects into workspace
 - Check option “copy projects into workspace”
 - Import examples (copy option is not required)



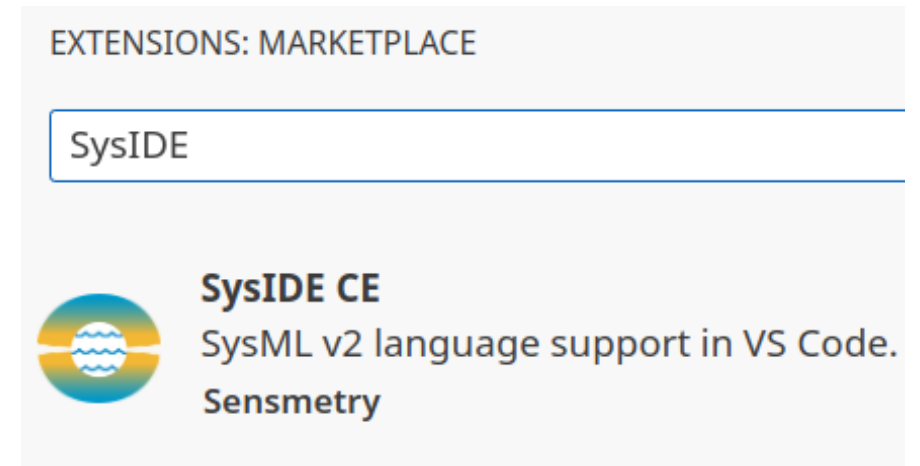
Installation instructions – SysON

- <https://doc.mbse-syson.org/syson/v2025.1.0/installation-guide/index.html>
- Install docker & docker compose first
- Download YAML file for single user installation
<https://github.com/eclipse-syson/syson/blob/v2025.1.0/docker-compose.yml>



Installation instructions – SysIDE

- Get a current VS code installation
- Open Extensions > Type SysIDE in the filter
 - Install also the SysML library



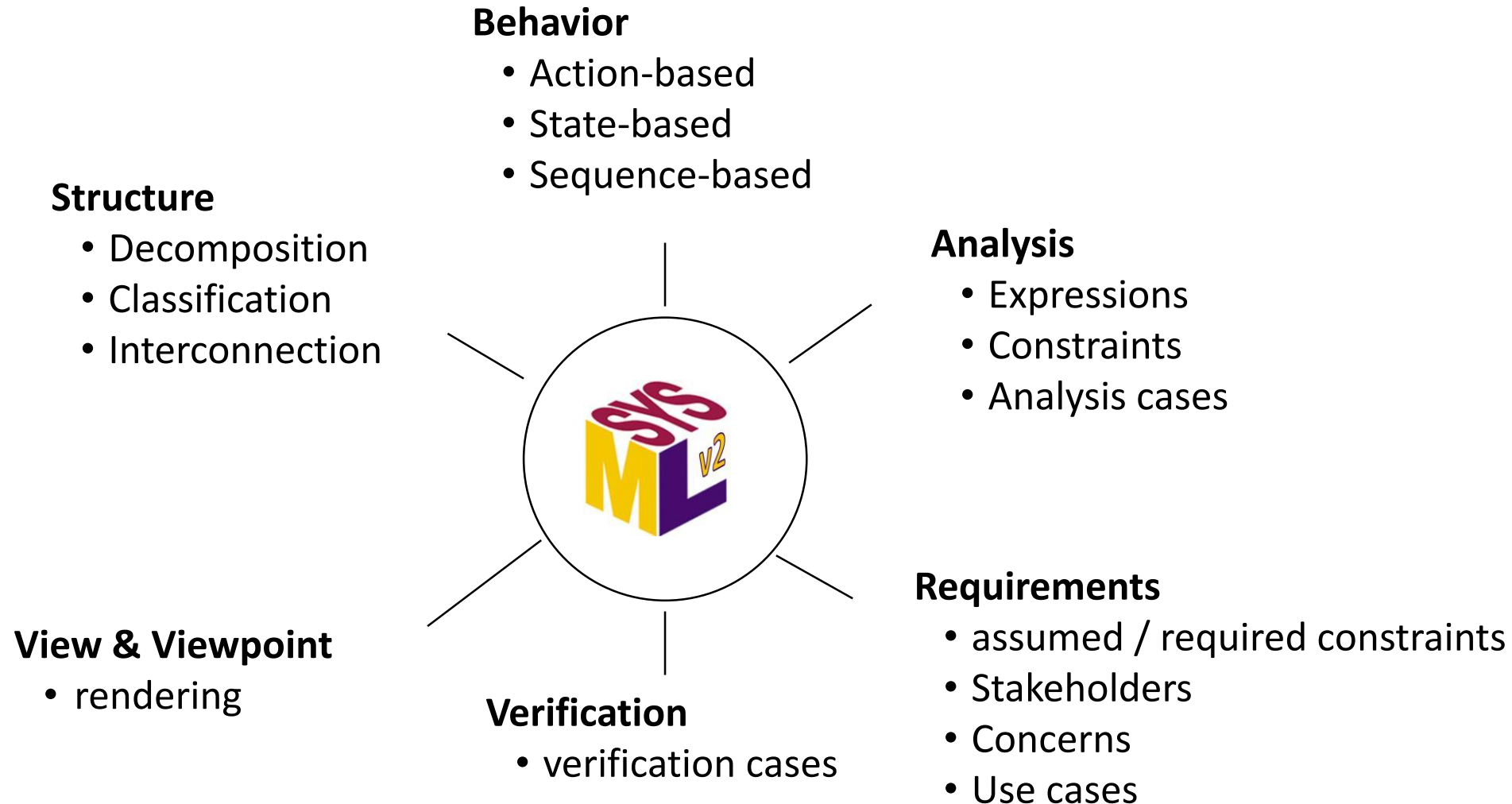
Advantages/inconveniences

- Eclipse-based reference implementation
 - Quite complete, large set of examples (which have been copied to the instn git)
 - Diagrams are automatically generated, based on PlantUML
 - based on Eclipse + Xtext, (minor) performance issues
- SysON
 - Collaborative, built on same technology as PapyrusWeb
 - Text mode not yet integrated (likely based on SysIDE)
 - Graphical editor (arrange your boxes as needed, choose subset)
- SysIDE
 - Fast and easy to use
 - Only text, advanced features only in paid version

Tool conclusions

- Choose the tool that you like, textual specifications are exchangeable.
- The following slides use screenshots from SysIDE along with generated PlantUML diagrams via the reference implementation

SysML v2 – Overview

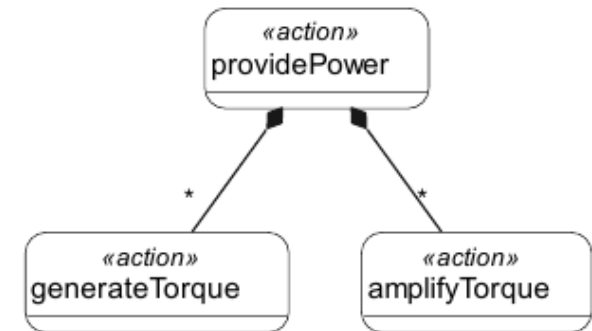
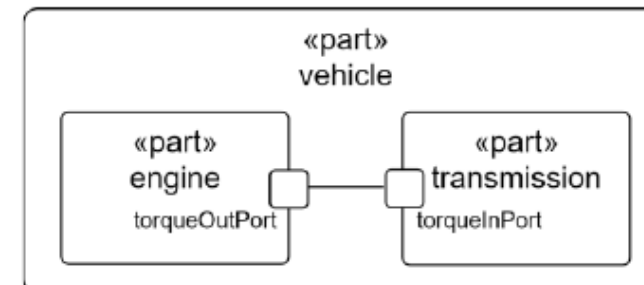
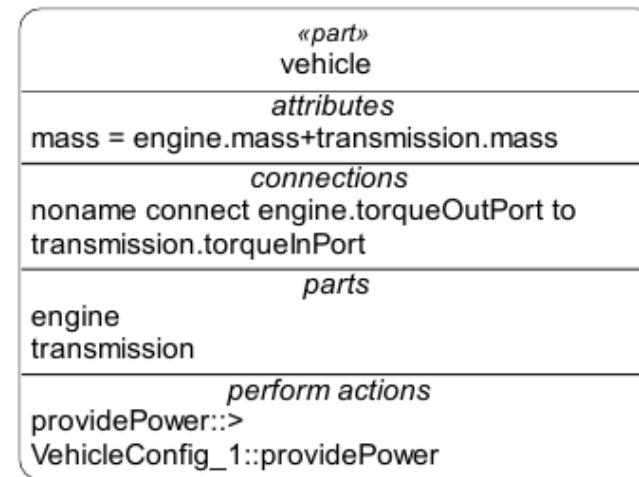


SysML v2

- Corresponding textual and graphical notations for each language construct.
- Comprehensive expression language.
- Textual notations can be used consistently on graphical diagrams.

