

# Narwhal-Bullshark

## DAG BFT Protocols Made Practical

Alberto Sonnino

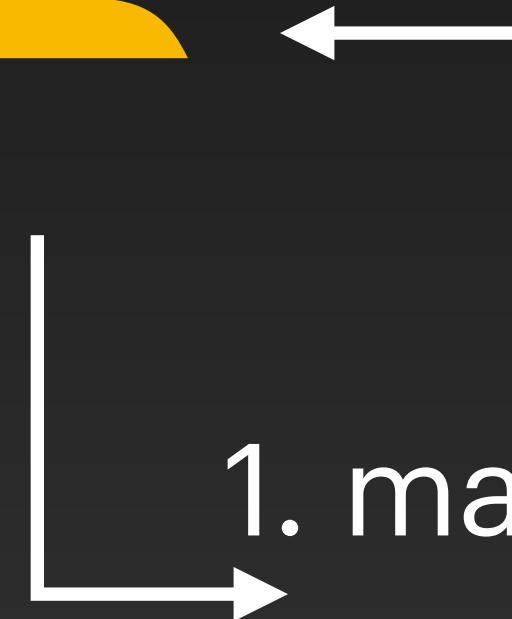
# Byzantine Fault Tolerance



$> 2/3$



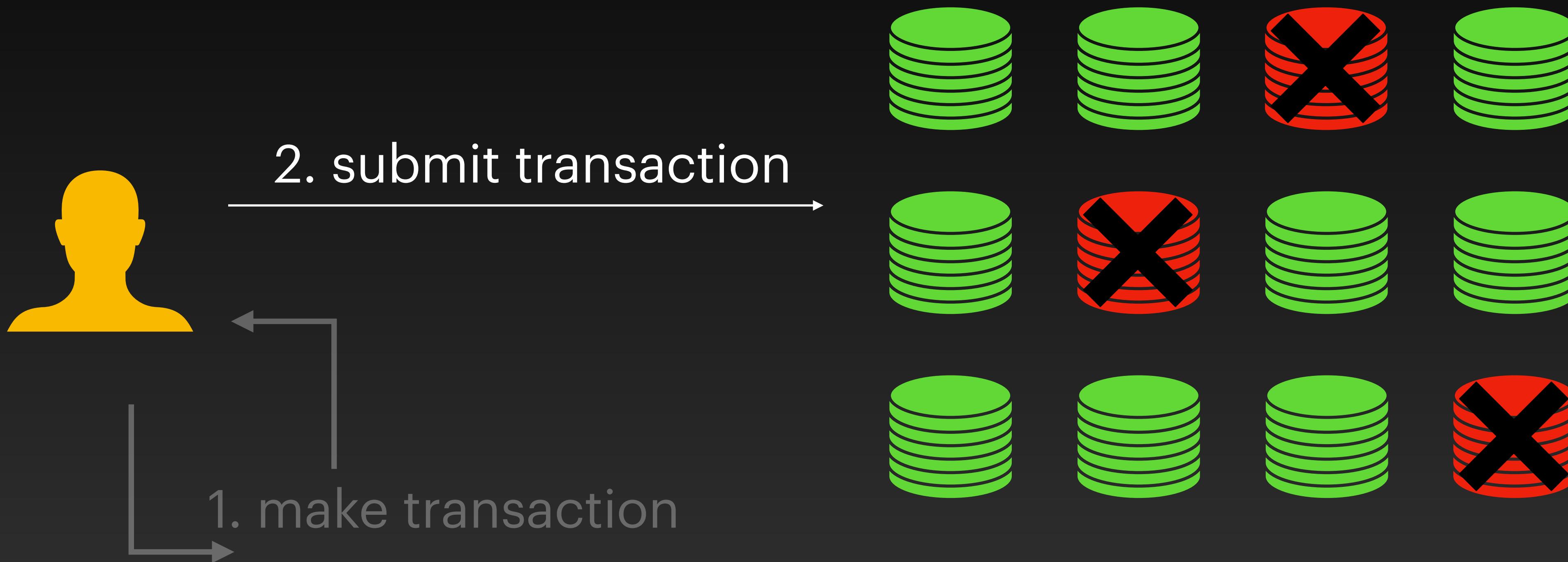
# Blockchains



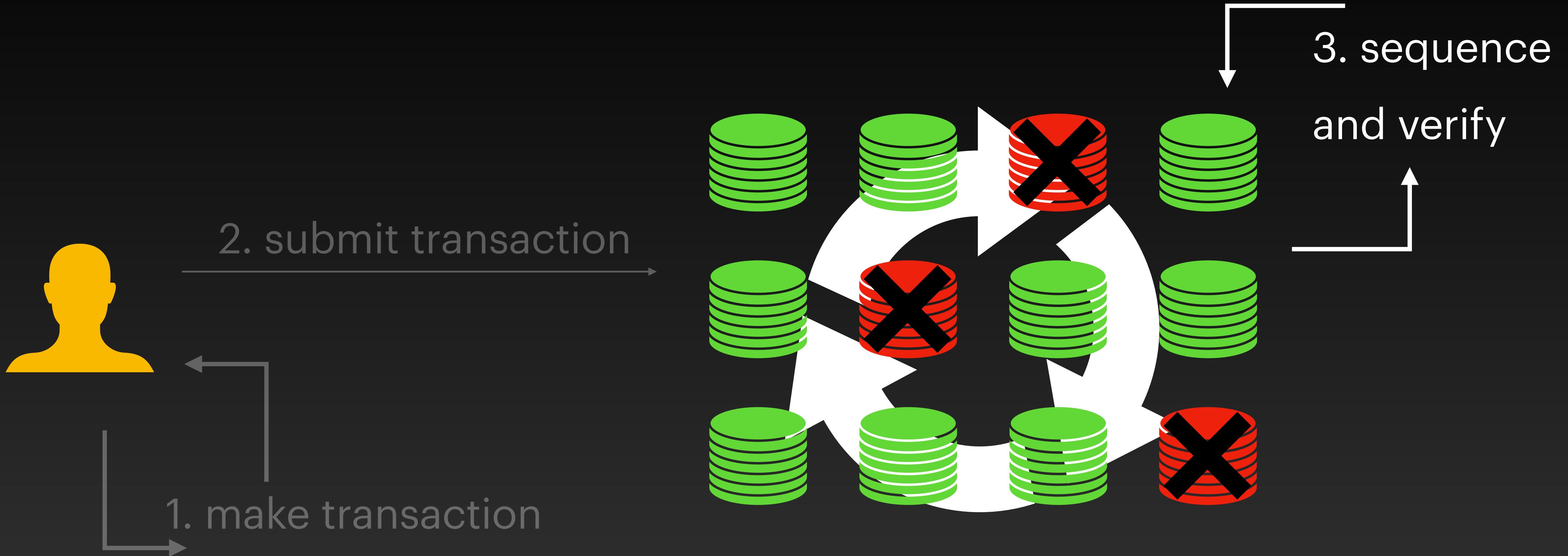
1. make transaction



# Blockchains



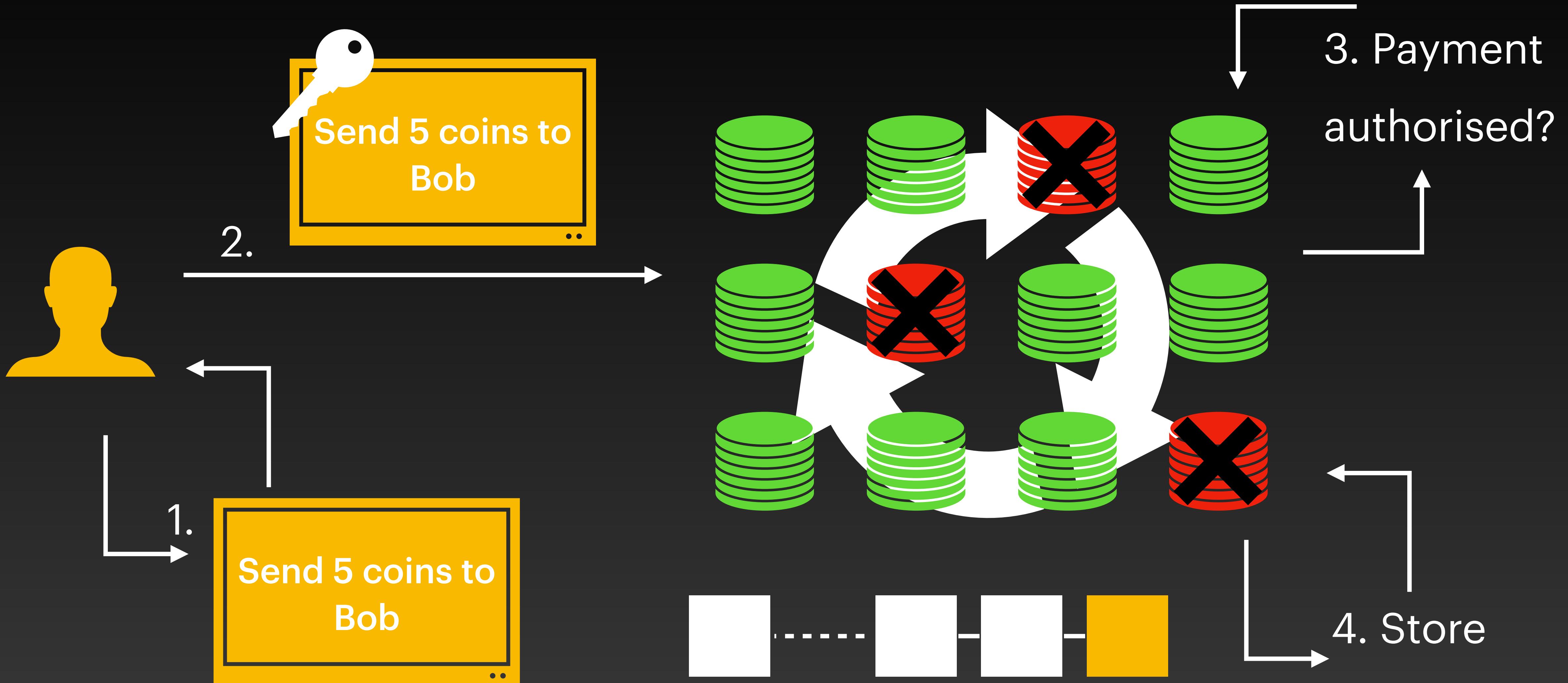
# Blockchains



# Blockchains



# The best example



# Consensus on top of Narwhal

## Goal of this project

### Simple

- Zero-message overhead
- No view-change
- No common-coin

### Performant

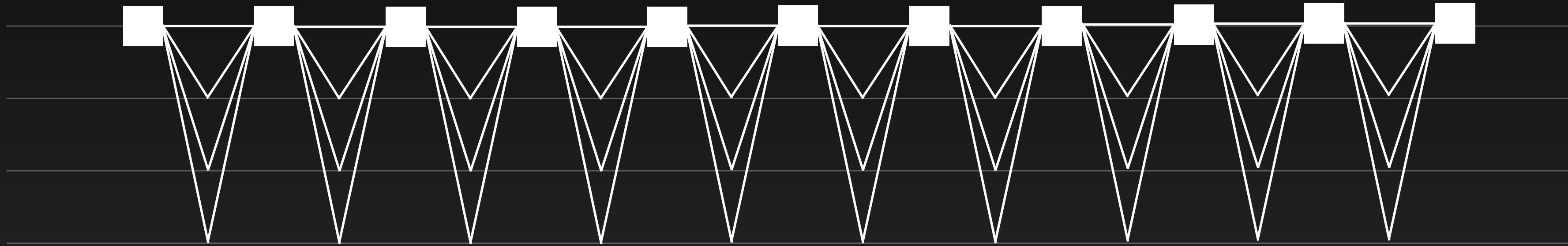
- Take advantage of Narwhal
- Exploit periods of synchrony

# Current Designs

- Monolithic protocol sharing transaction data as part of the consensus
- Optimize overall message complexity of the consensus protocol
- Complex & Error-prone view-change protocol

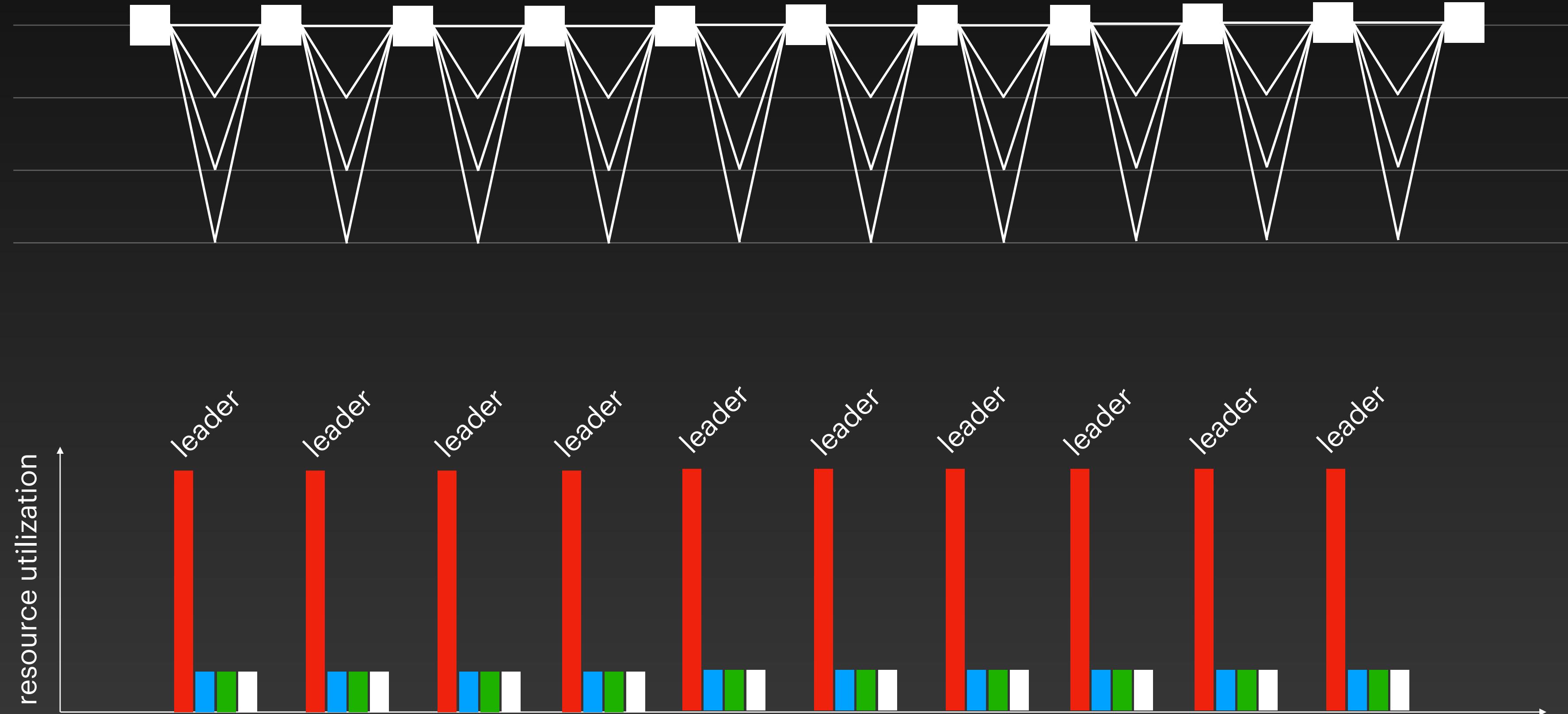
# Current Designs

## Typical leader-based protocols



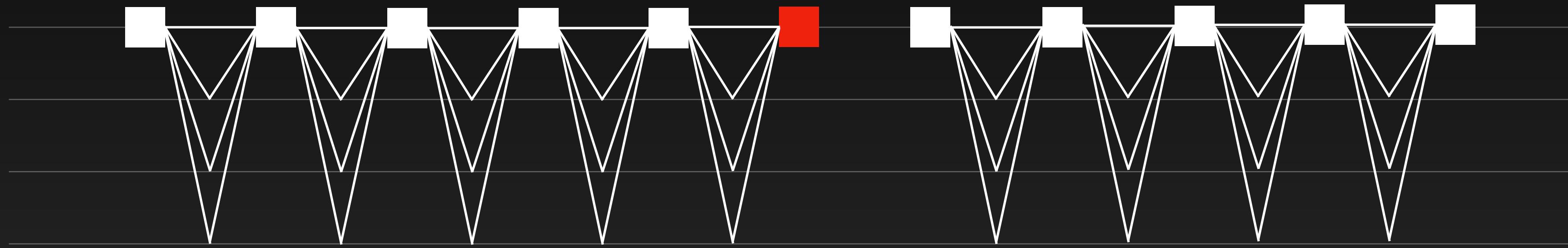
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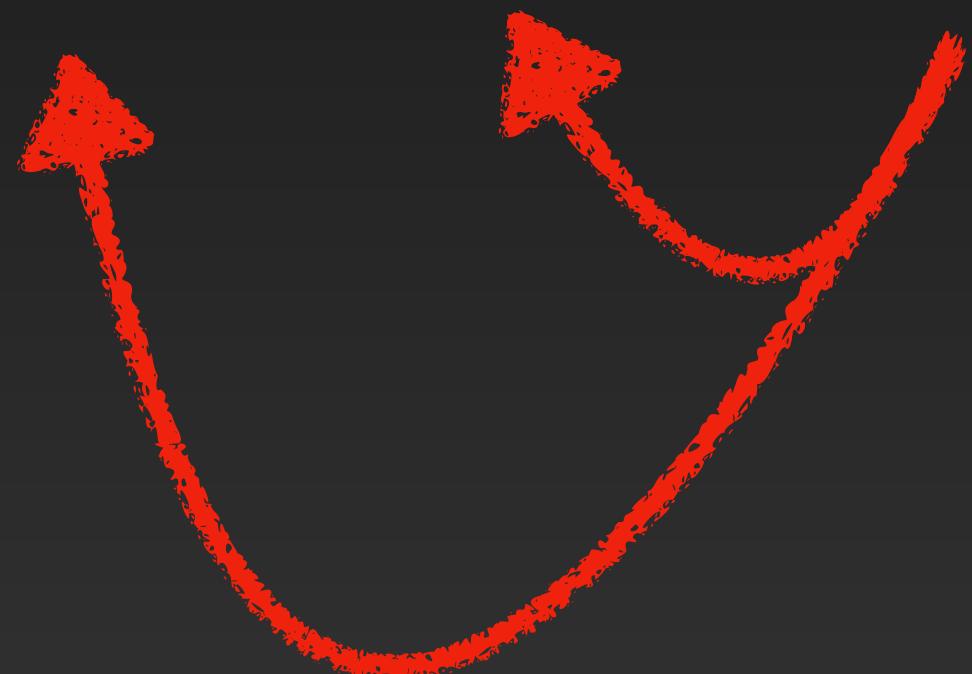
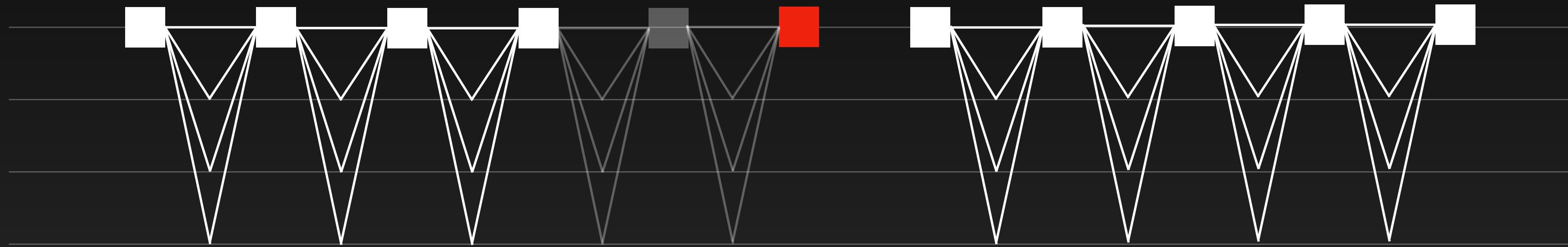
# Current Designs

