

A Deep Learning Method for Mathematical Formulas Detection in PDF Documents

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Abstract—In this paper, we provide a deep learning method to detect mathematical formulas in scientific PDF documents. This task is quite different from the extraction of mathematical expressions in images. The task of mathematical formulas detection has three main challenges: a large scale span, a large variation of the ratio between the width and the height, and a rich character set and mathematical expressions. Considering these challenges, we use Faster R-CNN, a real-time object detection model, with ResNet50, and a suitable level of Feature Pyramid Network. Our model is trained, tested, and evaluated on the IBEM dataset and provides significant results on both embedded and isolated formulas.

Index Terms—Mathematical Formulas Detection, PDF Documents, Deep Learning, Faster R-CNN

I. INTRODUCTION

In the modern world, the Portable Document Format – PDF format of documents is widely used for sharing and printing documents, because unlike other types such as docx, the PDF type does not change the contents and format (layout, font, etc) when we read it on different devices. The scientific documents are no exception. In these documents, mathematical formulas play important parts. As a result, there is a need of a tool that detect these formulas, which is a precondition for reusing these formulas in our own documents. A good example is the preprint repositories [arXiv.org](https://arxiv.org), which gives readers access to the L^AT_EX source files along with the PDF files, but there is only a small number of the existing PDF documents on this website. We ourselves used to meet difficulties when we tried to re-type math formulas in PDF documents to our ones, therefore we want to build a model that can do the task of mathematical formula detection in PDF documents.

Unlike comment text content, general OCR software fails to detect math formulas. Usually, we have to detect the regions of mathematical formulas in documents. We proposed a model with Faster R-CNN and ResNet50 as the “core” as our solution for this problem.

0.9453 This specific value of the dilaton coupling in the Einstein frame follows from starting from a string frame action of the form

$$S = \int d^D x \sqrt{G_D} e^{-\phi} \left[R(G) + (\nabla\phi)^2 - \frac{1}{12} H_{\mu\nu\rho} H^{\mu\nu\rho} \right] \quad (9)$$

where $G_{\mu\nu} = \exp(2\phi/(D-2)) g_{\mu\nu}$ is the string frame metric, $\phi = \sqrt{D-2} \phi_{\text{Einstein}}$ is the dilaton, $H_{\mu\nu\rho}$ is the exterior derivative of the 2-form $B_{\mu\nu}$. The action (9) is (in the corresponding critical dimension) a common subsector (NS-NS) of all string theories. [But it is only for the closed bosonic string $D=26$ that (9) is the full, tree-level bosonic action.] Anyway, we consider here (9) as a toy model to see how dilaton couplings can modify the stability exponents of the forms so much as to quench the form-induced chaos. To study the Kasner stability of the model (9) it is convenient to work with the string-frame Kasner exponents, say p_i , instead of the Einstein-frame ones α_i . The string-frame exponents are defined by writing the Kasner-solution in terms of the string-frame scale factors l_i and the string-frame cosmological time τ : $(G_{\mu\nu} dx^\mu dx^\nu = -d\tau^2 + \sum_i (l_i dx^i)^2)$; $\bar{l}_i \propto \tau^{p_i}$. They are linked to α_i by $p_i = (d-1)\alpha_i/(d-1-\sigma)$, $p_e = (d-1-\sigma)/(d-1-\sigma)$, where $\sigma \equiv (\sum_i \alpha_i) - d$ is the Kasner sphere S^{d-1} defined by Eqs. (2) becomes simply $\sum_{i=1}^d \alpha_i^2 = 1$. It is easily found, either by transforming the Einstein-frame exponents, or by a direct analysis in the string frame, that the string-frame exponents p_i defined such that the “dangerous terms”, i.e. the potential walls, grow like τ^{2p_i} ($\mathcal{H} = (1-\sigma/(d-1))\tau$, for corresponding Einstein-frame exponent, α_i read $\mathcal{H} = 1 + \alpha_i - \alpha_j - \alpha_k$) $\mathcal{H}_{ij} = 1 - \alpha_i - \alpha_j - \alpha_k$. Here, $\mathcal{H}_{ij} \dots \mathcal{H}_{j-3}$ is a permutation of $\{1, \dots, d\}$. We shall show that, when considering all these exponents, the Kasner stability conditions $(\bar{l}_i, \tau^{(2)}, \bar{l}_i^2)$ all ≥ 1 can be satisfied only when $D \geq 11$. This implies, for instance, that the NS-NS sector of type I or heterotic superstring theories in $D=10$ are chaotic. However, in the present paper we are interested in considering only the simple purely electric Bianchi I models. In these models, there are only “electric walls”, so that the only stability condition to satisfy is $\bar{l}_i^2 = \alpha_i^2 > 1$. Clearly this is always satisfied in some region of the Kasner sphere $\sum_{i=1}^d \alpha_i^2 = 1$ (as long as $d \geq 3$, which is anyway necessary to consider a $B_{\mu\nu}$). Therefore, we conclude that the electric Bianchi I model (9) (in $D \geq 3$) will not be chaotic, and will contain at most a finite number of oscillations.

