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PYTORCH CHEAT SHEET

Imports

General

Neural Network API

```
import torch.autograd as autograd  # computation graph
from torch import Tensor  # tensor node in the computation graph
import torch.nn as nn  # neural networks
import torch.nn.functional as F  # layers, activations and more
import torch.optim as optim  # optimizers e.g. gradient descent, ADAM, etc.
from torch.jit import script, trace  # hybrid frontend decorator and tracing jit
```

See autograd, nn, functional and optim

TorchScript and JIT

```
torch.jit.trace()  # takes your module or function and an example
# data input, and traces the computational steps
# that the data encounters as it progresses through the model

@script  # decorator used to indicate data-dependent
# control flow within the code being traced
```

See Torchscript

ONNX

See onnx

Vision

```
from torchvision import datasets, models, transforms  # vision datasets,
# architectures &
# transforms

import torchvision.transforms as transforms  # composable transforms
```

See torchvision

Distributed Training

```
import torch.distributed as dist  # distributed communication
from torch.multiprocessing import Process  # memory sharing processes
```

Tensors

Creation

See tensor

Dimensionality

```
x.size()
                                         # return tuple-like object of dimensions
x = torch.cat(tensor_seq, dim=0)
                                         # concatenates tensors along dim
y = x.view(a,b,...)
                                         # reshapes x into size (a,b,...)
y = x.view(-1,a)
                                         # reshapes x into size (b,a) for some b
y = x.transpose(a,b)
                                         # swaps dimensions a and b
y = x.permute(*dims)
                                         # permutes dimensions
y = x.unsqueeze(dim)
                                         # tensor with added axis
y = x.unsqueeze(dim=2)
                                         # (a,b,c) tensor -> (a,b,1,c) tensor
                                         # removes all dimensions of size 1 (a,1,b,1) -> (a,b)
y = x.squeeze()
y = x.squeeze(dim=1)
                                         # removes specified dimension of size 1 (a,1,b,1) -> (a,b,1)
```

See tensor

Algebra

```
ret = A.mm(B)  # matrix multiplication
ret = A.mv(x)  # matrix-vector multiplication
x = x.t()  # matrix transpose
```

See math operations

GPU Usage

```
torch.cuda.is_available
                                                            # check for cuda
x = x.cuda()
                                                            # move x's data from
                                                            # CPU to GPU and return new object
x = x.cpu()
                                                            # move x's data from GPU to CPU
                                                            # and return new object
if not args.disable_cuda and torch.cuda.is_available():
                                                            # device agnostic code
    args.device = torch.device('cuda')
                                                            # and modularity
else:
                                                            #
                                                            #
    args.device = torch.device('cpu')
net.to(device)
                                                            # recursively convert their
                                                            # parameters and buffers to
                                                            # device specific tensors
x = x.to(device)
                                                            # copy your tensors to a device
                                                            # (gpu, cpu)
```

See <mark>cud</mark>a

Deep Learning

```
# fully connected layer from
nn.Linear(m,n)
                                               # m to n units
                                              # X dimensional conv layer from
nn.ConvXd(m,n,s)
                                              # m to n channels where X \in \{1, 2, 3\}
                                              # and the kernel size is s
nn.MaxPoolXd(s)
                                              # X dimension pooling layer
                                              # (notation as above)
nn.BatchNormXd
                                              # batch norm layer
nn.RNN/LSTM/GRU
                                              # recurrent layers
nn.Dropout(p=0.5, inplace=False)
                                              # dropout layer for any dimensional input
nn.Dropout2d(p=0.5, inplace=False)
                                              # 2-dimensional channel-wise dropout
nn.Embedding(num_embeddings, embedding_dim) # (tensor-wise) mapping from
                                              # indices to embedding vectors
```

See nn

Loss Functions

```
nn.X

# where X is L1Loss, MSELoss, CrossEntropyLoss

# CTCLoss, NLLLoss, PoissonNLLLoss,

# KLDivLoss, BCELoss, BCEWithLogitsLoss,

# MarginRankingLoss, HingeEmbeddingLoss,

# MultiLabelMarginLoss, SmoothL1Loss,

# SoftMarginLoss, MultiLabelSoftMarginLoss,

# CosineEmbeddingLoss, MultiMarginLoss,

# or TripletMarginLoss
```

See loss functions

Activation Functions

```
nn.X

# where X is ReLU, ReLU6, ELU, SELU, PReLU, LeakyReLU,

# RReLu, CELU, GELU, Threshold, Hardshrink, HardTanh,

# Sigmoid, LogSigmoid, Softplus, SoftShrink,

# Softsign, Tanh, TanhShrink, Softmin, Softmax,

# Softmax2d, LogSoftmax or AdaptiveSoftmaxWithLoss
```

See activation functions

Optimizers

```
opt = optim.x(model.parameters(), ...)  # create optimizer
opt.step()  # update weights
optim.X  # where X is SGD, Adadelta, Adagrad, Adam,
# AdamW, SparseAdam, Adamax, ASGD,
# LBFGS, RMSprop or Rprop
```

See optimizers

Learning rate scheduling

```
scheduler = optim.X(optimizer,...)  # create lr scheduler
scheduler.step()  # update lr after optimizer updates weights
optim.lr_scheduler.X  # where X is LambdaLR, MultiplicativeLR,
# StepLR, MultiStepLR, ExponentialLR,
# CosineAnnealingLR, ReduceLROnPlateau, CyclicLR,
# OneCycleLR, CosineAnnealingWarmRestarts,
```

See learning rate scheduler

Data Utilities

Datasets

```
Dataset  # abstract class representing dataset
TensorDataset  # labelled dataset in the form of tensors
Concat Dataset  # concatenation of Datasets
```

See datasets

Dataloaders and DataSamplers

DataLoader(dataset, batch_size=1, ...) # loads data batches agnostic
of structure of individual data points

sampler.Sampler(dataset,...) # abstract class dealing with
ways to sample from dataset

sampler.XSampler where ... # Sequential, Random, SubsetRandom,
WeightedRandom, Batch, Distributed

See dataloader

Also see

- Deep Learning with PyTorch: A 60 Minute Blitz
- PyTorch Forums
- PyTorch for Numpy users

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