## Typical leader-based protocols



# Current Designs

## Typical leader-based protocols



# Narwhal

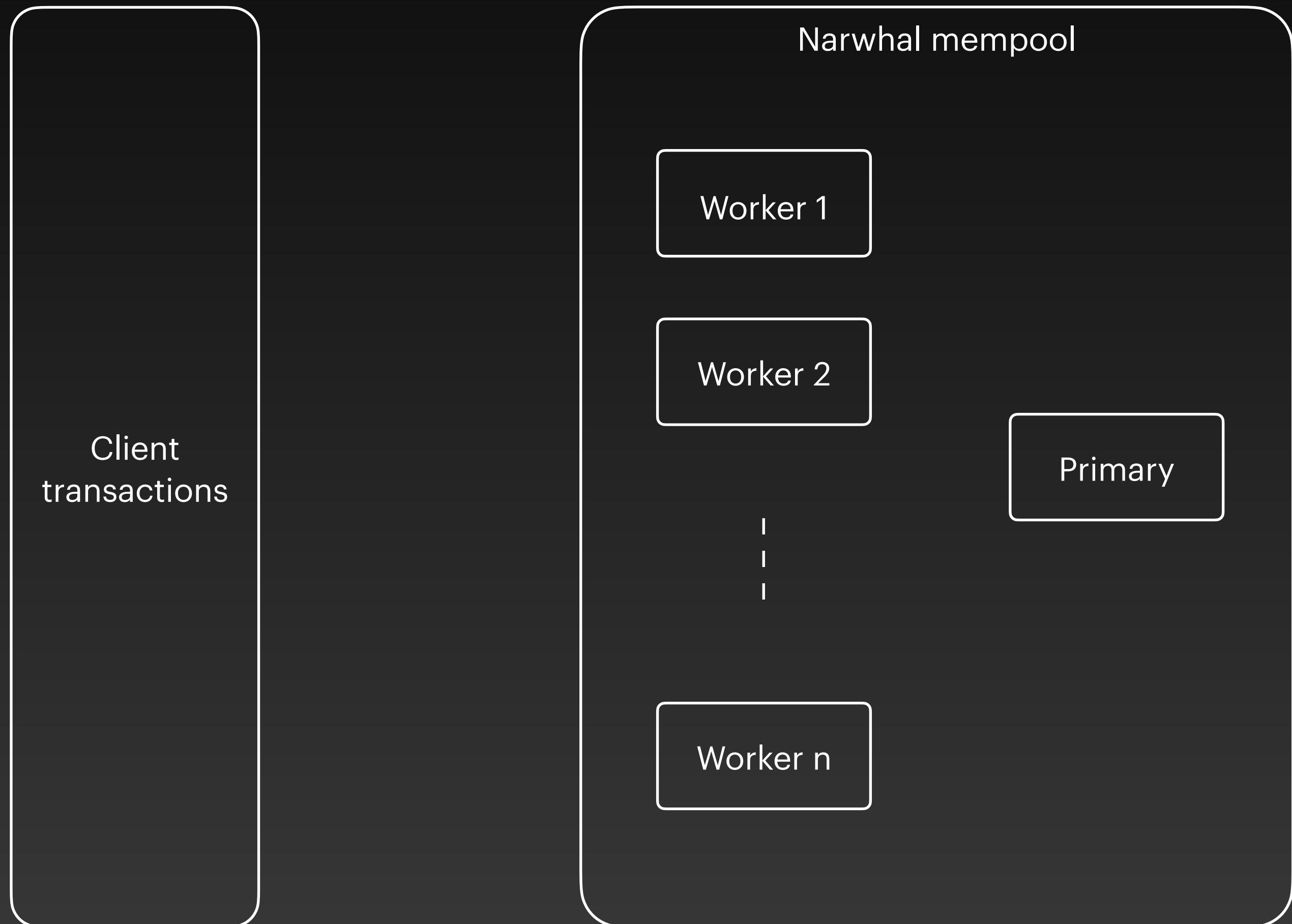
Dag-based mempool

**The mempool is the key**

Reaching consensus on metadata is cheap

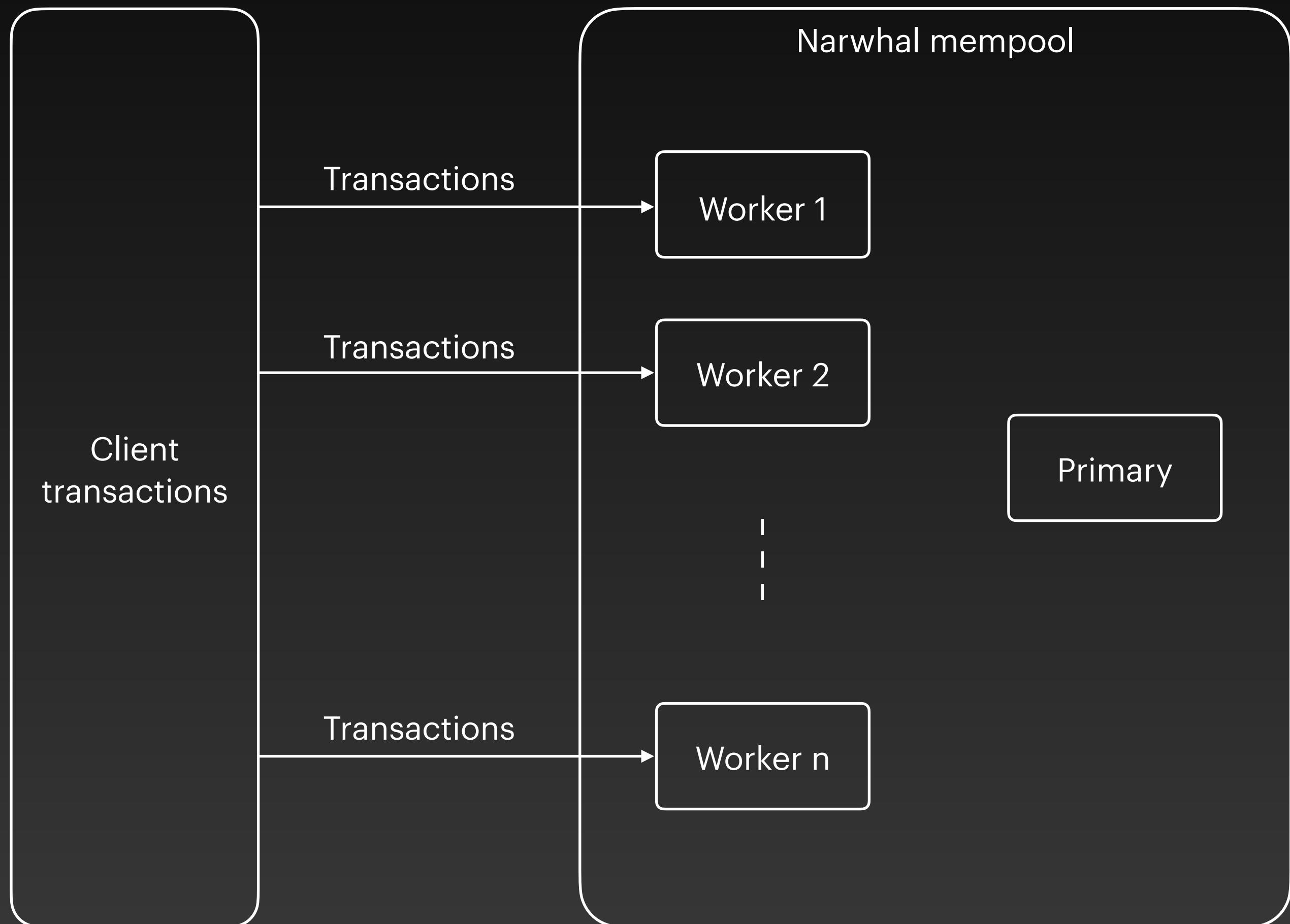
# Narwhal

## The workers and the primary



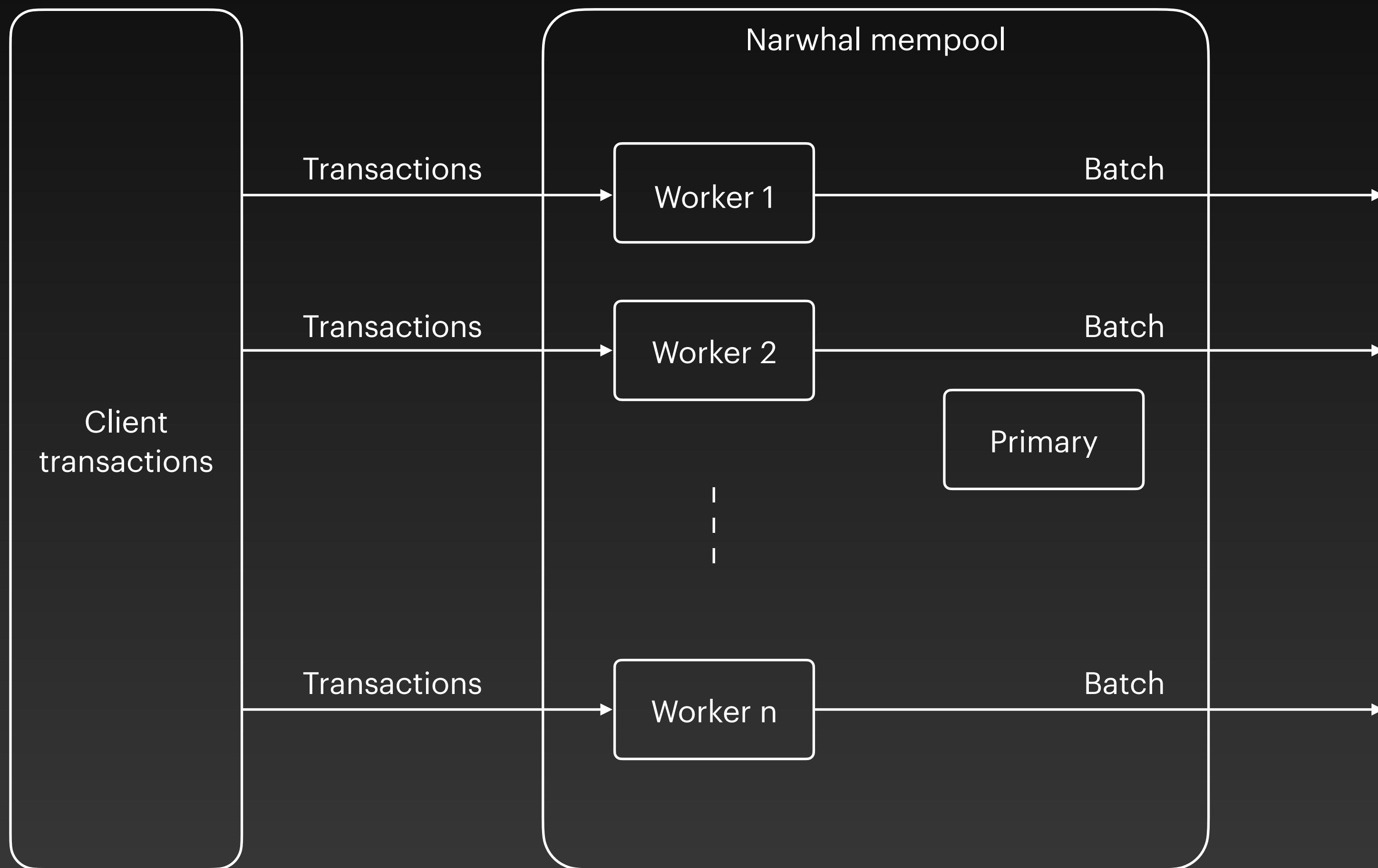
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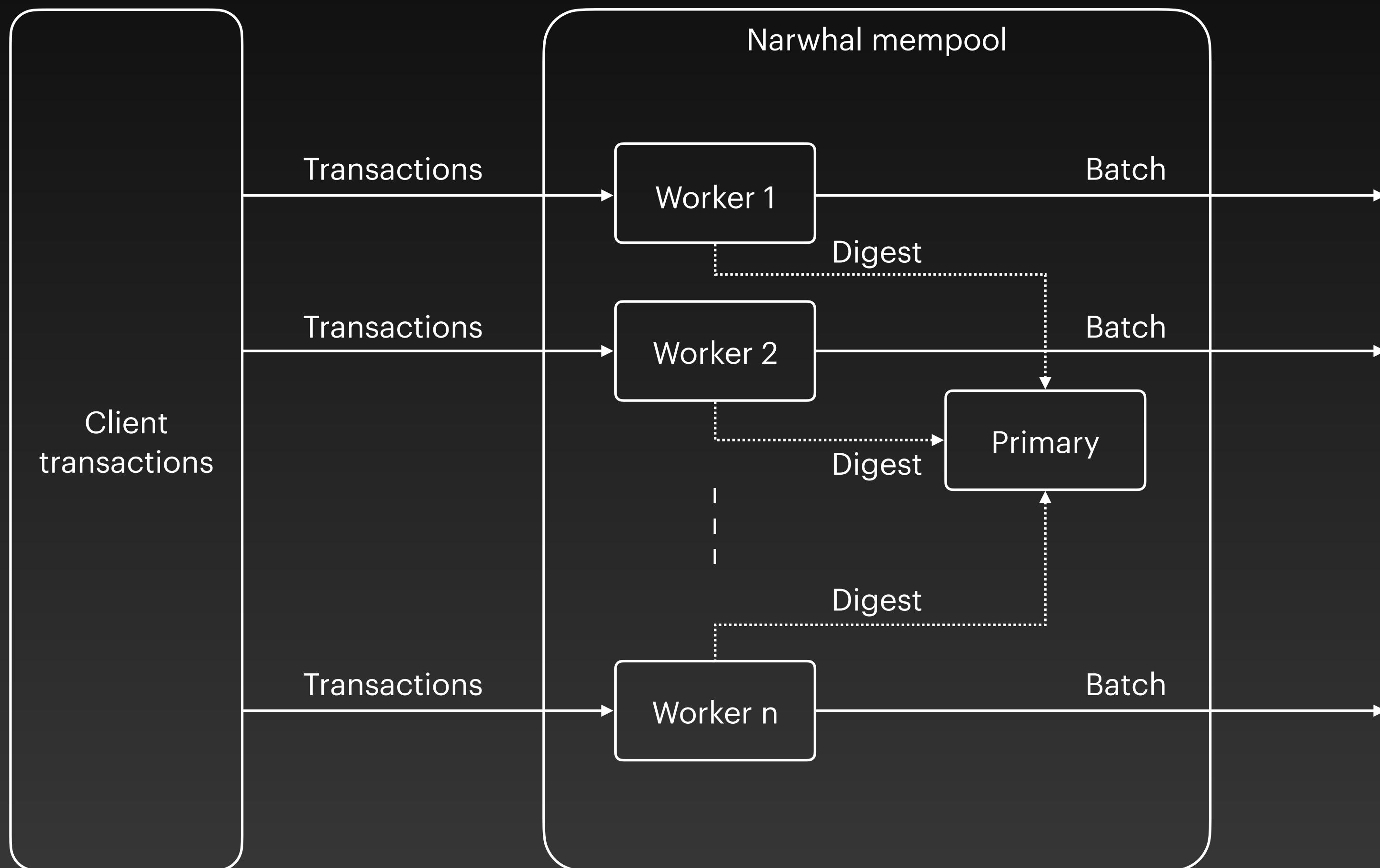
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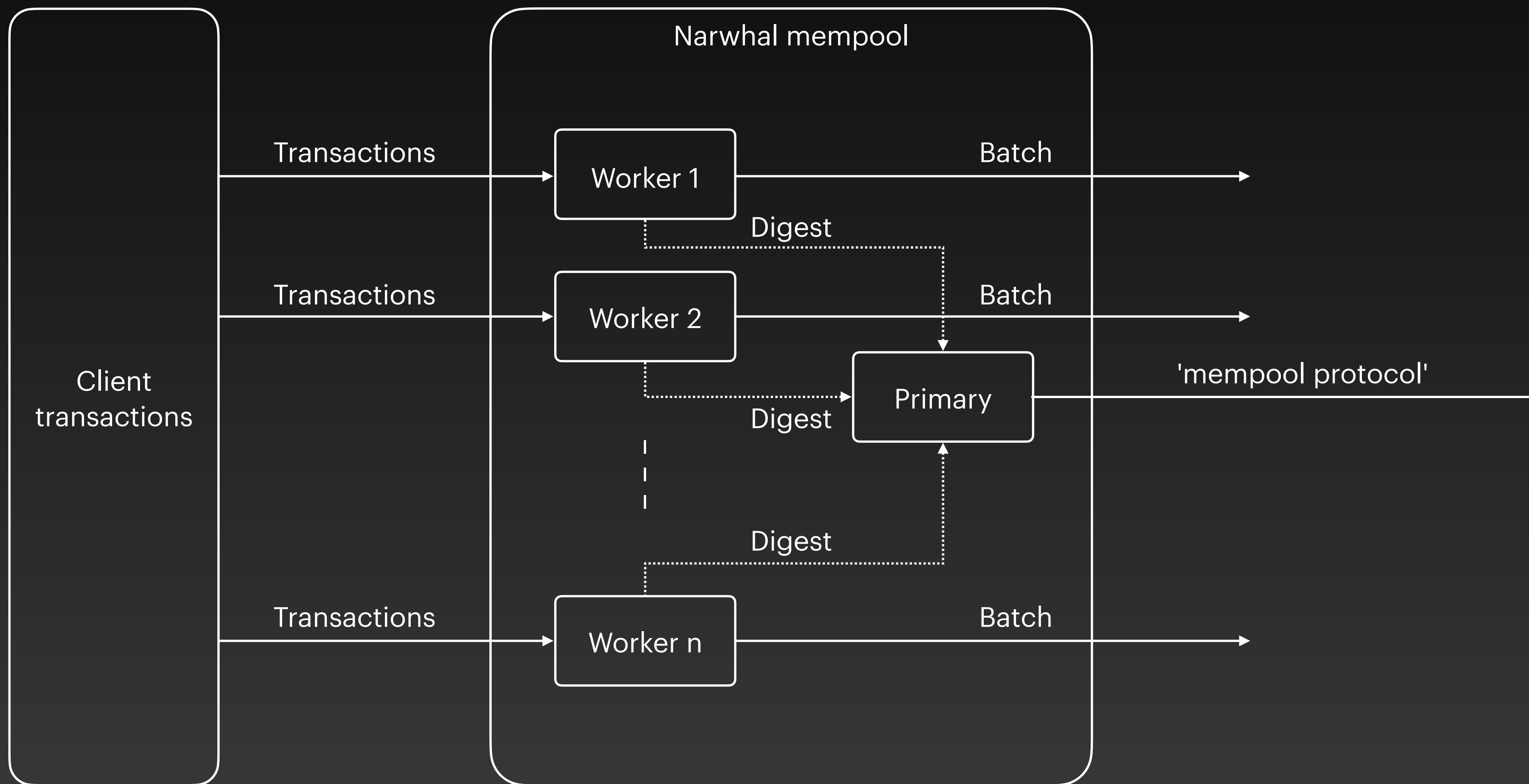
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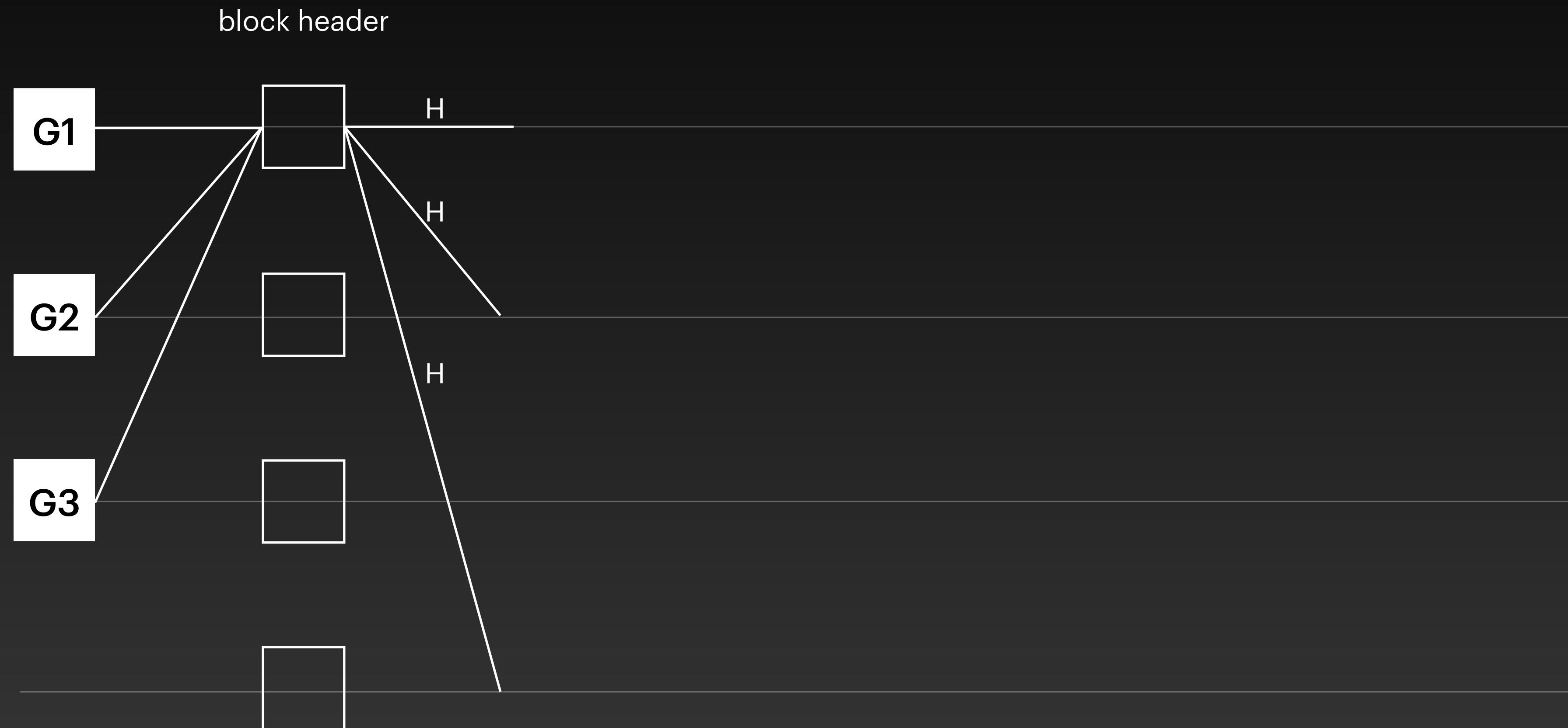
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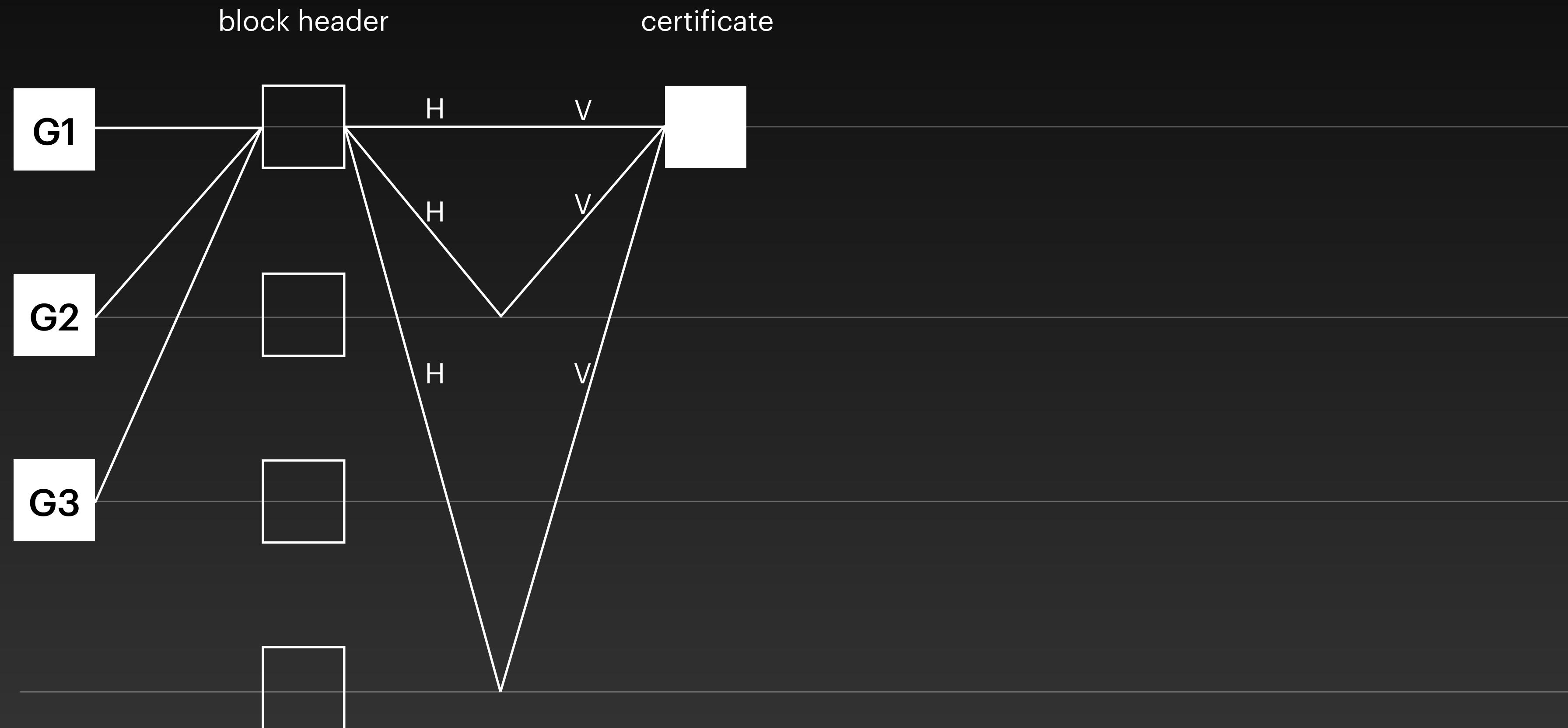
# Narwhal

