

Assembly Coding 2024

introduzione al vostro prossimo hobby preferito



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who we are



Sandro "guly" Zaccarini

fix if broken, break if works

(wine|food|security|martial) artist

<https://github.com/theguly>



Diego "freshness" Barzon

somewhat miscellaneous useful computer related task for making the ends meet

useless passion-leaded computer stuff to fill the free time holes

<https://github.com/freshness79>

1-minute intro to assembly

- ❖ not a language, but a set of instructions
- ❖ such instructions set is CPU dependent (eg: arm != x86)
- ❖ closest to hardware, if you don't want to code with binary numbers
- ❖ no (or very little) abstraction

1-minute intro to assembly - data

- ❖ registers
 - ❖ accumulator, counter, general, instruction pointer, ...
 - ❖ flags
 - ❖ speed/size
- ❖ memory:
 - ❖ code: not read-only ;)
 - ❖ data
 - ❖ stack versus heap

C source - linear disassembly

```
// gcc -m32 -g hello.c -o hello
#include <stdio.h>
int main () {
    printf("Hello World!\n");
    return 0;
}
```

00401146 int32_t main(int32_t argc, char** argv, char** envp)			
00401146	55	push	rbp {__saved_rbp}
00401147	4889e5	mov	rbp, rsp {__saved_rbp}
0040114a	bf04204000	mov	edi, 0x402004 {"Hello World!"}
0040114f	b800000000	mov	eax, 0x0
00401154	e8d7ffff	call	printf
00401159	b800000000	mov	eax, 0x0
0040115e	5d	pop	rbp {__saved_rbp}
0040115f	c3	retn	{__return_addr}

use cases

- ❖ pwn/exploit
- ❖ reverse engineering
- ❖ high performances
- ❖ embedded/very low resources
- ❖ very specific tasks

use case > pwn

- ❖ when you wear a black hat you usually have very low resources
- ❖ custom assembly routines are often the only way

use case > pwn > shellcode

08049000	6a0b
08049002	58
08049003	682f736800
08049008	682f62696e
0804900d	89e3
0804900f	cd80
08049011	??

```
push    0xb {var_4}
pop     eax {var_4} {0xb}
push    0x68732f {var_4}
push    0x6e69622f {var_8}
mov    ebx, esp {var_8}
int    0x80
??
```