We can, in fact, be more precise and determine the maximum number of oscillations by considering the “collision law” induced by an electric wall. This law follows from the general collision law given in [1] (Eq. (9) then reads $\mathcal{H}_{ij} = 1 - \alpha_i - \alpha_j - \alpha_k$). The Kasner exponents are the “velocities” $\alpha_i = d\beta/d\tau$, $\beta = \ln \bar{l}$, $d\tau = \lambda e^{\beta} d\lambda$ with a normalization constant λ such that $\alpha_0 = d\phi/d\tau = -1$. In terms of the incoming (α_i) outgoing (α'_i) exponents, the collision law corresponding to the wall $(\alpha_i, \alpha_j, \alpha_k) \propto e^{2(\alpha_i+\alpha_j)\tau}$ (see below) reads $\alpha'_i = -\alpha_i$, $\alpha'_j = -\alpha_j$, $\alpha'_k = \alpha_k$. If one starts at some initial time τ_0 with some initial values of α_i and with some electric components α_e that are all of the same order of magnitude, one generically expects that the first collision encountered as τ decreases will be the

³We follow the convention to put the cosmological singularity at $\tau=0$ say starting from $\tau < 0$ with $\mathcal{H} \sim -\phi \sim \ln \bar{l}$ going to $-\infty$ at the singularity.

Fig. 1. Detection of mathematical formulas in PDF documents

II. RELATED WORK

For many years, the detection of mathematical formulas has been recognized as a difficult task [2]. There are several existing methods for detecting mathematical expressions in PDF documents using formatting information, for example, page layout, character labels, character locations, font sizes, etc. However, there are many different tools for generating PDF documents, and there is a variants in their character quality. Lin et al. [8] show that mathematical formulas can be a composition of some object types. For instance, the square root sign in a PDF generated by \LaTeX consists of the text object representing a radical sign and a graphical object for the horizontal line, which results in the fact that some symbols must be identified from multiple drawings elements [10]. Lin et al. [8] categorized the methods of formula detection into three types, based on the features they used, which are: character-based, image-based and layout-based methods. The first type, character-based methods use OCR to identify characters, and those which are not recognized by the OCR engine are considered candidates for mathematical expressions. The second category uses image segmentation, which we will not mention in this paper because our method process PDF documents only. The last one, layout-based methods use features such as line height, line spacing, alignment, etc to detect formulas. A lot of published papers use a combination of character, layout, and context features [10].

A. Traditional Methods

Chaudhuri and Garain investigated over 10000 document pages and found out the frequencies of each mathematical character in formulas [3]. These frequencies are used to develop a detector for embedded expressions, which scans each text line and decides if the line consists of one of the 25 most frequent characters. After finding the leftmost word that contains a mathematical symbol, the detector enlarges the region around the word on the left and right with rules to find the formula region.