## The primary machine



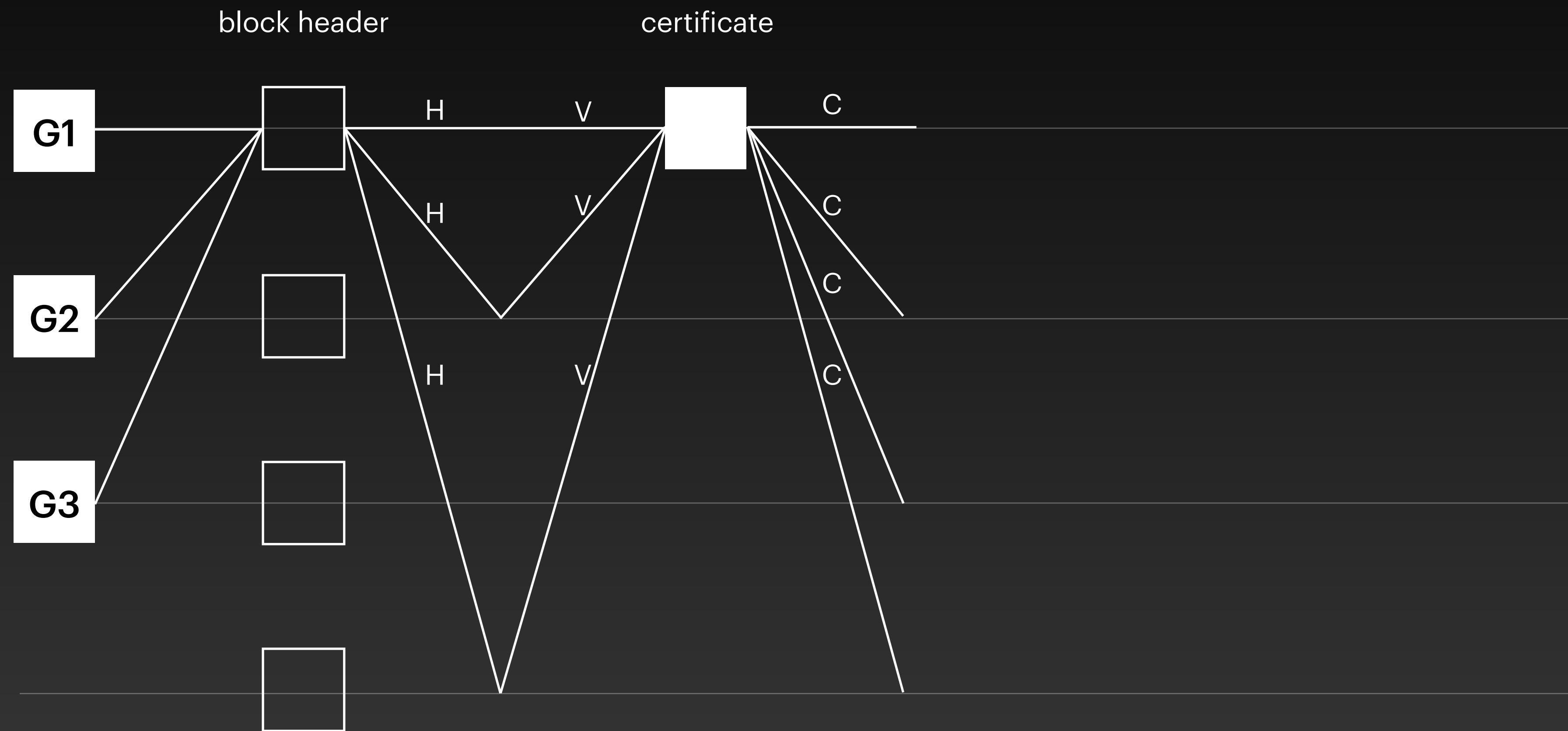
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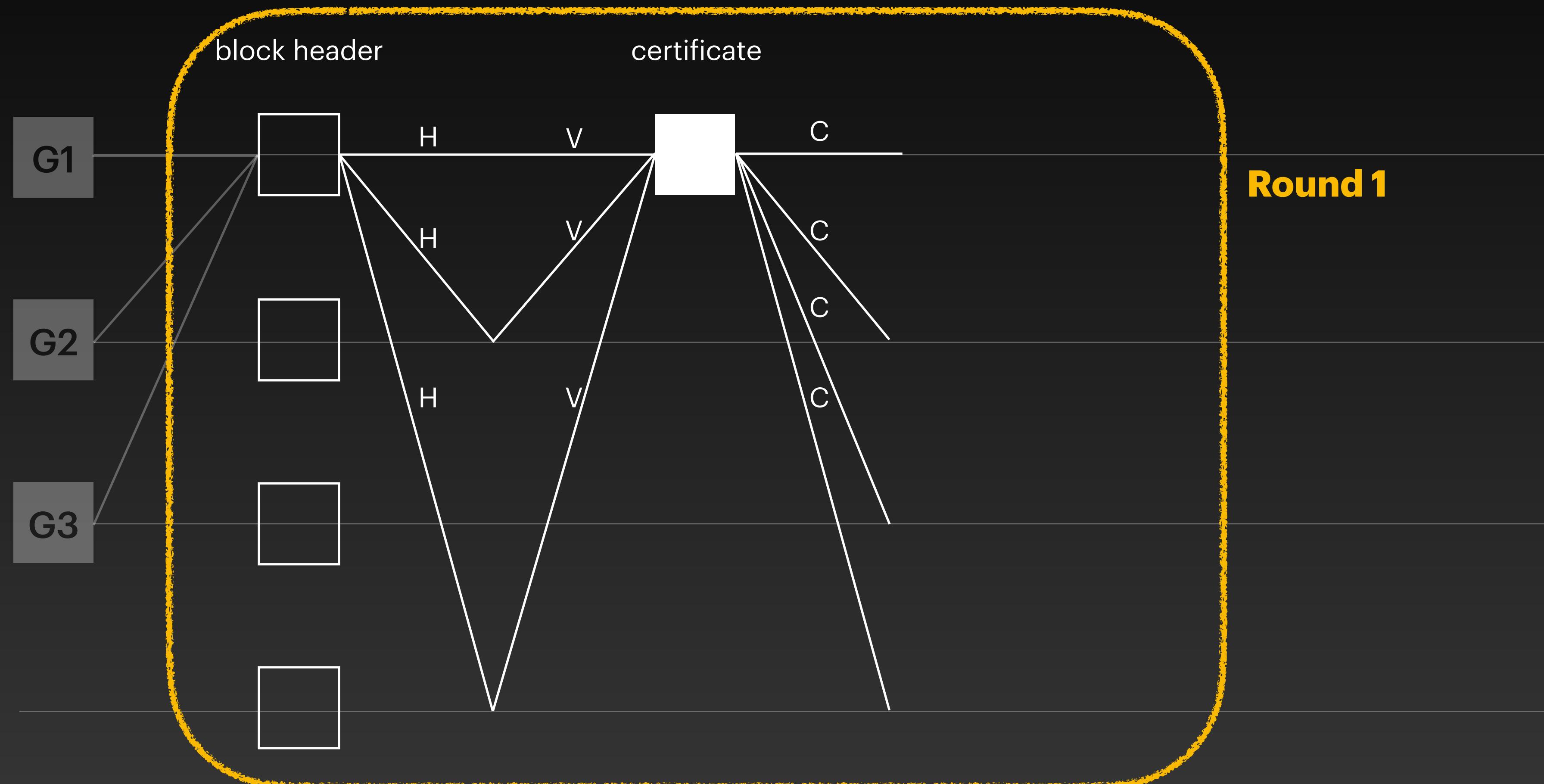
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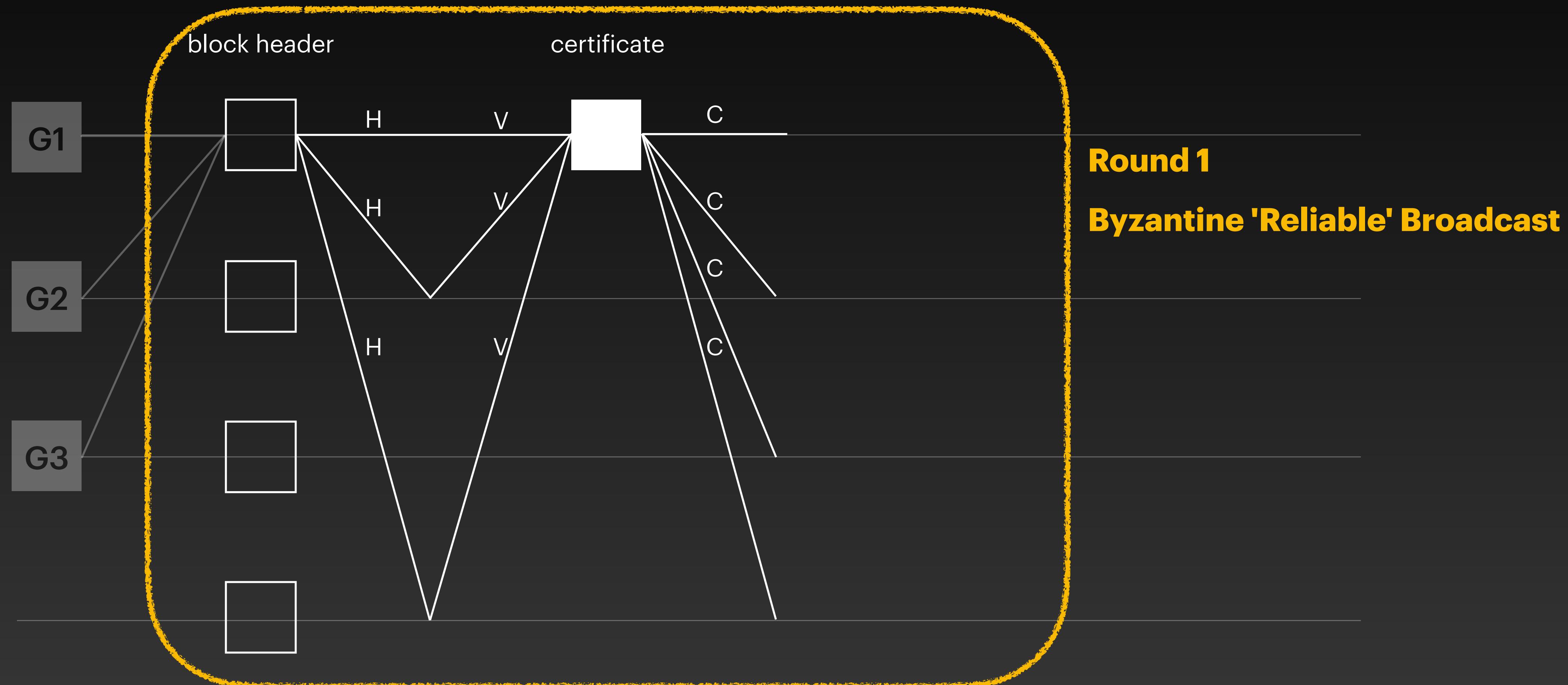
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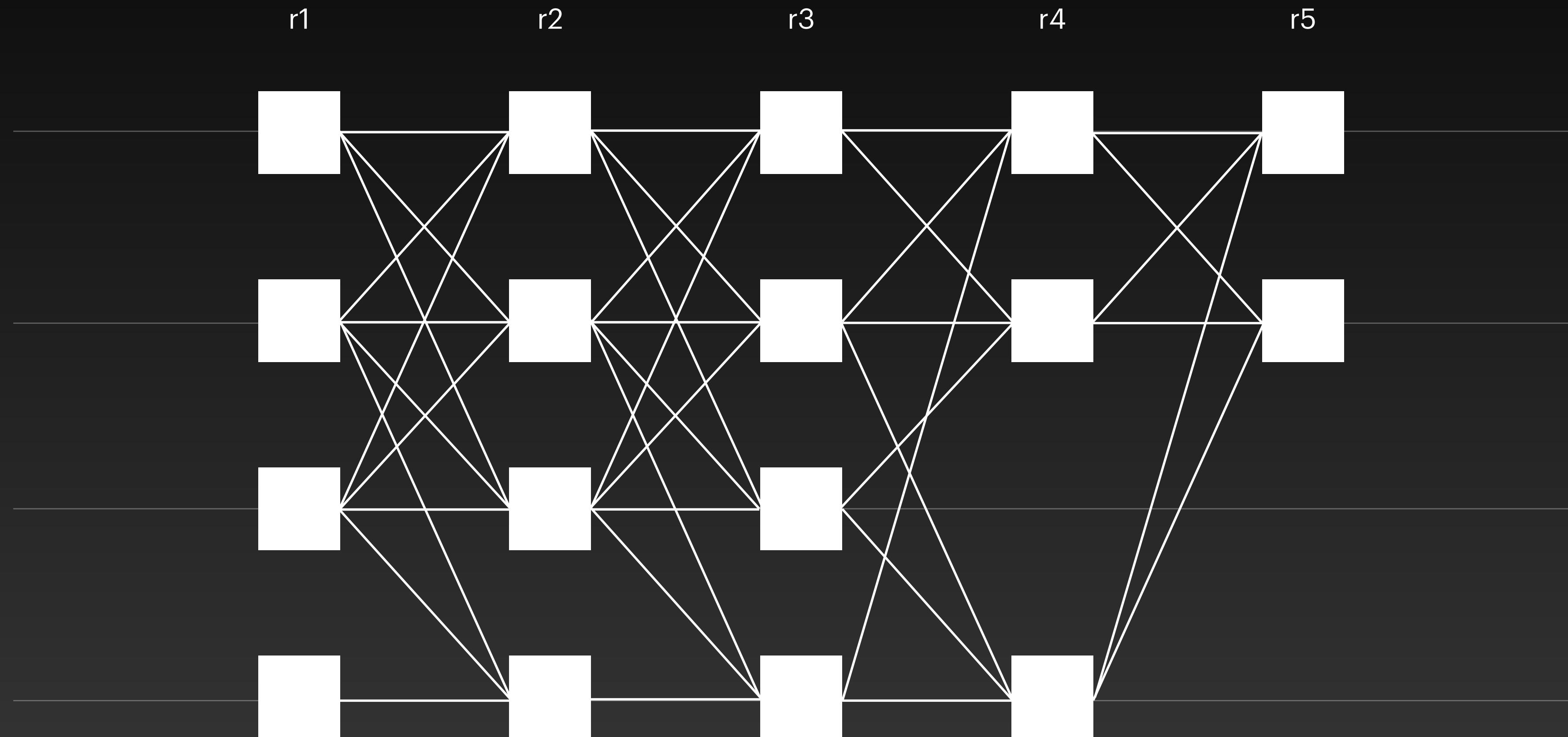
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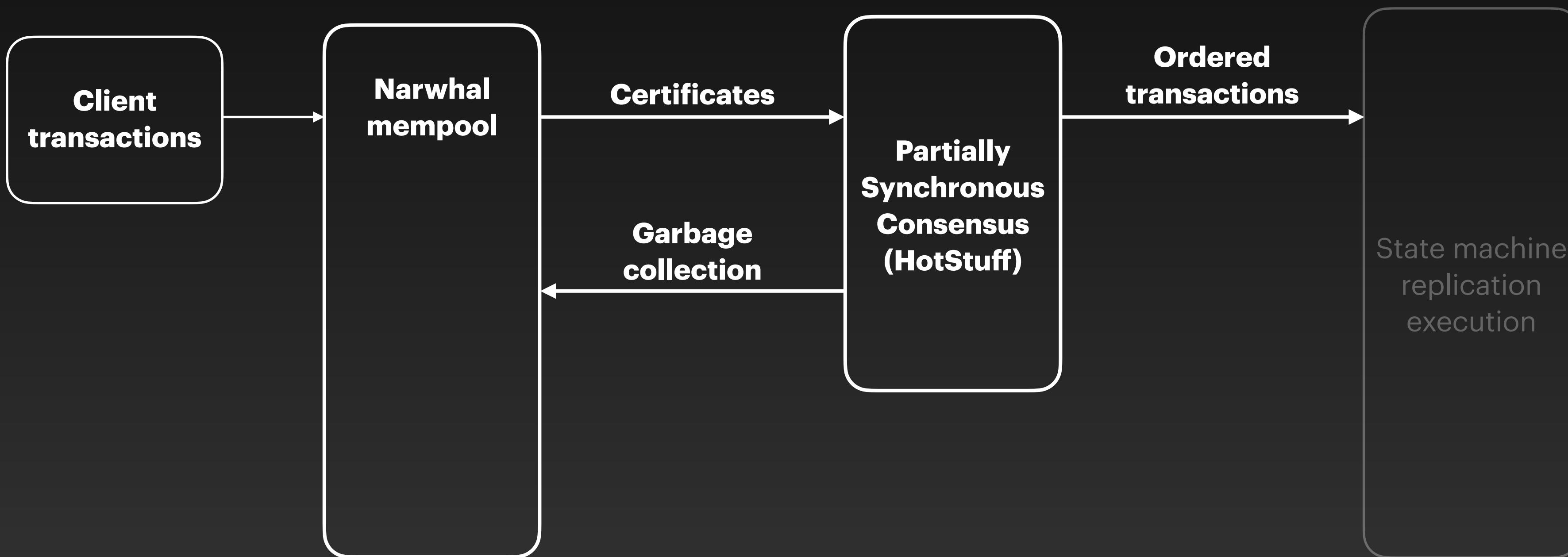


