

Lab 4 Design Document

Group 2

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Introduction

Interprocess communication is essential for a workstation that supports multiple processes. The operating system must provide a tool for processes or managers to communicate with each other. This communication can be used for synchronization, multi-threaded programming, and information sharing.

Design Decisions

Each manager will be essentially a queue, using our queue manager. Each message queue will be length five. This small size will make things easier to test. Also, it should be a reasonable number in a system where we can only have up to 20 processes. It will be easy to change in the future on a per-manager basis if we decide it is too large or too small.

We will have to modify our queue manager to handle messages, rather than just `process_control_block`. This will be done by copying the `queuemanager` and modifying it to use message structs instead of process control block structs.

The message will be a struct, making it easier to change the structure of the message in the future. For now, it will contain a variable noting which manager was the source manager, and a char array of size 256 for the message, as well as the necessary variables to be in a queue (`prev` and `next`).

Each message queue will be referenced by an integer from 0 to 9. This may later be adapted to use an enum once we know what exactly they are, which would be exactly the same anyway. This method of reference will be used both internally and in the commands to the test manager.

Flow Charts/State Diagrams

IPC Message Flow Chart

This flow chart describes the flow of events a message will experience in our IPC Manager. A send command will signify when a message is to be created. During the message creation if any errors are encountered (such as a malformed message), the manager will

discard the message and return the error accordingly. If no errors arise during the message creation process the message is enqueued into the corresponding destination queue. Upon a receive command being issued for the destination queue, the message will be dequeued from that queue. If there are no messages in the queue, that is an error. In the test manager, the message will be printed to the terminal.

IPC State Diagram

This state diagram describes the states and transition that are related to a message within our IPC Manager. There are three possible states that a message can be in, “New,” “Enqueued,” and “Consumed/Deleted.”

When a message is first created, it is in the “New” state. This means that the IPC manager is in the process of allocating space for the message and checking it for errors. If there are any errors, it is deleted, so it goes to the “Consumed/Deleted” state. Possible errors could be malformed message, bad source or destination, or if the IPC queue that the message is to go in is full.

If there are no errors, it is enqueued in the proper queue. It remains here until it reaches the top of the queue and the destination receives it. When this happens, it is consumed, and the space used by the message is reallocated. As far as the IPC manager is concerned, consumed and terminated are equivalent, because in both cases, the memory that was used for the message is reallocated, and the IPC manager is no longer aware of the message itself. Hence, they are the same state.

In other words, when a message is received, we consider this to be the end of the message’s life. If the same message is sent again somewhere else, we consider that to be the creation of a new (identical) message.

In the “New” state, little can be asserted about the message, other than that memory has been allocated for it (we do not enter the diagram at all if there is no memory available). In the “Enqueued” state, it can be asserted that a message has no errors, including any errors about source and destination. Furthermore, the message is in a queue. In the “Consumed/Deleted” state, we can assert that the memory for a message is free again, and it cannot be used further.