

Mecánica 2014

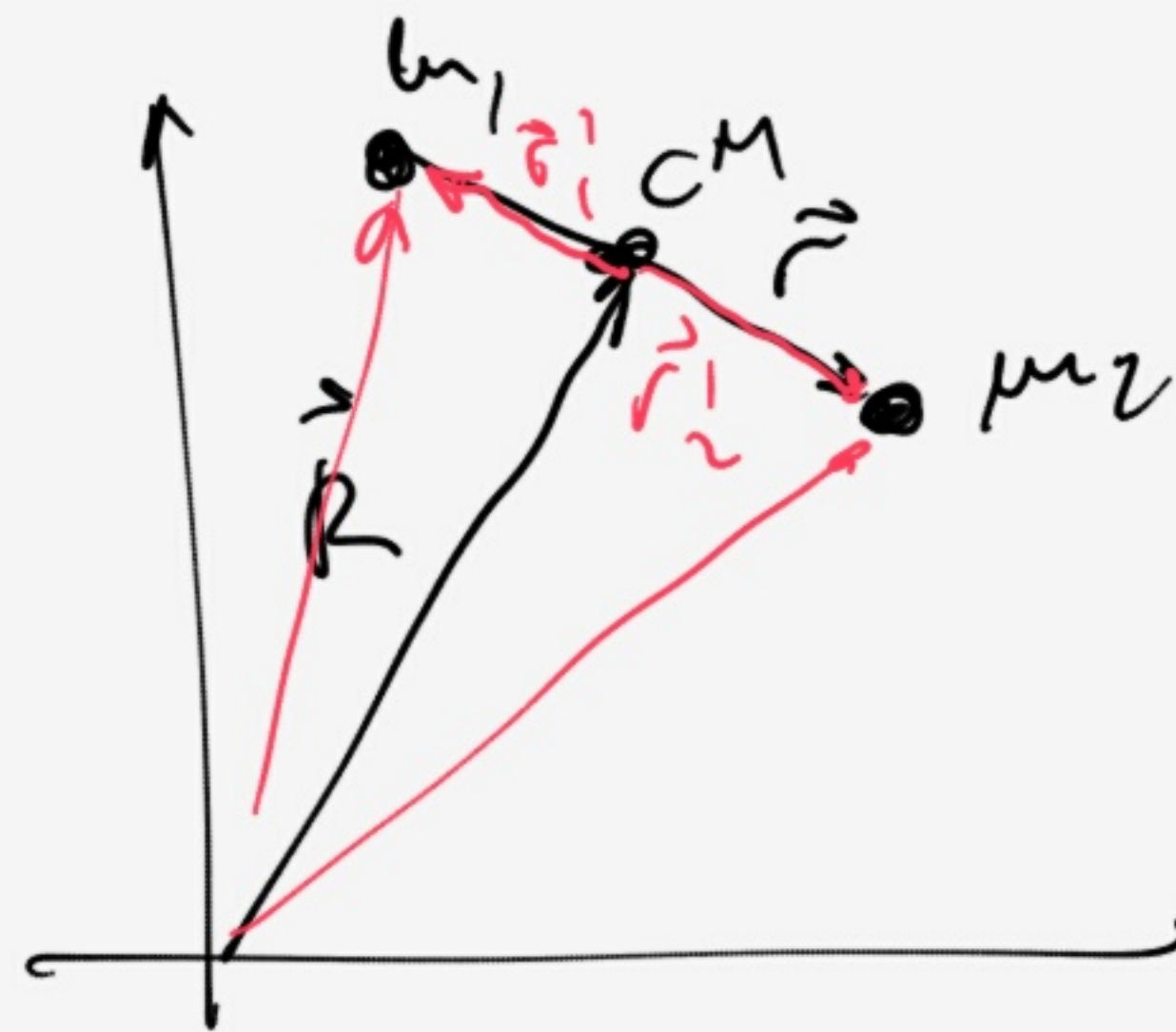
U02C01: Introducción
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En un sistema, la energía solo está solo dependiente de la posición relativa de los cuerpos interactuantes y de la magnitud de las cargas interactuantes.