# HotStuff on Steroids

Just by replacing the mempool

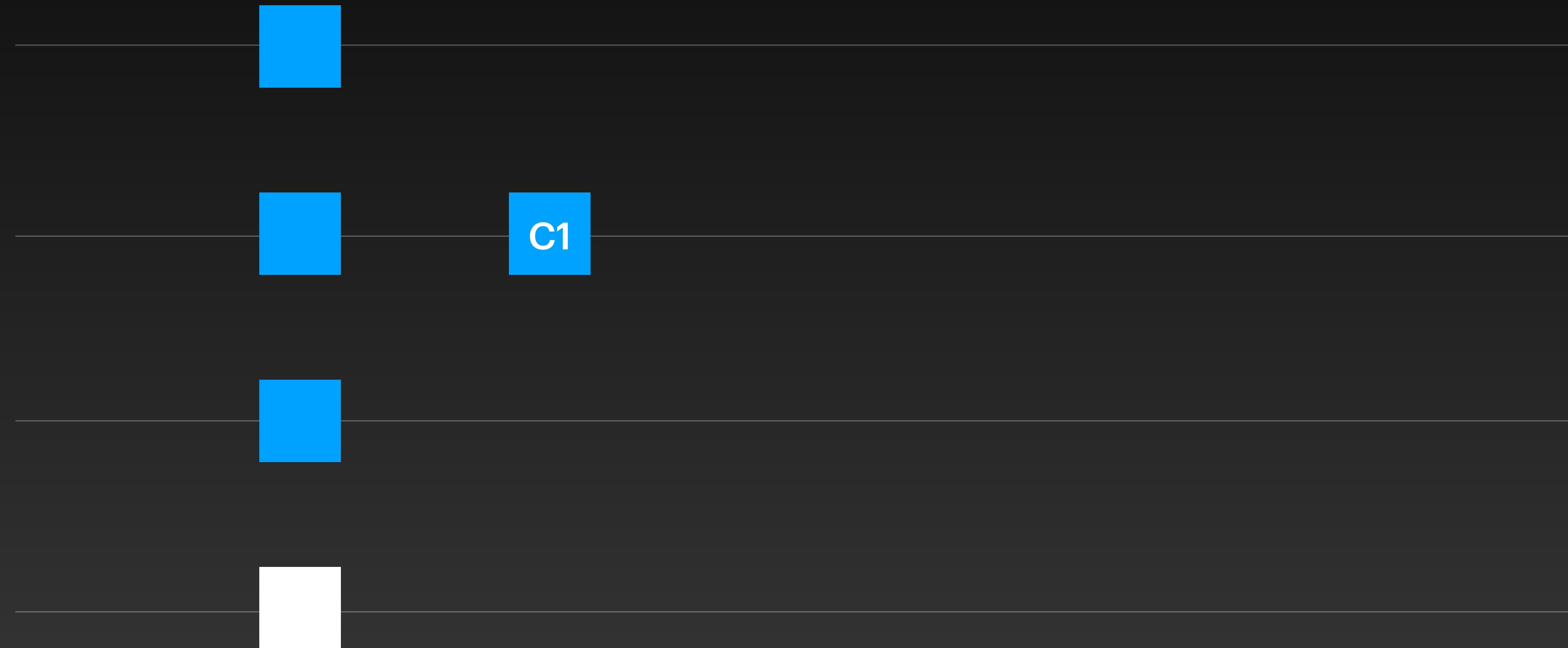
# HotStuff on Narwhal

## Overview



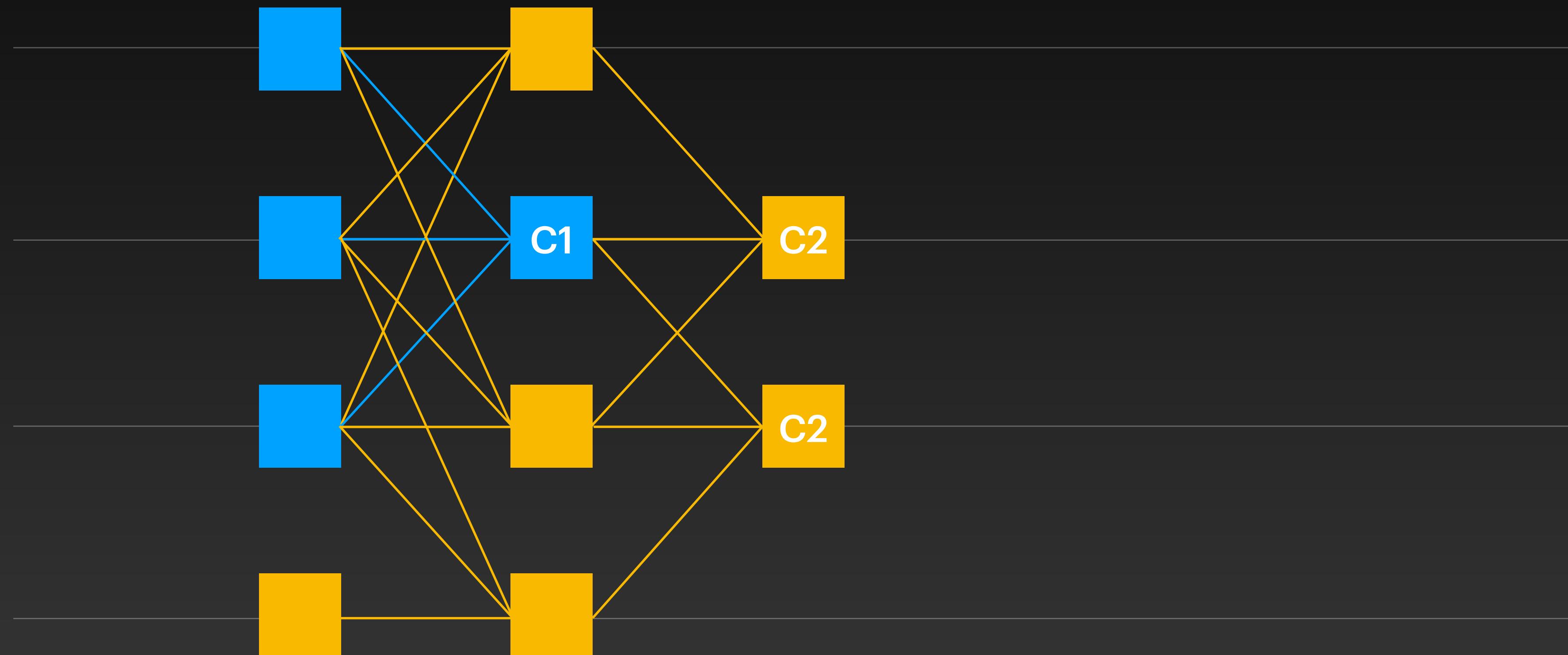
# HotStuff on Narwhal

## Enhanced commit rule



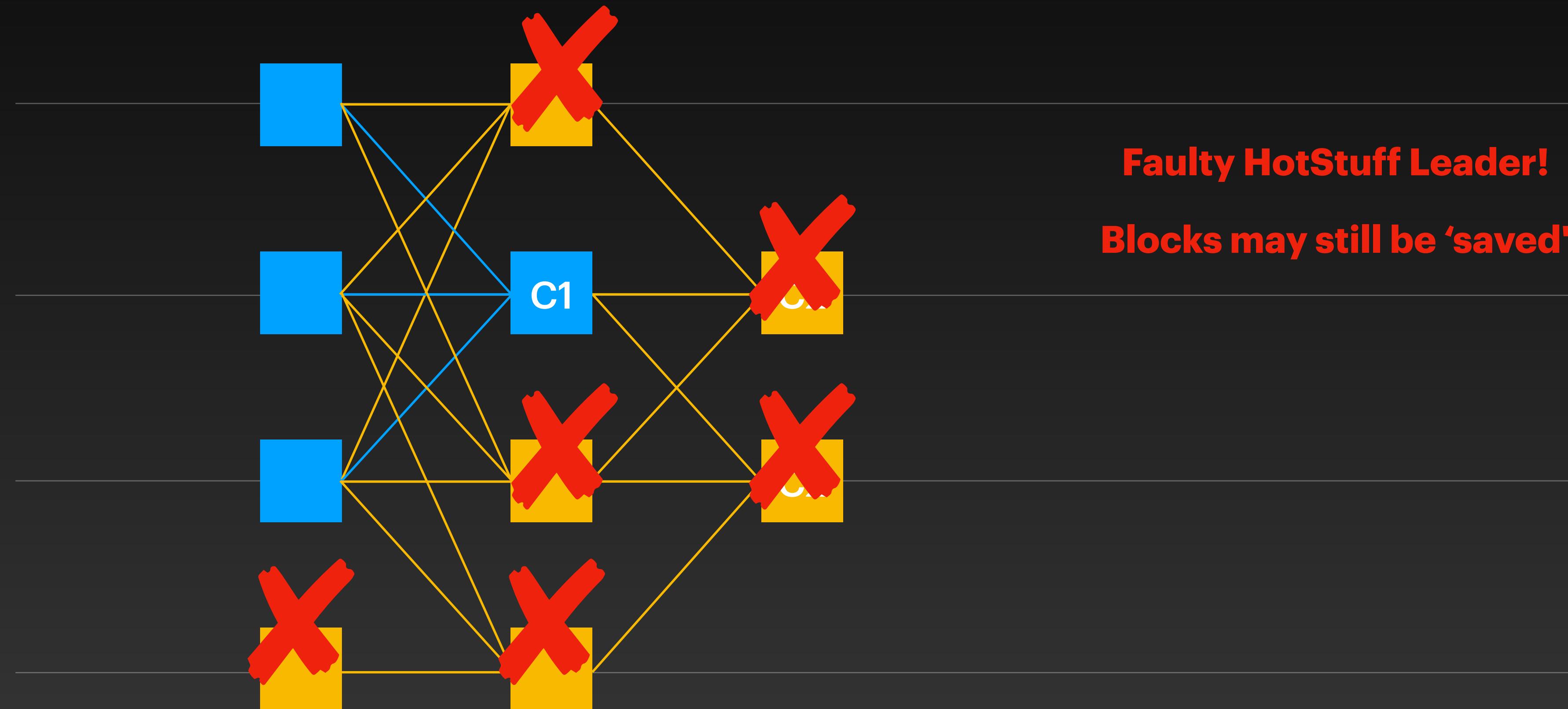
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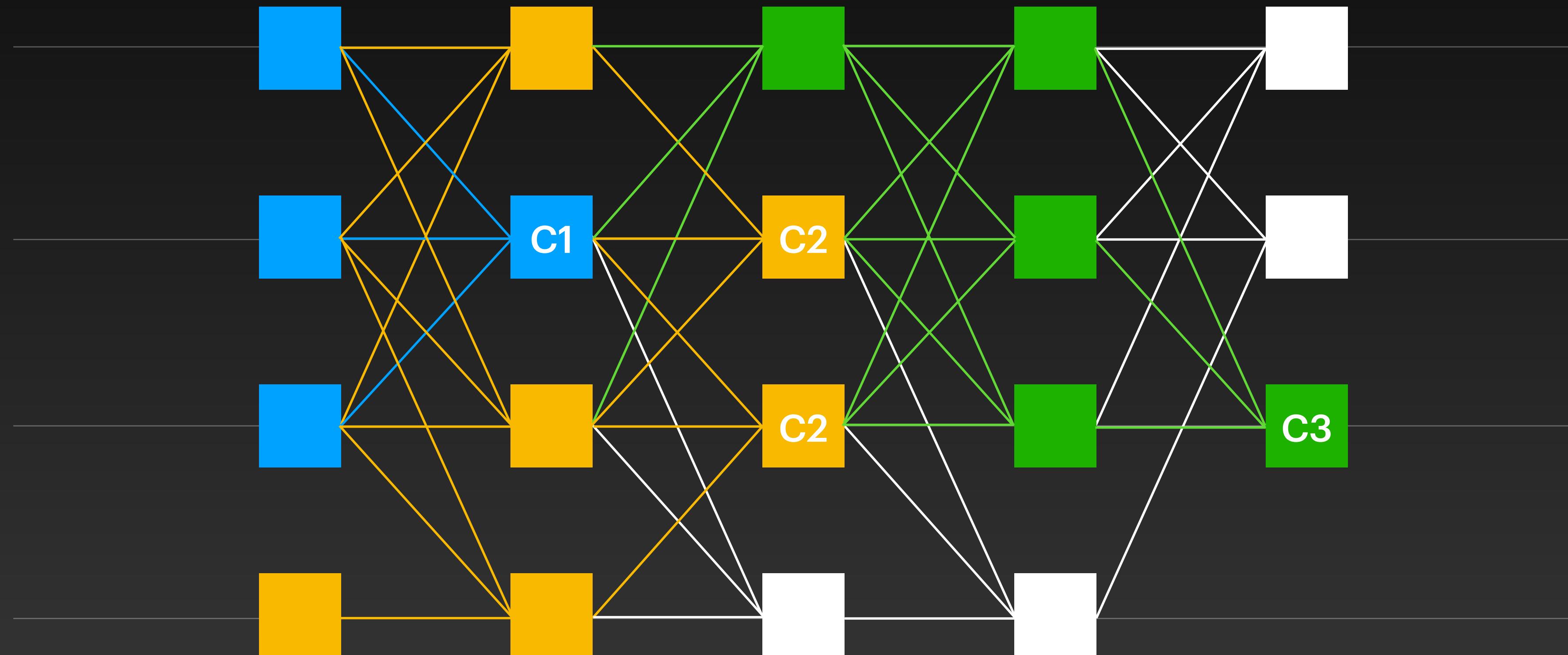
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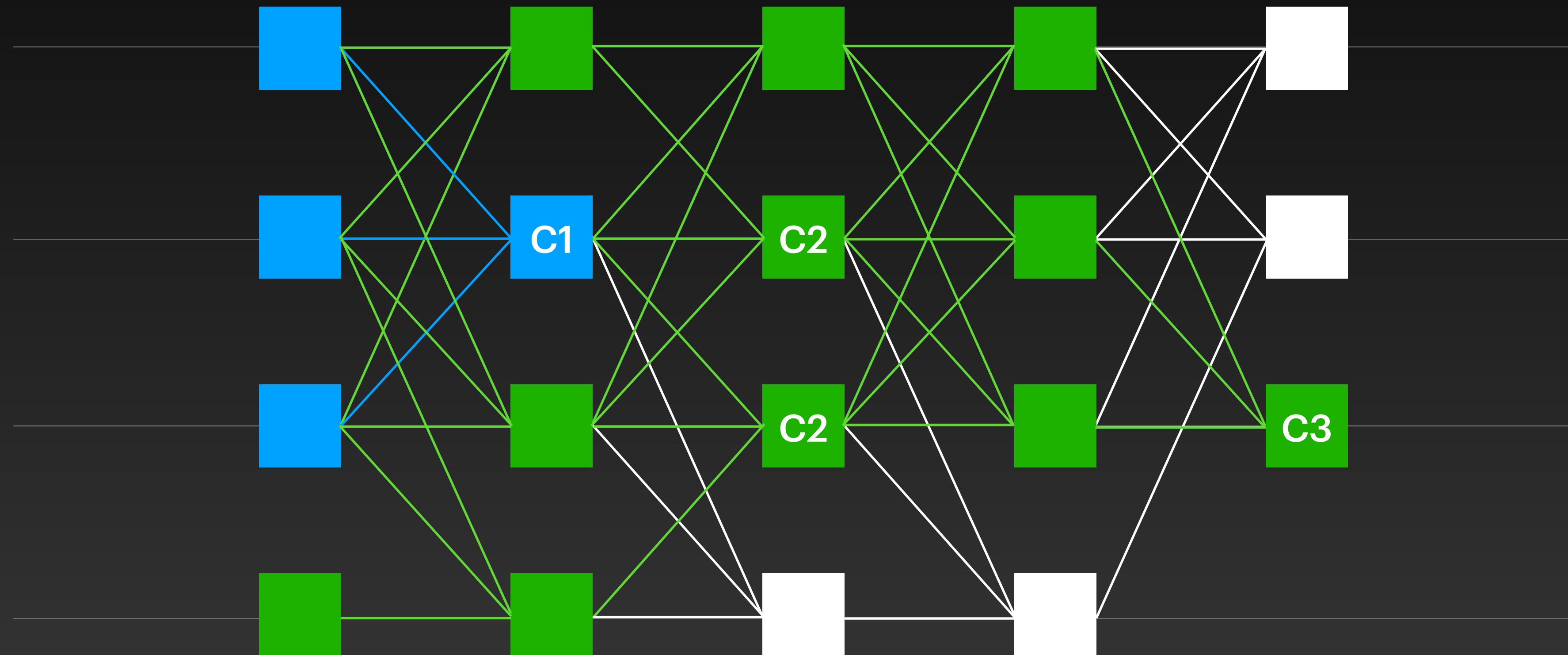
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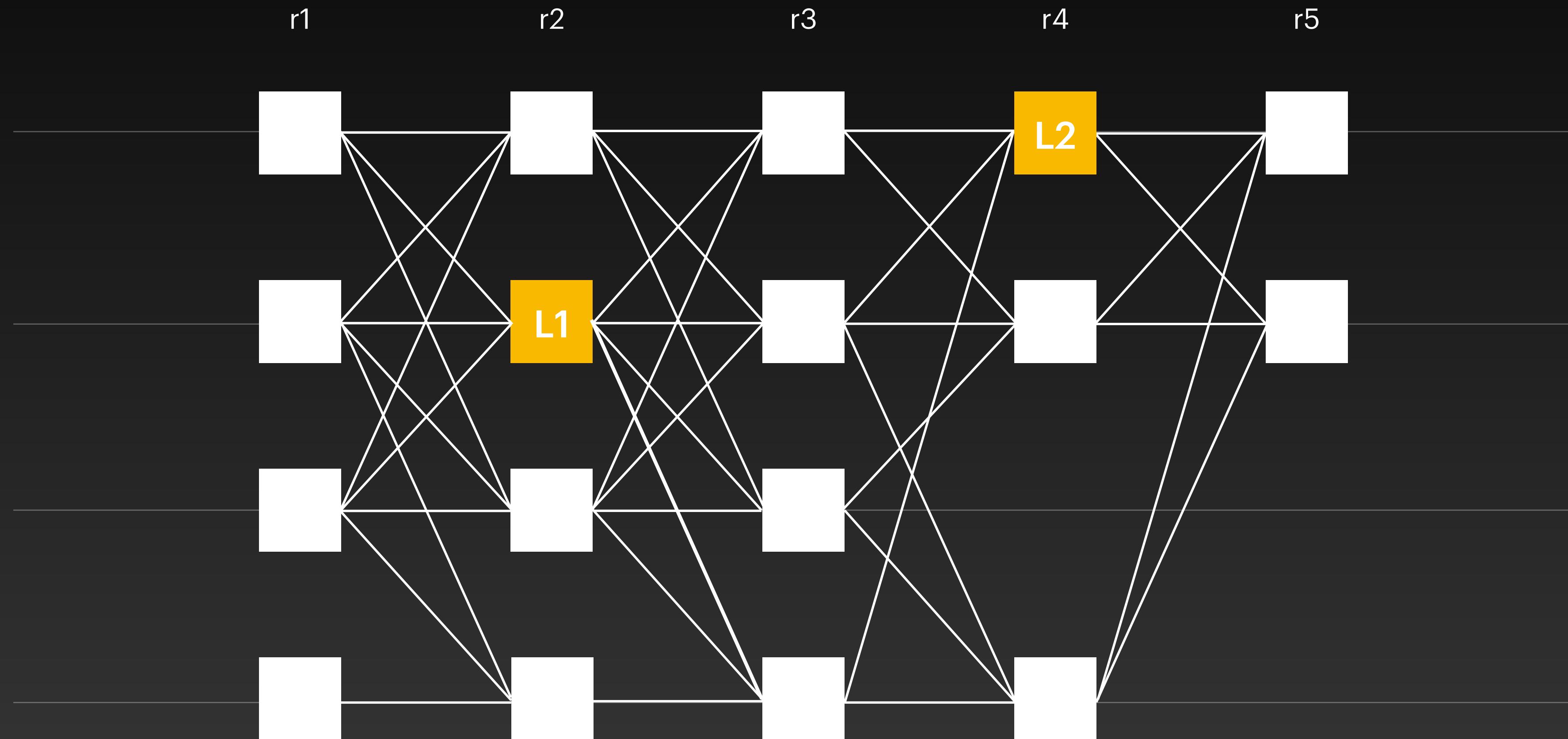


# Modified Narwhal

Adapt Narwhal for partial-synchronous networks

# Modified Narwhal

Even rounds: wait for the leader (or to timeout)