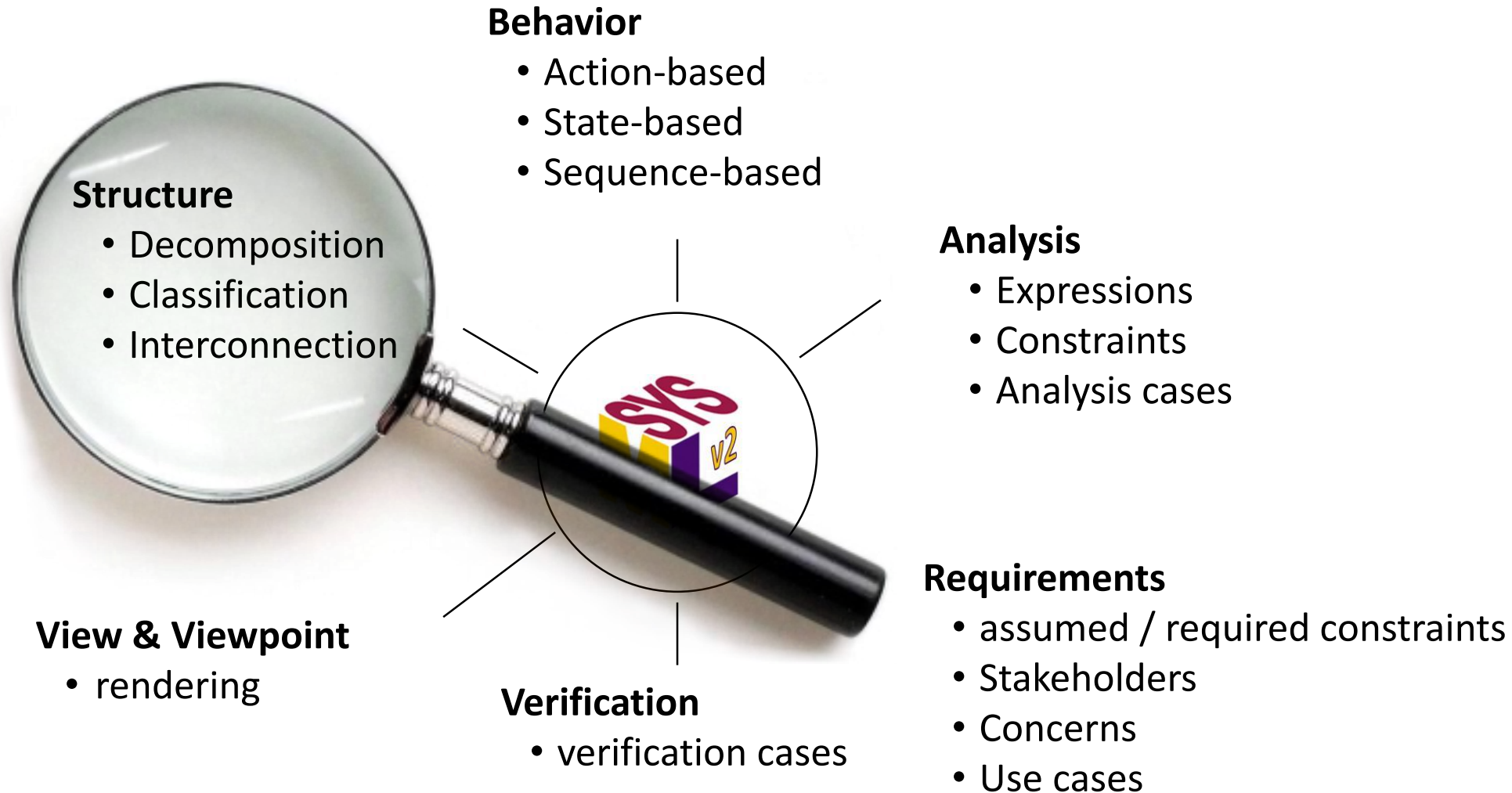
```
part vehicle {  
  attribute mass = engine.mass + transmission.mass;  
  perform providePower;  
  part engine {  
    attribute mass;  
    port torqueOutPort;  
    perform providePower.generateTorque;  
  }  
  part transmission {  
    attribute mass;  
    port torqueInPort;  
    perform providePower.amplifyTorque;  
  }  
  connect engine.torqueOutPort to transmission.torqueInPort;  
}  
  
action providePower {  
  action generateTorque;  
  action amplifyTorque;  
}
```

vehicle.sysml



Generated PlantUML
diagram

SysML v2 – Structure



UML vs SysML v2 terminology

UML	SysML v2
package / member / visibility	package / member / visibility
element import / package import	membership import / namespace import
owned member / imported member	owned member / imported member / alias member
comment	comment / documentation

SysML v2

As in UML : namespace for its members and container for its owned members.

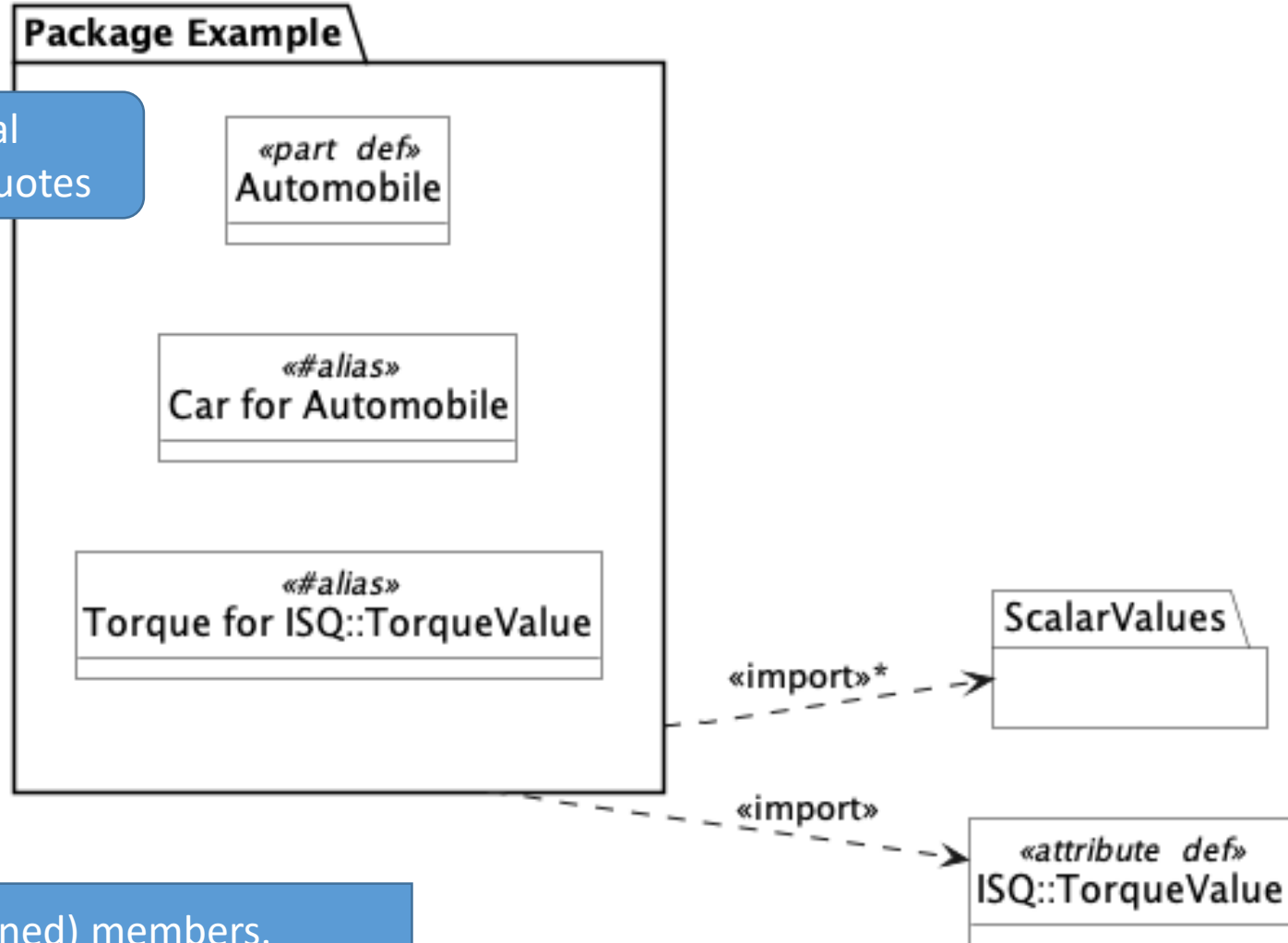
spaces or other special characters ⇒ single quotes