$$\Rightarrow U_{ij} = f(\Delta \vec{r}_{ij}, \Delta \dot{\vec{r}}_{ij})$$

\Rightarrow Para un sistema con los cuerpos de masa m_1 y $m_2 \Rightarrow$ Ecuaciones de libertad.



$$\vec{r} = \vec{r}_2 - \vec{r}_1$$

$$\Rightarrow \mathcal{L} = T - V = T(\dot{\vec{R}}, \dot{\vec{r}}) - V(\vec{r}, \vec{r}_1, \dots)$$

$$T = \frac{1}{2} (m_1 + m_2) \dot{\vec{R}}^2 + \frac{1}{2} m_1 \dot{\vec{r}}_1'^2 + \frac{1}{2} m_2 \dot{\vec{r}}_2'^2$$

And $\vec{r}_1' = -\frac{m_2}{m_1 + m_2} \vec{r}$

and $\vec{r}_2' = \frac{m_1}{m_1 + m_2} \vec{r}$

$$\Rightarrow T' = \frac{1}{2} m_1 \left(\frac{m_2}{m_1 + m_2} \right)^2 \dot{\vec{r}}^2 + \frac{1}{2} m_2 \left(\frac{m_1}{m_1 + m_2} \right)^2 \dot{\vec{r}}^2$$

$$T' = \frac{1}{2} \dot{\vec{r}}^2 \left(\frac{m_1 m_2^2 + m_2 m_1^2}{(m_1 + m_2)^2} \right) = \frac{1}{2} \dot{\vec{r}}^2 \cdot m_1 m_2 \left(\frac{m_1 + m_2}{(m_1 + m_2)^2} \right)$$

$$\Rightarrow T = \frac{1}{2} \frac{m_1 m_2}{m_1 + m_2} \dot{r}^2 \quad \mu \equiv \text{massa reducida}$$

$$\Rightarrow \mathcal{L} = \underbrace{\frac{1}{2} (m_1 + m_2) \dot{Q}^2}_{\text{CM}} + \underbrace{\frac{1}{2} \frac{m_1 m_2}{m_1 + m_2} \dot{r}^2 - U(r, \dot{r}, \dots)}_{\text{mov. relativos.}}$$

$$\Rightarrow \mathcal{L} = \mathcal{L}_{\text{CM}} + \mathcal{L}_{\text{rel}}$$

$$\mathcal{L}_{\text{rel}} = \frac{1}{2} \frac{m_1 m_2}{m_1 + m_2} \dot{r}^2 - U(r, \dot{r}, \dots)$$

$$\Rightarrow \mathcal{L}_{\text{rel}} = \frac{1}{2} \mu \dot{r}^2 - U(r, \dot{r}, \dots)$$

Für 200 Informationen \rightarrow 1000000

\rightarrow Energie total ist konstant

$$E = T + V = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + V(r) = \text{cte}$$