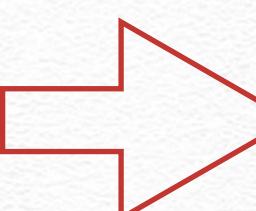
hs/
nib/

/bin/sh

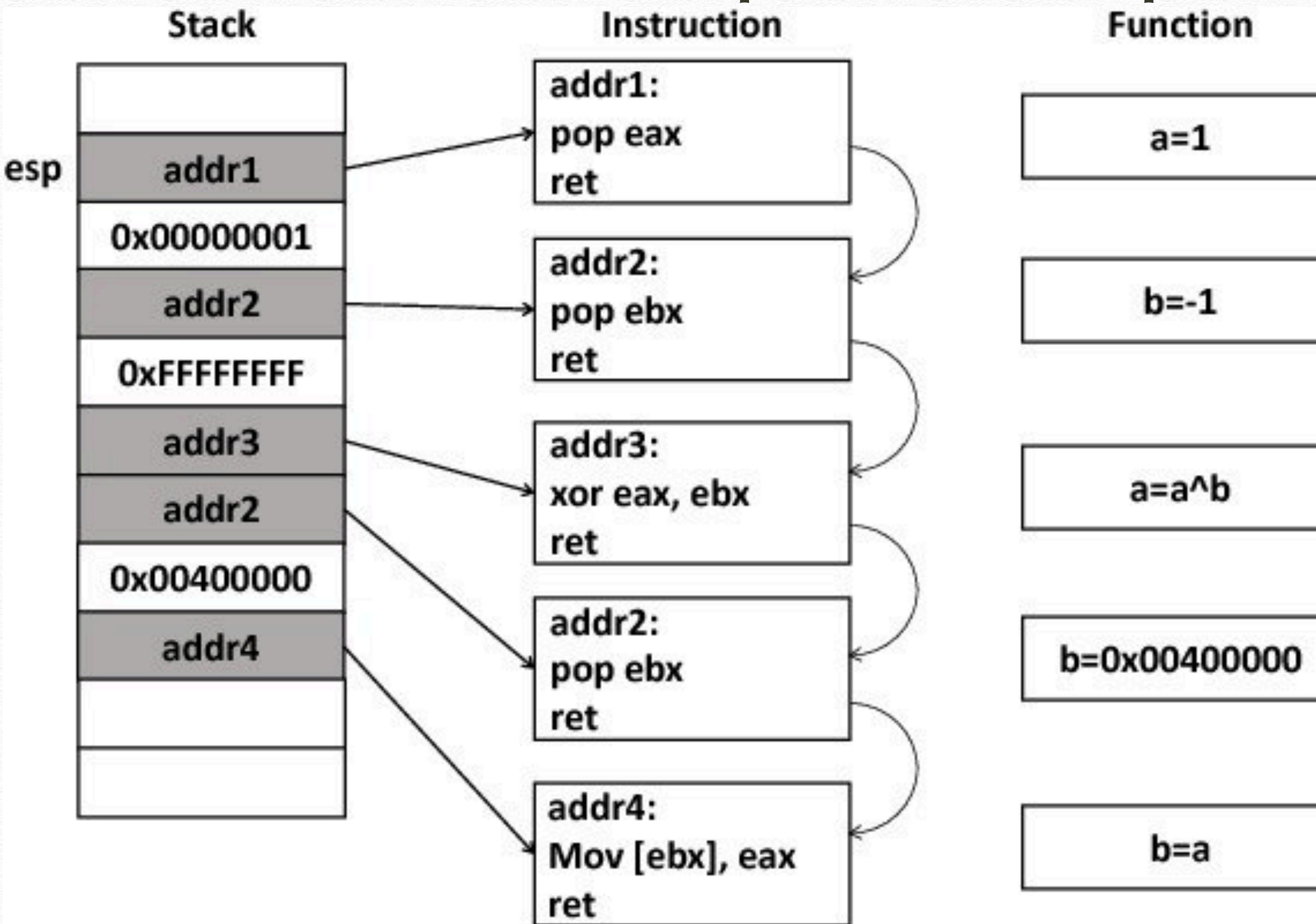
use case > pwn > shellcode

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```
push    0xb {var_4}
pop     eax {var_4} {0xb}
push    0x68732f {var_4}
push    0x6e69622f {var_8}
mov    ebx, esp {var_8}
int    0x80
```

syscall(0xb, *ptr)  execve("/bin/sh")

use case > pwn > rop



use case > pwn > rop

```
$ ropper -f target --nocolor
[INFO] Load gadgets from cache
[LOAD] loading... 100%
[LOAD] removing double gadgets... 100%
0x080484eb: pop ebp; ret;
0x080484e8: pop ebx; pop esi; pop edi; pop ebp; ret;
0x080482ed: pop ebx; ret;
0x080484ea: pop edi; pop ebp; ret;
0x080484e9: pop esi; pop edi; pop ebp; ret;
0x08048484: popal; cld; ret;
```

use case > pwn > rop

```
1 # size 0x21000 in ecx
2 buf = p32(0x080484bd)          # pop ecx; pop edx; ret
3 buf+= p32(0x01031101)
4 buf+= p32(0x01010101)
5 buf+= p32(0x08048332)          # sub ecx, edx; not eax; and eax, ecx; ret;
6
7 # 7 in edx
8 buf+= p32(0x0804831d)          # xor eax, eax; ret;
9 buf+= p32(0x08048330)          # xchg eax, edx; ret;
10 buf+= p32(0x080482a4) * 7     # inc edx; ret;
11
12 # stack in ebx
13 buf+= p32(0x080482ed) + stack_addr # pop ebx; ret;
14 buf+= p32(0x080482b6)          # dec ebx; ret;
15
16 buf+= mprotect_addr           # mprotect(addr, len, permissions)
17
```

use case > reversing

- ❖ patching/fix
- ❖ malware/ransomware decrypt0r
- ❖ undocumented/undocumented features
- ❖ decompiling

use case > reversing > patching

- ❖ recompile is not an always option...
- ❖ ...especially if source code is not available
- ❖ by mastering assembly, you *could* replace small pieces of a binary
- ❖ "everything is open source if you can reverse engineer"

```
mov     eax, dword [rbp-0x4 {var_c_1}]
movsxd rdx, eax
mov     rax, qword [rbp-0x10 {var_18}]
add    rax, rdx
movzx  eax, byte [rax]
movsx  eax, al
lea    ecx, [rax-0x1]
mov    rax, qword [rbp-0x20 {var_28}]
add    rax, 0x8
mov    rdx, qword [rax]
mov    eax, dword [rbp-0x4 {var_c_1}]
cdqe
add    rax, rdx
movzx  eax, byte [rax]
movsx  eax, al
cmp    ecx, eax
je    0x4011c4
```

```
add    dword [rbp-0x4 {var_c_1}], 0x1
```

```
mov    edi, 0x402020 {"Invalid license"}
call   puts
mov    eax, 0x1
jmp    0x401205
```

```
mov    edi, 0x402030 {"License validated"}
call   puts
mov    eax, 0x0
```

use case > reversing > ransomware

- ❖ <https://decoded.avast.io/threatresearch/decrypted-akira-ransomware/>
- ❖ <https://github.com/srlabs/black-basta-buster>

use case > reversing > ReactOS

- ❖ "Imagine running your favorite Windows applications and drivers in an open-source environment you can trust"
- ❖ a bunch of people disassembly Windows DLL/Drivers and documents what they understand

use case > reversing > OpenDUNE

- ❖ take an abandonware
- ❖ write a decompiler
- ❖ decompile runtime
- ❖ conquer arrakis



source: <https://github.com/OpenDUNE/OpenDUNE/issues/228>

use case > reversing > OpenDUNE

- ❖ take an abandonware
- ❖ write a decompiler
- ❖ decompile runtime
- ❖ conquer arrakis