01. Packages/Package Example

```
package 'Package Example' {  
  public import ISQ::TorqueValue;  
  private import ScalarValues::*;  
  
  private part def Automobile;  
  
  public alias Car for Automobile;  
  alias Torque for ISQ::TorqueValue;  
}
```

Import either single member or all members of an imported package

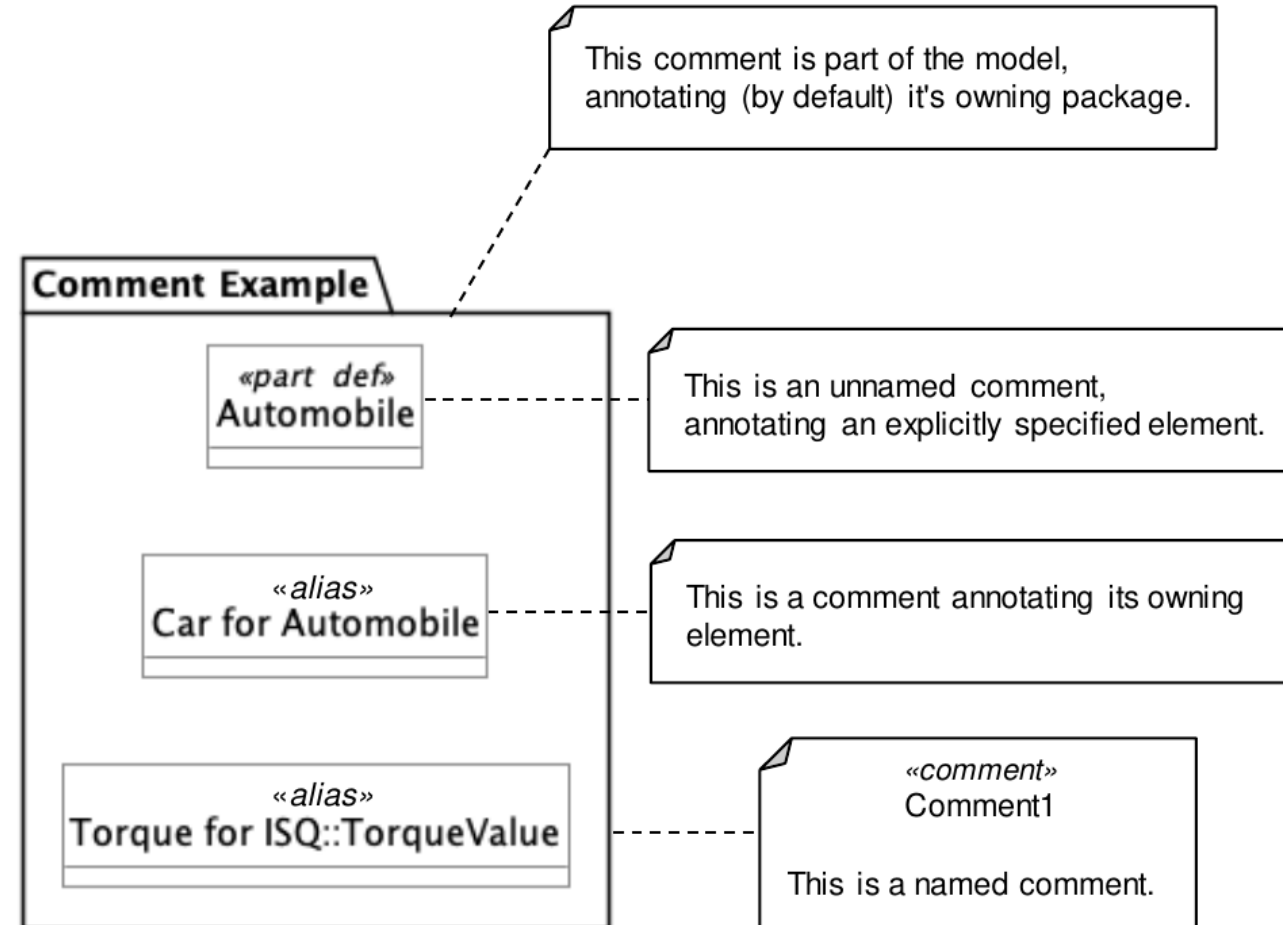
Introduce alias for (owned) members. Use sparingly / with care, since all members are re-exported!



SysML v2 – Comments and Notes

01. Packages/Comment Example

```
package 'Comment Example' {  
    /* This comment is part of the model,  
     * annotating (by default) it's owning package. */  
  
    comment Comment1 /* This is a named comment. */  
  
    comment about Automobile  
    /* This is an unnamed comment, annotating an  
     * explicitly specified element.  
     */  
  
    part def Automobile;  
  
    alias Car for Automobile {  
        /*  
         * This is a comment annotating its owning  
         * element.  
         */  
    }  
  
    // This is a note. It is in the text, but not part  
    // of the model.  
    alias Torque for ISQ::TorqueValue;  
}
```



UML - SysML v2 – Terminology differences

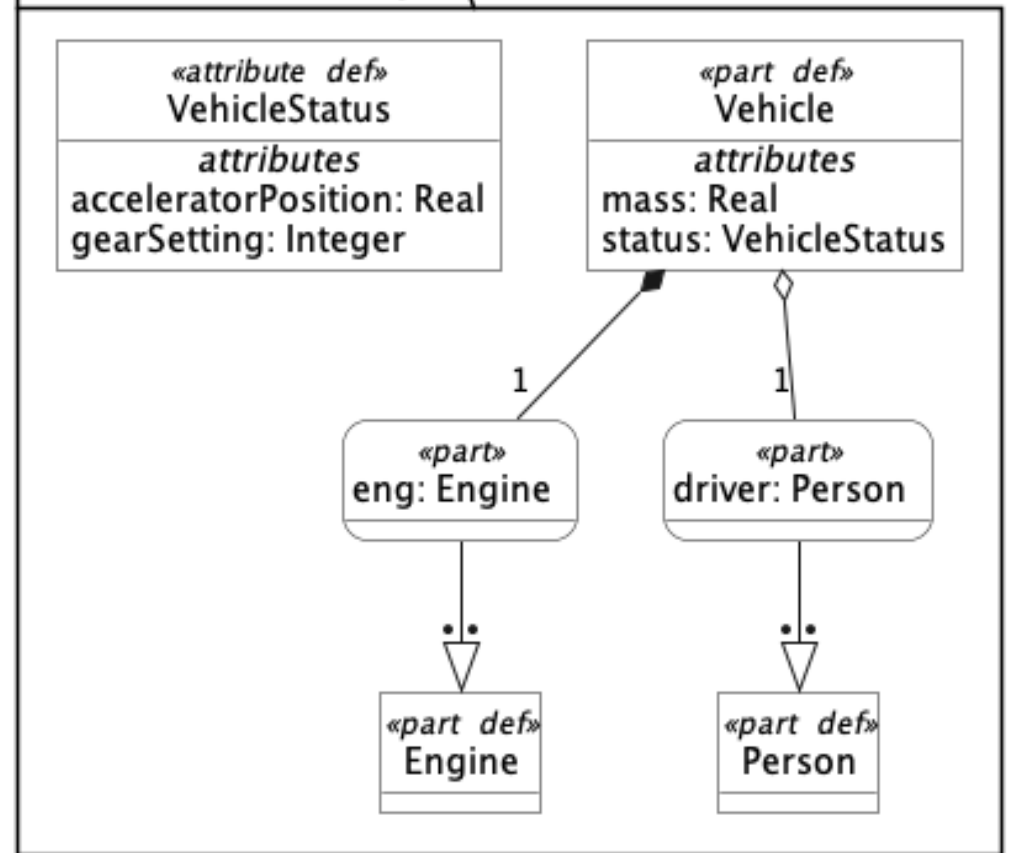
UML / SysML v1	SysML v2
class / property	item definition / item usage
block / part property	part definition / part usage
value type / value property	attribute definition / attribute usage
interface block / proxy port (flow property)	port definition / port usage (directed usage)
association block / connector	connection definition / connection usage interface definition / interface usage
item flow	flow connection definition / flow definition usage

SysML v2 – part definition (blocks)

```
part def Vehicle {  
  attribute mass : Real;  
  attribute status : VehicleStatus;  
  
  part eng : Engine;  
  
  ref part driver : Person;  
}  
  
attribute def VehicleStatus {  
  attribute gearSetting : Integer;  
  attribute acceleratorPosition : Real;  
}
```

```
part def Engine;  
part def Person;
```

Part Definition Example



Specialization /Generalization

As in UML, defines a subset of the classification of its generalization.

```
abstract part def Vehicle;
```

```
part def HumanDrivenVehicle specializes Vehicle {  
  ref part driver : Person;  
}
```

equivalent to specializes keyword.

