TIME SCALES OF THE FREDRICKSON-ANDERSEN MODEL ON POLLUTED \mathbb{Z}^2 AND \mathbb{Z}^3

ASSAF SHAPIRA AND ERIK SLIVKEN

ABSTRACT. We study the Kinetically Constrained Model on the polluted square lattice, with two-neighbor constraints. For a quenched polluted environment with low pollution density we give bounds on the infection time of the origin.

1. Introduction

The Fredrickson-Andersen k-spin facilitated model (FAkf) was introduced in physics [10] in order to study the liquid-glass transition, and it is a part of a family of interacting particle systems called Kinetically Constrained Models (KCM). One may also see them as the stochastic counterpart of a well known family of cellular automata called Bootstrap Percolation (BP); and the Fredrickson-Andersen k-spin facilitated model is the KCM corresponding to the k-neighbors bootstrap percolation.

Both bootstrap percolation and the kinetically constrained models have been studied extensively in homogeneous environment, and in particular on the lattice \mathbb{Z}^d (see, e.g., [27, 1, 8, 15, 2, 4, 7, 23, 22, 20]). Some results are known for the bootstrap percolation in random environments (e.g., [17, 3, 16, 5, 24, 13, 11]).

Kinetically constrained models in random environments have only been considered very recently in the mathematical literature [25]. Their study is a natural extension of bootstrap percolation in random environments, and they could model physical systems which are not homogeneous (e.g. granular materials with more than one type of grains).

We will focus on the 2-neighbors model on the polluted lattice, introduced in [13] for \mathbb{Z}^2 and recently analyzed on \mathbb{Z}^3 [11, 12]. This model lives on the lattice, \mathbb{Z}^2 or \mathbb{Z}^3 , where some of the sites have been removed. We then consider a Markov process on the space of configurations, where each site (that has not been removed) is in one of two states – healthy or infected. In this dynamics sites may change their state, but only when at least two of their neighbors are infected. When this constraint is satisfied, a site will resample its state with rate 1, becoming infected with probability q and healthy with probability 1-q.

We study the divergence of time scales in this model for the stationary settings when q is small, and in particular the infection time of the origin. In the two dimensional case this time is infinite with very high probability whenever more than $O(q^2)$ sites are removed. When a lower density of sites is removed, we show that it diverges as $e^{1/q}$ (up to logarithmic corrections), just like the non-polluted case. In the three-dimensional case, when the proportion of removed

This work has been supported by the ERC Starting Grant 680275 "MALIG", ANR-15-CE40-0020-01.

sites is small (but fixed as $q \to 0$), we bound the infection time between $e^{1/q}$ and $e^{1/\sqrt{q}}$. We conjecture that the correct behavior is given by the upper bound, which is the scaling for the non-polluted lattice.

2. Model, notation and main result

We consider the random environment giving each $x \in \mathbb{Z}^d$ a quenched variable

(2.1)
$$\omega_x \in \{\text{susceptible, immune}\}\$$
.

These variables are chosen in the beginning according to a measure ν , which is the product of *i.i.d.* Bernoulli random variables, where for some fixed $\pi \in (0,1)$,

(2.2)
$$\nu(\omega_x = \text{immune}) = \pi, \\ \nu(\omega_x = \text{susceptible}) = 1 - \pi.$$

Once the environment is fixed, the stochastic dynamics will take place on the subset of susceptible sites, $S \subset \mathbb{Z}^d$.

Susceptible sites are in one of two states: infected or healthy. The stochastic dynamics is defined over configurations $\Omega = \{i, h\}^{\mathcal{S}}$, where i corresponds to an infected site, and h corresponds to a healthy site. We will denote such configurations by $\eta \in \Omega$. We may wish to specify the state after changing the configuration on a set of sites X. For $a \in \{i, h\}$, and $\eta \in \Omega$, let $\eta^{X \leftarrow a}$ denote the configuration which agrees with η on all sites in $\mathcal{S} \setminus X$ and equals a on every site in X. For brevity, when X is the singleton set $\{x\}$ we let $\eta^{x \leftarrow a} = \eta^{\{x\} \leftarrow a}$. We let η^x denote the configuration that agrees with η on $\mathcal{S} \setminus \{x\}$ and differs from η at x. For a function $f: \Omega \to \mathbb{R}$, $\nabla_x f(\eta) = f(\eta^x) - f(\eta)$.

