

LB1930M

Single-Channel Low Saturation Voltage Forward/Reverse Motor Driver

Overview

The LB1930M is a low saturation voltage H-bridge forward/reverse motor driver that supports low-voltage drive. This device is optimal for CD, MD, and cassette player loading motors.

Functions and Features

 The low saturation voltage reduces IC internal heating and allows a high voltage to be applied to the motor.
 Thus this device can be used even in environments with a high operating ambient temperature.

Output saturation voltage:

 $Vsat1 = 0.25 V typical (I_O = 0.2 A)$

(High side + low side):

 $Vsat2 = 0.55 V typical (I_O = 0.5 A)$

Operating temperature range:

 $Ta = -30 \text{ to } +85^{\circ}\text{C}$

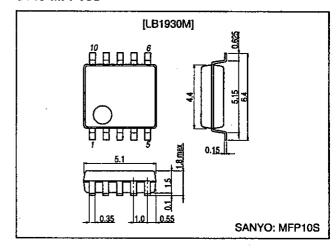
- The LB1930M features the wide operating voltage range of 2.2 to 10.8 V and the low standby current drain of 0.1 μA, and therefore can easily be used in battery operated systems.
- To minimize through currents, the LB1930M internal logic passes through an internal standby state when switched by the input signals between forward/reverse and brake, or between forward and reverse.
- There are no constraints on the relationship between the input voltage and the supply voltage. For example, the LB1930M can be used with $V_{CC} = 3 \text{ V}$, and $V_{IN} = 5 \text{ V}$.

- If the IC chip exceeds 180°C due to an output short causing a large current flow, the built-in thermal protection circuit suppresses the drive current to prevent fires or destruction of the IC.
- MFP-10S miniature package. Also, the LB1930M features the high allowable power dissipation of Pd = 800 mW.

Package Dimensions

unit: mm

3148-MFP10S

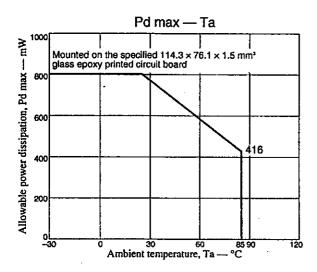


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Specifications Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	V _{CC} max		11	V
Output current	I _{OUT} max		1000	mA
Output voltage handling	V _{OUT} max		Vcc + V _{SF}	V
Applied input voltage	I _H max		10.5	V
Allowable power dissipation	Polmax	Mounted on the specified printed circuit board*	800	mW
Operating temperature	Topr		-30 to +85	°C
Storage temperature	Tstg		-55 to +150	·c

Note *: $114.3 \times 76.1 \times 1.5 \text{ mm}^{\text{s}}$ glass epoxy printed circuit board



Allowable Operating Ranges at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Supply voltage	Vcc		2.2 to 10.8	V
High-level input voltage	V _{IH}		2.0 to 10	V
Low-level input voltage	V _{IL}		-0.3 to +0.3	V

Electrical Characteristics at $Ta = 25^{\circ}C$, $V_{CC} = 3~V$

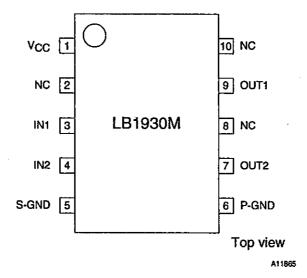
Parameter	Symbol	Conditions	Ratings			Γ
Faidhetei	Symbol Conditions		min	typ	max	Unit
	I _{CC} 1	Standby mode		0.1	5	μА
Supply current	I _{CC} 2	Forward or reverse drive operation		15	21	mA
·	I _{CC} 3	Braking		22	31	mA
	V _O (sat)1	Forward or reverse drive: High side + low side, Io = 200 mA	•		0.35	٧
Output saturation voitage	V _O (sat)2	Forward or reverse drive: High side + low side, I _O = 500 mA		0.55	0.75	V
	V _O (sat)3	Forward or reverse drive: High side only, I _O = 200 mA		0.15	0.25	v
Spark killer diode forward voltage	V _{SF}	I _O = 200 mA		0.9	1.7	V
Spark killer diode reverse current	las	V _{OUT} = 10 V		0,1	5	μA
Input current	I _{IN}	V _{IN} = 5 V		70	95	μA
Thermal detection operating temperature	THD	Design target value*	150	180	200	°C

Note *: This value is a design guarantee and is not measured.