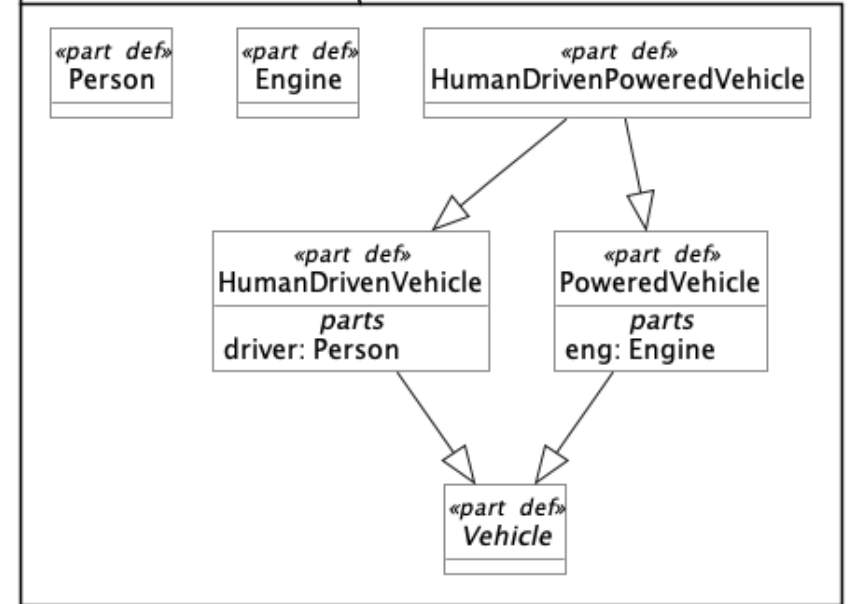
```
part def PoweredVehicle :> Vehicle {  
  part eng : Engine;  
}
```

Can define additional features.

```
part def HumanDrivenPoweredVehicle :>  
  HumanDrivenVehicle, PoweredVehicle;
```

```
part def Engine;  
part def Person;
```

Generalization Example



SysML v2 – enumerations

```
enum def TrafficLightColor {  
    enum green;  
    enum yellow;  
    enum red;  
}
```

Values of an attribute usage are limited to the defined set of enumerated values.

```
part def TrafficLight {  
    attribute currentColor : TrafficLightColor;  
}
```

```
part def TrafficLightGo specializes TrafficLight {  
    attribute redefines currentColor = TrafficLightColor::green;  
}
```

06. Enumeration Definitions/Enumeration Definitions-1

This shows an attribute being bound to a specific value (more on binding later).

SysML v2 – Item definitions

```
item def Fuel;  
item def Person;  
  
part def Vehicle {  
    attribute mass : Real;  
  
    ref item driver : Person;  
  
    part fuelTank {  
        item fuel: Fuel;  
    }  
}
```

Defines class of things that exist in space and time but are **not** necessarily considered "parts" of a system being modeled.

continuous, if any portion is the same kind of thing.
A portion of fuel is still fuel. Not true for a person.

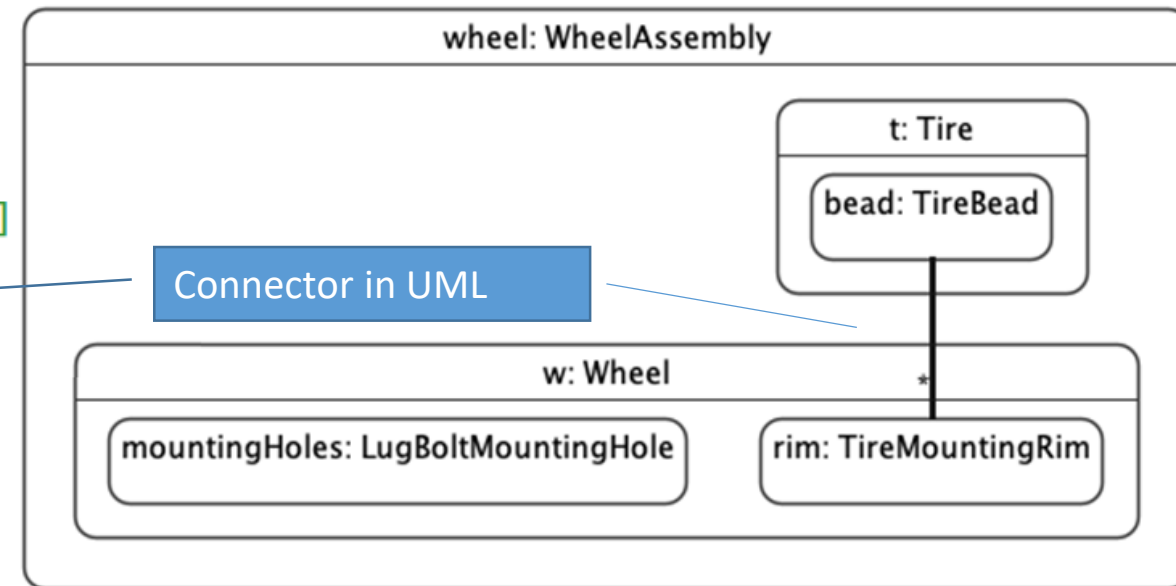
All parts can be treated as items, but not all items are parts. The design of a system determines what should be modeled as its "parts".

Structure – Connections and connection definitions

```
part wheelHubAssembly : WheelHubAssembly {  
  
  part wheel : WheelAssembly[1] {  
    part t : Tire[1] {  
      part bead : TireBead[2];  
    }  
    part w: Wheel[1] {  
      part rim : TireMountingRim[2];  
      part mountingHoles : LugBoltMountingHole[5]  
    }  
    connection : PressureSeat  
      connect bead references t.bead  
      to mountingRim references w.rim;  
  }  
}
```

```
connection def PressureSeat {  
  end bead : TireBead[1];  
  end mountingRim : TireMountingRim[1];  
}
```

Association in UML
(typed connectors not really used in UML)



Ports and port definitions

```
port def FuelPort {  
  attribute temperature : Temp;  
  out item fuelSupply : Fuel;  
  in item fuelReturn : Fuel;  
}
```

```
part def FuelTank {  
  port fuelTankPort : FuelPort;  
}
```

```
part def Engine {  
  port engineFuelPort : ~FuelPort;  
}
```

Port definition has implicit **conjugate** port definition reversing input and output features. Name is prefixed with ~ (e.g. ~FuelPort)

Ports are **compatible** if they have directed features that match with inverse directions

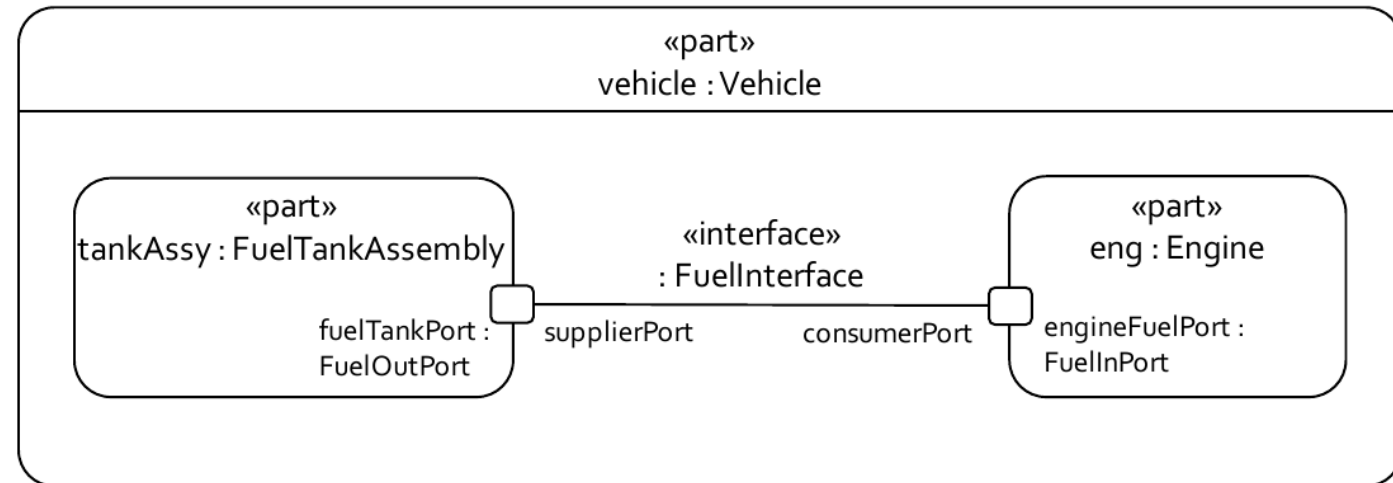
Directed features are always referential

