(

$$I_{Q} = \begin{pmatrix} KA \\ d \end{pmatrix} \begin{pmatrix} KA \\ R^{-1} \end{pmatrix}$$

$$I_{Q} = \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \begin{pmatrix} KA \\ R \end{pmatrix} \end{pmatrix} \begin{pmatrix} KA \\$$

$$T_{qz} = \frac{k_2 \cdot A}{L_z} \left(T_c - T\right)$$

$$T_{q_1} = \frac{k_1 \cdot A}{L_1} \left(T_c - T_f\right)$$

$$T_{q_2} = \frac{k_2 \cdot A}{L_2} \left(T_c - T_f\right)$$

$$T_{q_3} = \frac{k_2 \cdot A}{L_1} \left(T_c - T_f\right)$$

$$T_{q_4} = \frac{1}{L_2} \left(T_c - T_f\right)$$

$$T_{q_4} = \frac{1}{L_2} \left(T_c - T_f\right)$$

$$T_{q_4} = \frac{1}{L_2} \left(T_c - T_f\right)$$

$$T_{q_5} = \frac{1}{L_2} \left(T_c - T_f\right)$$

$$T_{q_5}$$

T= L1K2Tc+ L2K, Tf

K, L, +K2 L2 belozono

d tersini

3

$$R_{1} = \frac{DL_{1}}{K_{1}A} \quad R_{2} = \frac{L_{2}}{K_{2}A}$$

$$t = \frac{T - Tf}{R_{1}} \quad T_{2} = \frac{T_{2} - T}{R_{2}}$$

$$t = \frac{T_{2} - T}{R_{2}} \quad T_{2} = \frac{T_{2} - T}{R_{2}}$$

$$t = \frac{T_{2} - Tf}{R_{2}} = \frac{T_{2} - T}{R_{2}}$$

$$T = \frac{T_{2} - Tf}{R_{1}} = \frac{T_{2} - Tf}{R_{2}} = \frac{T_{2} - Tf}{R_{2} - Tf}$$

$$T_{2} = \frac{T_{2} - Tf}{R_{1}} = \frac{T_{2} - Tf}{R_{1} + R_{2}}$$

$$T_{3} = \frac{T_{3} - Tf}{R_{3}} = \frac{T_{3} - Tf}{R_{1} + R_{2}}$$

$$T_{4} = \frac{T_{4} - Tf}{R_{1} + R_{2}} = \frac{T_{4} - Tf}{R_{1} + R_{2}}$$

$$T_{5} = \frac{T_{5} - Tf}{R_{1} + R_{2}} = \frac{T_{5} - Tf}{R_{1} + R_{2}}$$

$$T_{6} = \frac{T_{6} - Tf}{R_{1} + R_{2}}$$

$$T_{7} = \frac{T_{7} - Tf}{R_{2}}$$

$$T$$

Rep= R1+RZ Reg = RI+RZ Rep = S Ri 1 = & 1 Ri

de cout deugra T entre pro-unded se tre ps. (B(X,T) J) Defarbolteran. de = J. A E J. 4.

Jen peroto dul J= 5,67 ×10-8 W de - JActe de total Ste = OA (Tth-Tch)

St St St Th-Tch)

(6)