Plus central au fur et à mesure \Rightarrow

Le potentiel dépend seulement de $|\vec{r}| \Rightarrow$

$$\vec{F} \propto \vec{r}$$

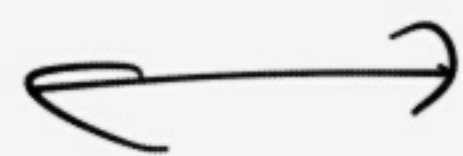
Noether

Symétries



Mag. Angulaire

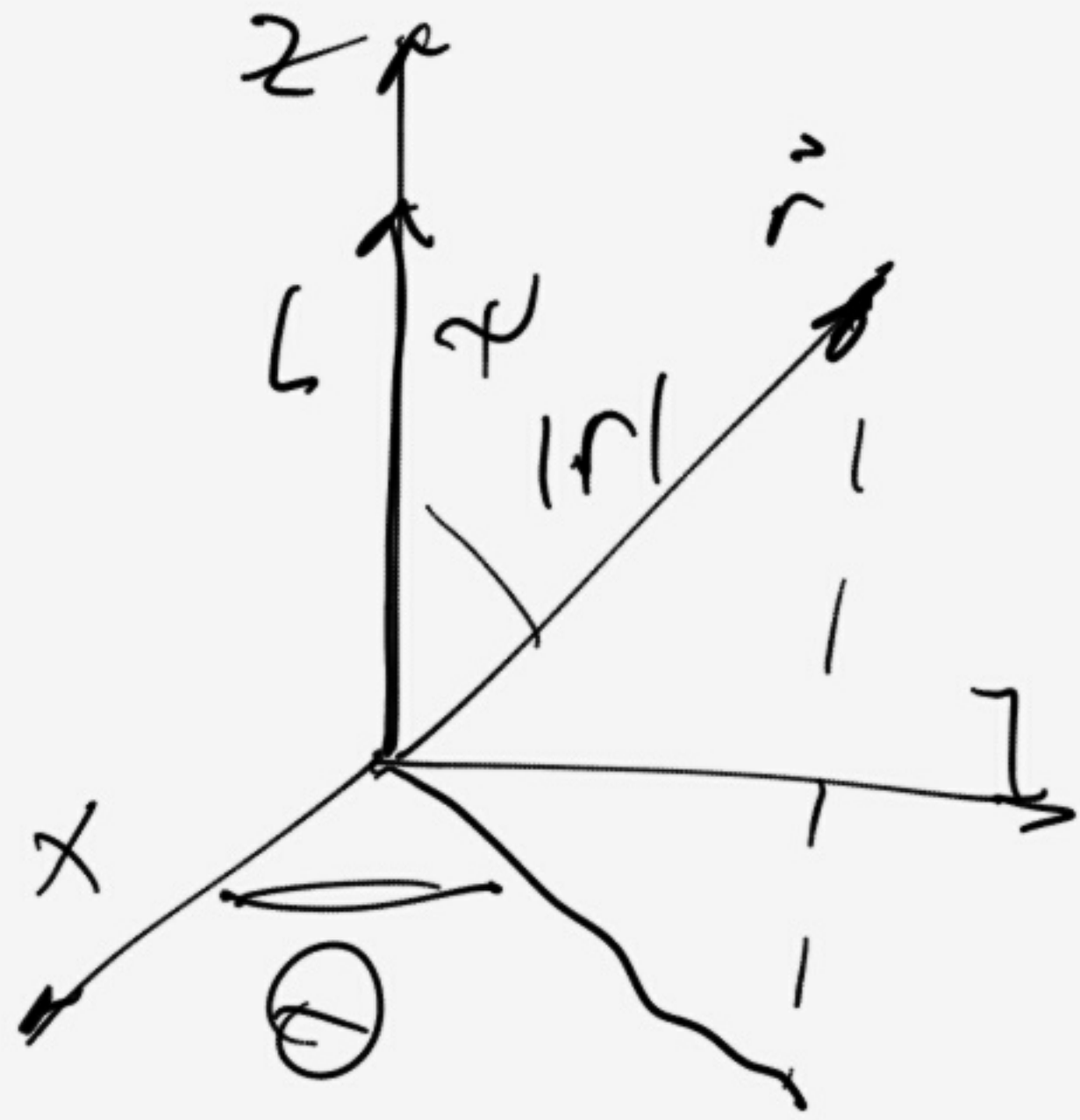
Symétries



Momento angulaire

$$\Rightarrow \vec{L} = \vec{r} \times \vec{p} \rightarrow \dot{L} = 0$$

Esto se cumple si \vec{r} y $\dot{\vec{r}}$ están alineados
 en plano \perp a \vec{L} . Si $\dot{\vec{L}} = 0 \Rightarrow \vec{r} \parallel \dot{\vec{r}} \rightarrow MR$
 Si $\vec{L} = L \hat{k} \Rightarrow \varphi = \pi/2$