# Bullshark

Zero-message partially-synchronous consensus

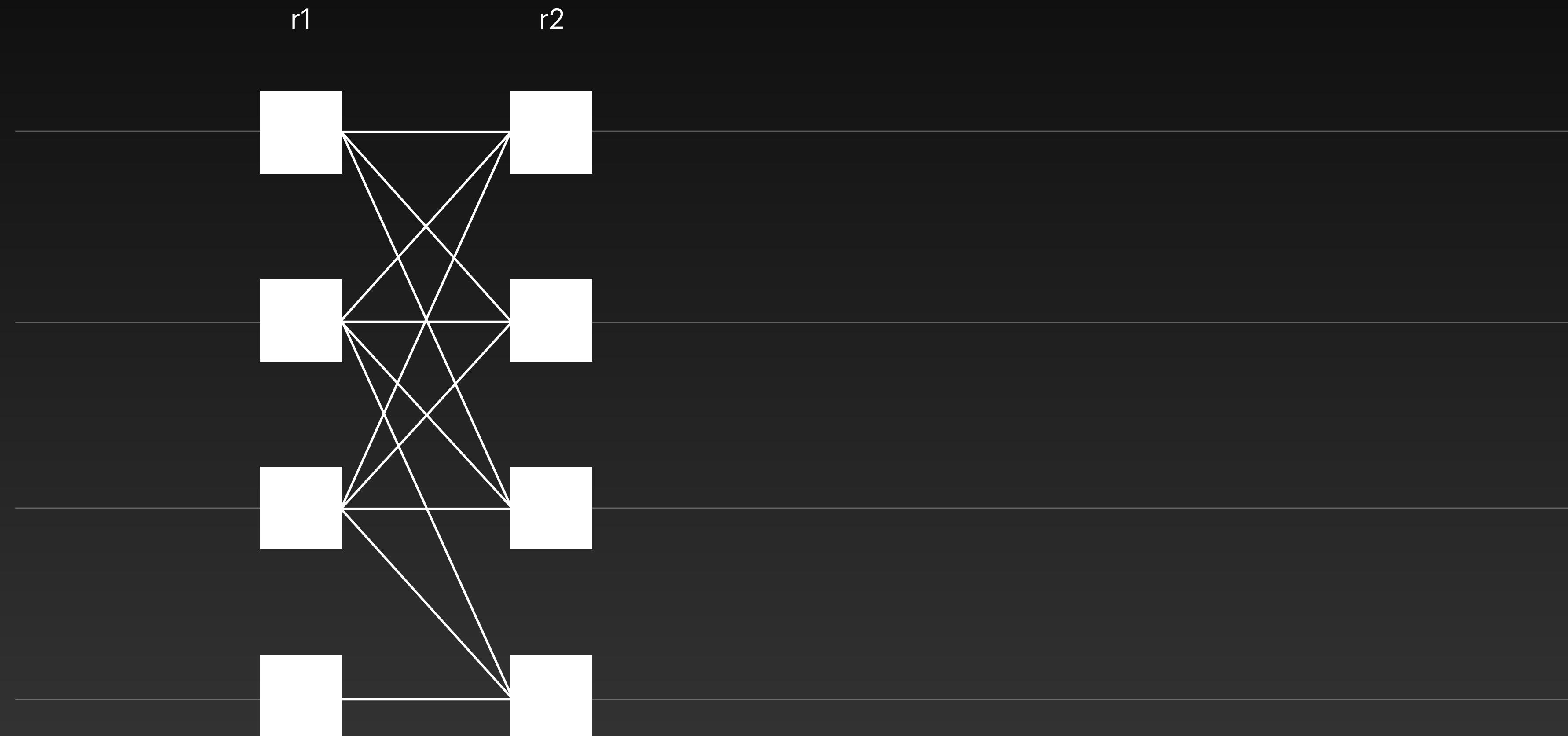
# Bullshark

Zero-message partially-synchronous consensus

\* without asynchronous fallback

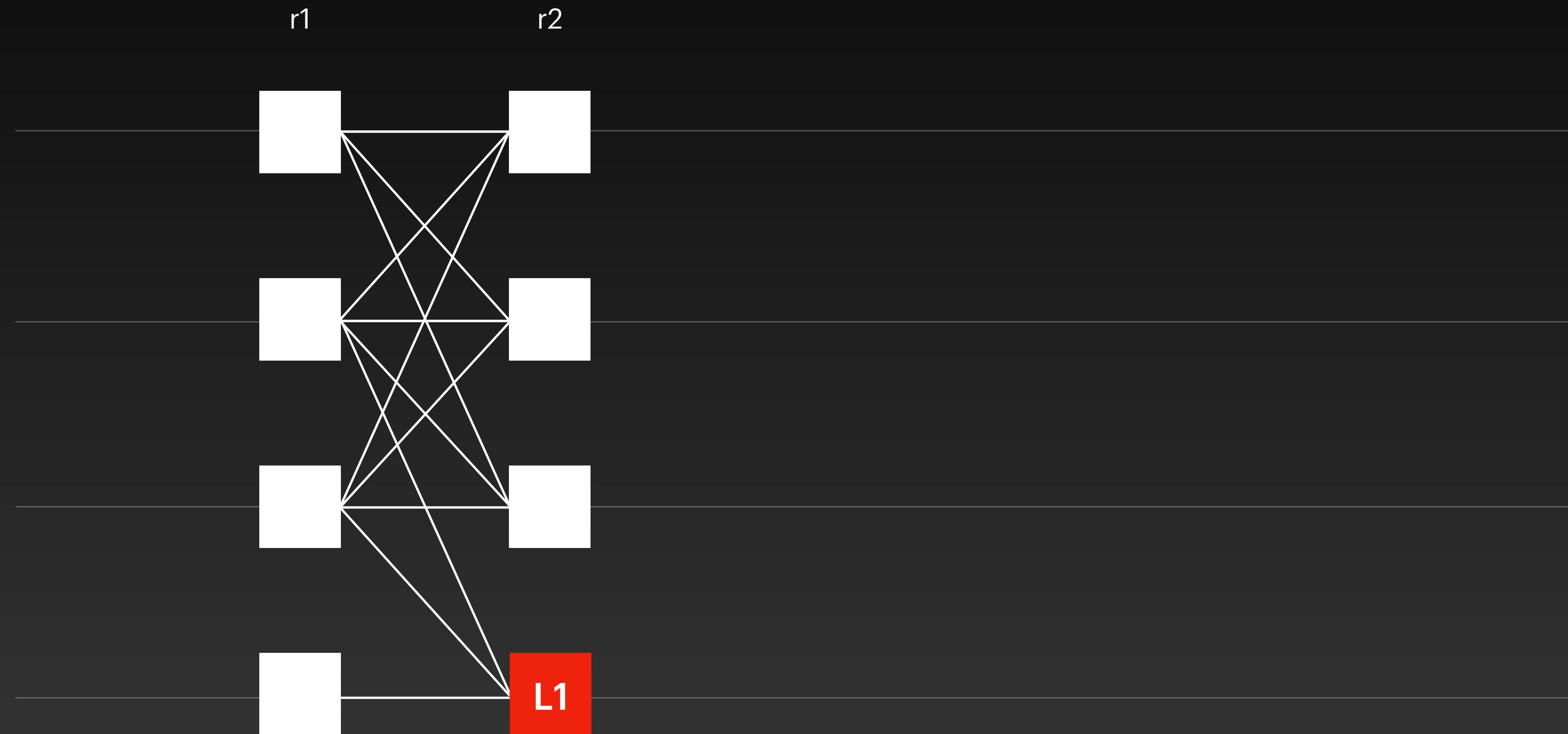
# Bullshark

## Just interpret the DAG



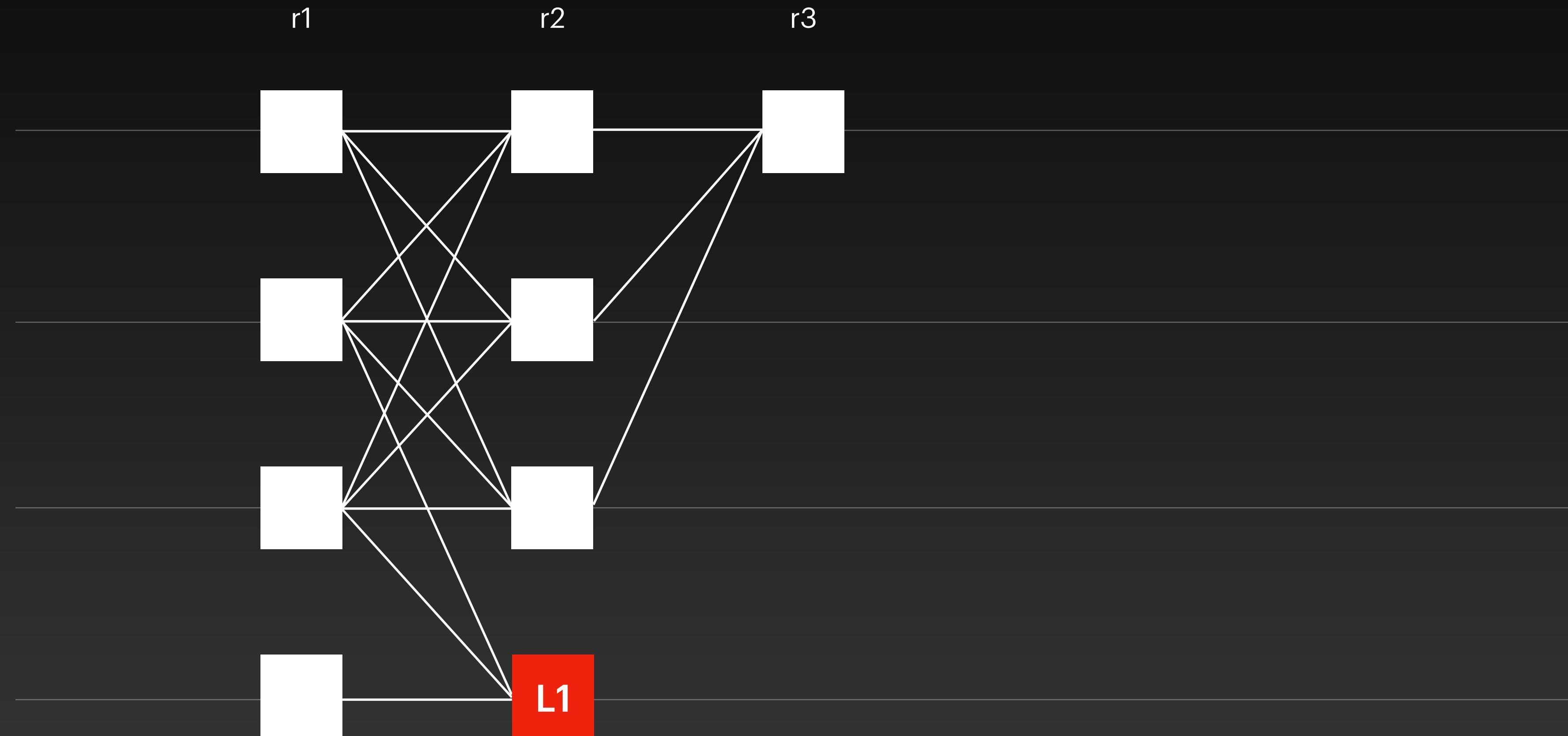
# Bullshark

## Deterministic leader every 2 rounds



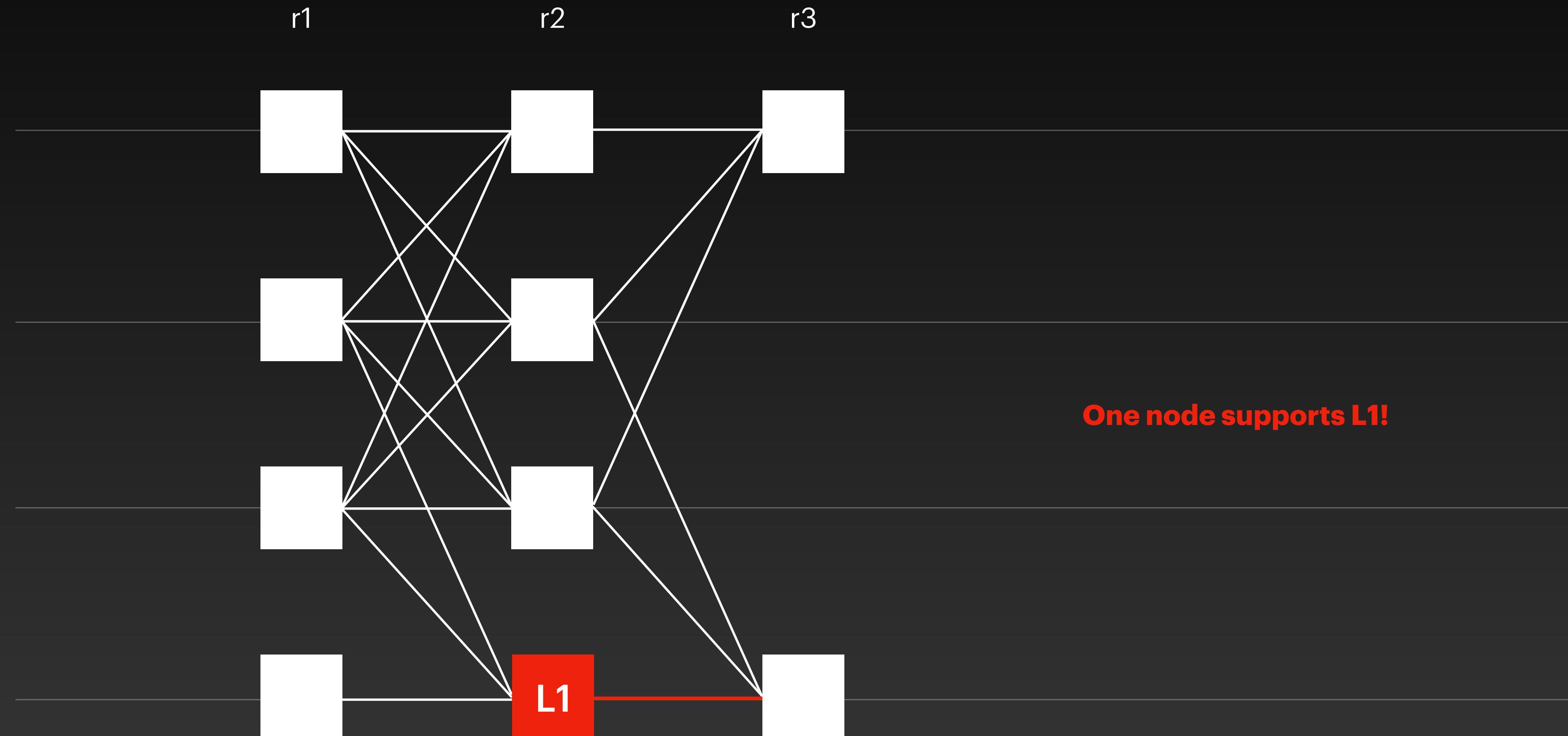
# Bullshark

## The leader needs $f+1$ links from round $r$



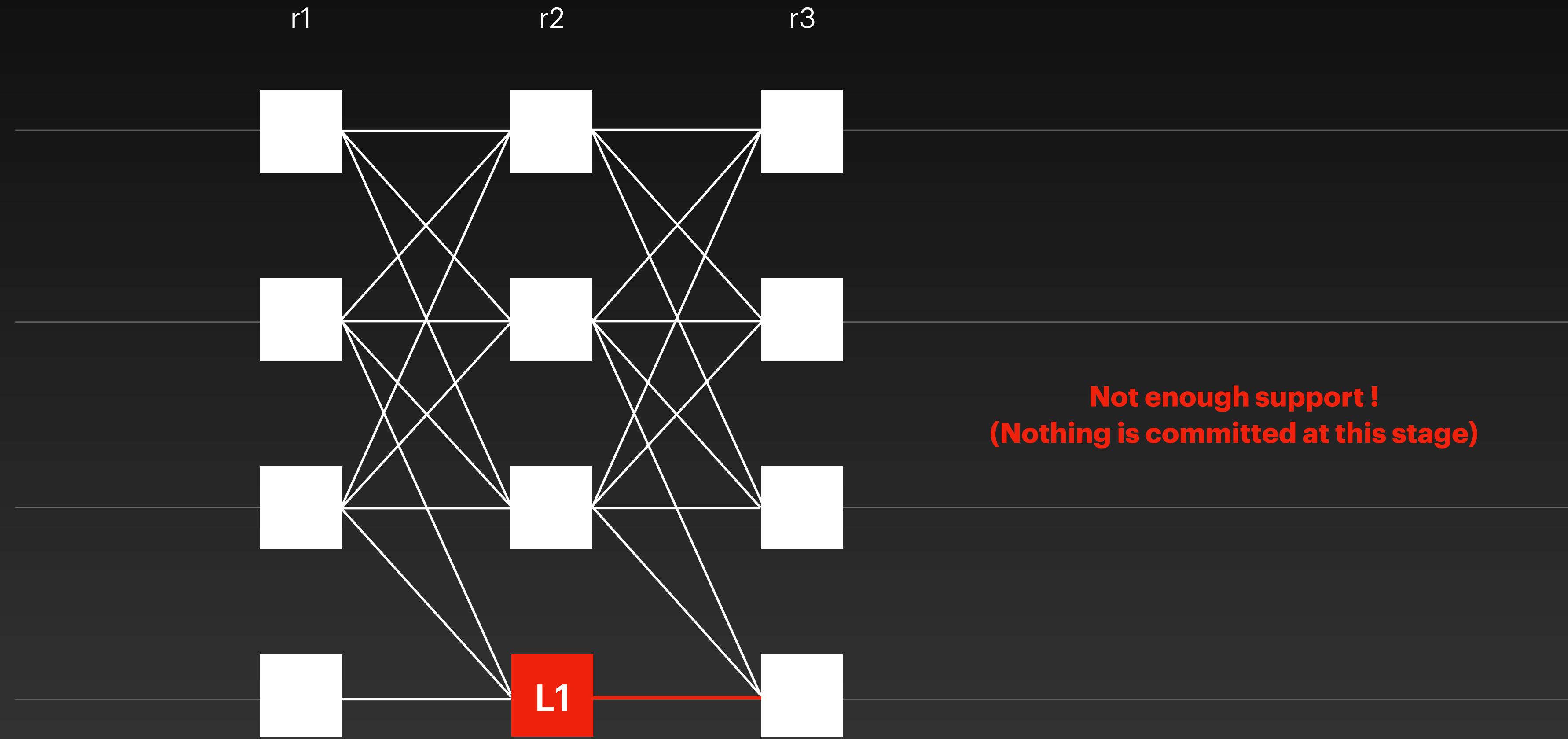
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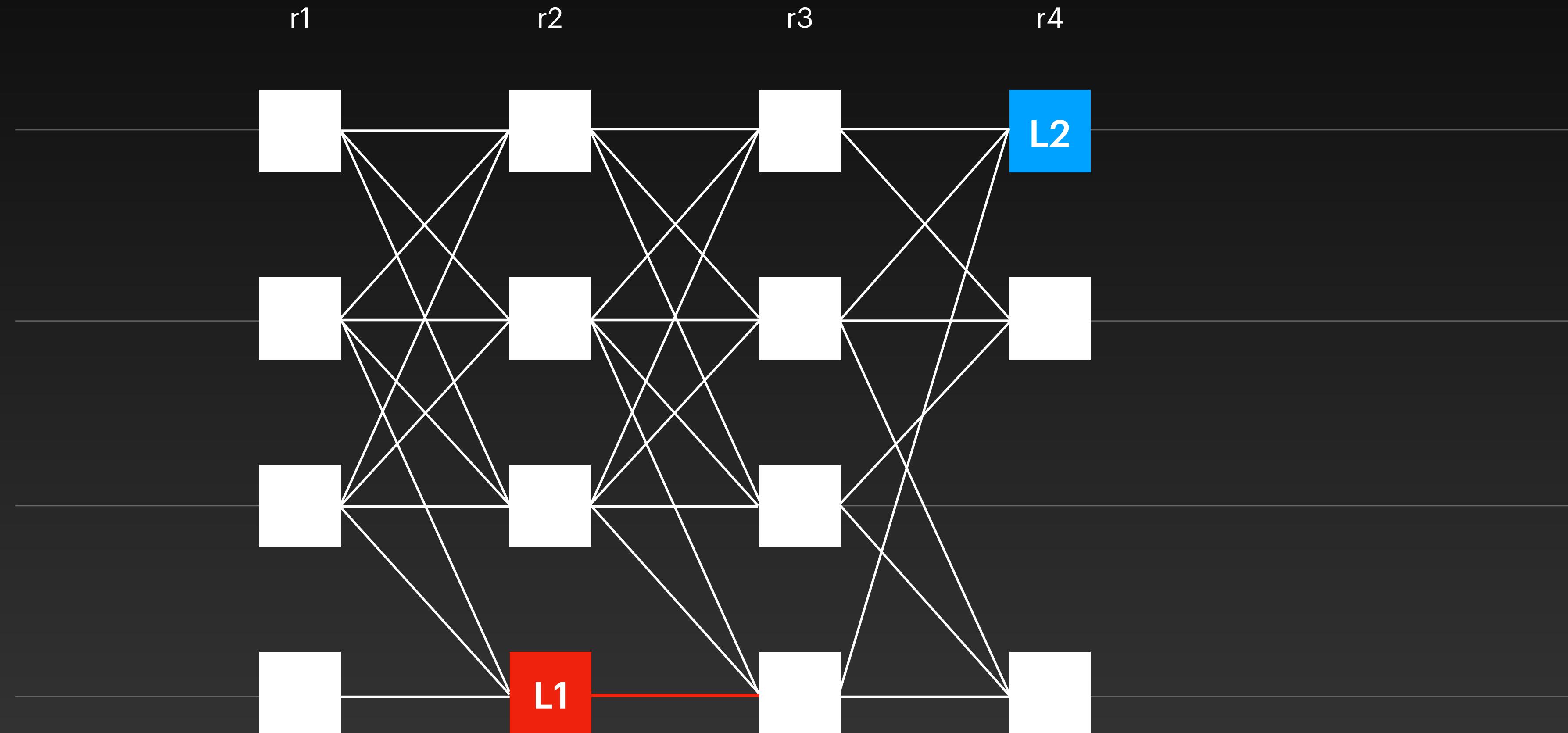
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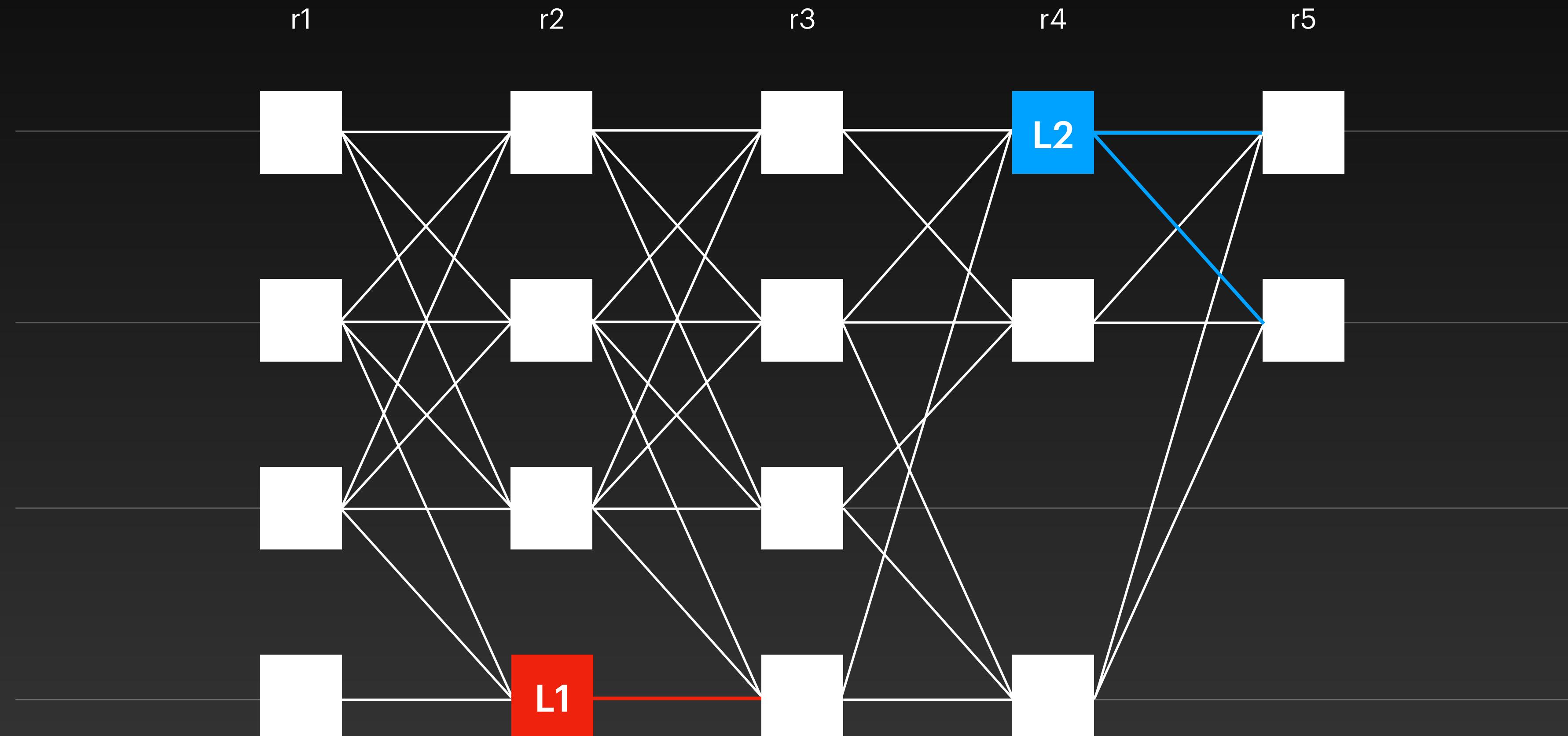
# Bullshark

## Elect the leader of r4



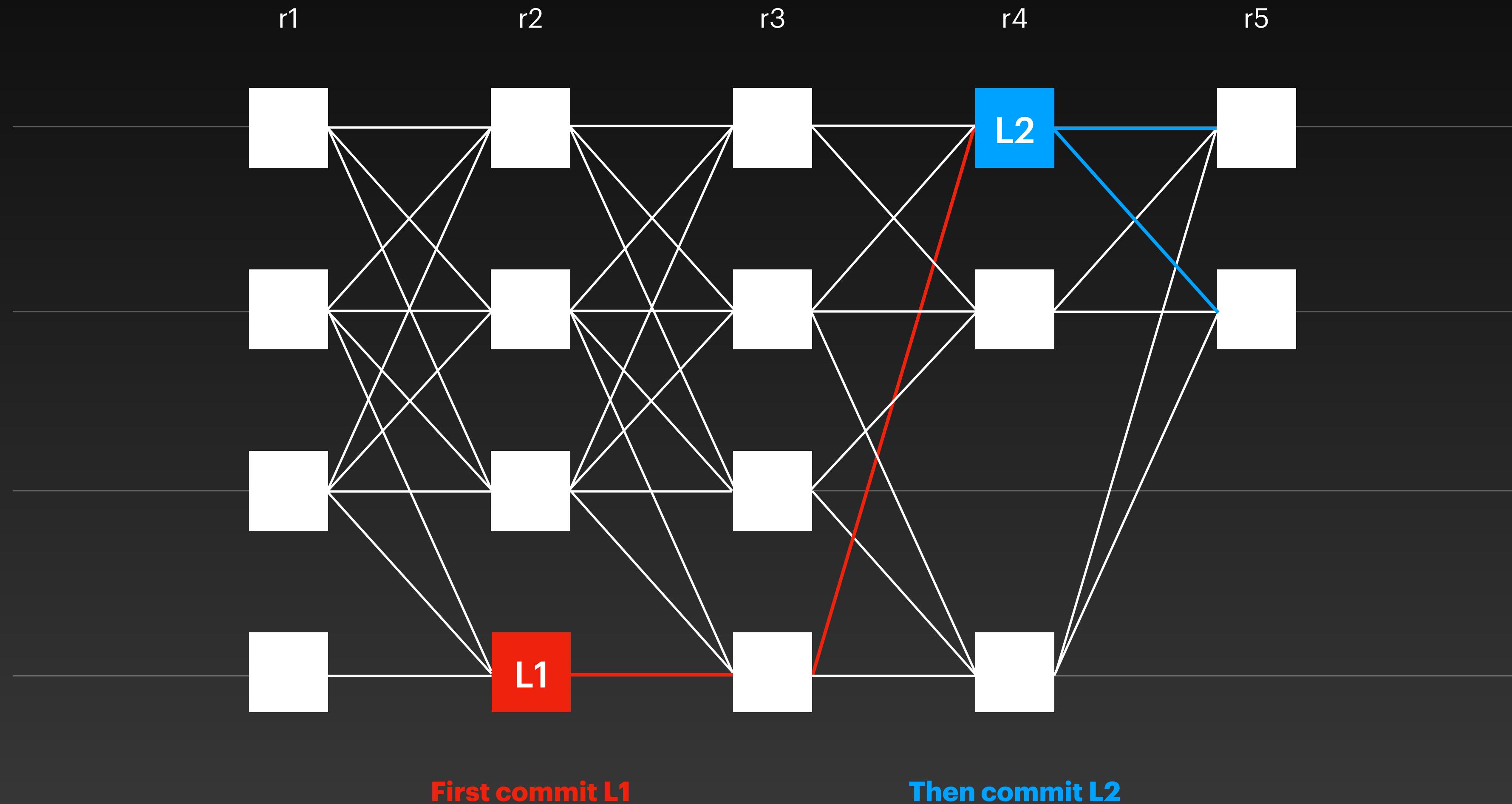
# Bullshark

## Leader L2 has enough support



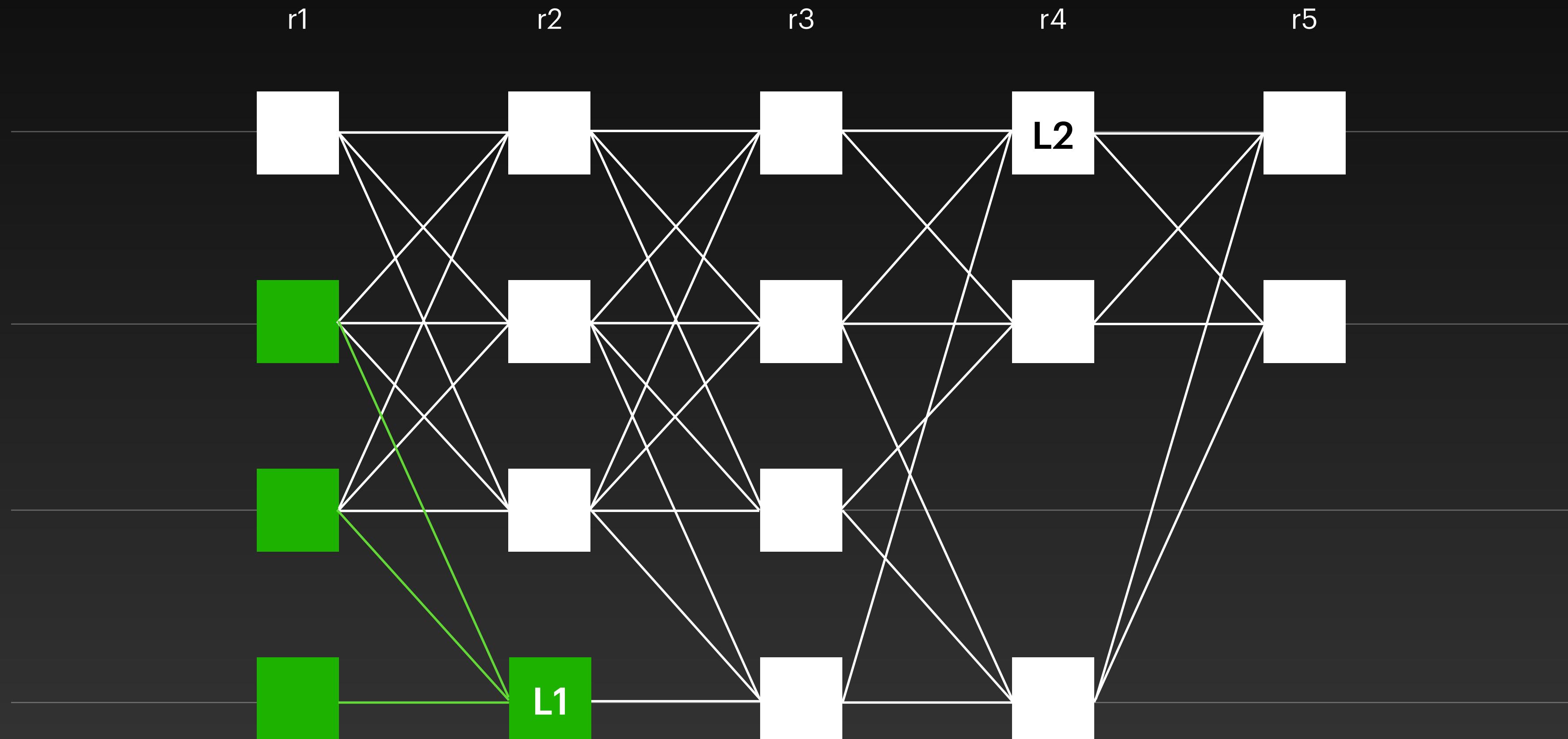
# Bullshark

## Leader L2 has links to leader L1



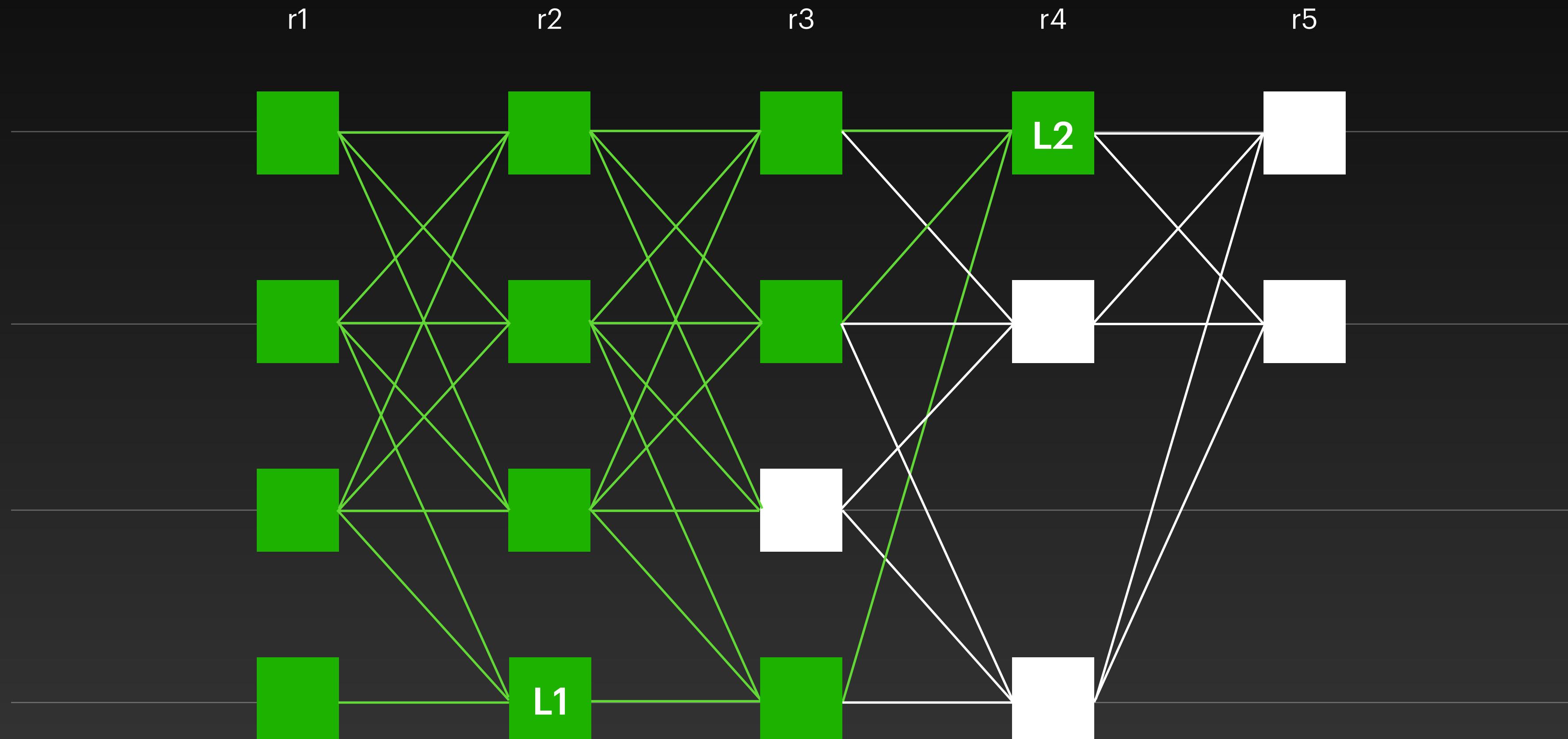
# Bullshark

## Commit all the sub-DAG of the leader



# Bullshark

## Commit all the sub-DAG of the leader



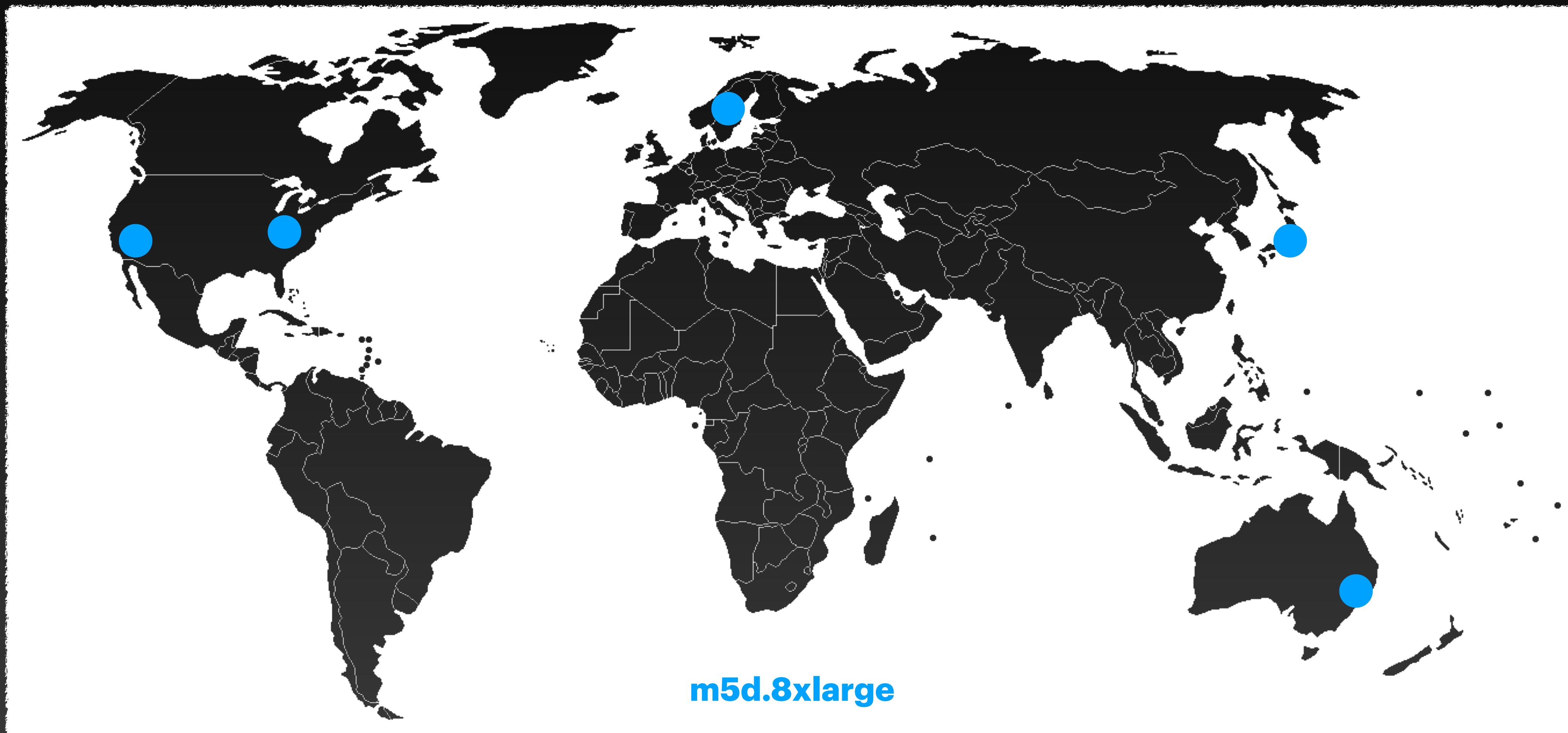
# Implementation

- Written in Rust
- Networking: Tokio (TCP)
- Storage: RocksDB
- Cryptography: ed25519-dalek