The FA dynamics will be chosen to be reversible with respect to a product measure μ , giving each site probability q to be infected and 1-q to be healthy for a small parameter $q \in (0,1)$. We will often take the expectation of a function with respect to a single site x, which we dente by

(2.3)
$$\mu_x(f) = qf\left(\eta^{x \leftarrow i}\right) + (1 - q)f\left(\eta^{x \leftarrow h}\right).$$

In order to define the FA dynamics we need to define the constraints for $x \in \mathcal{S}$:

(2.4)
$$c_x(\eta) = \begin{cases} 1, & x \text{ has at least 2 susceptible infected neighbors;} \\ 0, & \text{otherwise.} \end{cases}$$

The dynamics will then follow the following rules – each site rings at rate 1. If the constraint is not satisfied (i.e. $c_x = 0$), do nothing. If the constraint is satisfied (i.e. $c_x = 1$) we toss a coin (independently of everything) that gives i with probability q and h with probability 1 - q. Then set the state of x to the result of the coin toss. This could be equivalently described [19]

by the generator of the Markov semi-group defined by

(2.5)
$$\mathcal{L}f(\eta) = \sum_{x \in \mathcal{S}} c_x(\eta) \mu_x f,$$

where $f: \Omega \to \mathbb{R}$ is a local function, i.e. depends on the state of finitely many sites. The Dirichlet form corresponding to \mathcal{L} is

(2.6)
$$\mathcal{D}f = -\mu(f\mathcal{L}f) = -\int f(\eta)\mathcal{L}f(\eta)d\mu(\eta) = q(1-q)\int \sum_{x\in\mathcal{S}} c_x(\eta)(\nabla_x f(\eta))^2 d\mu(\eta).$$

Probabilities and expected values with respect to this process starting at some initial state η will be denoted by \mathbb{P}_{η} and \mathbb{E}_{η} . When starting from equilibrium we use \mathbb{P}_{μ} and \mathbb{E}_{μ} . Though not mentioned explicitly in the notation, these measures depend on the quenched variables, ω , which describe the disorder.

Bootstrap percolation is deterministic in discrete time. At each step t, sites that satisfy the constraint $(c_x(\eta_t) = 1)$ get infected, and remain so forever. Sites that would never be infected under the bootstrap percolation dynamics will never change their state under the corresponding KCM dynamics with the same starting configuration.

Remark 1. The terminology and notation used by the KCM community is not the same as that of the bootstrap percolation community, e.g., "occupied" and "empty" have an inverse meaning, as well as the labels 0 and 1. Here we chose to use the more neutral terminology "infected" and "healthy", hoping it will be equally confusing for readers of all backgrounds.

As $q \to 0$, more and more sites are healthy, the constraint is more difficult to satisfy, and the dynamics slows down. In order to quantify this slowing down we should study typical time scales of the system. One approach is to study the spectral gap of the generator (e.g. [7]), which gives a lot of information for many time scales of the system, and in particular, the loss of correlation. In disordered systems, however, the spectral gap tends to focus on "bad" parts of the environment, giving an overly pessimistic estimation which does not describe actual time scales of the system [25].

One is then tempted to try to hide these bad regions, e.g., by removing them from the graph and replace them with entirely healthy boundary conditions. This choice should give, in a sense, a dynamics which is the slowest possible (as more sites will not satisfy the constraints in this setting); and for the other bound we may take entirely infected boundary conditions (possibly increasing the number of sites which satisfy the constraints). Unfortunately, KCMs are not attractive, and a monotone coupling of the dynamics with hidden parts and the original one is not possible.