There is another method based on mathematical symbols location, and then growing formula regions around the symbols. This method used fuzzy logic, which was developed by Kacem et al. [6].

In 2011, Lin et. al proposed a four-step detection process, which finds embedded math formulas by merging characters tagged as math characters [8]. SVM classification was used for both character classification into math and non-math, and isolated math formulas detection.

B. CRF and Deep Learning-Based Methods

For digital PDF documents, in 2017, Iwatsuki et al. [5] developed a manually annotated dataset and applied conditional random fields (CRF) for detecting the zone of math expressions using both layout features (such as font types) and linguistic features (such as n-grams) extracted from PDF documents.

In 2017 also, Gao et al. [4] published a mathematical formula detection method that combined CNN and RNN,

which performs both top-down layout analysis based on XY-cutting, and bottom-up layout analysis based on connected components to generate formula region candidates.

In 2020, Mali et al. [10] presented ScanSSD - Scanning Single Shot Detector for Mathematical Formulas in PDF Document Images. This method used only visual features for detection, which located formulas at multi scales using sliding windows, after which candidate detections are pooled to obtain page-level results.

Recently, Zhong et al. [15] proposed a method for detecting mathematical expressions using Generalized Focal Loss, an anchor-free method, instead of an anchor-based method and they found some tricks that were effective in this task. Their method was ranked 1st place among 15 teams in the final of the 2021 ICDAR Competition on Mathematical Formula Detection. We found the dataset as well as ideas for our method here.

III. METHOD

We use the Faster R-CNN model with ResNet50 as the backbone for our model. Moreover, the Feature Pyramid Network (FPN) module is used to improve our solution. The Faster R-CNN is a real-time object detection model, which consists of 2 modules. The first module of the Faster R-CNN model is a deep fully convolutional network that proposes regions. The second module is a detector that uses proposed regions from the first one [11]. This is a single, unified network for object detection. By using the recently popular terminology of neural networks as the 'attention' mechanisms, the Region Proposal Networks (RPN) tells the Faster R-CNN where to look.

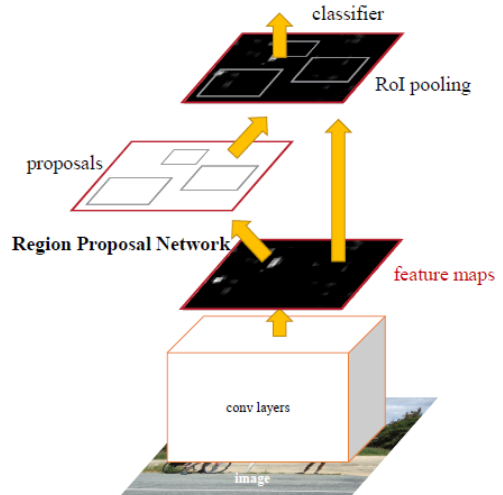


Fig. 2. Faster R-CNN is a single, unified network for object detection. The RPN module plays the role of the 'attention' of this network.

A. Region Proposal Networks

An RPN takes an image as input and outputs a set of rectangular object proposals each with an objectness score, which measures membership to a set of object classes. This

process is modeled with a fully convolutional network. The structure of the RPN is shown in Figure 3, and figure 4 shows some examples of object detection using RPN proposals, on the PASCAL VOC 2007 test. The method introduced in [11] detects objects in a wide range of scales and aspect ratios.