```
7  /**
8  * Decompiled function f__0070_0040_0005_1DBE()
9  *
10 * @name f__0070_0040_0005_1DBE
11 * @implements 0070:0040:0005:1DBE ()
12 *
13 * Called From: 0000:0000:0000:0000
14 * Called From: 2756:0623:0006:2DB2
15 */
16 void f__0070_0040_0005_1DBE()
17 {
18     emu_syscall(0x8);
19
20     /* Return from this function */
21     emu_pop(&emu_ip);
22     emu_pop(&emu_cs);
23     emu_popf();
24
25 }
```

use case > high performances

- ❖ especially when hardware upgrade is not an option, asm snippets can still be faster or smaller than compilers made code
- ❖ gaming console are a good example: on a specific platform the hardware can't be improved

use case > high performances > microcontroller

- ❖ when resources are limited, compiler may not be clever enough to fit all needed code
- ❖ microcontrollers are literally everywhere, and they are often slow and small in terms of memory

use case > high performances > AoE



Think Assembly code is useless to learn?
Age of Empires I+II used ~13,000 lines of x86 32-bit assembly code.
"The use of assembly in the drawing core resulting in a ~10x sprite"

source: <https://twitter.com/lauriewired/status/1744063043716399290>
original: <https://www.reddit.com/r/aoe2/comments/18ysttu/>

use case > high performances > RCT



Sawyer wrote 99% of the code for RollerCoaster Tycoon in assembly code for the Microsoft Macro Assembler, with the remaining one percent written in C.

source: [https://en.wikipedia.org/wiki/RollerCoaster_Tycoon_\(video_game\)](https://en.wikipedia.org/wiki/RollerCoaster_Tycoon_(video_game))

use case > high performances > KolibriOS

"KolibriOS is a tiny yet incredibly powerful and fast operating system. This power requires only a few megabyte disk space and 8MB of RAM to run. Kolibri features a rich set of applications that include word processor, image viewer, graphical editor, web browser and well over 30 exciting games. Full FAT12/16/32 support is implemented, as well as read-only support for NTFS, ISO9660 and Ext2/3/4. Drivers are written for popular sound, network and graphics cards. [CUT] This speed is achieved since the core parts of KolibriOS (kernel and drivers) are written entirely in FASM assembly language!"

use case > specific tasks

- ❖ specific routines
- ❖ hardware requirements

use case > specific tasks > C vs ASM

```
90 // Test C function
91 printf("Starting C optimized function:\n");
92     for(int i=0;i<64000;i++)
93         test2[i] = 0;
94 c_start = clock();
95 for(long i=0;i<50000;i++) {
96     unsigned int data;
97     ((unsigned char *)&data)[0] = 0;
98     ((unsigned char *)&data)[1] = 64;
99     ((unsigned char *)&data)[2] = 128;
100    ((unsigned char *)&data)[3] = 192;
101    for(int i=0;i<16000;i++) {
102        ((char *)&data)[0] += 1;
103        ((char *)&data)[1] += 1;
104        ((char *)&data)[2] += 1;
105        ((char *)&data)[3] += 1;
106        ((unsigned int *)test2)[i] = data;
107    }
108 }
109 c_end = clock();
110 total = (float)((c_end - c_start)/50000);
111 printf("Done - Elapsed: %5.1f\n",total);
```