In fact, the only information we can gain from such a coupling is the finite speed of propagation of information – if we are interested in the process until time t, we may change the environment at distances greater than 100t without effecting the dynamics near the origin (see, e.g., [21, section 3.3]). In the analysis of the FA1f model on polluted \mathbb{Z}^2 this coupling indeed

allows us to hide bad regions [26, section 3.6]. However, for the FA2f model this is impossible – at distances of the time scales we are considering, the system is not ergodic, even for entirely infected boundary conditions. For example, in the case of \mathbb{Z}^2 , at distance of order π^{-4} from the origin we will find four corners of a rectangle that are all immune. If in the initial configuration all sites in this rectangle are healthy, none could ever be infected, and we cannot hope for correlations to be lost. We will see in Theorem 2 that the typical time scale for the evolution of the system is much longer than π^{-4} (recall equation (2.2)), so we will not be able to use an argument based on the finite speed of propagation.

The way we approach this problem is by studying the infection time of the origin. Unlike the spectral gap, this is a concrete observable, so it will be affected by far away regions only to the extent that the observed dynamics depends on them in practice. Moreover, the reversibility of the process gives tools that allows us to study the Poisson problem related to this time.

We therefore define the main quantity of this paper

(2.7)
$$\tau_0 = \inf \{ t \mid \eta_0(t) = i \}.$$

In the two dimensional case, [13] show that when q is small and $\pi < cq^2$ the probability that the origin is eventually infected is big, but when $\pi > Cq^2$ it is small. We will thus concentrate on the case $\pi < cq^2$, taking some margins that will simplify the analysis.

Theorem 2. Consider the FA2f model on \mathbb{Z}^2 with $\pi < q^{2+\varepsilon}$. Then for all $\varepsilon > 0$, with ν -probability at least $1 - 5q^{\varepsilon/6}$, ω is such that

$$\mathbb{P}_{\mu}\left(\tau_{0} > e^{-q^{-1-\varepsilon}}\right) \leq 3q^{\varepsilon/12}.$$

Moreover, in the other direction, uniformly in ω , there exits C such that

$$\mathbb{P}_{\mu}\left(\tau_{0} < e^{-Cq^{-1}}\right) \xrightarrow{q \to 0} 0$$

For polluted environments in \mathbb{Z}^3 , it is shown in [11] that for π small enough (but not going to 0 with q) the BP infects the origin with high probability even when q tends to 0.

Theorem 3. Consider the FA2f model on polluted \mathbb{Z}^3 . For all $\varepsilon > 0$, with ν -probability that tends to 1 as $\pi \to 0$ uniformly in q, ω is such that

$$\mathbb{P}_{\mu}\left(\tau_{0} > e^{-q^{-1-\varepsilon}}\right) = o(1)$$

In the other direction, uniformly in ω , there exist C such that

$$\mathbb{P}_{\mu}\left(\tau_{0} < e^{-Cq^{-1/2}}\right) \xrightarrow{q \to 0} 0$$

Remark 4. The exponents in the upper and lower bounds of the theorem above do not match. The reason is that the proof of upper bound uses an infection mechanism that takes place in a two dimensional surface, and indeed the power q^{-1} fits the scaling of the two dimensional FA model. We conjecture, however, that in the true dynamics infection would be able to propagate in three directions, giving $q^{-1/2}$ as in the lower bound (perhaps up to logarithmic corrections).

Remark 5. We mention for comparison the scaling of τ_0 in the homogeneous (non-polluted) model. In \mathbb{Z}^2 it scales (up to logarithmic corrections) as $e^{1/q}$, and in \mathbb{Z}^3 as $e^{1/\sqrt{q}}$.

3. Preparation

In order to prove the upper bounds we fix some high probability event E, and show that the process cannot spend a lot of time in E before hitting $\{\eta_0 = 0\}$. Since E has high probability, the process spends a lot of time in E and therefore τ_0 cannot be too big. This entire section will assume the pollution, ω , to be fixed.