<https://github.com/asonnino/narwhal>

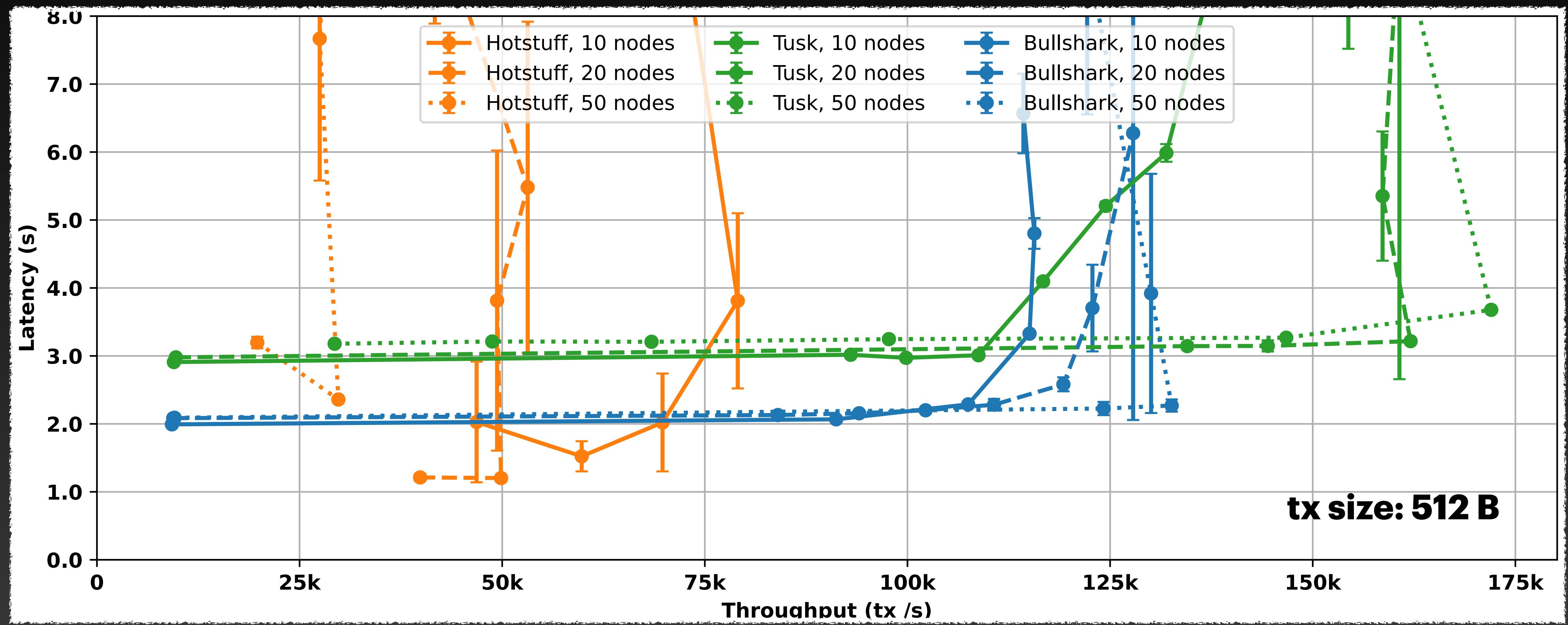
# Evaluation

## Experimental setup on AWS



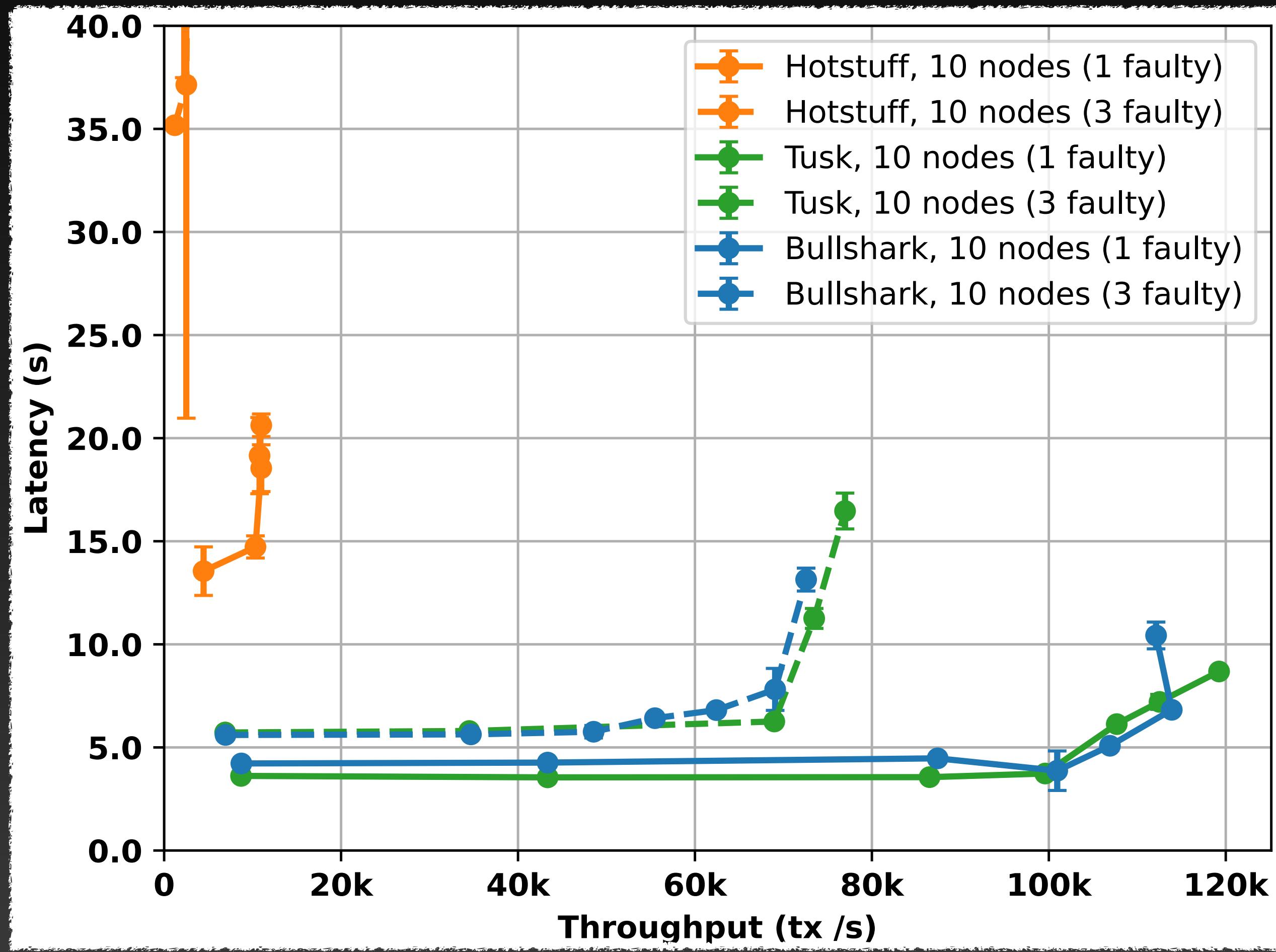
# Evaluation

## Throughput latency graph



# Evaluation

## Performance under faults



# Summary

## Bullshark

- Zero-message overhead, no view-change, no common-coin
- Disseminate data with Narwhal, exploits periods of synchrony
- **Paper:** <https://sonnino.com/papers/bullshark.pdf>
- **Code:** <https://github.com/asonnino/narwhal>

# Engineering

Lessons Learned

# Evaluation

## Our biggest mistakes

- 😢 Add crash-recovery after-the-fact
- 😢 Add the synchroniser after-the-fact
- 😢 Add epoch changes after-the-fact
- 😢 Do not benchmark from day 1
- 😢 Start with fancy crypto
- 😢 Hide away serialisation
- 😢 Complex networked systems
- 😢 Isolate modules as in papers
- 😢 (Use grpc and magic network stack)

# Evaluation

## Our biggest mistakes

- ⌚ Add crash-recovery after-the-fact
  - ⌚ Add the synchroniser after-the-fact
  - ⌚ Add epoch changes after-the-fact
- 
- **What is the minimum state you need to persist across crash-recovery?**
  - **The synchroniser will eventually be your bottleneck / source of instability**
  - **Epoch changes are more complex than they look (sync new validators/ update configs from chain) — Advise: kill the node and reboot it.**

# Evaluation

## Our biggest mistakes

- ⌚ Add crash-recovery after-the-fact
  - ⌚ Add the synchroniser after-the-fact
  - ⌚ Add epoch changes after-the-fact
  - ❗ Do not benchmark from day 1
- 
- **Many concurrency bugs found on WAN benchmarks under high load**
  - **Spent months optimising blinding**

# Evaluation

## Our biggest mistakes

- ⌚ Add crash-recovery after-the-fact
- ⌚ Add the synchroniser after-the-fact
- ⌚ Add epoch changes after-the-fact
- ⌚ Do not benchmark from day 1
- ⌚ Start with fancy crypto
- ⌚ Hide away serialisation
- **Huge complexity; resulted redundant crypto operations**
- **Crypto serialisation was a bottleneck**

# Evaluation

## Our biggest mistakes

- ⌚ Add crash-recovery after-the-fact
  - ⌚ Add the synchroniser after-the-fact
  - ⌚ Add epoch changes after-the-fact
  - ⌚ Do not benchmark from day 1
  - ⌚ Start with fancy crypto
  - ⌚ Hide away serialisation
  - ⌚ Complex networked systems
- **Harder crash-recovery / should start with collocated workers**

# Evaluation

## Our biggest mistakes

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  - ⌚ Add the synchroniser after-the-fact
  - ⌚ Add epoch changes after-the-fact
  - ⌚ Do not benchmark from day 1
  - ⌚ Start with fancy crypto
  - ⌚ Hide away serialisation
  - ⌚ Complex networked systems
- **Debugging / perf improvement nightmare**

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Alberto Sonnino

# **EXTRA**

## **Benchmark of BFT Systems**

# Evaluation

## Typical mistakes

- 😢 Forgo persistent storage
- 😢 Do not sanitise messages
- 😢 Local/LAN benchmark + ping
- 😢 Many nodes on same machine
- 😢 Change parameters across runs
- 😢 Set transaction size to zero
- 😢 Preconfigure nodes with txs
- 😢 Send a single burst of transactions
- 😢 Benchmark for a few seconds
- 😢 Start timer in the batch maker
- 😢 Evaluate latency w/ only the first tx
- 😢 Separate latency and throughput
- 😢 Only benchmark happy path

# Evaluation

## Set the benchmark parameters

Faults: 0 node(s)

Committee size: 10 node(s)

Transaction size: 512 B

# Evaluation

## Set the benchmark parameters

Faults: 0 node(s)

Committee size: 10 node(s)

Transaction size: 512 B

Header size: 1,000 B

Max header delay: 200 ms

GC depth: 50 round(s)

Sync retry delay: 5,000 ms

Sync retry nodes: 3 node(s)

batch size: 500,000 B

Max batch delay: 200 ms

# Evaluation

## Typical mistakes

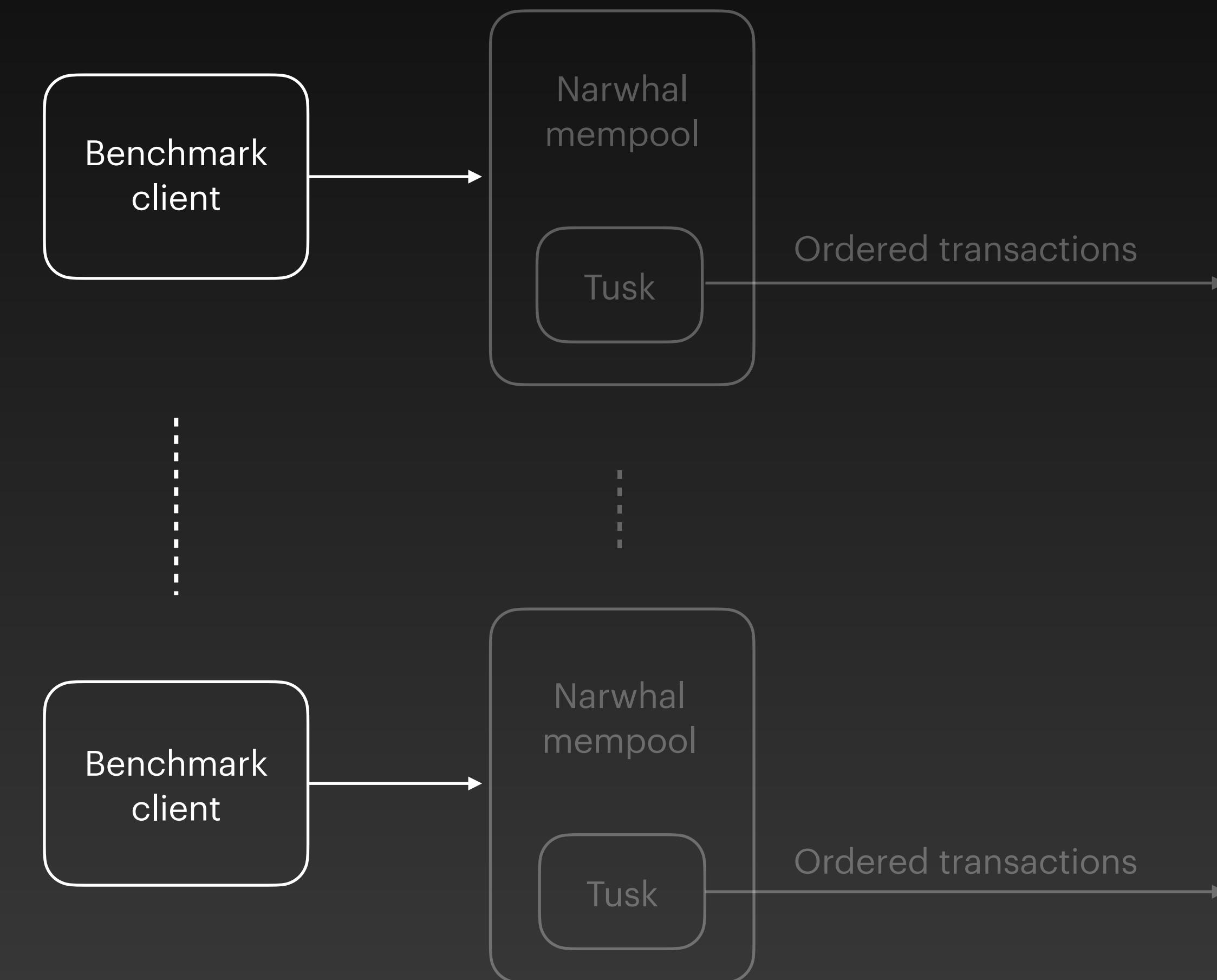
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# Evaluation

## Benchmark clients

Fixed input rate

For a long time  
(minutes)



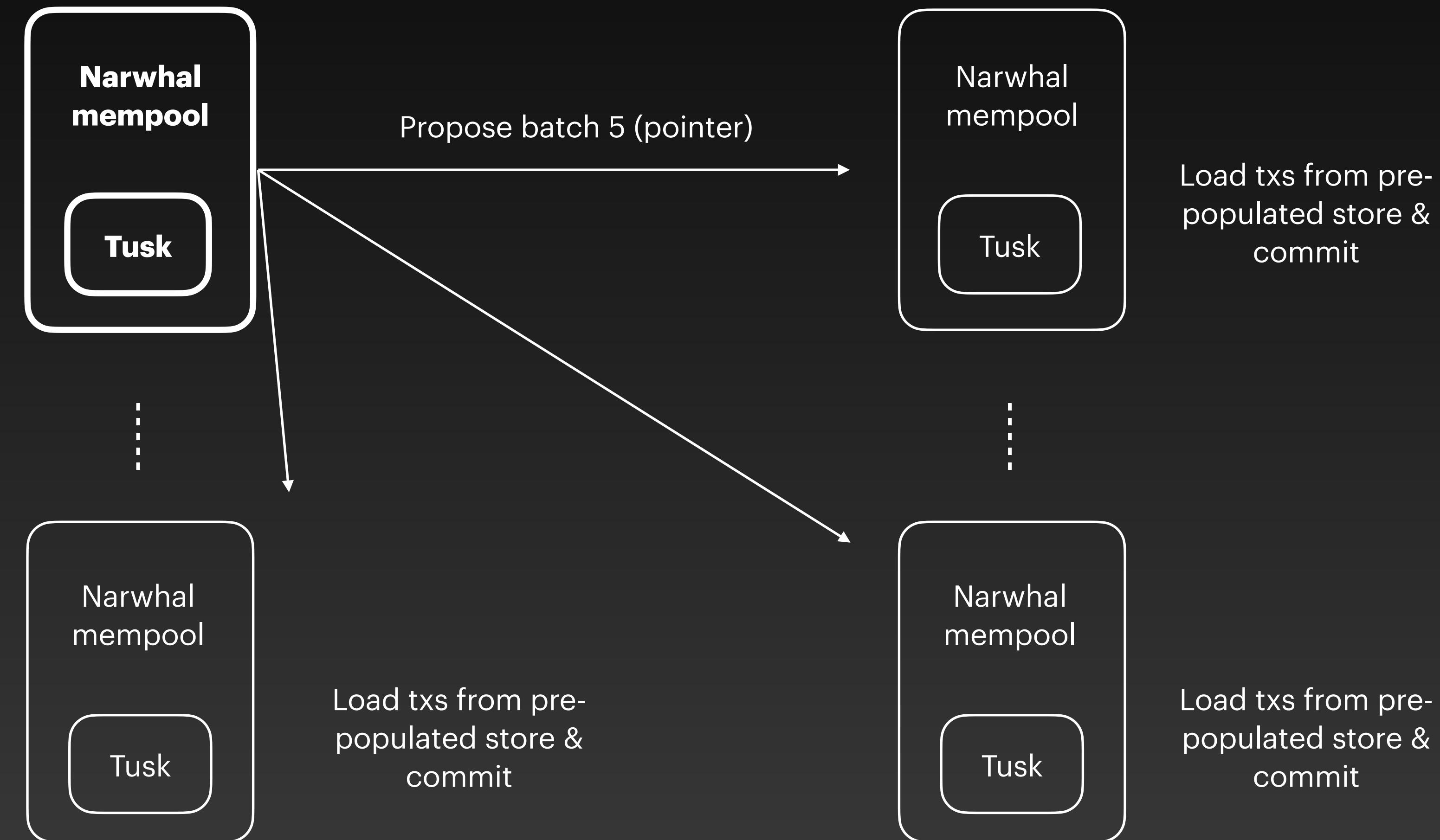
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# Evaluation

## Typical mistake



# Evaluation

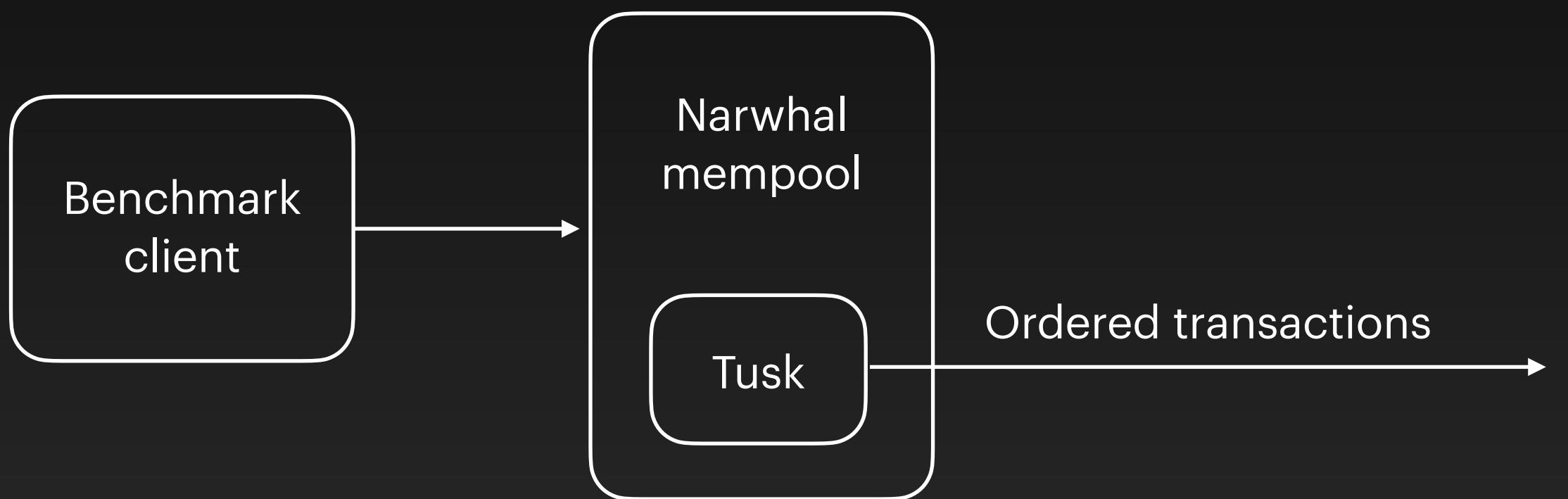
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# Evaluation