```
1 BITS 64
2 ; RDI has "test" 64 bit buffer pointer (standard arg passing)
3 ; We need to save only RBX, which must not be clobbered
4 ; across function calls (RBX, RBP, R12-R15)
5
6 push rbx
7 mov dx, 0xc080
8 mov ebx, 0x4000
9 mov ecx, 16000
10 mainloop:
11 add dl,1
12 add dh,1
13 mov eax,edx
14 shl eax,16
15 add bl,1
16 add bh,1
17 add eax,ebx
18 stosd
19 dec ecx
20 jne mainloop
21 pop rbx
22 ret
```

46seconds vs 31seconds => ASM is 32% faster

use case > specific tasks > CPU

- ❖ all modern OS running on Intel CPUs executes the so called "Protected Mode Jump"
- ❖ other platforms require similar operation when booting
- ❖ those ops are mostly carried out by small pieces of assembly code

use case > specific tasks > emulator

- ❖ Z80 emulator written in ARM assembly for Nintendo DS:

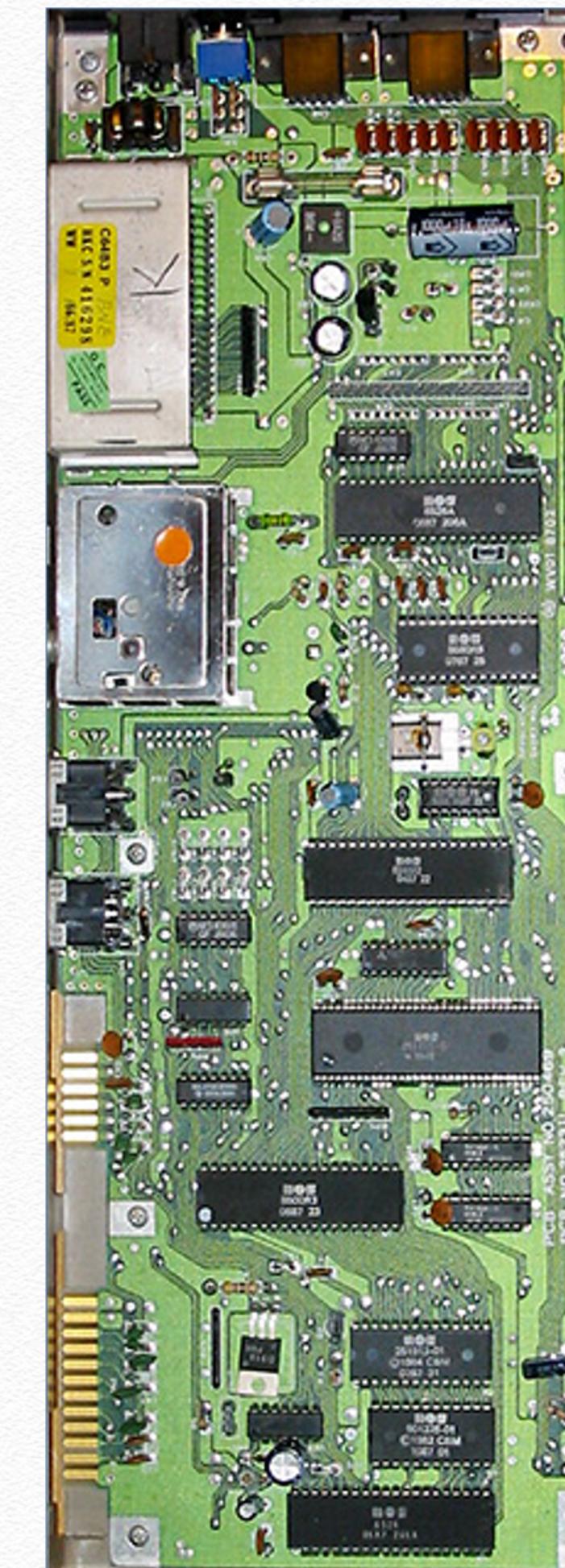