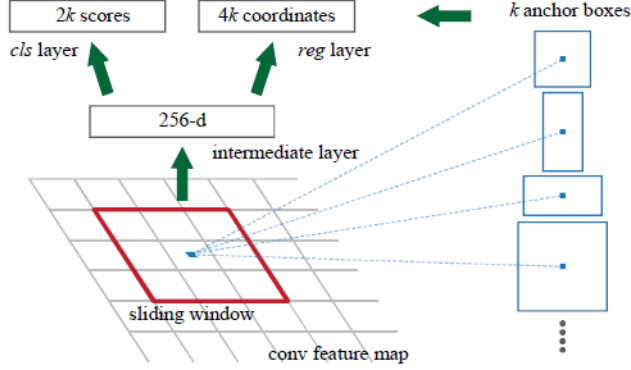


Fig. 3. Region Proposal Network (RPN)

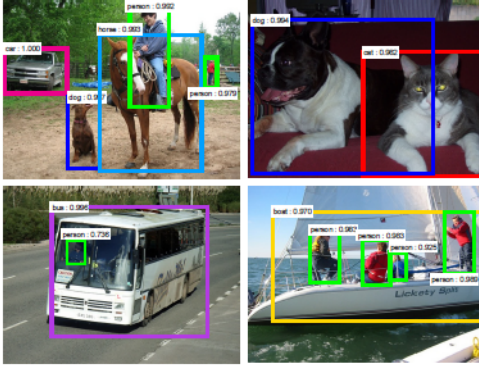


Fig. 4. Examples of object detection using RPN proposals

Loss function: From [11], the loss function of the RPN is:

$$L(\{p_i\}, \{t_i\}) = \frac{1}{N_{cls}} \sum_i L_{cls}(p_i, p_i^*) + \lambda \frac{1}{N_{reg}} \sum_i p_i^* L_{reg}(t_i, t_i^*).$$

B. Sharing Features for RPN and Fast R-CNN

In the Faster R-CNN model, they use a 4-step training algorithm to learn shared features via alternating optimization. In the first step, the RPN is trained end-to-end by back-propagation and stochastic gradient descent (SGD). In the second step, they train a separate detection network by Fast R-CNN. In the third step, they use the detector network to initialize RPN training, and they let the two networks share convolutional layers. Finally, they keep the shared convolutional layers fixed, they fine-tune the unique layers of Fast R-CNN.

C. ResNet50

ResNet50 is a variant of the ResNet model, consisting of 48 convolution layers with 1 MaxPool and 1 Average Pool layer. It has 3.8×10^9 floating points operations. The ResNet50 is a widespread ResNet model.

Table I shows the architecture of the ResNet50. We can see that [7], in a ResNet50 architecture, there are:

- A convolution with a kernel size of 7×7 and 64 different kernels all with a stride of size 2 there is 1 layer.
- Next there is a max pool with also a stride size of 2.
- In the next convolution there is a 1×1 , 64 kernel following this a 3×3 , 64 kernel and at last a 1×1 , 256 kernel. These three layers are repeated in total 3 times so there are 9 layers in this step.
- Next we see a kernel of 1×1 , 128 after that a kernel of 3×3 , 128 and at last a kernel of 1×1 , 512 this step was repeated 4 times so there are 12 layers in this step.
- After that there is a kernel of 1×1 , 256 and two more kernels with 3×3 , 256 and 1×1 , 1024 and this is repeated 6 times there are a total of 18 layers.
- And then again a 1×1 , 512 kernel with two more of 3×3 , 512 and 1×1 , 2048 and this was repeated 3 times there are a total of 9 layers.
- After that we do an average pool and end it with a fully connected layer containing 1000 nodes and at the end a softmax function so this gives us 1 layer.

There are $1 + 9 + 12 + 18 + 9 + 1 = 50$ layers in total.

D. Feature Pyramid Network

The Feature Pyramid Network (FPN) is used to address the problem of the large-scale span. The task of Mathematical Formulas Detection (MFD) contains a large number of extremely small formulas, which brings great challenges for us. As shown in figure 5 [15], for a single extremely small character formula, its short side is usually about 16 pixels. We discover that for any layer of FPN, the limit of the detector is 3 pixels, which means that if we use the default (3-7), the short side needs to be at least 24 pixels to be detected. It can be seen clearly that there are many small embedded formulas that do not satisfy this condition. As a result, we have changed the selection of the FPN level to (2-6), so that our model can overcome this challenge.