Fix an event $E \subseteq \Omega$ and t > 0. We will define the time spent in E by time t as

(3.1)
$$T_t^E = \int_0^t \mathbb{1}_E \left(\eta \left(s \right) \right) \mathrm{d}s.$$

With some abuse of notation we will also considered its averaged version

$$T_{t}^{E}\left(\eta\right) = \mathbb{E}_{\eta}\left[T_{t}^{E}\right]$$

where we recall that $\mathbb{E}_{\eta}[\cdot]$ is the expectation over the stochastic process starting from the configuration η .

For some event $A \subseteq \Omega$, τ_A denote the hitting time for this event.

Definition 6. Let $E, A \subseteq \Omega$ be two events. The time spent in E before hitting A is

$$T_A^E = T_{\tau_A}^E$$
.

Also for T_A^E we define

(3.2)
$$T_A^E(\eta) = \mathbb{E}_{\eta} \left[T_A^E \right].$$

Recall that \mathcal{L} is the generator of the Markov process. The function T_A^E solves the Poisson problem (see, e.g., [6, equation (7.2.45)])

(3.3)
$$\mathcal{L}T_{A}^{E}(\eta) = -\mathbb{1}_{E}(\eta) \qquad \eta \notin A,$$

$$T_{A}^{E}(\eta) = 0 \qquad \eta \in A.$$

Multiplying both sides by T_A^E and integrating with respect to μ gives

Corollary 7. $\mu\left(T_A^E\mathbb{1}_E\right)=\mathcal{D}\left(T_A^E\right)$.

We will use this formula in order to bound $\mu\left(T_A^E\mathbb{1}_E\right)$.

Lemma 8. Fix $E, A \subseteq \Omega$, $N, D, V \in \mathbb{N}$. Assume that for every $\eta \in E$ there exist a sequence η_0, \ldots, η_N of configurations and a sequence of sites $x_0, \ldots x_{N-1}$ such that

- (1) $\eta_0 = \eta$,
- (2) $\eta_N \in A$,
- (3) $\eta_{i+1} = \eta_i^{x_i} \text{ or } \eta_{i+1} = \eta_i$,
- (4) $c_{x_i}(\eta_i) = 1$,

(5) for all $i \leq N$, η_i differs from η on a set X whose size is at most D, and X is contained in a set $Y(x_i)$, depending only on x_i , whose size is at most V.

Then
$$\mu\left(T_A^E \mathbb{1}_E\right) \leq N^2\binom{V}{D} 2^D q^{-D-1}$$
.

Proof. Consider $\eta \in E$. By Property (2) in the hypothesis of the lemma, $T_A^E(\eta_N) = 0$. Thus, denoting $\nabla_i T_A^E = T_A^E(\eta_{i+1}) - T_A^E(\eta_i)$,

(3.4)
$$T_A^E(\eta) = \sum_{i=0}^{N-1} c_{x_i}(\eta_i) \nabla_i T_A^E.$$

Note that $\nabla_i T_A^E$ is either $\nabla_{x_i} T_A^E (\eta_i)$ or 0 (since we allow empty moves). We can then write

$$\mu \left(T_{A}^{E} \mathbb{1}_{E} \right)^{2} \leq \mu \left(\left(T_{A}^{E} \mathbb{1}_{E} \right)^{2} \right) = \sum_{\eta \in E} \mu \left(\eta \right) \left(\sum_{i=0}^{N-1} c_{x_{i}} \left(\eta_{i} \right) \nabla_{i} T_{A}^{E} \right)^{2}$$

$$\leq \sum_{\eta \in E} \mu \left(\eta \right) N \sum_{i=0}^{N-1} c_{x_{i}} \left(\eta_{i} \right) \left(\nabla_{i} T_{A}^{E} \right)^{2}$$