<https://github.com/FluBBaOfWard/ARMZ80/blob/main/ARMZ80.s>

demo time

- ❖ demo1: abuse instruction behavior to overcome hardware limits
- ❖ demo2: playable arkanoid in 506bytes

demo > platform

- ❖ CPU: 6510 (6502)
 - ❖ ~1Mhz
 - ❖ 8bit
 - ❖ 56(151) instructions
- ❖ RAM 64Kb (a bit more...)
- ❖ Video: 320x200, 16 colors

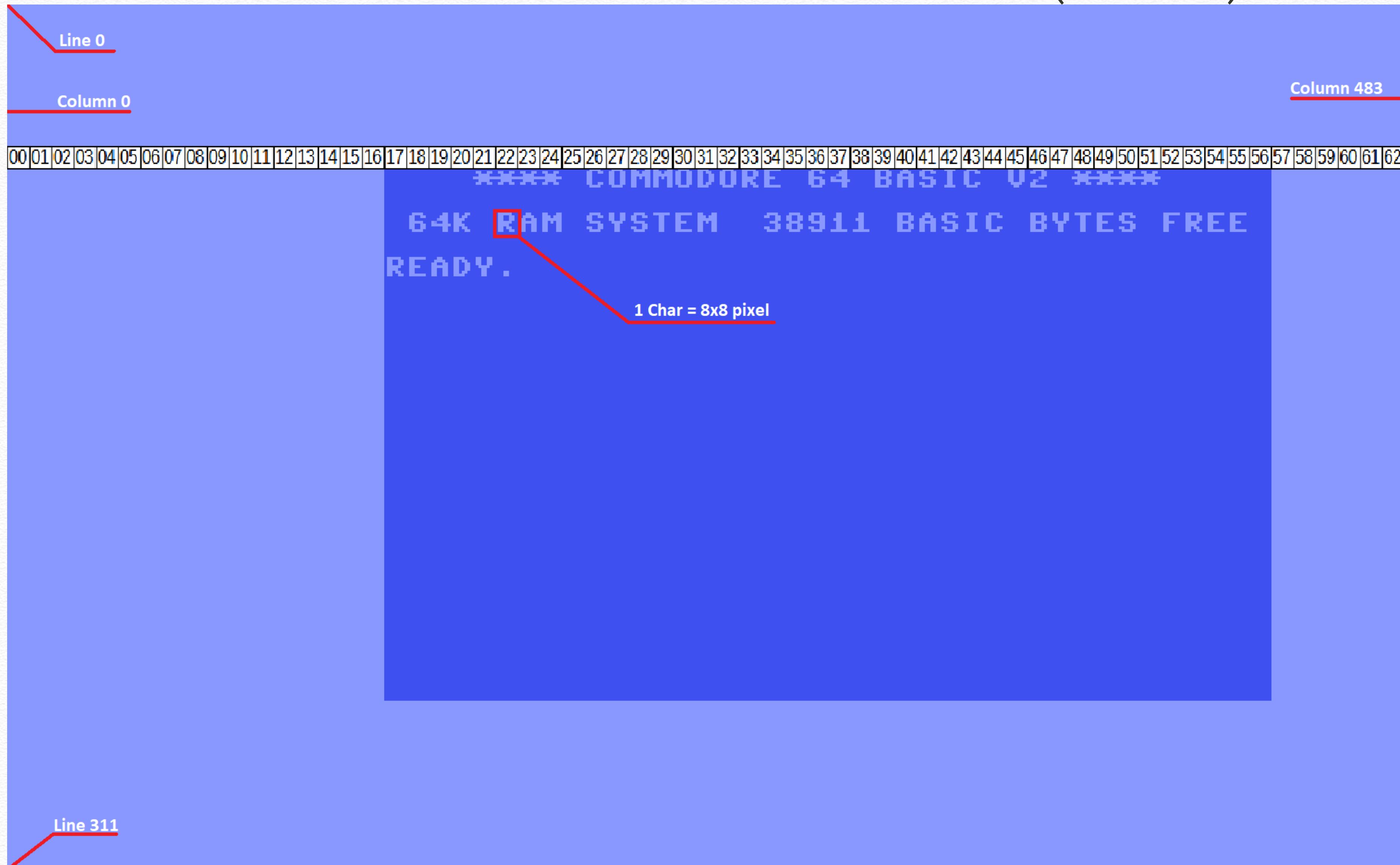


demo > instruction timings

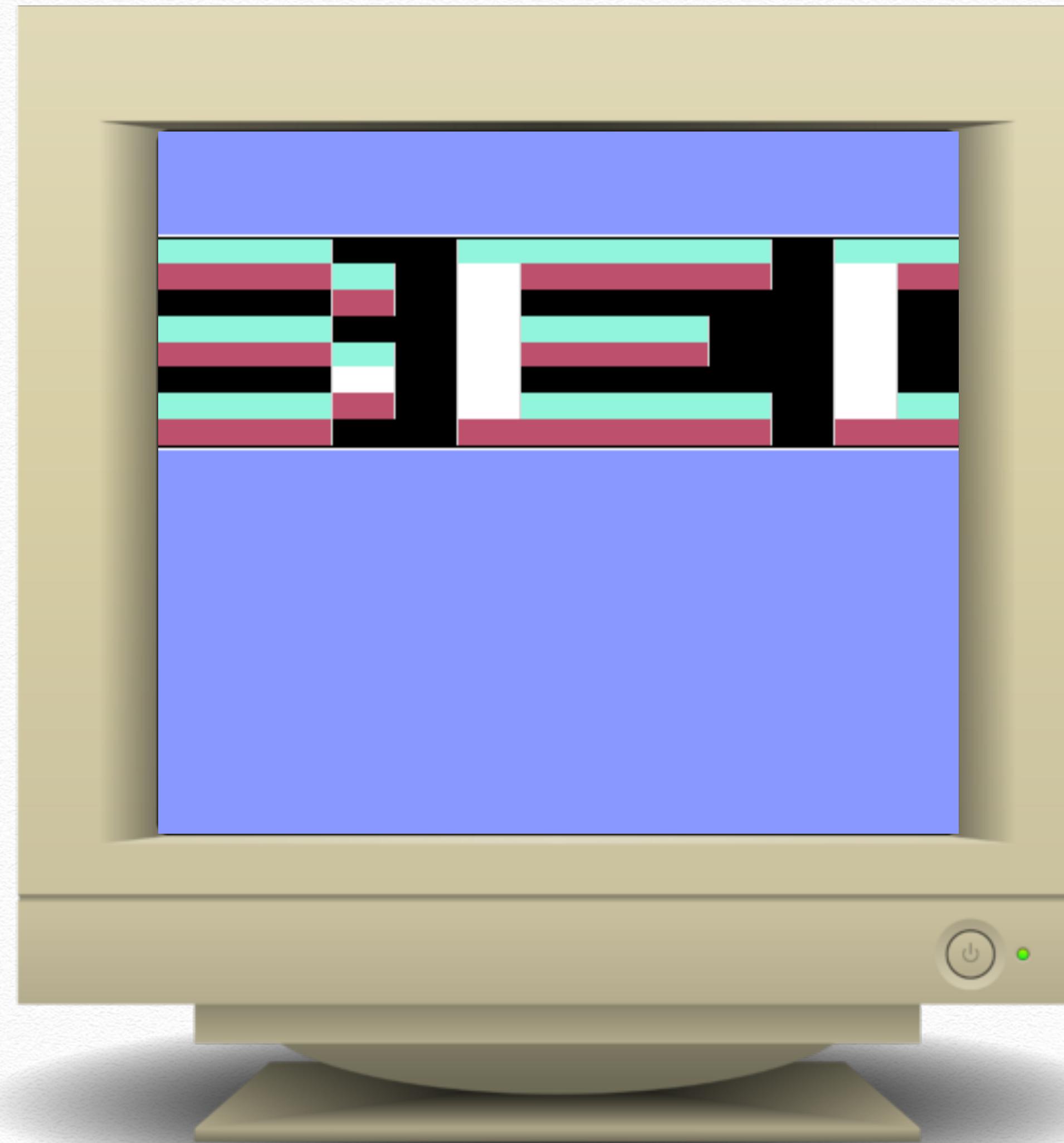
Instruction cycles: 2 - 8

2. NOP, LDA #imm, CLC, BEQ (*)
3. LDA zp, BIT zp, BEQ (*)
4. LDA abs, STA abs, LDA abs,x, BEQ (*)
5. INC zp, STA abs,x, LDA abs,x (**)
6. INC abs, DEC abs
7. INC abs,x, DEC abs,x
8. ISC (zp),y, DCP (zp),y

demo > video details (PAL)



demo > scroller



demo > synchronization loop

Always cycle 3 to 10

62 cycles, a bit less
than a line