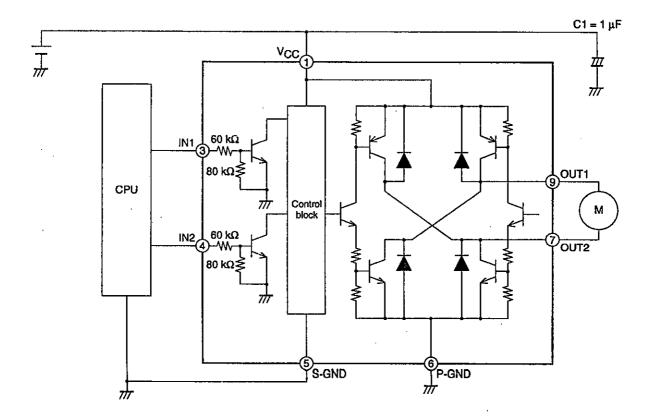
Truth Table

IN1	IN2	OUT1	OUT2	Mode
L	L	OFF	OFF	Standby
H	L	Н	L.	Forward
L	Н	L	Н	Reverse
Н	H	Н	Н	Brake

Pin Assignment



Block Diagram and Sample Application Circuit



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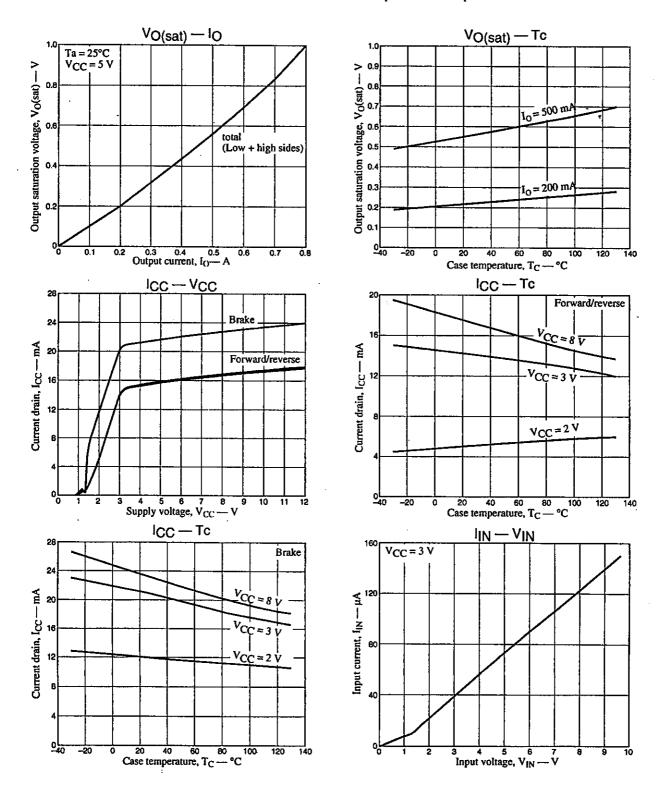
Usage Notes

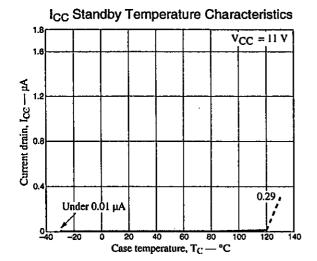
Oscillation may occur in the V_{CC} and P-GND lines, since these lines carry a wide range of currents. The following may help if this is a problem.

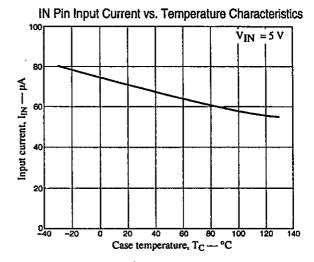
- Lower the inductance of the wiring by making lines wider and shorter.
- · Insert capacitors with good frequency characteristics close to the IC.
- Consider adopting the following methods if the CPU and this IC are mounted on different printed circuit boards that could easily have different ground potentials.

Connect S-GND to the CPU ground and connect P-GND to the power system ground.

Insert resistors of about 10 k Ω in series between the controller outputs and the inputs on this IC.







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