## Andrew S. Morgan

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## **EDUCATION**

YALE UNIVERSITY – NEW HAVEN, CT (STARTED AUG, 2017)

- Pursuing DOCTOR OF PHILOSOPHY DEGREE IN ROBOTICS (DEPARTMENT OF MECHANICAL ENGINEERING AND MATERIALS SCIENCE)
- Cumulative GPA: 4.0/4.0

YOUNGSTOWN STATE UNIVERSITY - YOUNGSTOWN, OH (COMPLETED MAY, 2017)

- Received Two Honors Degrees: BEng in Computer Engineering; BS in Computer Science
- Cumulative GPA: 3.98/4.0

#### **WORK EXPERIENCE**

3D PRINTING OUTREACH INSTRUCTOR FOR YOUNGSTOWN BUSINESS INCUBATOR. YOUNGSTOWN, OH (08/16 - 07/17: variable summer weeks)

- Develop a curriculum for High School students to learn the business side of 3D Printing
- Inform students of the capabilities of a rapidly growing technology additive manufacturing
- **RELATED SKILLS:** 3D Printing, Teaching, Plan Management, Public Speaking

AUBURN REU ON SMART UAVS. Auburn University. Auburn, AL

(05/16 - 07/16; summer semester)

- Develop new technologies associated with "see and avoid" strategies and recovery systems
- Worked towards two publishable papers and presentations for later representation of my work
- RELATED SKILLS: Computer Vision, C++, Embedded Systems, OpenCV, Academic Writing, Project Coordination

HONORS ENGINEERING TEACHING ASSISTANT / ENGINEERING LAB MANAGER. Youngstown, OH

(07/14 - 06/16)

- Aid students in the understand of fundamentals learned throughout their coursework
- Develop student mentor relationships with incoming freshman honor students
- RELATED SKILLS: Microsoft Products, 3D Printing, Leadership, MATLAB, Solid Modeling, Project Coordination

TEST ENGINEERING CO-OPERATIVE. ABB Inc. Wickliffe, OH

(05/15 - 08/15; summer semester)

- Test ABB Power Systems components and modules for corresponding tasks
- Organize and coordinate co-op fundraising WE CARE charity event
- **RELATED SKILLS:** Microsoft Products, C, C++, Cisco Networking, Communications, Event Planning

## AWARDS/HONORS

Youngstown State University Scholars Program (full 4-year academic scholarship based on outstanding academic achievement)

Robert E. Apfel Graduate Fellowship 2018 (one-year) (08/01/2017)

National Science Foundation GRFP Honorable Mention 2017 (03/17/2017)

Tau Beta Pi Graduate Fellow 2017 and Tau Beta Pi Scholar 2016 (04/07/2016)

Barry M. Goldwater Scholar 2016 (03/31/2016)(07/13/2016)

Ohio House of Representatives & Ohio Senate Recognition Awards

## **PUBLICATIONS**

## Refereed Journal Articles (J), Refereed Conference Papers (C), Magazine Articles (M), and Provisional Patents (P):

- J1. Meyers, K., Morgan, A. S., and Conner, B. "Using 3D Printing to Understand the Design Iteration Process". Global Journal of Engineering Education, Vol. 18, Issue 1, 2016.
- J2. Morgan, A. S., Jones, Z., Chapman, R., and Biaz, S., "An Unmanned Aircraft "See and Avoid" Algorithm Development Platform using OpenGL and OpenCV", Journal of Computing Sciences in Colleges, Consortium for Computing in Colleges, Vol. 33, No. 2, pp. 229-236, 2017.
- J3. Hang, K., Morgan, A. S., and Dollar, A. M., "Pre-Grasp Sliding Manipulation Planning of Thing Objects Using Soft, Compliant, or Underactuated Hands", IEEE Robotics and Automation Letters, 2019. (In Review)
- J4. Sintov, A., Morgan, A. S., Kimmel, A., Dollar, A. M., Bekris, K. E., and Boularias, A., "Learning the Dynamics of an Underactuated Adaptive Hand", IEEE Robotics and Automation Letters, 2019. (In Review)
- J5. Spiers, A., Morgan, A. S., Srinivasan, K., Calli, B., and Dollar, A. M., "Using Variable-Friction Finger Surfaces and Proprioceptive Sensing to Classify Objects during Robotic Within-Hand Manipulation", Transactions on Robotics, 2019. (In Review)
- C1. Morgan, A. S., Sharif, B., and Crosby, M. "Understanding a Novice Programmer's Progression of Reading and Summarizing Source Code". Koli Workshop 2014. Koli, Finland. 2014.
- C2. Meyers, K., Morgan, A. S., and Conner, B. "3D Printing in a First-Year Engineering Design Project". American Society for Engineering Education National Conference, New Orleans, 2016.
- C3. Calli, B., Srinivasan, K., Morgan, A. S., and Dollar, A. M., "Learning Modes of Within-hand Manipulation." IEEE International Conference on Robotics and Automation (ICRA), Brisbane, Australia, 2018. Nominated for best paper in manipulation.
- C4. Morgan, A. S., Bircher, W. G., Calli, B., and Dollar, A. M., "Learning From Transferable Mechanics Models: Generalizable Online Mode Detection in Underactuated Dexterous Manipulation", IEEE International Conference on Robotics and Automation (ICRA), 2019. (In Review)
- C5. Bircher, W. G., Morgan, A. S., Hang, K., and Dollar, A. M., "Energy Gradient-Based Graphs for Planning Within-Hand Caging Manipulation", IEEE International Conference on Robotics and Automation (ICRA), 2019. (In Review)
- M1. Morgan, A. S., Chapman, R., and Biaz, S., "DIY Drone Recovery Parachute", Make Magazine, Vol. 61, Feb/March Issue, pp. 42., 2018.
- P1. Morgan, A.S., and Kreatsoulas, N., Provisional Patent completed in April 2015, "IV Locking Device", Patent Application Number: 62/146,434.