Port = connection point through which a part definition makes some of its features available

Interfaces and interface definitions

```
part def Vehicle;  
  
interface def FuelInterface {  
  end supplierPort : FuelOutPort;  
  end consumerPort : FuelInPort;  
}  
  
part vehicle : Vehicle {  
  part tankAssy : FuelTankAssembly;  
  part eng : Engine;  
  
  interface : FuelInterface connect  
    supplierPort ::> tankAssy.fuelTankPort to  
    consumerPort ::> eng.engineFuelPort;  
}
```

interface definition = connection definition whose ends are port definitions

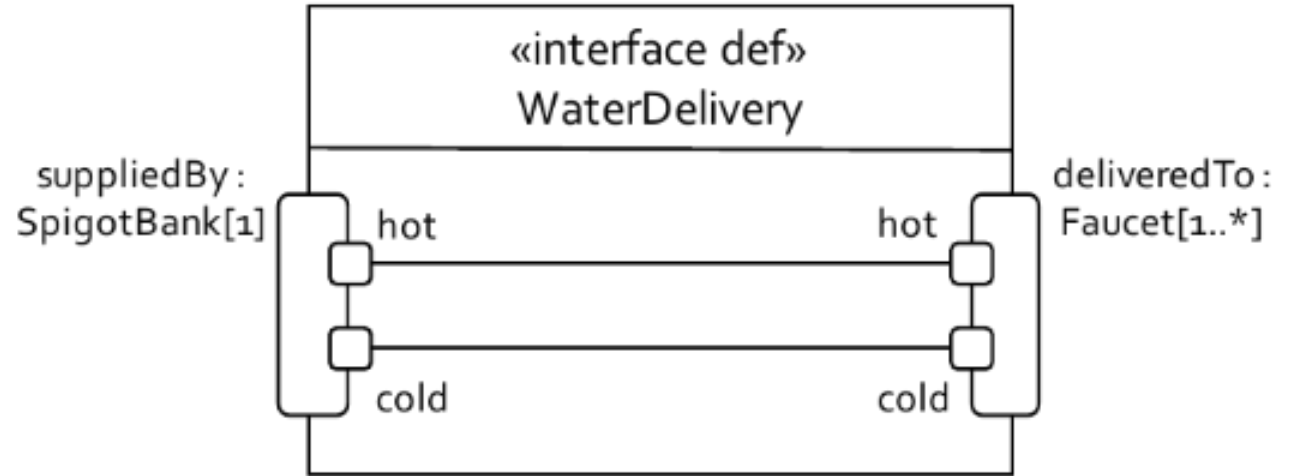


CAVEAT

Same term as in UML, but SysML v2 interfaces are very different from UML interfaces

Complex interface definitions

```
interface def WaterDelivery {  
  end suppliedBy : SpigotBank[1] {  
    port hot : Spigot;  
    port cold : Spigot;  
  }  
  end deliveredTo : Faucet[1..*] {  
    port hot : FaucetInlet;  
    port cold : FaucetInlet;  
  }  
  
  connect suppliedBy.hot to deliveredTo.hot;  
  connect suppliedBy.cold to deliveredTo.cold;  
}
```



Beyond UML

enable identification of sub-connections,
“cables”

Binding connections vs. Flow connections

- A **binding connection** asserts the equivalence of the connected features (equal values in the same context).

```
part vehicle : Vehicle {  
  part tank : FuelTankAssembly {  
    port redefines fuelTankPort {  
      out item redefines fuelSupply;  
      in item redefines fuelReturn;  
    }  
  
    bind fuelTankPort.fuelSupply = pump.pumpOut;  
    bind fuelTankPort.fuelReturn = tank.fuelIn;  
  
    part pump : FuelPump {  
      out item pumpOut : Fuel;  
      in item pumpIn : Fuel;  
    }  
  }  
  ...  
}
```

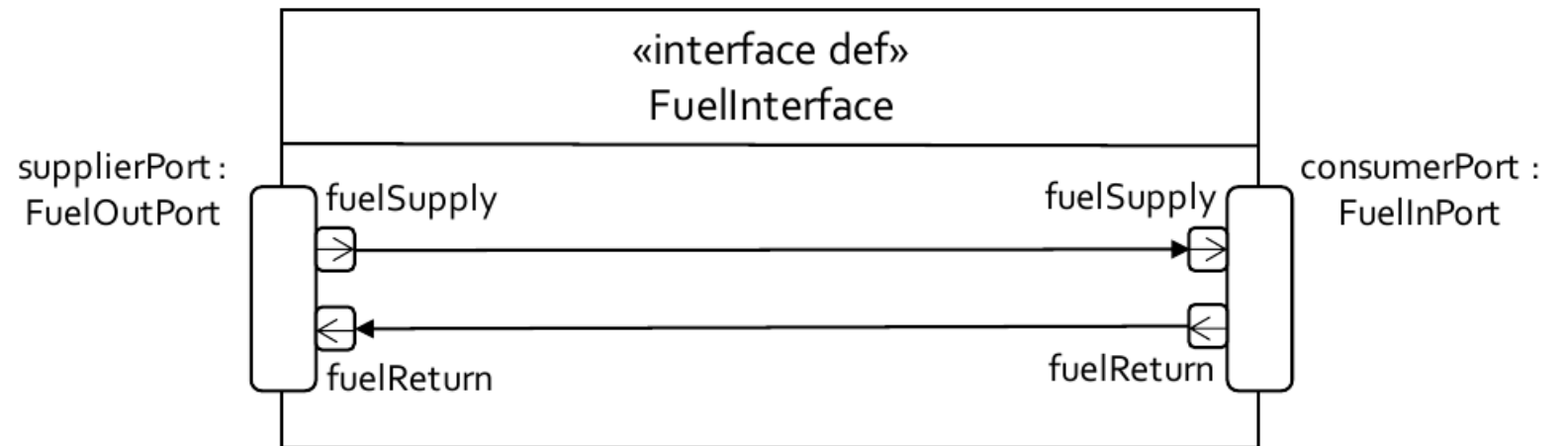
12. Binding Connectors/Binding Connectors Example-1