$$\leq \sum_{\eta \in E} \sum_{i=0}^{N-1} \sum_{\eta'} \sum_{x} \mathbb{1}_{\eta' = \eta_{i}} \mathbb{1}_{x = x_{i}} \frac{\mu \left(\eta \right)}{\mu \left(\eta' \right)} \mu \left(\eta' \right) N c_{x} \left(\eta' \right) \left(\nabla_{x} T_{A}^{E} \left(\eta' \right) \right)^{2}$$

$$\leq N q^{-D} \sum_{\eta'} \sum_{x} \sum_{\eta \in E} \sum_{i=0}^{N-1} \mathbb{1}_{\eta' = \eta_{i}} \mathbb{1}_{x = x_{i}} \mu \left(\eta' \right) c_{x} \left(\eta' \right) \left(\nabla_{x} T_{A}^{E} \left(\eta' \right) \right)^{2}$$

$$\leq N^{2} \binom{V}{D} 2^{D} q^{-D} \sum_{\eta'} \sum_{x} \mu \left(\eta' \right) c_{x} \left(\eta' \right) \left(\nabla_{x} T_{A}^{E} \left(\eta' \right) \right)^{2}$$

$$\leq N^{2} \binom{V}{D} 2^{D} q^{-D-1} \mathcal{D} T_{A}^{E} = N^{2} \binom{V}{D} 2^{D} q^{-D-1} \mu \left(T_{A}^{E} \mathbb{1}_{E} \right),$$

where the last equality is due to Corollary 7.

Proposition 9. Under the hypotheses of Lemma 8

(3.5)
$$\mathbb{P}_{\mu}\left(\tau_{A} > N^{2} {V \choose D} 2^{D} q^{-D-2}\right) \leq 2q + \delta + \sqrt{\delta},$$

where $\delta = 1 - \mu(E)$.

Proof. Let $t = (1 - \sqrt{\delta}) N^2 {V \choose D} 2^D q^{-D-2}$. By Lemma 8 and Markov's Inequality

(3.6)
$$\mathbb{P}_{\mu}\left(T_{A}^{E}\mathbb{1}_{E}\left(\eta\left(0\right)\right)\geq t\right)\leq 2q.$$

Since $\mu(E) = 1 - \delta$,

$$\mathbb{P}_{\mu}\left(T_{A}^{E} \geq t\right) = \mathbb{P}_{\mu}\left(T_{A}^{E} \geq t \text{ and } \eta\left(0\right) \in E\right) + \mathbb{P}_{\mu}\left(T_{A}^{E} \geq t \text{ and } \eta\left(0\right) \notin E\right)$$

$$\leq 2q + \delta.$$

On the other hand, for all s > 0

$$\mathbb{E}_{\mu}\left(T_{s}^{E}\right) = s\mu\left(E\right) = (1 - \delta)\,s,$$

and since $T_s^E \leq s$ we can again apply Markov's Inequality (for the positive variable $s-T_s^E$), obtaining

(3.8)
$$\mathbb{P}_{\mu}\left(T_{s}^{E} \leq \left(1 - \sqrt{\delta}\right)s\right) \leq \sqrt{\delta}.$$

In particular, chosing $s = N^2 \binom{V}{D} 2^D q^{-D-2}$ yields

$$\mathbb{P}_{\mu} (\tau_A \ge s) \le \mathbb{P}_{\mu} (T_{\tau_A}^E \ge T_s^E) \le \mathbb{P}_{\mu} (T_{\tau_A}^E \ge t) + \mathbb{P}_{\mu} (T_s^E \le t)$$

$$\le 2q + \delta + \sqrt{\delta}.$$

The lower bounds can be obtained by comparison to the associated bootstrap percolation (see also [7]).

Definition 10. τ_0^{BP} is the μ -random variable describing the infection time of the origin for bootstrap percolation.

Lemma 11. Fix
$$t > 0$$
, $\delta > 0$, and assume $\mu \left(\tau_0^{BP} < 100t \right) < \delta$. Then $\mathbb{P}_{\mu} \left(\tau_0 < t \right) < \delta + e^{-t}$.