$$\Rightarrow \mathcal{L} = T - V$$

$$= \frac{1}{2} \mu \dot{r}^2 - V(r)$$

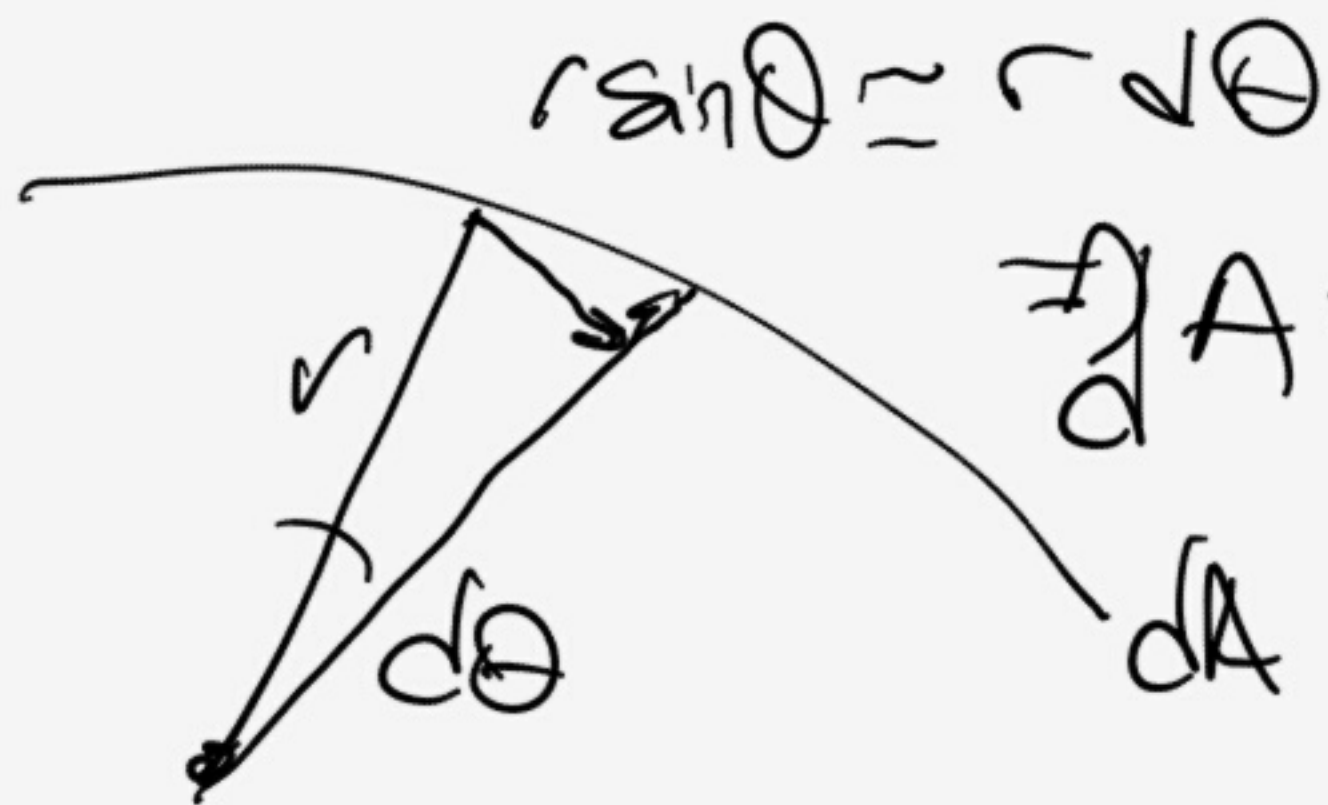
$$\mathcal{L} = \frac{1}{2} \mu (\dot{r}^2 + r^2 \dot{\theta}^2) - V(r)$$

$$\Rightarrow p_{\theta} = \frac{\partial \mathcal{L}}{\partial \dot{\theta}} = m r^2 \dot{\theta}$$

y la conservación de L implica $p_{\theta} = 0 \Rightarrow \frac{d}{dt} m r^2 \dot{\theta} = 0$

$$\Rightarrow m r^2 \dot{\theta} = L = \text{cte}$$

2º ley de Kepler



$$dA = \frac{1}{2} r r d\theta$$

$$dA = \frac{1}{2} r^2 d\theta \Rightarrow \frac{dA}{dt} = \frac{1}{2} r^2 \dot{\theta} = \text{cte}$$