```
42 // Synchronize timer to raster (countdown 6 => 0)
43 synctimer:
44     lda #$00
45     sta $dc0e          // Stop timer
46     lda #$08
47     sta $dc04
48     lda #$00          // Set timer to 9 cycles
49     sta $dc05
50     ldx #$ff          // Wait for lower part of the screen
51 waitlowerscreen:
52     cpx $d012          // 4
53     bne waitlowerscreen // 3/2 -> Max jitter 7 cycles
54
55 // Sync loop: 62 cycles
56 waitline:
57     ldy #10          // 2
58 waitcycles:
59     dey              // 2      Loop: (5*10)-1 = 49
60     bne waitcycles   // 3/2
61     lda #$11          // 2
62     inx              // 2
63     cpx $d012          // 4
64     beq waitline      // 3/2
65     // Next instruction on cycle 3
66
67     nop          // 2
68     nop          // 2
69     nop          // 2
70     sta $dc0e      // 4 Start timer
71     rts
```

demo > synced loop

```
75 // -> Explicit 63 cycles block with different branches
76 .align $0100
77 < syncedblock:
78     ldx #$00
79
80 < openLoop:
81     cpx upperline    // 3
82
83     bne !+          // 2/3 - 17
84     nop             // 2 - If upper line reached
85     nop             // 2
86     nop             // 2
87     lda #$06         // 2 - Use color 06 (Blue)
88     bne bgsetColor  // 3
89 < !:
90     cpx lowerline   // 3
91     bne !+          // 2/3
92     lda #$0e         // 2 - If lower line reached
93     bne bgsetColor  // 3 - Use color 0e (Light blue)
94 < !:
95     bit $ff          // 3
96     clc              // 2
97     bcc nosetcolor   // 3 - No color changes on all other lines
98 < bgsetColor:
99     sta $d021        // 4
100
```

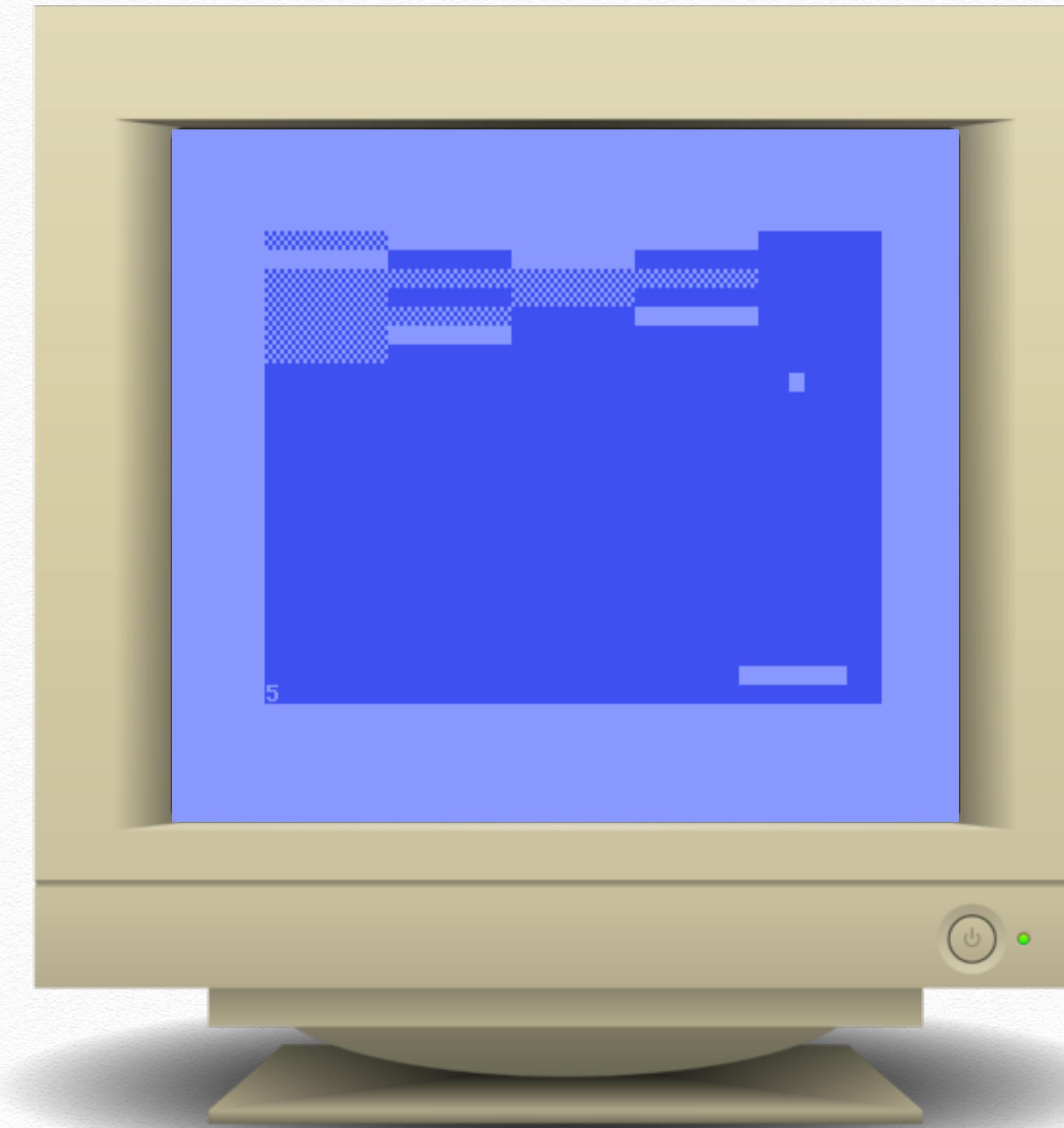
```
101 nosetcolor:
102     cpx #$03          // 2 - 18
103     bcs !+            // 2/3
104     nop               // 2 - Enable 24 rows screen mode
105     bit $ff            // 3
106     lda #$00            // 2
107     beq openscreen     // 3
108 !:
109     cpx #$c5            // 2
110     bcs !+            // 3/2
111     lda stophs:#$08     // 2
112     bpl openscreen     // 3
113 !:
114     lda #$00            // 2
115     nop               // 2 - Enable 25 rows screen mode
116 openscreen:
117     sta $d011            // 4
118
119     .fill 9,NOP          // 18 - 25 - Waste some cycles
120     inx                // 2
121     cpx #205             // 2
122     bne openloop        // 3 - Loop for the whole screen
123
124
125
126
```

demo > synced loop