TABLE I
RESNET50 ARCHITECTURE

layer name	output size	18-layer	34-layer	50-layer	101-layer	152-layer
conv1	112 × 112	7 × 7, 64, stride 2				
conv2_x	56 × 56	$\begin{bmatrix} 3 \times 3, 64 \\ 3 \times 3, 64 \end{bmatrix} \times 2$	$\begin{bmatrix} 3 \times 3, 64 \\ 3 \times 3, 64 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 64 \\ 3 \times 3, 64 \\ 1 \times 1, 256 \end{bmatrix} \times 3$
conv3_x	28 × 28	$\begin{bmatrix} 3 \times 3, 128 \\ 3 \times 3, 128 \end{bmatrix} \times 2$	$\begin{bmatrix} 3 \times 3, 128 \\ 3 \times 3, 128 \end{bmatrix} \times 4$	$\begin{bmatrix} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{bmatrix} \times 4$	$\begin{bmatrix} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{bmatrix} \times 4$	$\begin{bmatrix} 1 \times 1, 128 \\ 3 \times 3, 128 \\ 1 \times 1, 512 \end{bmatrix} \times 8$
conv4_x	14 × 14	$\begin{bmatrix} 3 \times 3, 256 \\ 3 \times 3, 256 \end{bmatrix} \times 2$	$\begin{bmatrix} 3 \times 3, 256 \\ 3 \times 3, 256 \end{bmatrix} \times 6$	$\begin{bmatrix} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{bmatrix} \times 6$	$\begin{bmatrix} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{bmatrix} \times 23$	$\begin{bmatrix} 1 \times 1, 256 \\ 3 \times 3, 256 \\ 1 \times 1, 1024 \end{bmatrix} \times 36$
conv5_x	7 × 7	$\begin{bmatrix} 3 \times 3, 512 \\ 3 \times 3, 512 \end{bmatrix} \times 2$	$\begin{bmatrix} 3 \times 3, 512 \\ 3 \times 3, 512 \end{bmatrix} \times 6$	$\begin{bmatrix} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{bmatrix} \times 3$	$\begin{bmatrix} 1 \times 1, 512 \\ 3 \times 3, 512 \\ 1 \times 1, 2048 \end{bmatrix} \times 3$
	1 × 1	average pool, 1000-d fc, softmax				
FLOPs		1.8×10^9	3.6×10^9	3.8×10^9	7.6×10^9	11.3×10^9

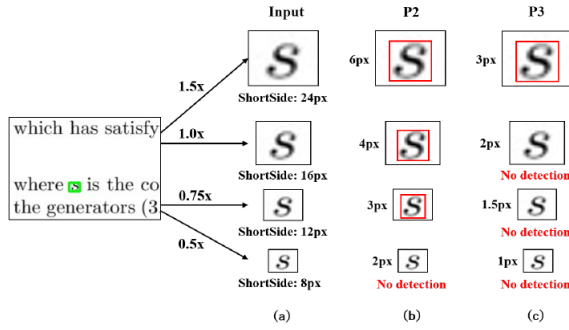


Fig. 5. The significance of FPN in the task of MFD. (a) Input size; (b): Corresponding size in P2, (c) Corresponding size in P3. Under some small cases, some positive samples will be missed

IV. EXPERIMENTS

In this section, we will describe the implementation of our mathematical formula detection system and dataset in detail.

A. Dataset

Our data is from the [IBEM dataset](#). This originally comprises 600 documents, with 8273 pages in total. Those documents are parsed from mathematical papers, then each page is annotated with a bounding box of 2 types: isolated and embedded. The dataset is then split into various sets for IC-DAR 2021 Competition on Mathematical Formula Detection, including Training, Test, and Validation sets.