from r theorem: $\frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{r}_j} - \partial \mathcal{L} / \partial r_j = 0$

$$\Rightarrow \mathcal{L} = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) - V(r)$$

$$r_j = r$$

$$\Rightarrow \frac{\partial \mathcal{L}}{\partial \dot{r}} = m \dot{r} \rightarrow \frac{d}{dt} \frac{\partial \mathcal{L}}{\partial \dot{r}_j} = m \dot{r}$$

$$\frac{\partial \mathcal{L}}{\partial r} = m r \dot{\theta}^2 - \partial V / \partial r$$

$$\frac{d}{dt} m \dot{r} - \left(m r \dot{\theta}^2 - \frac{\partial V}{\partial r} \right) = 0$$

$$\Rightarrow \text{Sup } m = \text{cte} \Rightarrow$$

$$m \ddot{r} - m r \dot{\theta}^2 = -\frac{\partial v}{\partial r} = f(r)$$

$$\text{donc } m r^2 \dot{\theta} = L \Rightarrow \underline{m^2 r^4 \dot{\theta}^2 = L^2} \Rightarrow m r \dot{\theta}^2 = \frac{L^2}{m r^3}$$

$$\Rightarrow m \ddot{r} - \frac{L^2}{m r^3} = f(r)$$

Ans, Eng'a $\mathbb{H} = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + v(r) = \text{cte}$

$$= \frac{1}{2} m \dot{r}^2 + \frac{1}{2} m r^2 \dot{\theta}^2 + v(r) = \text{cte} \quad \text{donc :}$$

$$m r^2 \dot{\theta} = L \Rightarrow \frac{1}{2} m^2 r^4 \dot{\theta}^2 = \frac{L^2}{2} \Rightarrow$$

$$\Rightarrow \frac{1}{2} m r^2 \dot{\theta}^2 = \frac{L^2}{2 m r^2} \quad \text{function of } r, \text{ for angular region}$$

$$E = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} m r^2 \dot{\theta}^2 + V(r) = \text{cte}$$

$$\Rightarrow E = \frac{1}{2} m \dot{r}^2 + \frac{L^2}{2 m r^2} + V(r) = \text{cte}$$

$$\Rightarrow \left\{ \begin{array}{l} L = m r^2 \dot{\theta} = \text{cte} \end{array} \right.$$

$$\left\{ \begin{array}{l} E = \frac{1}{2} m \dot{r}^2 + \frac{1}{2} \frac{L^2}{m r^2} + V(r) = \text{cte} \end{array} \right.$$

Resolvido esta para $\dot{r} \Rightarrow$

$$\Rightarrow \dot{r} = \sqrt{\frac{2}{m} \left(E - \frac{L^2}{2m r^2} - V(r) \right)} \equiv \alpha$$

$$\Rightarrow dt = \alpha^{-1} dr \Rightarrow t = \int_{r_0}^r \alpha^{-1} dr$$

$$\Rightarrow r \equiv t^{-1}(r_0, E, L)$$

Para θ , a partir de $r \Rightarrow$

$$L = m r^2 \dot{\theta} \Rightarrow \dot{\theta} = \frac{d\theta}{dt} = \frac{L}{m r^2} \Rightarrow d\theta = \frac{L}{m r^2} dt$$