```
309 // Speed code will be created this way:  
310 // sta $d020,x // 5 - 63 (5 + 13*4 + 6)  
311 // stx $d020 // 4  
312 // sty $d020 // 4  
313 // sax $d020 // 4  
314 // sta $d020 // 4  
315 // sta $d020 // 4  
316 // stx $d020 // 4  
317 // sta $d020 // 4  
318 // sty $d020 // 4  
319 // sta $d020 // 4  
320 // sax $d020 // 4  
321 // sty $d020 // 4  
322 // stx $d020 // 4  
323 // sax $d020 // 4  
324 // rts // 6
```

```
sta4cycles:  
.byte BIT_ABS, STX_ABS, STY_ABS, SAX_ABS  
.byte STA_ABS, BIT_ABS, STY_ABS, SAX_ABS  
.byte STA_ABS, STX_ABS, BIT_ABS, SAX_ABS  
.byte STA_ABS, STX_ABS, STY_ABS, BIT_ABS  
sta5cycles:  
.byte STA_ABSX, SHX_ABSY, SHY_ABSX, SHA_ABSY
```

demo > PETScIIInoid



demo > multiplication

- ❖ start conditions:
 - ❖ ballCoordHiTemp_2: current Y coordinate
 - ❖ A register: ballCoordHiTemp_2
 - ❖ DrawPTR: \$0100

```
// Multiply Y coord by 40
asl                      // x2
asl                      // x4
adc ballCoordHiTemp_2 + 1 // x5
asl                      // x10
!:
asl                      // x20 and x40
rol drawPtr + 1          // Shift hi byte to store carry and check higher bit to quit loop
bcs !-
sta drawPtr              // store lo byte

lda #WRITERINIT // All bits will be used for looping
sta writer      // but the variable will also store the lower bit of ball pattern
ldx #BALLPTRH   // 2 highest bits are used for looping,
stx drawPtr+1    // all remaining to store HI-byte of ball screen address
```

demo > every bit counts (1)

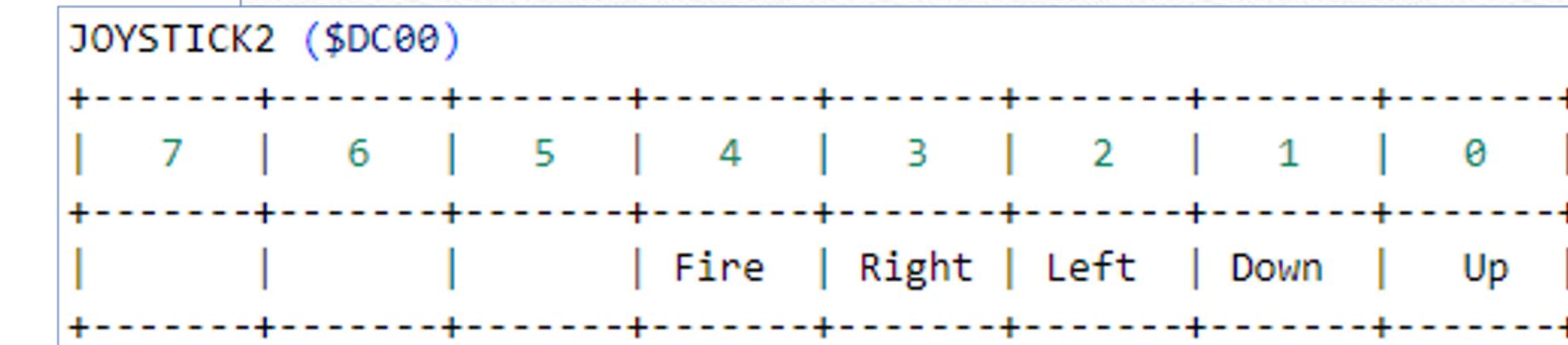
```
30 .const WRITERINIT = %10101000
31 .const BALLPTRH = %10000000 + (SCREENPAGE/$400)