## Typical mistake

**send 50k txs  
(once)**

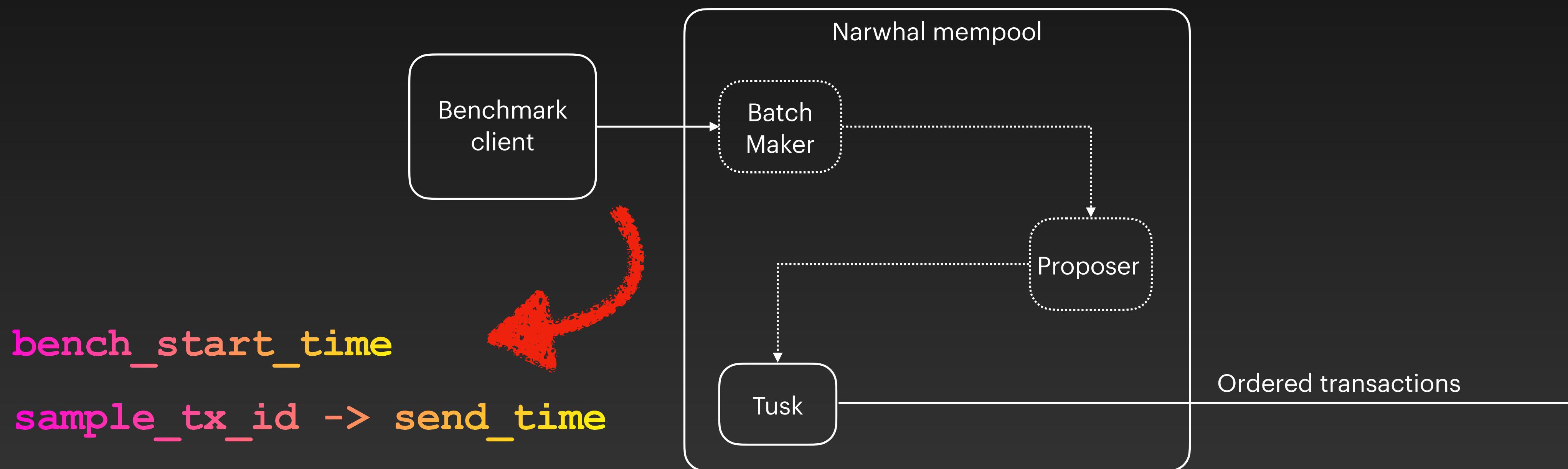


**output after  
400 ms**

😢 **TPS = 50k / 400ms = 125k tx/s** 😢

# Evaluation

## Instrument the codebase

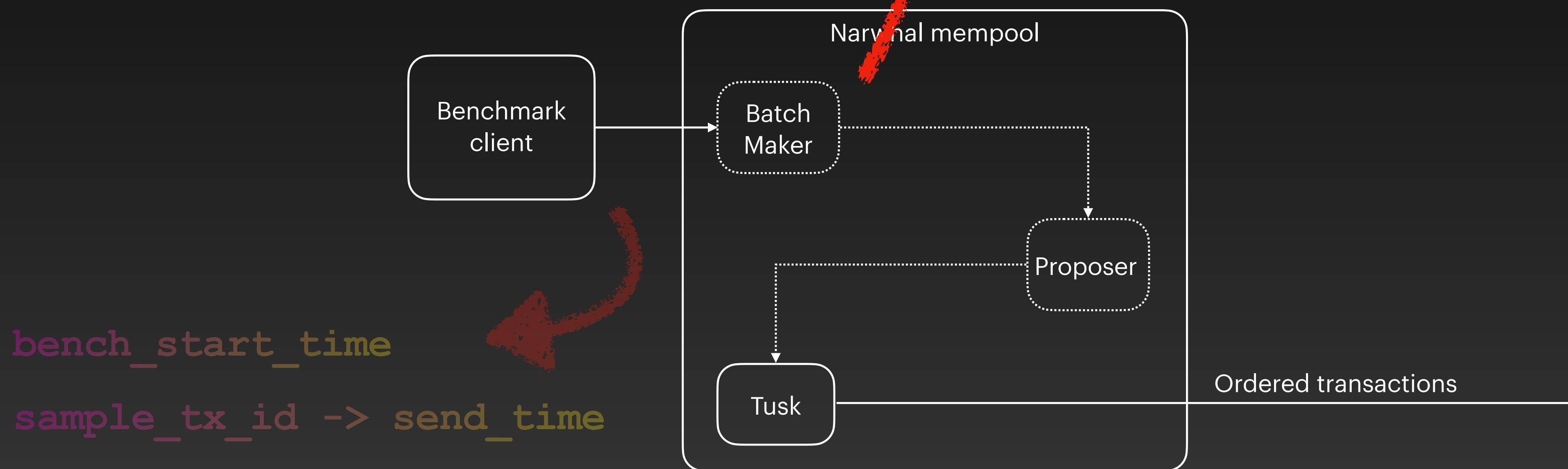


# Evaluation

## Instrument the codebase

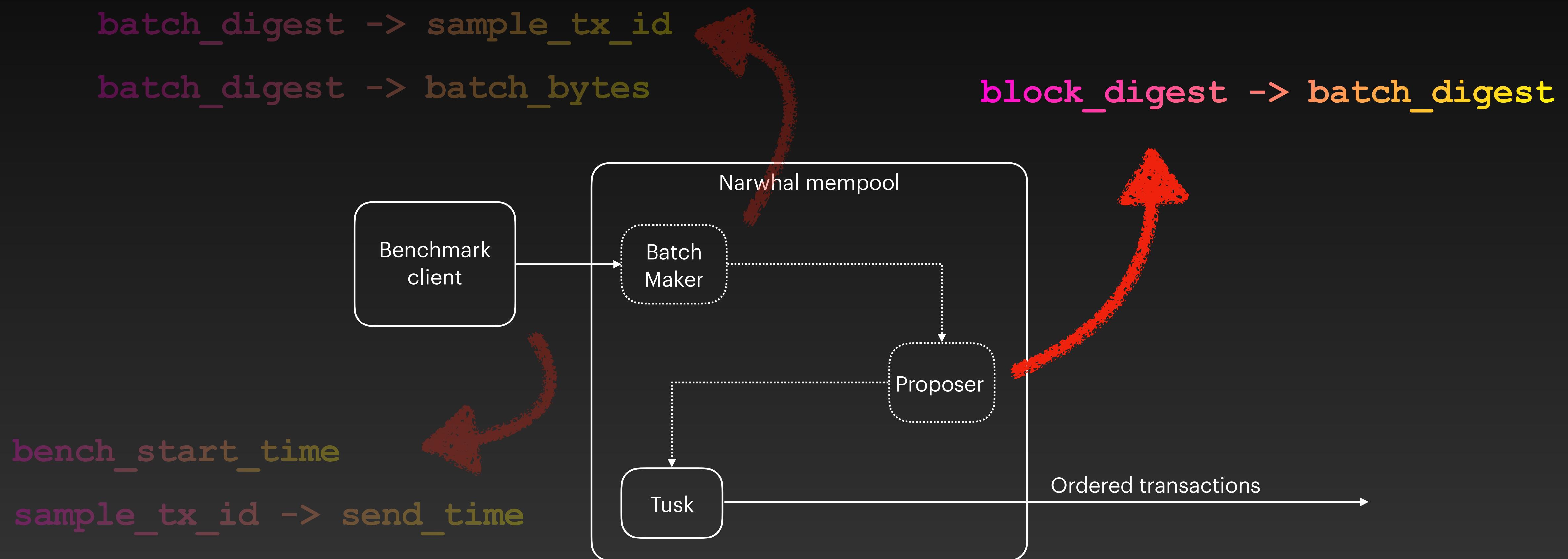
`batch_digest -> sample_tx_id`

`batch_digest -> batch_bytes`



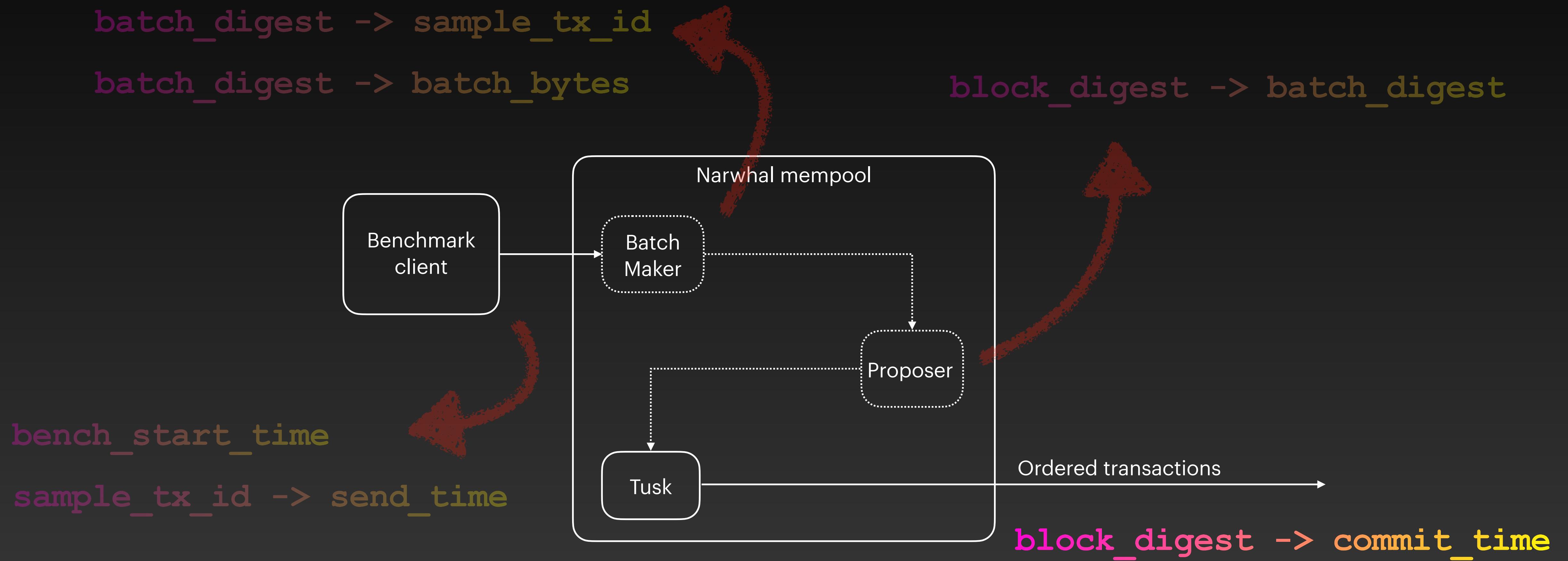
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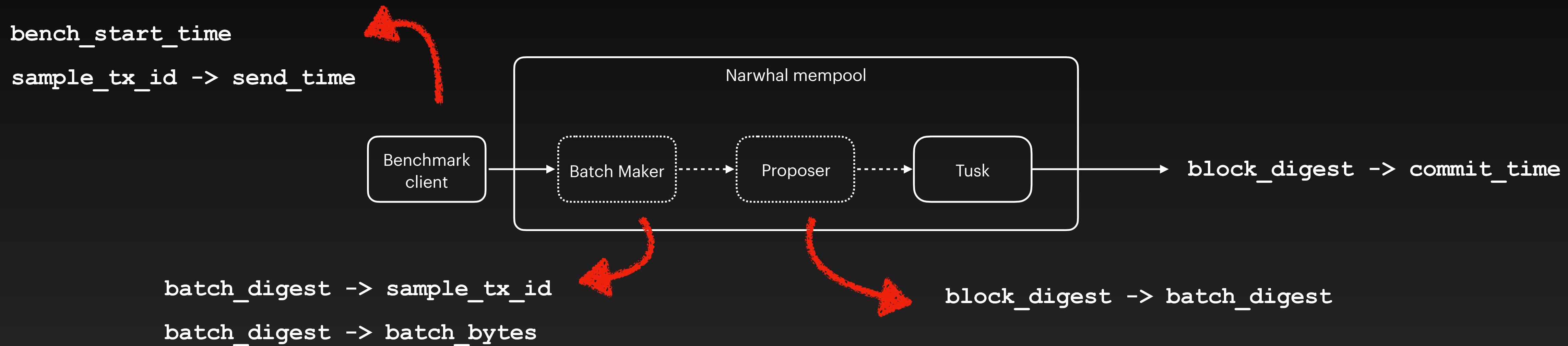
# Evaluation

## Instrument the codebase



# Evaluation

## Compute throughput



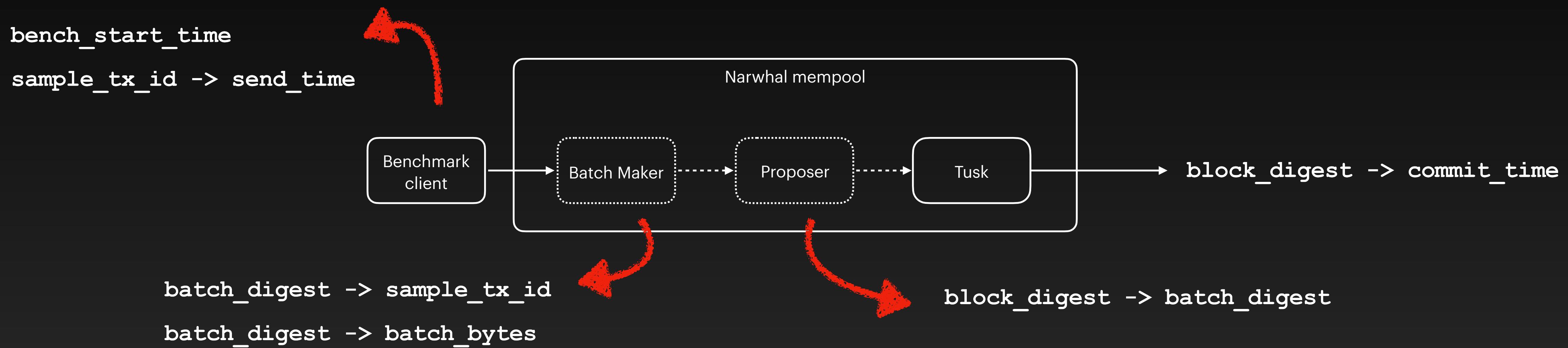
$\text{total\_time} = \text{last\_commit\_time} - \text{bench\_start\_time}$

$\text{BPS} = \text{total\_bytes} / \text{total\_time}$

$\text{TPS} = \text{BPS} / \text{transaction\_size}$

# Evaluation

## Compute latency



**samples = commit\_time - send\_time**

**latency = average(samples)**

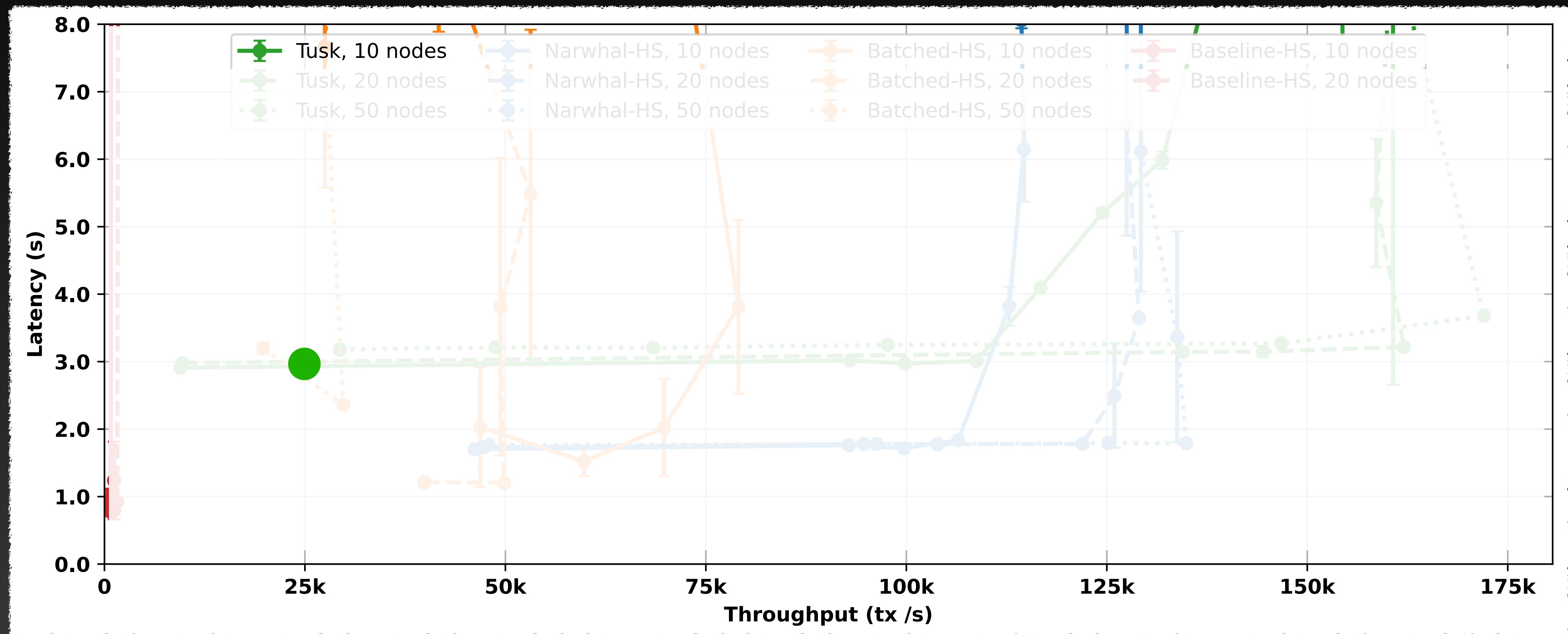
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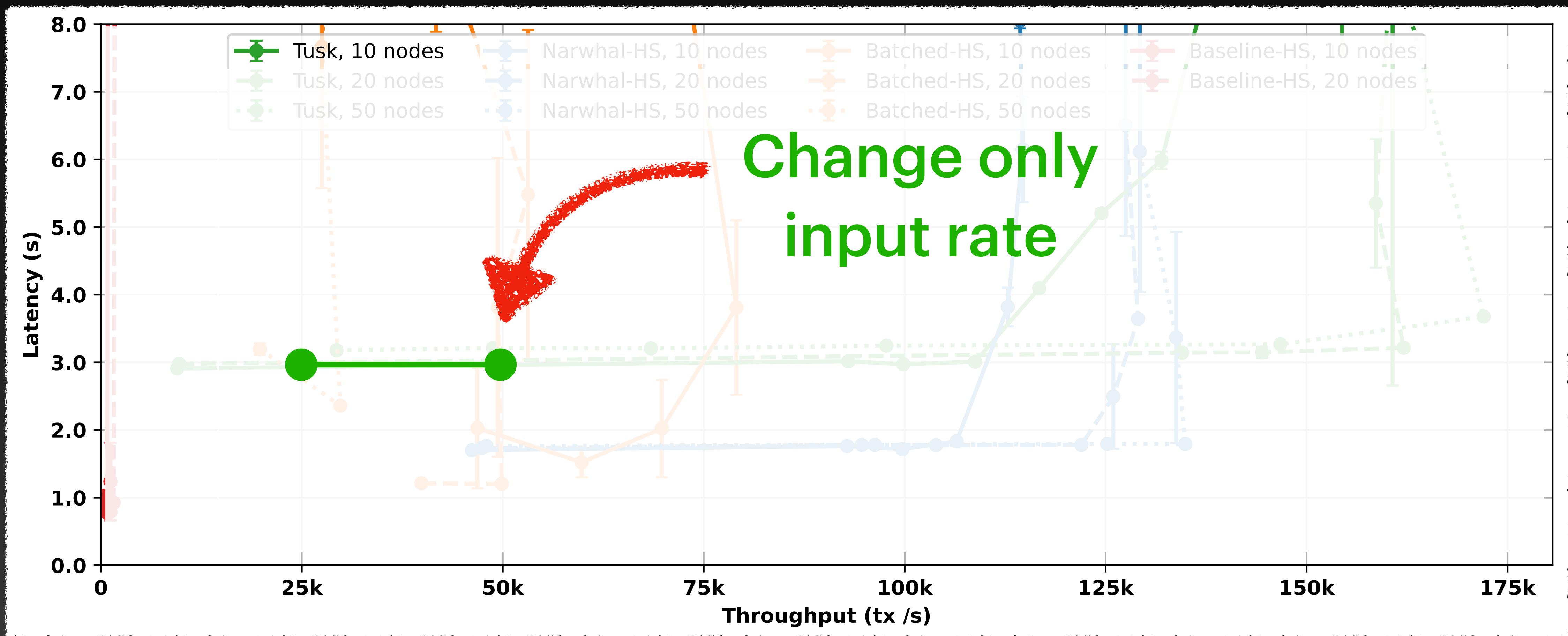
# Evaluation

