



## 2 Flux linkage

$$\begin{aligned} \lambda_a &= L \cdot i_a + N \phi_m \cos(\theta) \\ \lambda_b &= L \cdot i_b + N \phi_m \sin(\theta) \end{aligned}$$

$$\begin{bmatrix} e_a \\ e_b \end{bmatrix} = \frac{d}{dt} \begin{bmatrix} \lambda_a \\ \lambda_b \end{bmatrix}$$

$$4 \quad W_{\text{stored}} = \frac{1}{2} \begin{bmatrix} i_a & i_b \end{bmatrix} \cdot \begin{bmatrix} \lambda_a \\ \lambda_b \end{bmatrix} \quad \text{so } \tau = -\frac{d}{d\theta}(W_{\text{stored}})$$

$$\tau = \frac{1}{2} (-i_a N \phi_m \sin(\theta) + i_b N \phi_m \cos(\theta))$$

## 5 Equations

$$\begin{bmatrix} V_a & V_b \end{bmatrix}' = \begin{bmatrix} R i_a + L \frac{di_a}{dt} \end{bmatrix} - N \phi_m \sin(\theta) \frac{d(\theta)}{dt} ; \begin{bmatrix} R i_b + L \frac{di_b}{dt} \end{bmatrix} + N \phi_m \cos(\theta) \frac{d(\theta)}{dt}$$

$$T_{\text{or}} = J \frac{d^2\theta}{dt^2} + T_{\text{load}}$$

6 Block diagram can be drawn from above equations