367 // Prepare ball screen PTR and read current value
368 // #####
369 // This is used for:
370 // - Drawing ball
371 // - Checking obstacles
372 // - Drawing wall
373 prepareBallPtr:
374     // TOPIC: mess with bits!
375     lda #WRITERINIT // All bits will be used for looping
376     sta writer        // but the variable will also store the lower bit of ball pattern
377     ldx #BALLPTRH    // 2 highest bits are used for looping,
378     stx drawPtr+1    // all remaining to store HI-byte of ball screen address
379
380 !: // Prepare pattern based on fine tune bit
381     lda ballCoordHi - BALLPTRH,x      // Get least significant bit of the hi-byte of X,Y ball coords
382     lsr
383     sta ballCoordHiTemp_2 - BALLPTRH ,x
384     rol writer        // Store them in "writer" by shifting
385     inx
386     bcs !-           // Use higher bits of "writer" to exit at second iteration
```

```
410     // Draw ball pattern on screen
411 updateBall:
412     jsr prepareBallPtr
413     ldx writer
414 drawBallLoop:
415     lda ballchars-(<(WRITERINIT*4)), x
416     eor (drawPtr),y
417     sta (drawPtr),y
418     txa
419     axs #-4
420     iny
421     asl writer
422     bcs drawBallLoop
423     bpl quitPrepareBallPtr
424     tya
425     adc #(SCREENWIDTH-2)
426     tay
427     bcc drawBallLoop
428     inc drawPtr + 1
429     bcs drawBallLoop
```

demo > every bit counts (2)

```
319 // Bar update routine
320 // #####
321 ∵ barControl:
322     ldx barPosition
323     lda JOYSTICK2 // Load Joystick port 2
324     lsr
325     lsr // Skip bit 0-1
326     lsr
327     bcc barRight // If bit 2 is clear => move right
328     lsr
329     bcs barSkip // If bit 3 is clear => move left
330 ∵ barLeft:
331     cpx #((XYLIMIT - BARLENGTH) * 4) // Right border
332     bcs barSkip
333     txa
334     // using illegal
335     axs #($100-BARSPEED*2)
336 ∵ barRight:
337     txa // Left border
338     beq barSkip
339     axs #BARSPEED
340 ∵ barSkip:
341     stx barPosition
```



$X = (A \& X) - \#imm$

demo > linear feedback shift register

Pattern	0 0 0 1 0 0 0 1
Seed	0 0 0 0 0 0 0 1

LSR	0 0 0 0 0 0 0 0 0	1
EOR	0 0 0 1 0 0 0 1	
LSR	0 0 0 0 1 0 0 0	1
EOR	0 0 0 1 1 0 0 1	

LSR	0 0 0 0 1 1 0 0	1
EOR	0 0 0 1 1 1 0 1	
LSR	0 0 0 0 1 1 1 0	1
EOR	0 0 0 1 1 1 1 1	

LSR	0 0 0 0 1 1 1 1	1
EOR	0 0 0 1 1 1 1 0	
LSR	0 0 0 0 1 1 1 1	0

LSR	0 0 0 0 0 1 1 1	1
EOR	0 0 0 1 0 1 1 0	
LSR	0 0 0 0 1 0 1 1	0

LSR	0 0 0 0 0 1 0 1	1
EOR	0 0 0 1 0 1 0 0	
LSR	0 0 0 0 1 0 1 0	0

```
170    lsr
171    bcc lfsr1
172    eor #LFSRPATTERN
173    \<lfsr1:>
174    lsr
175    bcc lfsr2
176    eor #LFSRPATTERN
177    \<lfsr2:>
178    pha
```

demo > SP *is* a register

```
269 ∵ invertSpeed:  
270     txs          // Abuse stack pointer to detect inversion, $ff means no inversion  
271     ldx #$01  
272 ∵ invertSpeedLoop:  
273     lsr ballInvertFlags,x  
274     bcc invertSpeedSkip  
275     txs          // $00 or $01 means inversion  
276     lda #$00  
277     sbc ballSpeedLo,x  
278     sta ballSpeedLo,x // Carry always clear here  
279     lda #$00  
280     sbc ballSpeedHi,x  
281     sta ballSpeedHi,x // Carry always clear here  
282     lda #$01          // We avoid sec by adding 1  
283     sbc angle,X  
284     sta angle,x  
285 ∵ invertSpeedSkip:  
286     dex  
287     bpl invertSpeedLoop  
288  
289     // Loop till no inversion  
290     tsx  
291     bpl mainLoop      // Check stack pointer msb to decide whether an inversion is needed
```

“The performance of the task provided intrinsic reward.”



food to go

- ❖ if you think something is foolish, most probably somebody already did it...
- ❖ ...and somebody else forked it!
- ❖ if you think something is useless/broken and fear bugs and issues...
- ❖ ...publishing it you'll receive, and this means somebody used it!
- ❖ if you think you are still able to have fun like a child...
- ❖ ...join us to the ASM-side of the force!



source: <https://aceds.org/six-reasons-to-ask-a-question-from-the-audience-aceds-blog/>