Formule de folosit in slide-uri

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De început 1

• Markov assumption

$$P(q_t = s_j | q_{t-1} = s_i, q_{t-2} = s_k, \ldots) = P(q_t = S_j | q_{t-1} = s_i)$$

$$1 < i, j < N$$
(1)

• Time independence

$$a_{i,j} = P(q_t = s_j | q_{t-1} = s_i)$$
(2)

$$a_{i,j} \ge 0 \tag{3}$$

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 (3)
 $\sum_{j=1}^{N} a_{i,j} = 1, \quad 1 \le i \le N$ (4)

2 Parametrii modelului

• structure

$$\lambda = (A, B, \Pi) \tag{5}$$

• pi

$$\Pi = \{\pi_i\}, \quad 1 \le i \le N \tag{6}$$

$$\pi_i = P(q_1 = s_i) \tag{7}$$

• $A = \{a_{i,j}\}, \quad 1 \le i, j \le N$

$$a_{i,j} = P(q_{t+1} = s_j | q_t = s_i), \quad 1 \le i, j \le N$$
 (8)

 $\bullet \ B = \{b_{j,k}\}, \ \underset{1 \le l \le M}{\overset{1 \le j \le N}{\le N}}$

$$b_{j,k} = b_j(v_k) = P(o_t = v_k | q_t = s_j), \quad 1 \le j \le N, 1 \le k, \le M$$
 (9)

ullet observațiile O

$$O = [o_1 o_2 \cdots o_T] \tag{10}$$

 $\bullet\,$ variabilele de stare Q

$$Q = [q_1 q_2 \cdots q_T] \tag{11}$$

• stările s_1, s_2, \ldots, s_N

3 Niște probabilități

• Probabilitatea unei secvențe observate, dat fiind λ

$$P(O|Q,\lambda) = \prod_{t=1}^{T} P(o_t|q_t,\lambda)$$
(12)

4 Forward-Backward

4.1 Forward variables

• alpha definition

$$\alpha_{t,i} = P(o_1, o_2, \dots, o_t, q_t = S_i | \lambda) \tag{13}$$

• alpha initialization

$$\alpha_{1,i} = \pi_i b_i(o_1), \quad 1 \le i \le N \tag{14}$$

• alpha induction

$$\alpha_{t+1,j} = \left[\sum_{i=1}^{N} \alpha_{t,j} a_{i,j} \right] b_j(o_{t+1}), \quad {}^{1 \le t \le T-1,}_{1 \le j \le N}$$
(15)

• alpha termination

$$P(O|\lambda) = \sum_{i=1}^{N} \alpha_{T,i} \tag{16}$$

4.2 Backward variables

• beta (backward variable)

$$\beta_{t,i} = P(o_{t+1}o_{t+2}\cdots o_T|q_t = S_i, \lambda)$$
 (17)

• beta initialization

$$\beta_{T,i} = 1, \quad 1 \le i \le N \tag{18}$$

• beta induction

$$\beta_{t,i} = \sum_{j=1}^{N} a_{i,j} b_j(o_{t+1}) \beta_{t+1,j}, \quad t = T - 1, T - 2, \dots, 1, 1 \le i \le N \quad (19)$$

5 Viterbi

• Gamma

$$\gamma_{t,i} = P(q_t = s_i | O, \lambda) \tag{20}$$

$$\gamma_{t,i} = \frac{\alpha_{t,i}\beta_{t,i}}{P(O|\lambda)} = \frac{\alpha_{t,i}\beta_{t,i}}{\sum_{k=1}^{N} \alpha_{t,k}\beta_{t,k}}$$
(21)

 \bullet delta

$$\delta_{t+1,j} = \left[\max_{i} \delta_{t,i} \cdot a_{ij}\right] \cdot b_{j}(o_{t+1}) \tag{22}$$

6 Bau-Bau-Baum-Welch

• ksi definition

$$\xi_{t,i,j} = P(q_t = s_i, q_{t+1} = s_j | O, \lambda)$$
 (23)

• ksi computation

$$\xi + t, i, j = \frac{\alpha_{t,i} \cdot a_{i,j} \cdot b_{j}(o_{t+1}) \cdot \beta_{t+1,j}}{P(O|\lambda)}$$

$$= \frac{\alpha_{t,i} \cdot a_{i,j} \cdot b_{j}(o_{t+1}) \cdot \beta_{t+1,j}}{\sum_{k=1}^{N} \sum_{l=1}^{N} \alpha_{t,k} \cdot a_{k,l} \cdot b_{l}(o_{t+1}) \cdot \beta_{t+1,l}}$$
(24)