$$\Rightarrow \theta = \int_0^t \frac{L dt}{m r^2} + \theta_0$$

4 constantes de integración: E, L, r_0 y θ_0

Then we have, $m \ddot{r} - \frac{l^2}{mr^3} = f(r)$

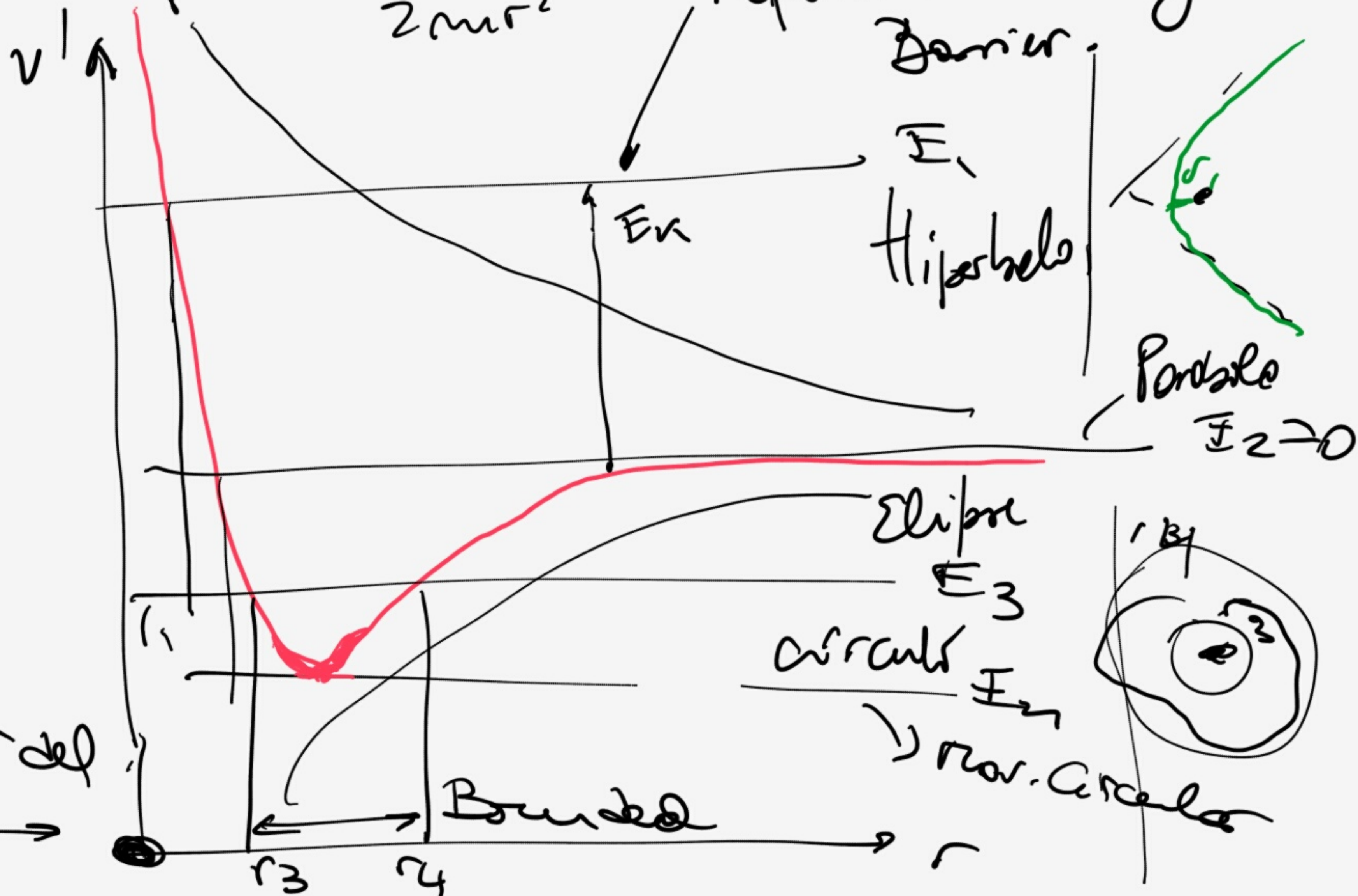
$\Rightarrow m \ddot{r} = f(r) + \underbrace{l^2 / mr^3}_{\text{force centrifugal}} \equiv f'(r)$