Training

- Tr00: 4082 pages.
- Tr01: 760 pages.
- Tr10: 329 pages.

Validation

- Va00: 577 pages.
- Va01: 380 pages.

Test

- Ts00: 736 pages.
- Ts01: 380 pages.

- Ts10: 699 pages.
- Ts11: 329 pages.

Our experiment uses Tr01, Tr10, Ts01 for training, Va01 for validation, and Ts11 for testing with 2178 pages in total ($\sim 26.33\%$ of the original dataset), and an approximate ratio of 4.47 : 1.16 : 1. The reason for this small subset is for the purpose of evaluating the ability of the model on small subsets, and the performance it gives (F1-score) through time (minutes).

The numbers of embedded and isolated bounding boxes in each set (figure 6) are:

- **Training:** 31074 embedded bounding boxes, 6617 isolated bounding boxes.
- **Validation:** 6595 embedded bounding boxes, 1346 isolated bounding boxes.
- **Test:** 5702 embedded bounding boxes, 1074 isolated bounding boxes.

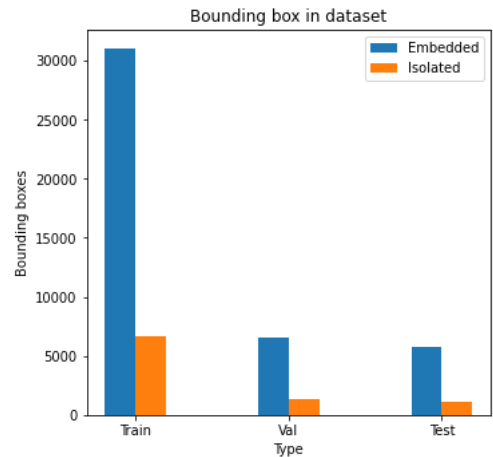


Fig. 6. The numbers of embedded and isolated bounding boxes

B. Implementation Details

Our baseline model is Faster R-CNN with ResNet50 as the backbone. We have trained on Kaggle with a 4-core CPU, 12GB RAM, and a NVIDIA Tesla P100 GPU ¹. The images are resized to 1447×2048 with the same ratio. The size of the region crops from the image is 1200×1120 to fit the limitation of the machine. They are also flipped and padded for data augmentation. For the feature aggregation, we use FPN (2-6). The loss function for the classifier is Cross-Entropy Loss and for the bounding box is L1 Loss. Test images are resized to 1583×2048 due to the distribution of the test dataset, flip augmentation is also applied. For post-processing, Non-Maximum Suppression (NMS) with 0.5 IoU threshold to remove redundant boxes. All models are trained based on the MMDetection toolbox and config given by Yuxiang Zhong. The optimizer for this baseline is Stochastic Gradient Descent (SGD) with a learning rate of 0.02.

C. Remarks

We have tested on 3 configs: Faster R-CNN with schedule 1x (12 epochs), Dynamic R-CNN with schedule 1x (12 epochs) to check if it is better than the faster one and Faster R-CNN with schedule 2x (24 epochs) to check if the model is underfitting with low epochs. The results are given in the figures below.

