## **Alexander Marc Spiridonov**

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**##** 04/09/2000

https://aspiridon0v.github.io/



#### **Education**

09/2022 – present	MSc. Robotics, Systems and Control, ETH Zurich
09/2019 – 09/2022	<b>BSc. Mechanical Engineering,</b> ETH Zurich final grade: 5.5 (Top 3%)
09/2011 - 06/2019	<b>Abitur,</b> Humboldt-Gymnasium Vaterstetten (HGV) final grade: 1.0

#### **Publications**

2023 SpaceHopper: A Small-Scale Legged Robot for Exploring Low-Gravity Celestial

> Bodies, Alexander Spiridonov, Fabio Buehler, Moriz Berclaz, Valerio Schelbert, Elena Krasnova, Emma Steinke, Jonas Toma, Joschua Wuethrich, Recep Polat, Wim Zimmermann, Philip Arm, Nikita Rudin, Hendrik Kolvenbach, and Marco Hutter Under review in IEEE Robotics and Automation Letters

### **Research Experience**

04/2023 – present	<b>Research Project,</b> Optimization & Decision Intelligence Group, ETH Zurich Working on a notion of adaptive safety for Active Exploration in MDPs, using Convex RL.
11/2022 – present	<b>Research Assistant,</b> <i>Robotic Systems Lab, ETH Zurich</i> Working on the Deep RL control concept of the robot SpaceHopper as part of the European Space Agencies PETRI Program.
11/2022 – present	<b>Semester Project,</b> Robotic Systems Lab, ETH Zurich Worked on Imitation Learning from graph-based expert demonstrations to pre-train Deep RL path planners for ANYmal in parkour terrains. Currently working towards a

publication.

02/2022 - 07/2022 **Bachelor Thesis,** Robotic Systems Lab, ETH Zurich

> Worked on highly parallelized Genetic and Supervised Parameter Tuning Methods for fast and accurate Zero Shot Sim to Real Transfer.

#### **Teaching Experience**

02/2022 – 06/2022	<b>Teaching Assistant,</b> <i>Institute of Electromagnetic Fields</i> Taught exercise classes for the course Electronics and Circuits.
09/2021 - 02/2022	<b>Teaching Assistant,</b> <i>Mechanics and Materials Laboratory</i> Taught exercise classes for the course Dynamics.

#### **Projects**

09/2021 - 06/2022

**SpaceHopper,** Team Lead - Modeling & Control

Created the Deep RL control pipeline, trained and deployed locomotion policies.

#### **Talks and Presentations**

12/2022	<b>IIT Bombay,</b> Official ETH Ambassador at IIT Bombay Techfest 2022. Presented the legged robot SpaceHopper.
05/2022	<b>TEDxThun,</b> Talked about the potential of legged robots for the exploration of asteroids and moons

#### **Awards**

05/2019 **e-fellows scholarship,** *e-fellows.net* 

05/2019 High School Graduate Award in Physics, German Physical Society

#### **Skills**

# Programming LanguagesFrameworksPython, C, C++, MATLABUNIX, PyTorch

#### Languages

German, English, Bulgarian, Latin

#### **Certificates**

**Cambridge English Certificate (C2)** 

#### **Selected Courses**

#### **Mathematics:**

Analysis I/II/III, Complex Analysis, Linear Algebra I/II, Probability Theory and Statistics

#### **Computer Science:**

Control Theory I/II, Models Algorithms and Data, Dynamic Programming and Optimal Control, Optimization for Data Science, Probalistic Artificial Intelligence, Foundations of Reinforcement Learning