Not a data-flow, rather an alias

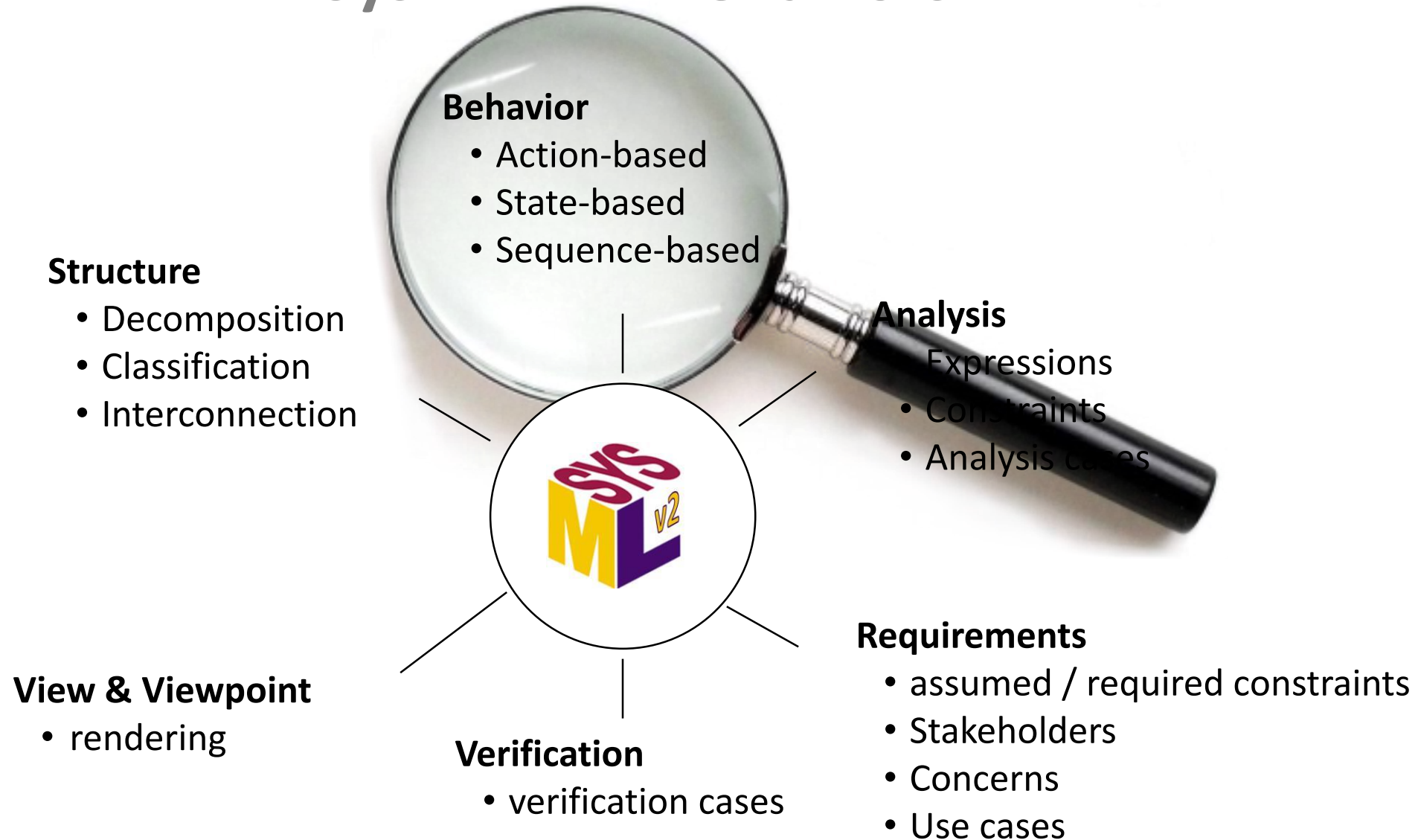
Flow connections in interfaces

```
interface def FuelInterface {  
  end supplierPort : FuelOutPort;  
  end consumerPort : FuelInPort;  
  
  flow supplierPort.fuelSupply to consumerPort.fuelSupply;  
  flow consumerPort.fuelReturn to supplierPort.fuelReturn;  
}
```

13. Flow Connections/Flow Connection Interface Example



SysML v2 – Behaviors

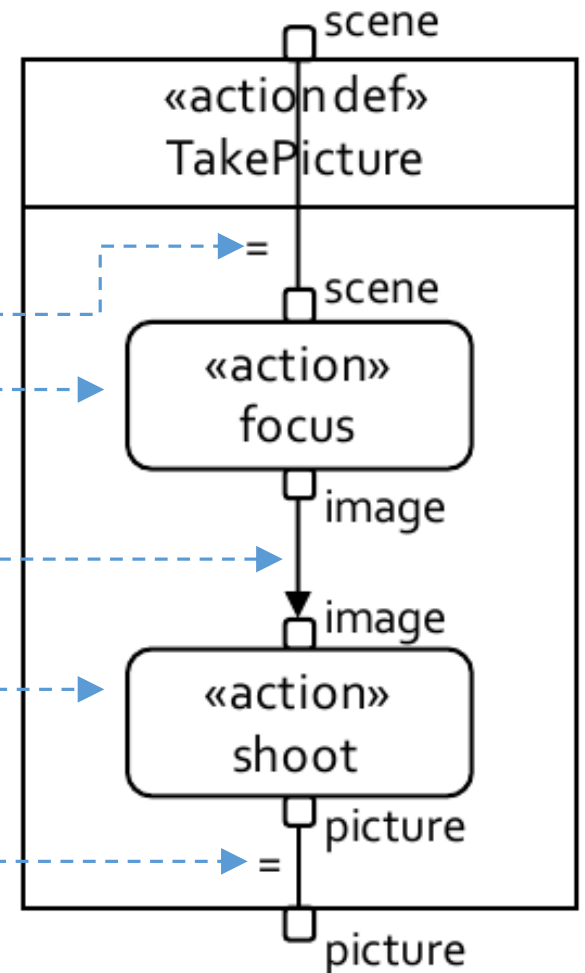


SysML v2 – Action definition

Directed features of an action definition are considered to be action parameters.

14. Action Definitions/Action Definition Example

```
action def Focus { in scene : Scene; out image : Image; }  
action def Shoot { in image: Image; out picture : Picture; }  
  
action def TakePicture { in scene : Scene; out picture : Picture;  
  bind focus.scene = scene;  
  
  action focus: Focus { in scene; out image; }  
  
  flow from focus.image to shoot.image;  
  
  action shoot: Shoot { in image; out picture; }  
  
  bind shoot.picture = picture;  
}
```



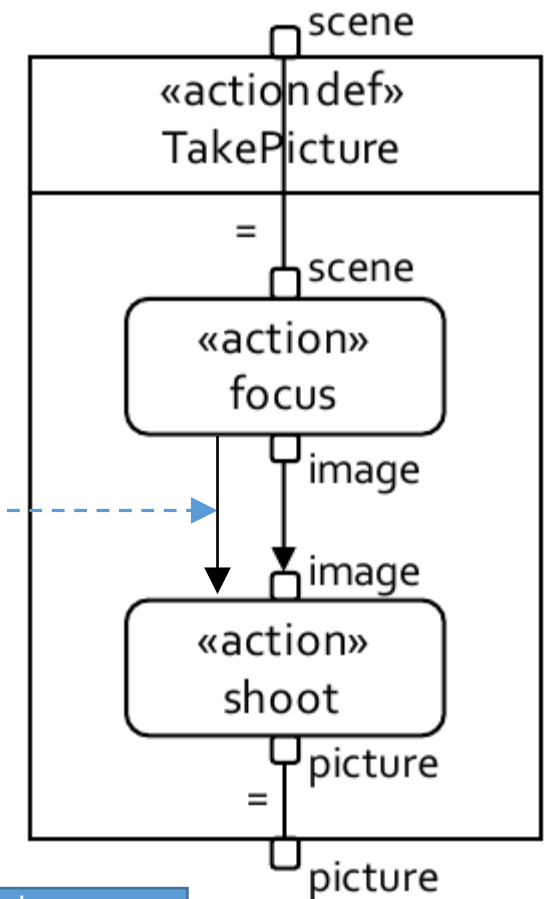
transfer items between actions via flow connection

SysML v2 – succession & succession flow

14. Action Definitions/Action Succession Example-1

```
action def Focus { in scene : Scene; out image : Image; }  
action def Shoot { in image: Image; out picture : Picture; }
```

```
action def TakePicture {  
  in item scene : Scene;  
  out item picture : Picture;  
  
  bind focus.scene = scene;  
  
  action focus: Focus { in scene; out image; }  
  
  flow from focus.image to shoot.image;  
  
  first focus then shoot;  
  
  action shoot: Shoot { in image; out picture; }  
  
  bind shoot.picture = picture;  
}
```



Succession asserts that 2nd action waits for completion of 1st

SysML v2 – shorthand / conditional successions

- **Shorthand**

Only prefix action with “then” (i.e. omit “first” – defaults to previous action)