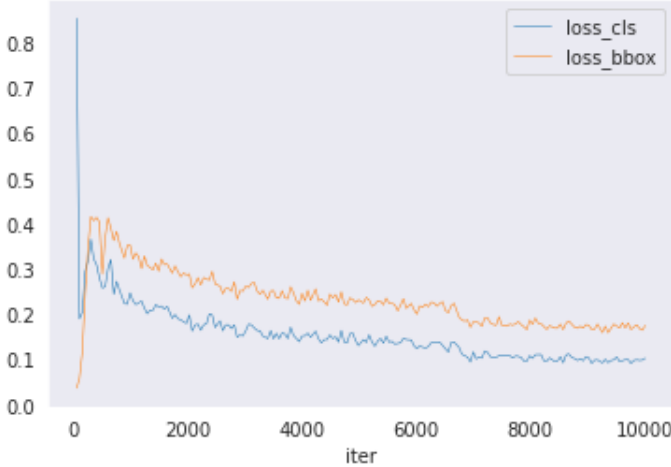


Fig. 7. Faster R-CNN with schedule 1x

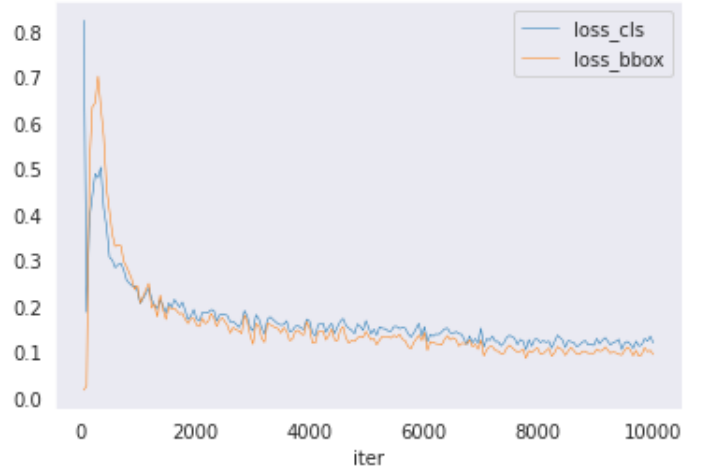


Fig. 8. Dynamic R-CNN with schedule 1x

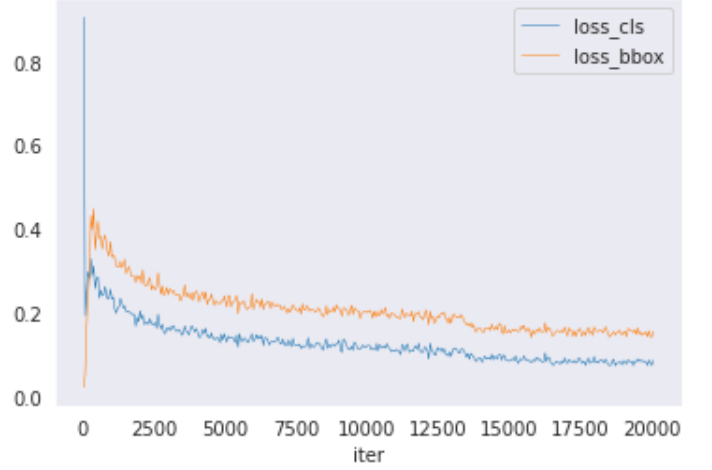


Fig. 9. Faster R-CNN with schedule 2x

The F1-score gained from the model is as follow.