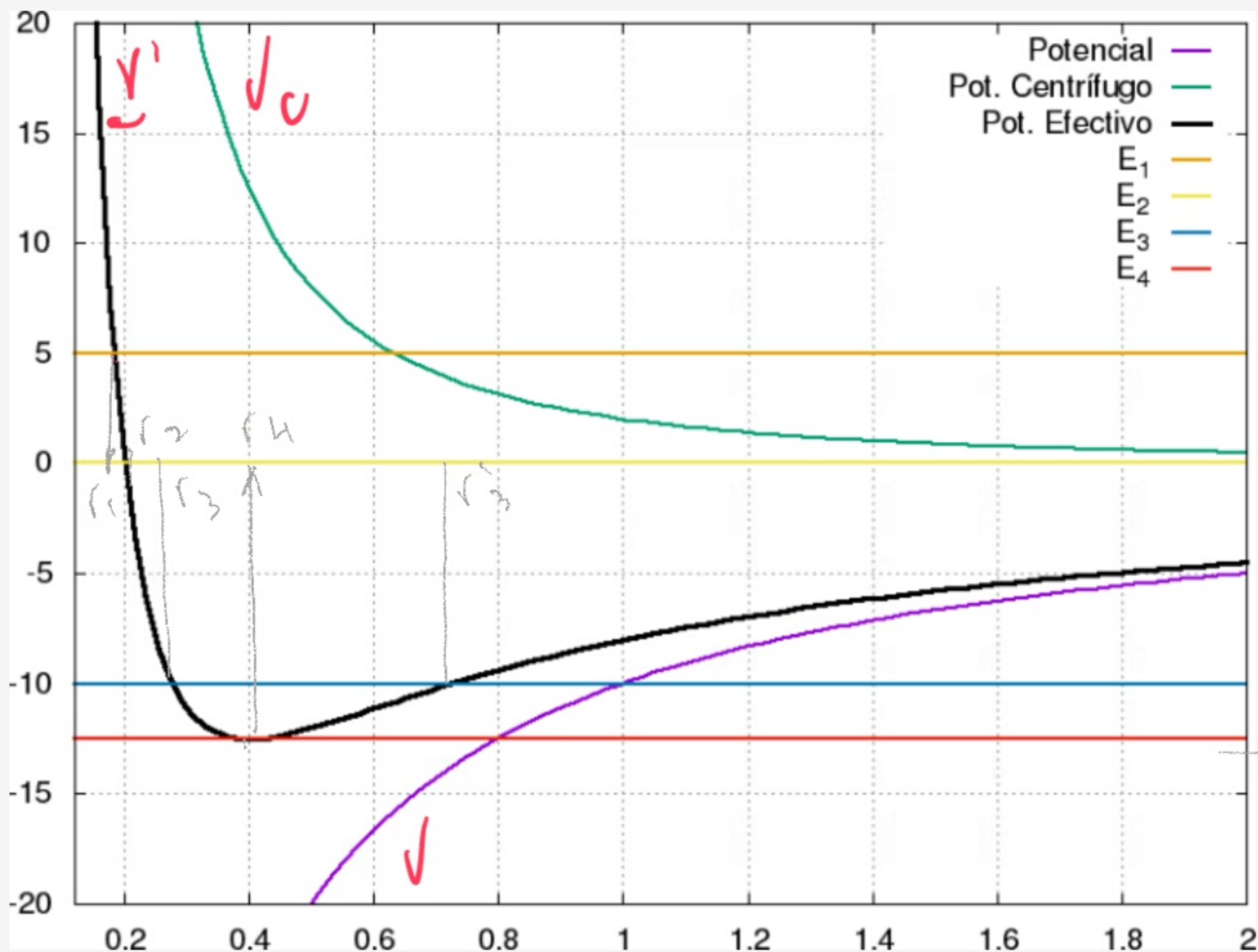
pero $f'(r) = -\partial V / \partial r \Rightarrow V' = V + \underbrace{\frac{l^2}{2mr^2}}_{\text{pot. centrifugal}}$

Fuerza de Atracción $\Rightarrow V = -k r^{-1}$

$$\Rightarrow V' = -\frac{\kappa}{r} + \frac{l^2}{2mr^2}$$

Repulsive centrifugal
Barrier.