e.g. **then action** shoot : Shoot

- **Conditional successions**

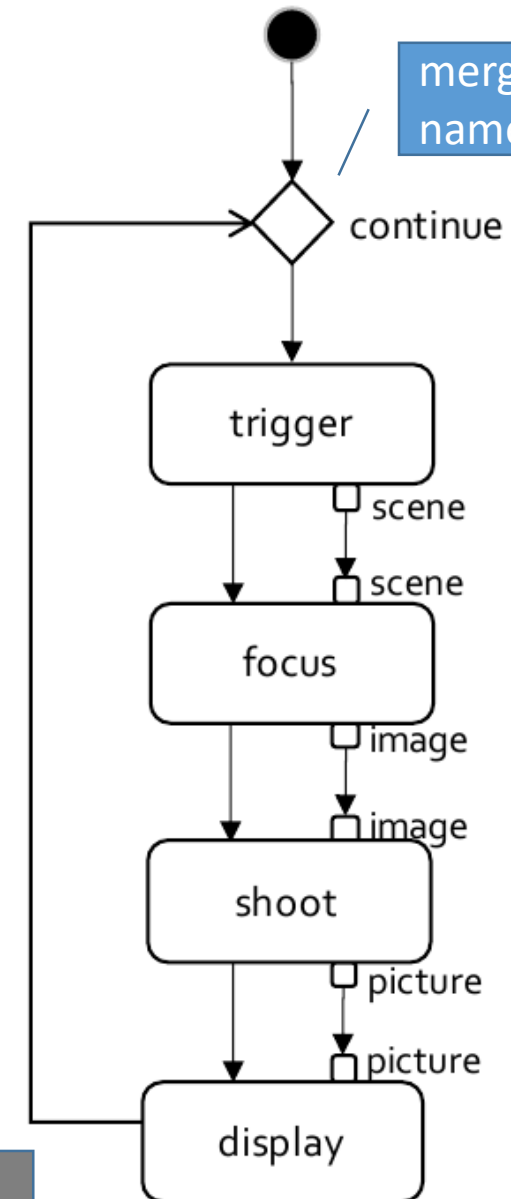
if <guard expr> **then** <action>

- Asserts that second action follows first only if a guard condition is true

SysML v2 – merge nodes / loops

```
action takePicture : TakePicture {  
  first start;  
  then merge continue;  
  then action trigger {  
    out item scene : Scene;  
  }  
  flow from trigger.scene to focus.scene;  
  then action focus : Focus {  
    in item scene;  
    out item image;  
  }  
  flow from focus.image to shoot.image;  
  then action shoot : Shoot {  
    in item image ;  
    out item picture;  
  }  
  flow from shoot.picture to display.picture;  
  then action display : Display {  
    in item picture;  
  }  
  then continue;  
}
```

Wait for start to complete



SysML v2 – merge nodes / loops

while takePicture >= 0.05 **action** takePicture {
 ...
}

Exit, if condition becomes false

or

loop action takePicture {
 ...
} **until** battery.charge < 0.05

Exit, if condition becomes true

17. Control/Control Structure Examples

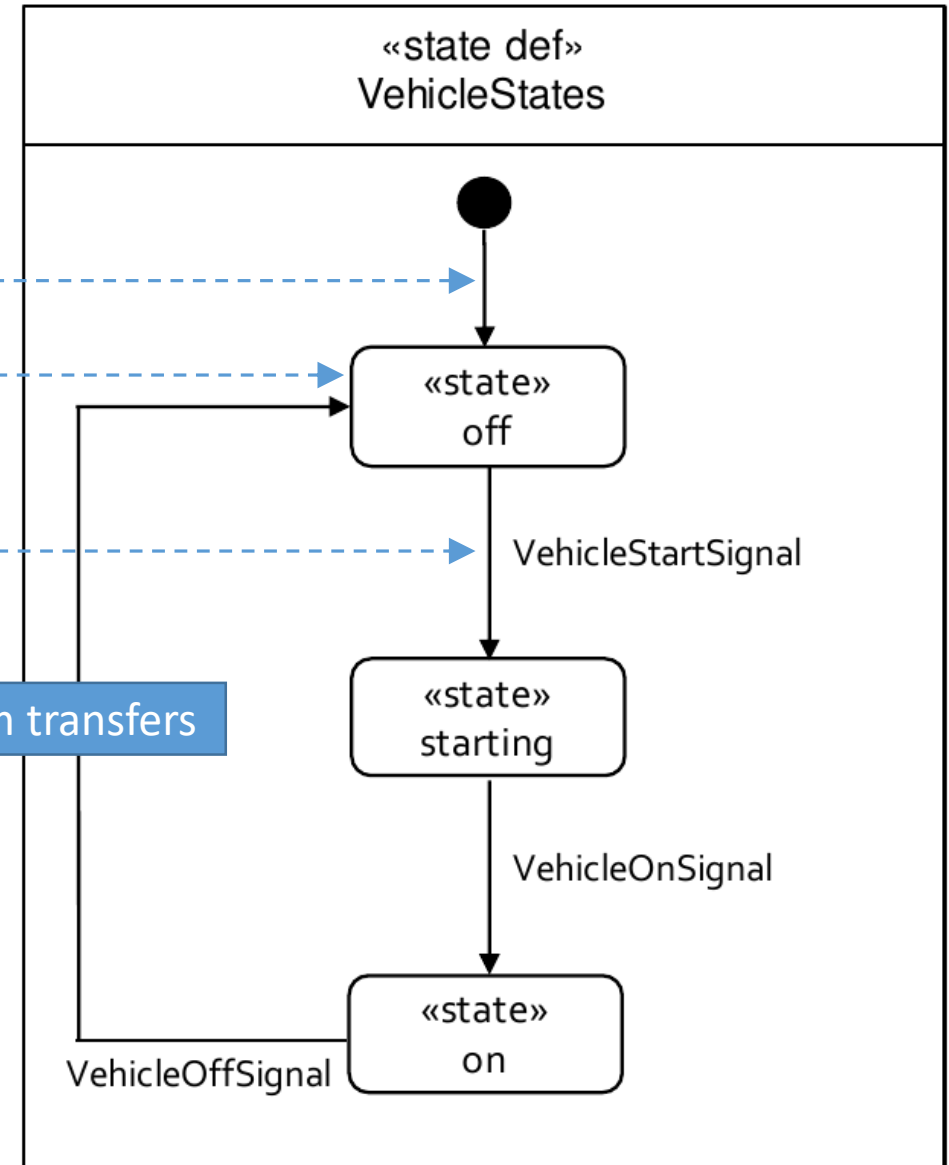
Beyond UML
Control structures as in programming
languages

States

```
package 'State Definition Example-2' {  
  
  attribute def VehicleStartSignal;  
  attribute def VehicleOnSignal;  
  attribute def VehicleOffSignal;  
  
  state def VehicleStates {  
    entry; then off; -----  
  
    state off; -----  
    accept VehicleStartSignal -----  
      then starting;  
  
    state starting;  
    accept VehicleOnSignal  
      then on;  
  
    state on;  
    accept VehicleOffSignal  
      then off;  
  }  
}
```

initial state after entry is "off"