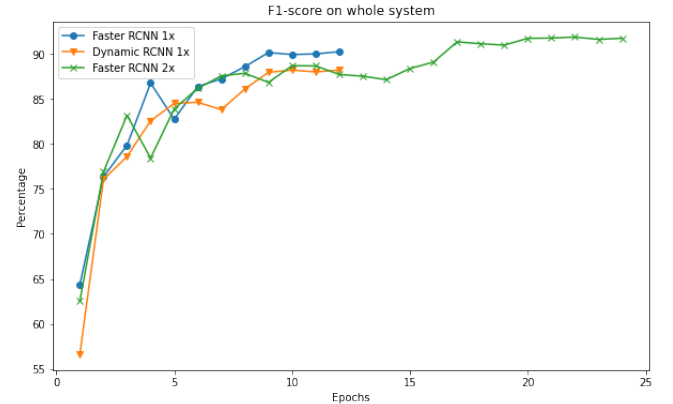


Fig. 10. F1-score on whole system

¹<https://www.kaggle.com/docs/notebooks>

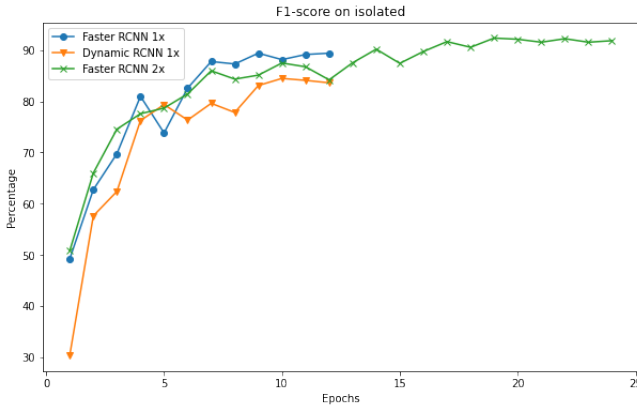


Fig. 11. F1-score with isolated bounding box

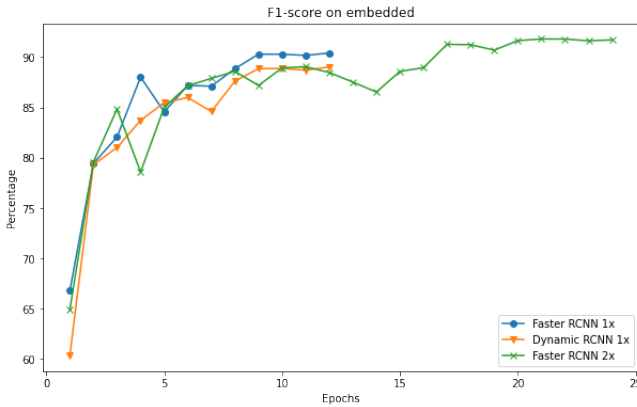


Fig. 12. F1-score with embedded bounding box

It can be seen from the graphs that on the whole system, with the same schedule 1x, the F1-scores given by the Faster R-CNN model are higher than the one by Dynamic R-CNN if we use the same number of epochs, except in the case of 5 epochs. The difference gets higher when we increase the number of epochs. Compared to the scores by Faster R-CNN with schedule 2x (24 epochs), although it gives a lower percentage when trained with a small number of epochs, the score becomes increasing to around 90%. Moreover, on the isolated bounding box, the Faster R-CNN model shows its benefit when compared with the number of Dynamic R-CNN, the F1-score of Faster R-CNN is nearly 90% while the one of Dynamic R-CNN reaches about 80% when they are both trained with 12 epochs. Considering the Faster R-CNN with schedule 2x, it gives the same F1-score with Dynamic R-CNN 1x at the point of 12 epochs, however, the score is about 90% at the point of 24 epochs. Besides that, it can be inferred from the figures of the embedded bounding box that with the same number of epochs (12 epochs), the Faster R-CNN model always provides better results than the Dynamic R-CNN, in spite of the fact that the difference is not large. When we increase the number of epochs to 24, we can observe that the F1-score of Faster R-CNN can reach the milestone of nearly 95%.

From the result given above, we can conclude that the Faster R-CNN model gives better F1-score than the Dynamic R-CNN model.

V. CONCLUSION AND FUTURE WORK

In this paper, we presented our solution to the problem of mathematical formula detection in PDF documents. Our method was implemented with Faster R-CNN with ResNet50 as the backbone and improved by Feature Pyramid Network. We used about a quarter of the IBEM dataset for training, validation, and testing. Our model has significant results, with the highest F1-score being more than 90% when tested with 3 configs on this dataset.

In the future, we intend to improve our model so that it can give better results when working with larger datasets. Moreover, based on this model, we want to build a model which can detect mathematical formulas in both PDF documents and image documents, as well as the model can transfer those formulas to \LaTeX commands, making it more convenient for people to re-type their scientific documents to \LaTeX .

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