## Throughput latency graph



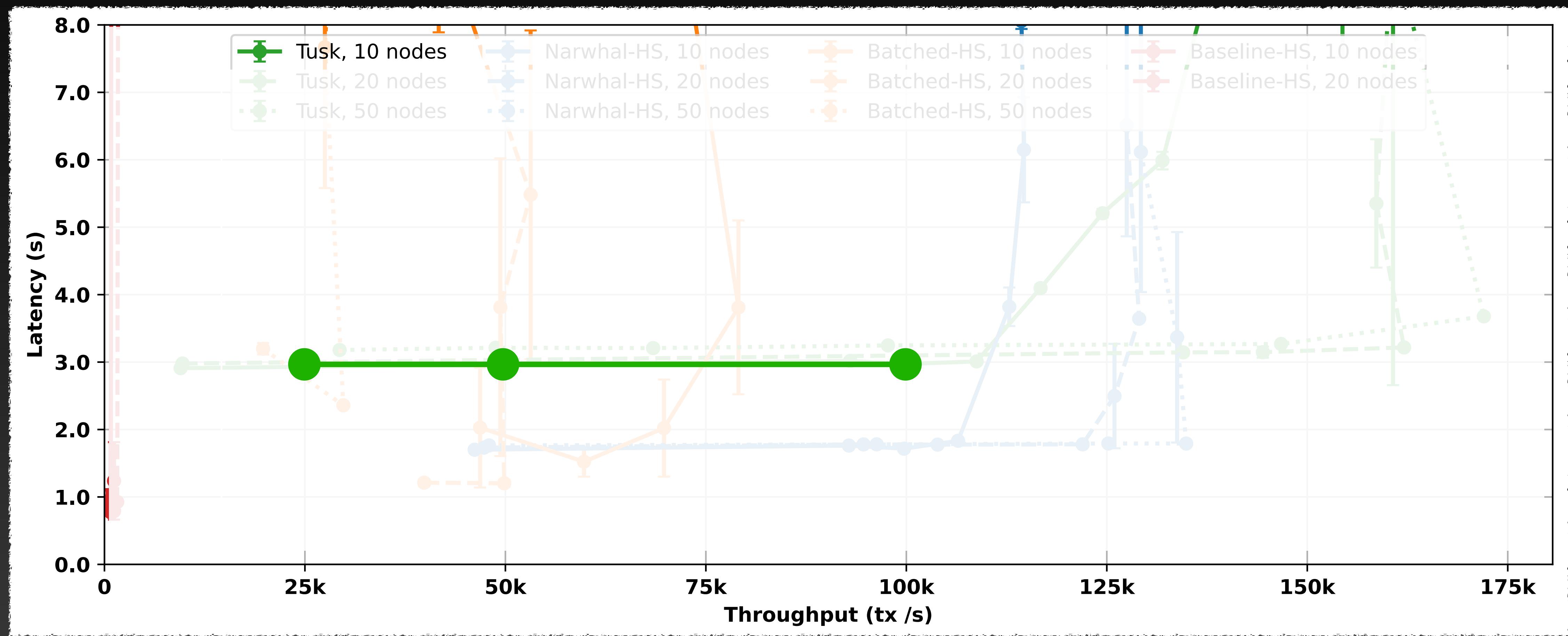
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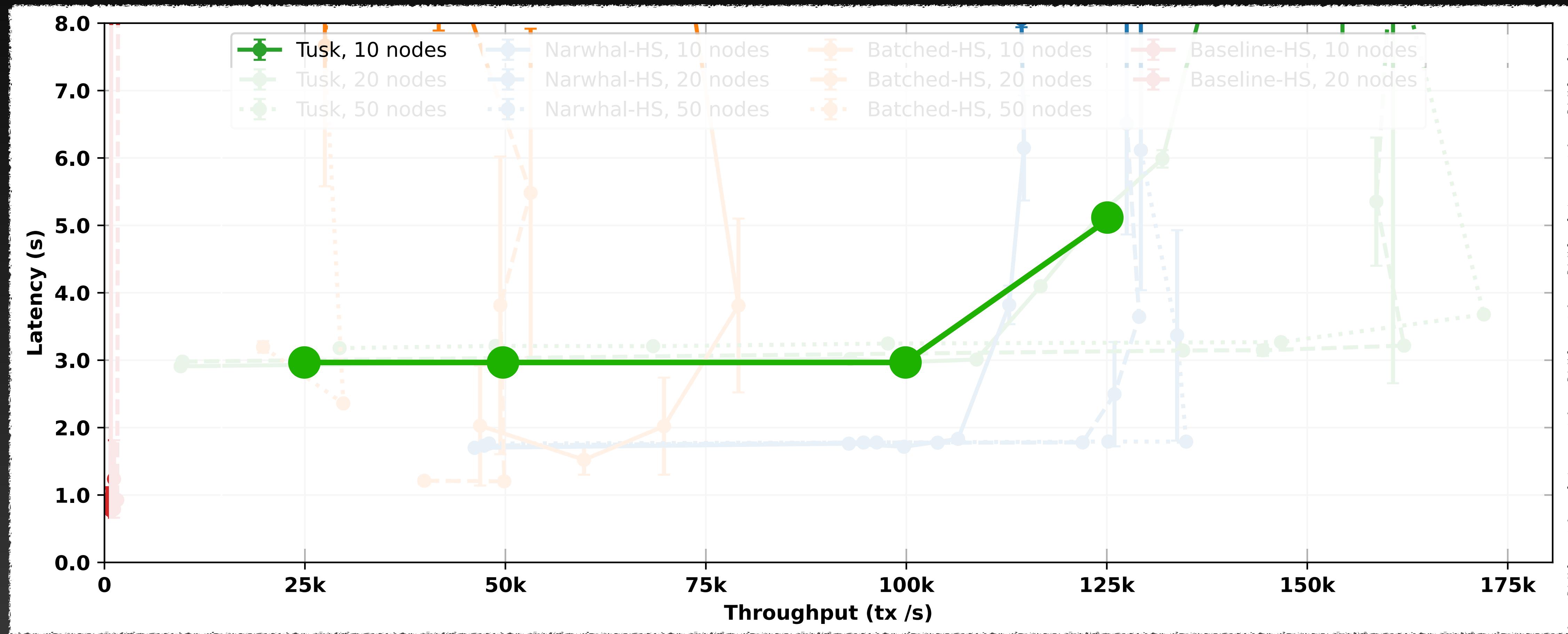
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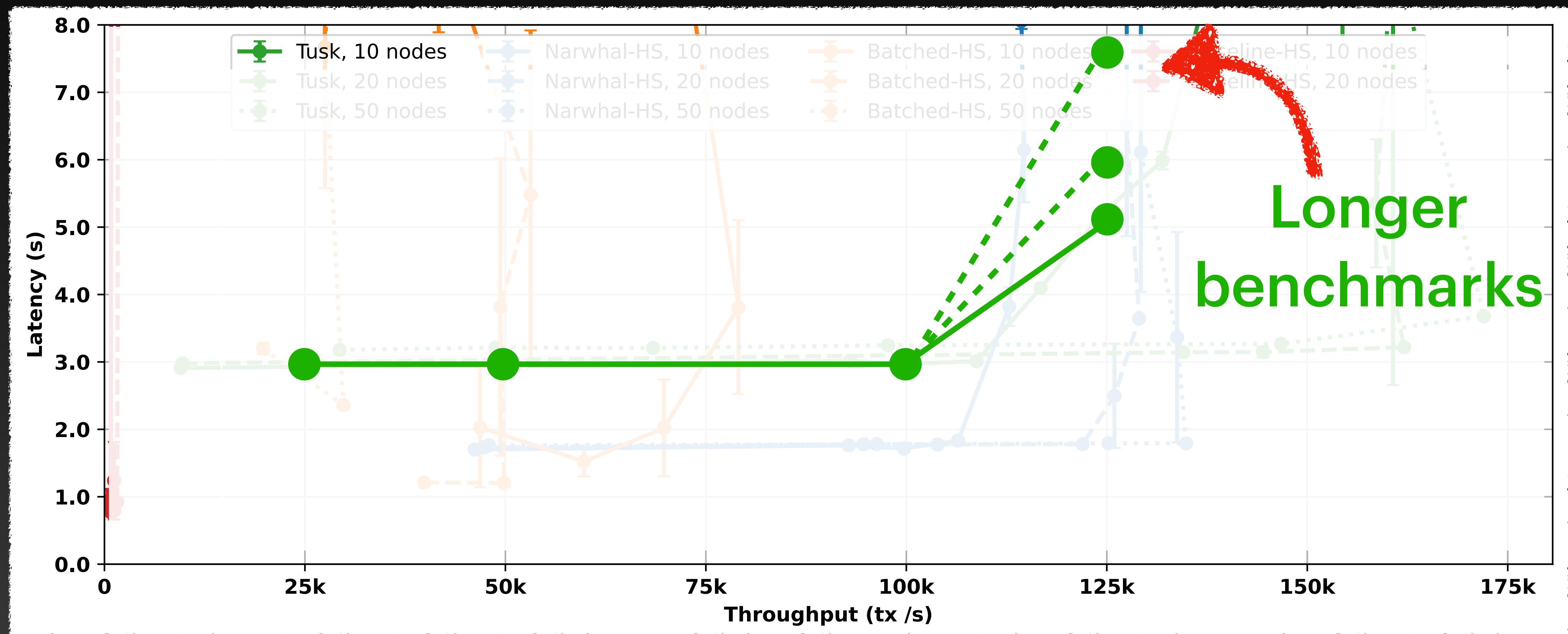
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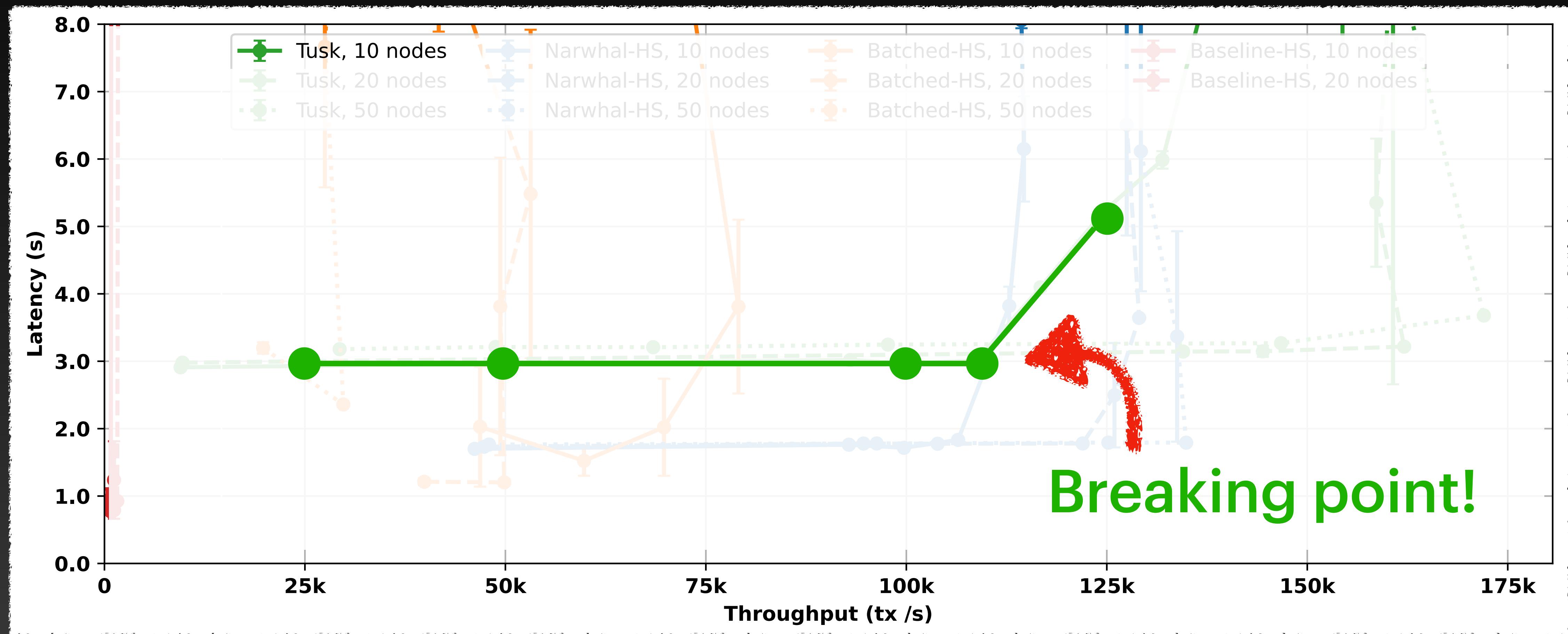
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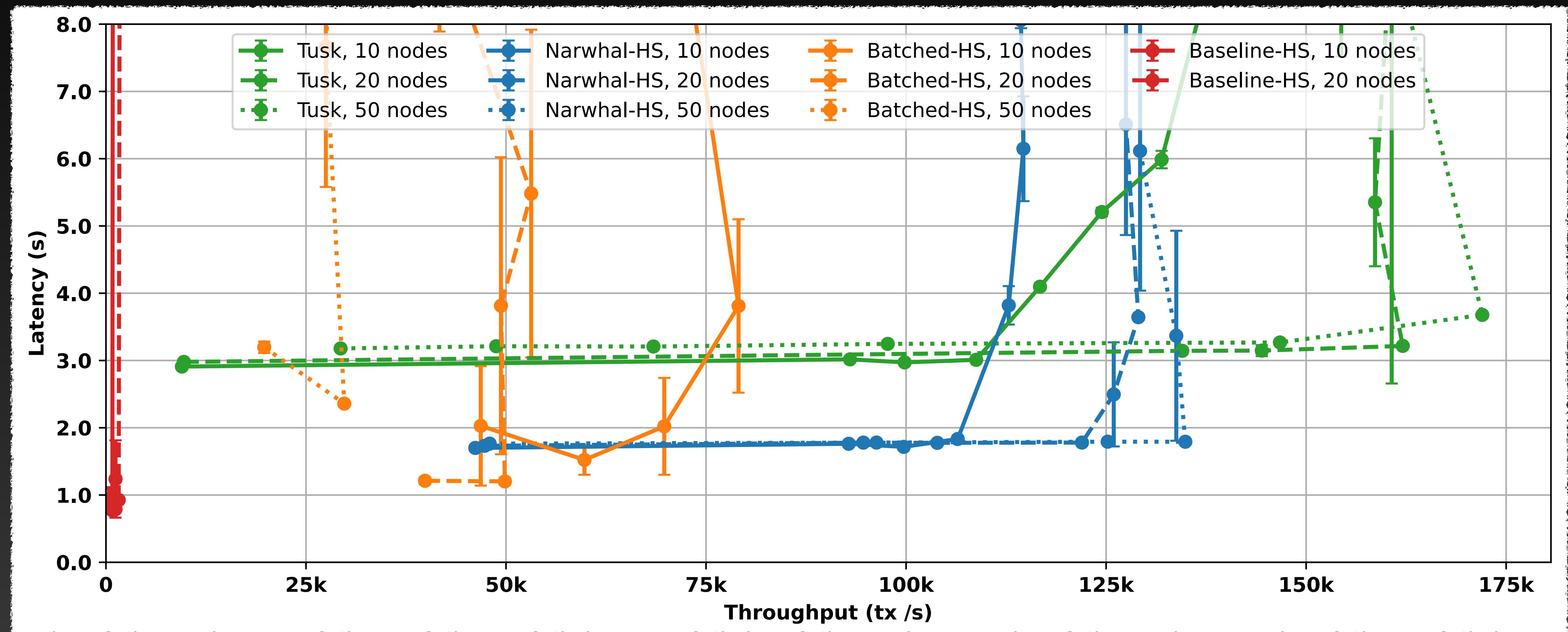
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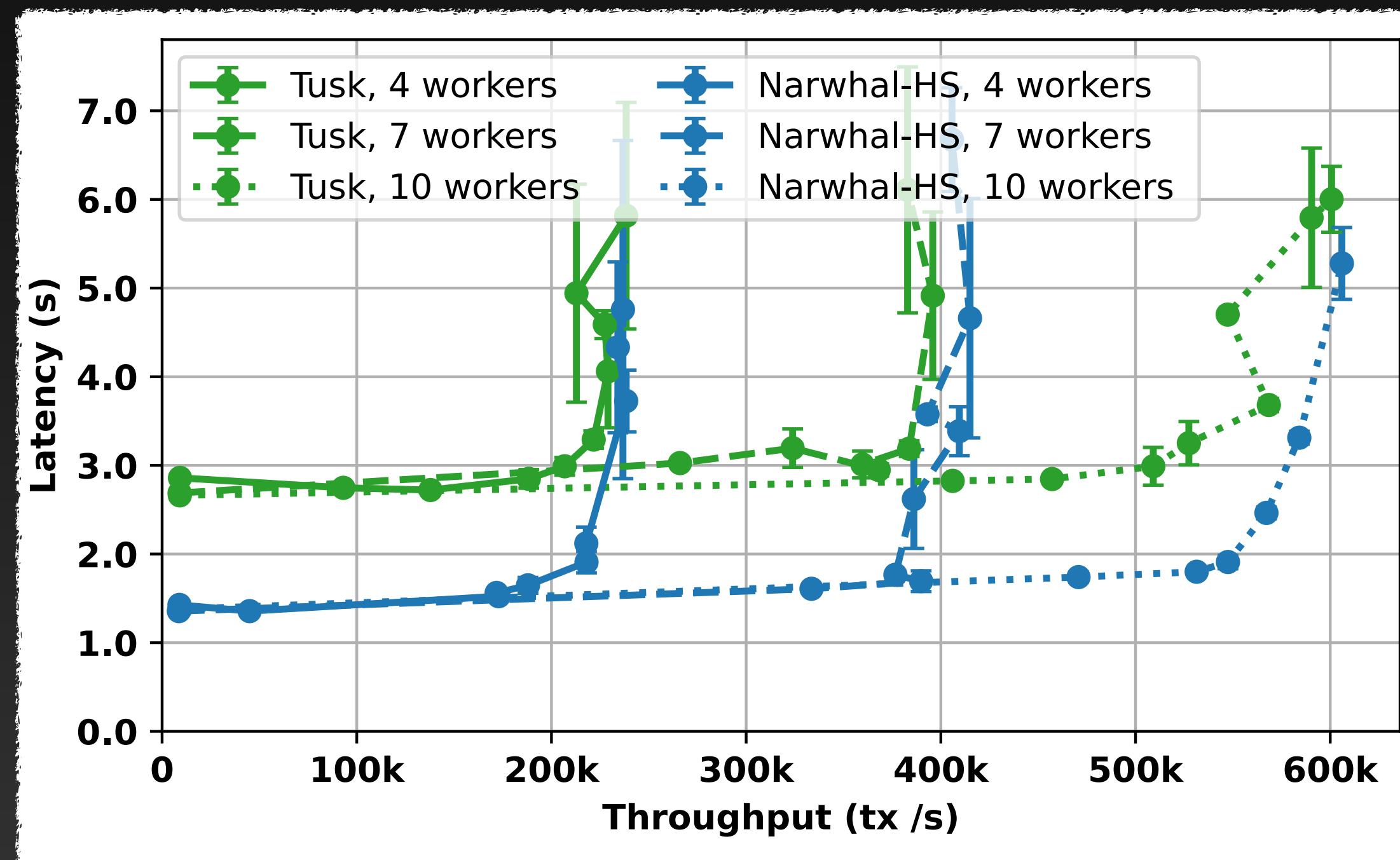
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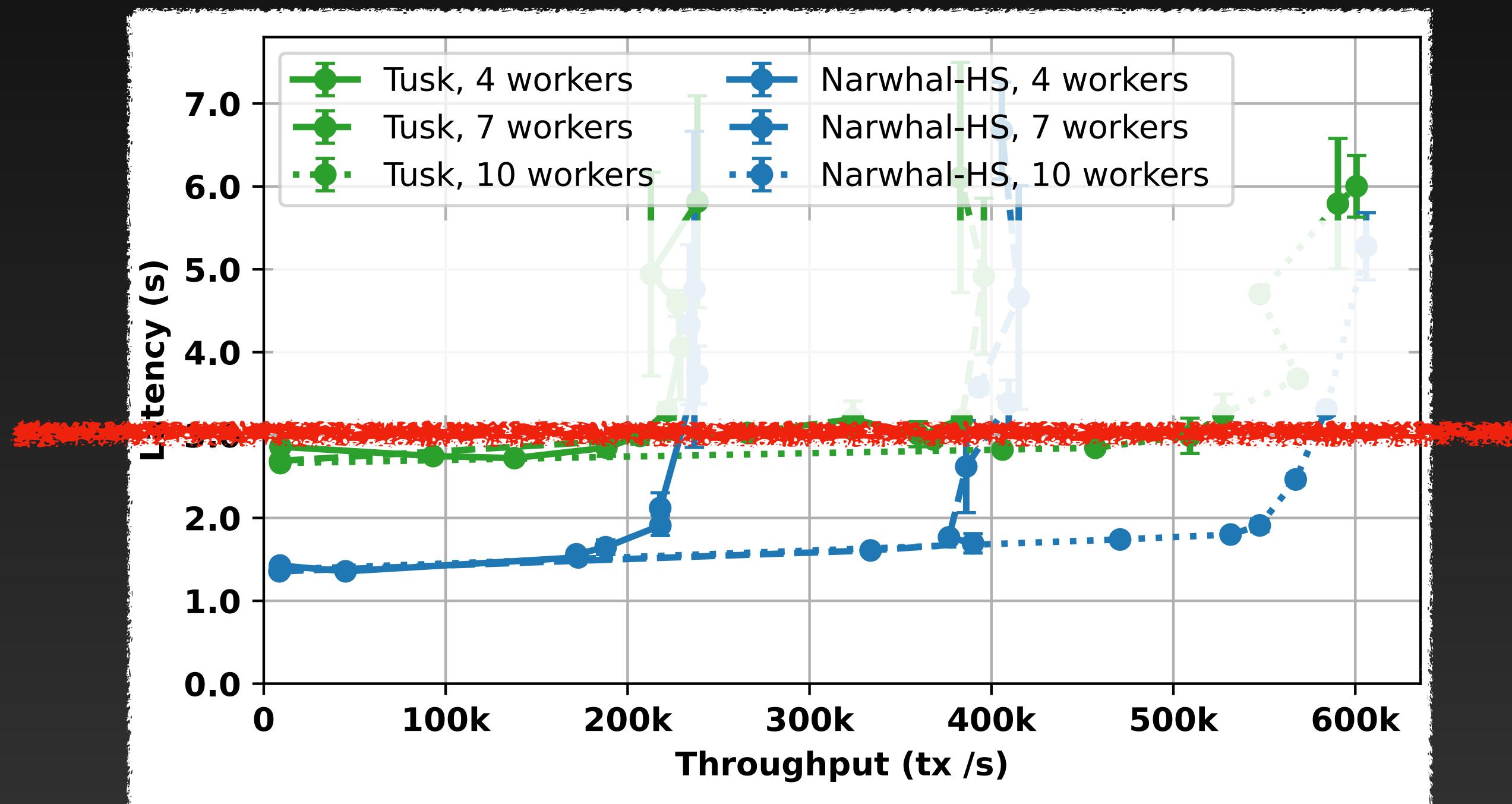
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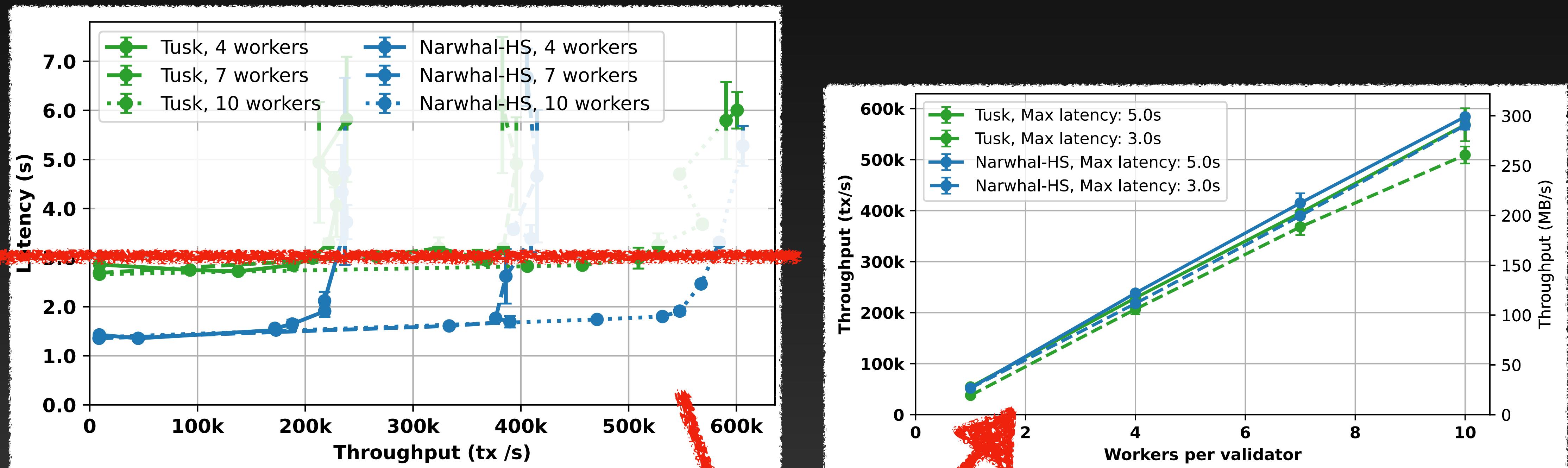
# Evaluation Scalability



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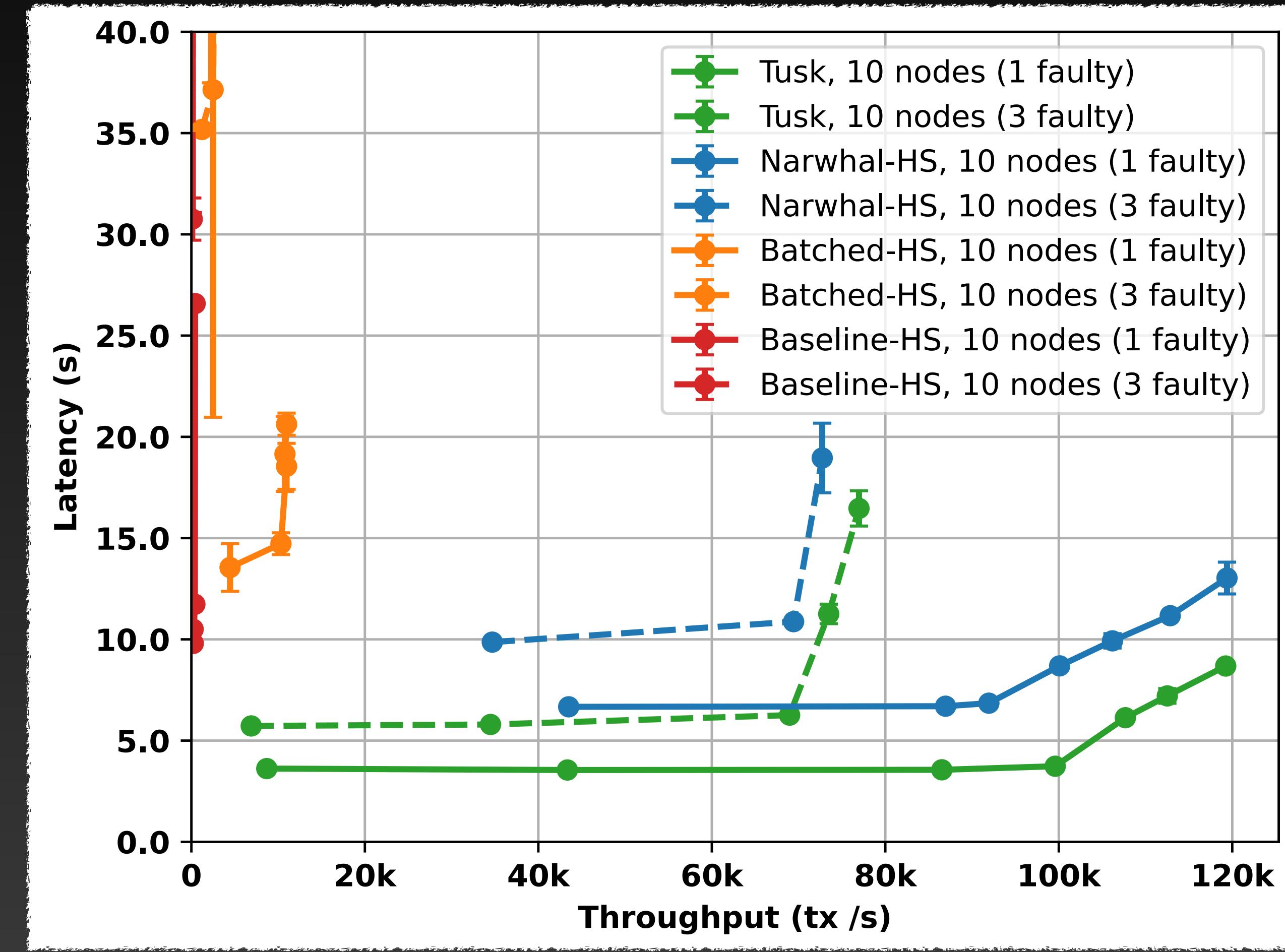


# Evaluation Scalability



# Evaluation

## Performance under faults



# Evaluation

## Typical mistakes

- ⌚ Forgo persistent storage
- ⌚ Do not sanitise messages
- ⌚ Local/LAN benchmark + ping
- ⌚ Many nodes on same machine
- ⌚ Change parameters across runs
- ⌚ Set transaction size to zero
- ⌚ Preconfigure nodes with txs
- ⌚ Send a single burst of transactions
- ⌚ Benchmark for a few seconds
- ⌚ Start timer in the batch maker
- ⌚ Evaluate latency w/ only the first tx
- ⌚ Separate latency and throughput
- ⌚ Only benchmark happy path

# Evaluation

## Still many caveats

- Perfect load balance
- Transaction deduplication
- Synthetic load
- No Byzantine adversary
- No network adversary
- Only AWS network