# **Alexander Marc Spiridonov**

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**##** 04/09/2000

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#### **Education**

09/2022 – present	MSc. Robotics, Systems and Control, ETH Zurich
09/2019 - 09/2022	<b>BSc. Mechanical Engineering,</b> <i>ETH Zurich</i> final grade: 5.5 (Top 3%)
09/2011 - 06/2019	<b>Abitur,</b> Humboldt-Gymnasium Vaterstetten (HGV) final grade: 1.0

## **Publications, Preprints, and In-Preparation**

2024 SpaceHopper: A Small-Scale Legged Robot for Exploring Low-Gravity Celestial

**Bodies,** Alexander Spiridonov, Marco Hutter et. al.

IEEE International Conference on Robotics and Automation

# **Research Experience**

11/2023 – present	<b>Research Assistant,</b> Secure, Reliable, and Intelligent Systems Lab, ETH Zurich Developing a comprehensive benchmarking framework for evaluating compliance of foundation models with the EU AI Act.
11/2022 - 12/2023	<b>Research Assistant,</b> <i>Robotic Systems Lab, ETH Zurich</i> Developing the Deep RL control concept of the robot SpaceHopper as part of the European Space Agencies PETRI Program.

## **Selected Projects**

04/2023 – 06/2023	Course Project, Optimization & Decision Intelligence Group, ETH Zurich Worked on Safe Active Exploration in MDPs with correlated state-action pairs using Convex RL.
11/2022 - 05/2023	<b>Semester Project,</b> Robotic Systems Lab, ETH Zurich Worked on Imitation Learning from graph-based expert demonstrations to pre-train Deep RL path planners for ANYmal robot in parkour terrains.
02/2022 - 07/2022	<b>Bachelor Thesis,</b> <i>Robotic Systems Lab, ETH Zurich</i> Worked on highly parallelized genetic and supervised learning methods for zero shot sim to real transfer of Deep RL policies.
09/2021 - 06/2022	<b>Focus Project,</b> <i>Robotic Systems Lab, ETH Zurich</i> Team Lead - Modeling & Control of SpaceHopper, created the Deep RL control pipeline, trained and deployed locomotion policies.

### **Teaching Experience**

02/2022 – 06/2022 **Teaching Assistant,** *Institute of Electromagnetic Fields* 

Taught exercise classes for the course Electronics and Circuits.

09/2021 – 02/2022 **Teaching Assistant,** *Mechanics and Materials Laboratory* 

Taught exercise classes for the course Dynamics.

#### **Talks and Presentations**

12/2022 IIT Bombay, Official ETH Ambassador at IIT Bombay Techfest 2022. Presented the

legged robot SpaceHopper.

05/2022 **TEDxThun,** Talked about the potential of legged robots for the exploration of

asteroids and moons

#### **Awards**

05/2019 High School Graduate Award in Physics, German Physical Society

#### **Skills**

Programming Languages
Python, C, C++, MATLAB

Frameworks

UNIX, PyTorch

## Languages

German, English, Bulgarian, Latin

#### **Certificates**

Cambridge English Certificate (C2)

#### **Selected Courses**

#### **Mathematics:**

Analysis I/II/III, Complex Analysis, Linear Algebra I/II, Probability Theory and Statistics

## **Computer Science:**

Control Theory I/II, Models Algorithms and Data, Dynamic Programming and Optimal Control, Optimization for Data Science, Probalistic Artificial Intelligence, Foundations of Reinforcement Learning, Machine Perception, Reliable and Trustworthy Artificial Intelligence