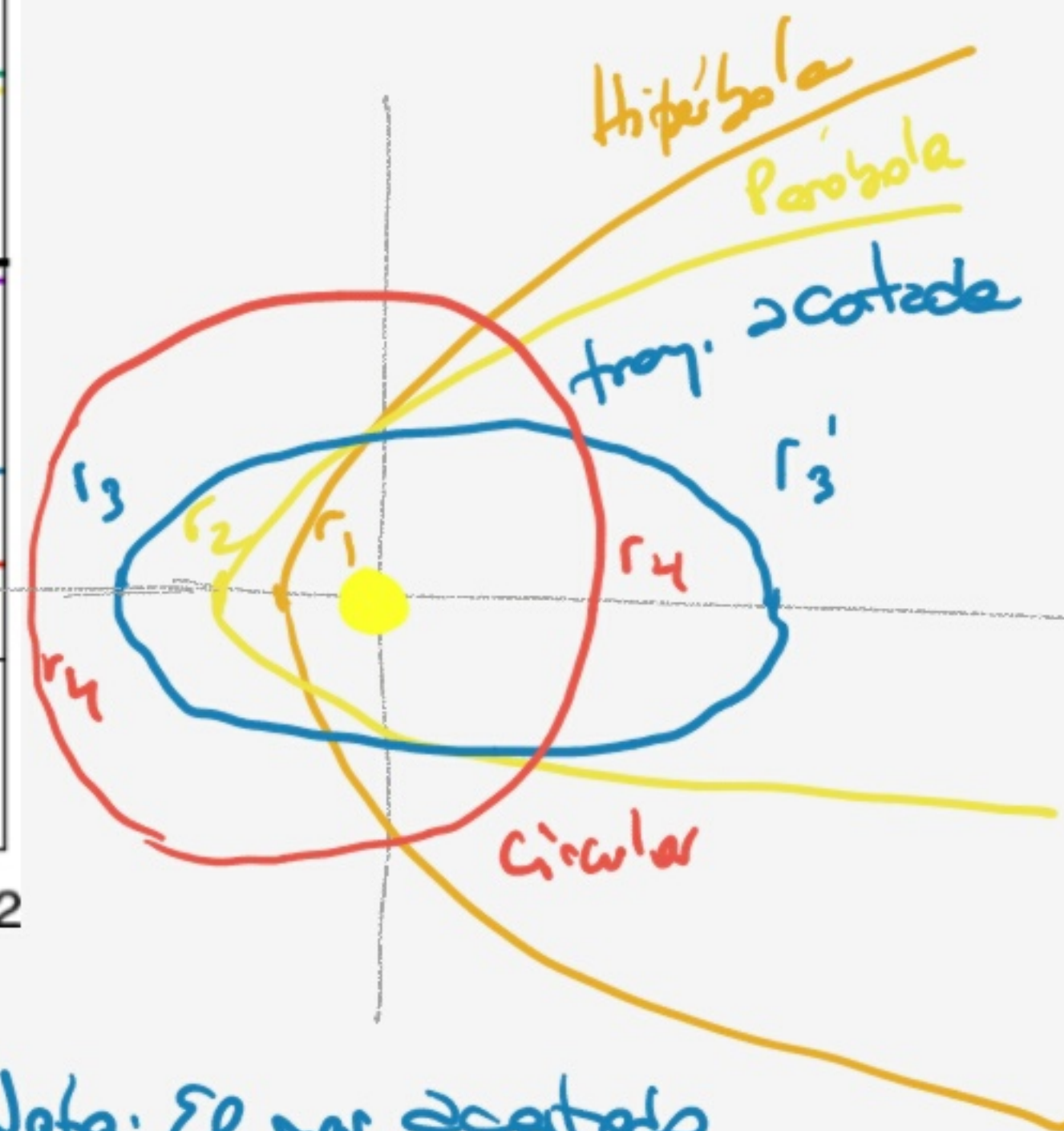




$$V'(r) = V(r) + V_c(r)$$

$$V(r) = -\frac{k}{r}$$

$$V_c(r) = \frac{L^2}{2\mu r^2}$$



Nota: El mov. acotado
puede ser circular