fire on *acceptance* of item transfers



Nested and concurrent states

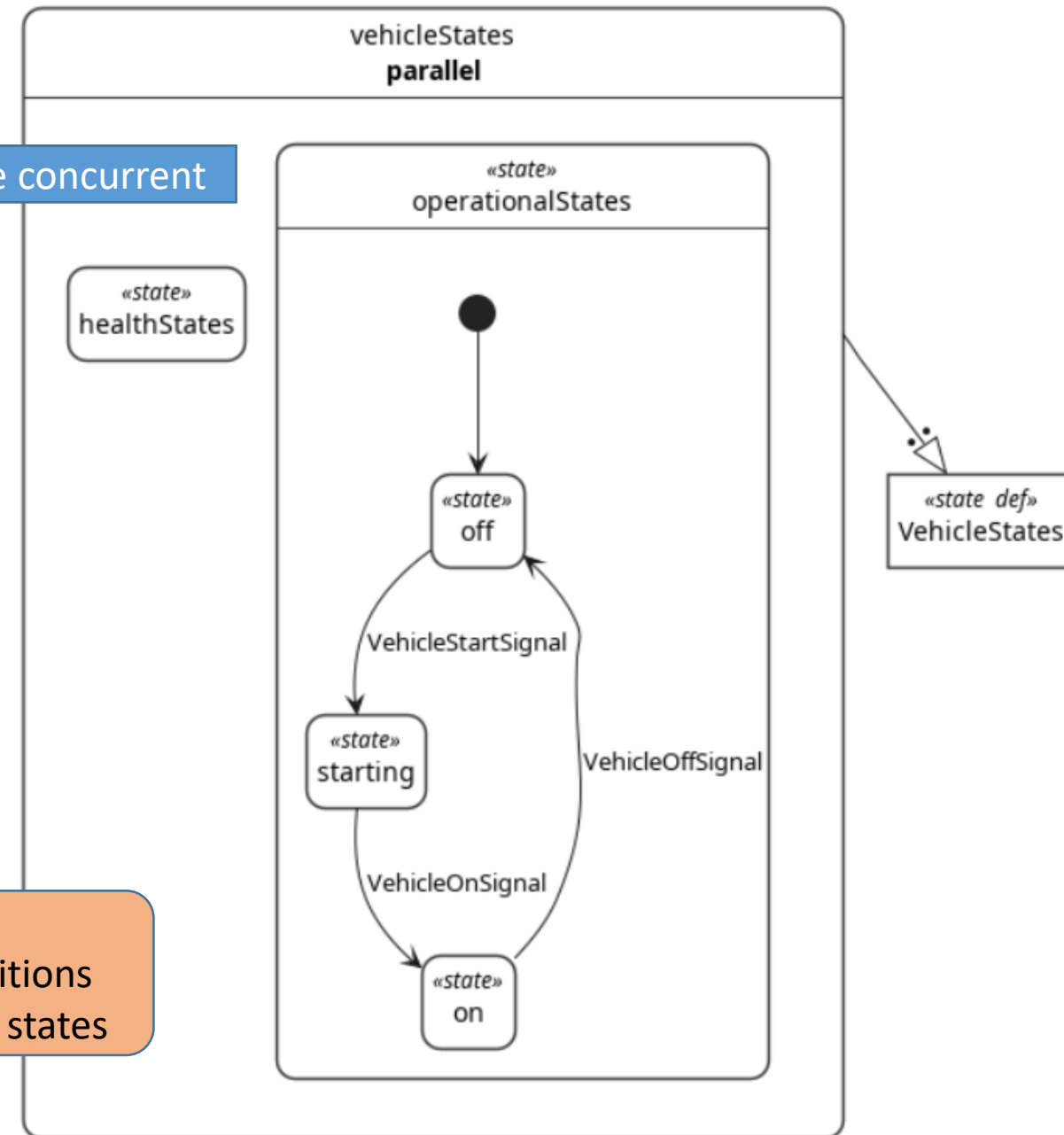
```
state def VehicleStates;
```

parallel state \Rightarrow nested states are concurrent

```
state vehicleStates : VehicleStates parallel {  
  state operationalStates {  
    entry; then off;  
  
    state off;  
    accept VehicleStartSignal then starting;  
  
    state starting;  
    accept VehicleOnSignal then on;  
  
    state on;  
    accept VehicleOffSignal then off;  
  }  
  
  state healthStates {  
    // ...  
  }  
}
```

CAVEAT

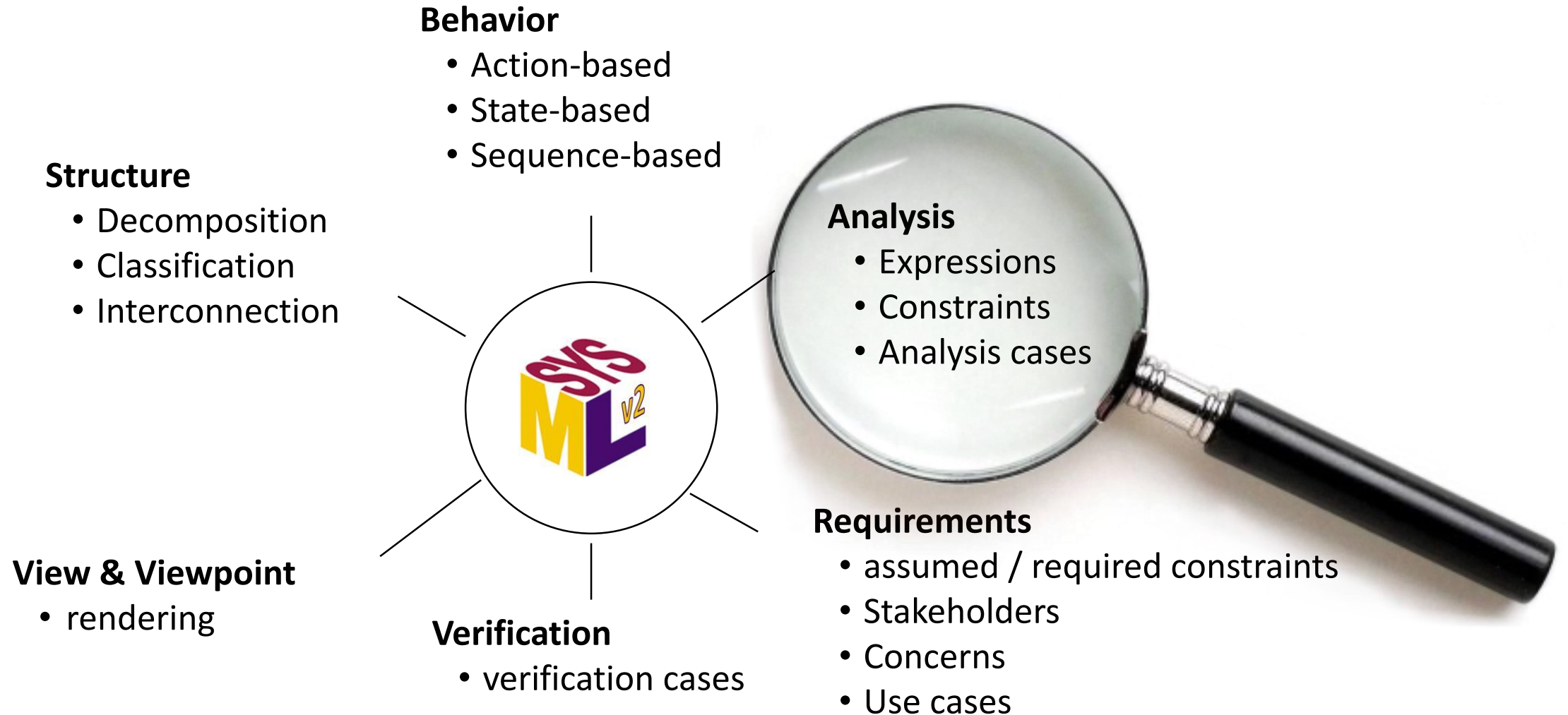
As in UML, no transitions between concurrent states



UML - SysML v2 action terminology

UML / SysML v1	SysML v2
activity / action (parameter / pin)	action definition / action usage (directed usage)
control flow	succession
object flow	flow connection usage
state machine / state	state definition / state usage
Transition / trigger	attribute definition (signal), accept

SysML v2 – Expressions and Constraints



SysML v2 – Calculations definitions (expressions)

Reusable, *parameterized* expression

directed features are parameters (as in actions), defaults to “in”

```
calc def Power { in whlpwr : PowerValue; in Cd : Real; in Cf : Real; in tm : MassValue; in v : SpeedValue;  
  attribute drag = Cd * v;  
  attribute friction = Cf * tm * v;  
  
  return : PowerValue = whlpwr - drag - friction;  
}
```

```
calc def Acceleration { in tp: PowerValue; in tm : MassValue; in v : SpeedValue;  
  return : AccelerationValue = tp / (tm * v);  
}
```

```
calc def Velocity { in dt : TimeValue; in v0 : SpeedValue; in a : AccelerationValue;  
  return : SpeedValue = v0 + a * dt;  
}
```

```
calc def Position { in dt : TimeValue; in x0 : LengthValue; in v : SpeedValue;  
  return : LengthValue = x0 + v * dt;  
}
```

Beyond UML

Calculations based on KerML

Calculation Usage

```
action straightLineDynamics {  
  in delta_t : TimeValue;  
  in v_in : SpeedValue;  
  in x_in : LengthValue;  
  out v_out : SpeedValue = vel.v;  
  out x_out : LengthValue = pos.x;  
  
  calc acc : Acceleration {  
    in tp = Power(wheelPower, C_d, C_f, mass, v_in);  
    in tm = mass;  
    in v = v_in;  
    return a;  
  }  
}
```


Constraint definition

31. Constraints/Constraints Example-1

```
constraint def MassConstraint {  
  in partMasses : MassValue[0..*];  
  in massLimit : MassValue;  
  
  sum(partMasses) <= massLimit  
}
```

Convention: usage with lowerCase, Definition with upper case

```
part def Vehicle {  
  /  
  constraint massConstraint : MassConstraint {  
    in partMasses = (chassisMass, engine.mass, transmission.mass);  
    in massLimit = 2500[kg];  
  }  
  
  attribute chassisMass : MassValue;  
  
  part engine : Engine {  
    attribute mass : MassValue;  
  }  
  
  part transmission : Engine {  
    attribute mass : MassValue;  
  }  
}
```

Beyond UML

Own constraint language
(not a separate language as OCL)

Requirements

32. Requirements/Requirement Definitions

```
package 'Requirement Definitions' {  
  private import ISQ::*;  
  private import SI::*;  
  
  requirement def MassLimitationRequirement {  
    doc /* The actual mass shall be less than or equal to the required mass. */  
  
    attribute massActual: MassValue;  
    attribute massReqd: MassValue;  
  
    require constraint { massActual <= massReqd }  
  }  
  
  part def Vehicle {  
    attribute dryMass: MassValue;  
    attribute fuelMass: MassValue;  
    attribute fuelFullMass: MassValue;  
  }  
}
```

Beyond UML

Can evaluate values within constraints