Proof. By the finite speed of propagation property (see, e.g., [21, section 3.3]), setting $X = x : ||x||_1 \ge 100t$, we may couple the dynamics starting at a configuration η with the dynamics starting at the configuration $\eta^{X \leftarrow h}$, such that with probability at least $1 - e^{-t}$ the state of the origin in both dynamics is equal up to time t. By the definition of bootstrap percolation, if $\tau_0^{\text{BP}} \ge 100t$, than the dynamics starting from the state $\eta^{X \leftarrow h}$ could never infect the origin. Therefore, the dynamics starting at η could infect the origin with probability at most e^{-t} . This concludes the proof.

4. KCM on polluted \mathbb{Z}^2

The upper bound for τ_0 is given by Lemma 11 and the estimates of $\tau_0^{\rm BP}$ in [1] for the non-polluted case (i.e., when all sites are susceptible), together with the observation that by adding immune sites $\tau_0^{\rm BP}$ could only increase.

For the lower bound, we start by fixing two scales:

$$(4.1) L = q^{-1-\varepsilon/3},$$

$$(4.2) l = q^{-L-1}.$$

Definition 12. A square (that is, a subset of \mathbb{Z}^2 of the form $x + [L]^2$) is *good* if all its sites are susceptible and each row and column contain at least one infected site.

Claim 13. For q small enough $\nu \otimes \mu$ ($[L]^2$ is good) $\geq 1 - 2q^{\varepsilon/3}$.

Proof. The probability that one of the sites of $[L]^2$ is immune is at most $L^2\pi$, which is bounded by $q^{-2-2\varepsilon/3}\,q^{2+\varepsilon}=q^{\varepsilon/3}$. The probability that one of the line or columns of $[L]^2$ is entirely healthy is at most $2L\,(1-q)^L$, which is asymptotically equivalent to $2q^{-1-\varepsilon/3}e^{-q^{-\varepsilon/3}}$. This bound tends to 0 much faster than $q^{\varepsilon/3}$, and the union bound given the proof of the claim.

We will consider the coarse grained lattice, i.e., the boxes of the form $L\hat{x} + [L]^2$ for $\hat{x} \in \mathbb{Z}^2$. The boxes of this lattice do not overlap, thus they are good or not good independently. That is, the notion of a good box defines a Bernoulli percolation process on the coarse grained lattice. Together with results from percolation theory (e.g. [9, 14, Theorem 1.33]) this implies the following corollary.

Corollary 14. The $\nu \otimes \mu$ -probability that the origin belongs to an infinite cluster of good boxes is at least $1 - 16q^{\varepsilon/3}$.

Definition 15. Consider a path of good boxes on the course-grained lattice. We say that the path is *super-good* if one of its boxes contains an infected line.

Claim 16. Fix a self avoiding path of boxes whose length is l. Then

(4.3)
$$\nu \otimes \mu \text{ (path is super-good } | \text{ path is good)} \geq 1 - e^{-1/q}.$$

Proof. Since the events {the path is good} and {one of the boxes contains an infected line} are both increasing we can use the FKG inequality [14], and bound this probability by the probability that a length l path of boxes (not necessarily good) does not contain an infected line. This conclude the proof, since

$$(4.4) (1 - q^L)^{lL} \le e^{-q^L q^{-L-1}}.$$

Claim 17. For q small enough $\nu \otimes \mu$ (0 belongs to a super-good path of length l) $\geq 1 - 25q^{\varepsilon/3}$.

Proof. By Corollary 14 the origin belongs to an infinite cluster of good boxes with probability greater than $1 - 16q^{\epsilon/3}$. In particular, it is contained in a self-avoiding path of length l. Then we use Claim 16 and the union bound to conclude the proof.

Definition 18. $p_{SG}(\omega)$ is the μ -probability that the origin is contained in a super-good path of length l.

Definition 19. We say that ω is low pollution if $p_{SG}(\omega) > 1 - 5q^{\varepsilon/6}$.

Claim 20. ν (low pollution) $\geq 1 - 5q^{\varepsilon/6}$.

Proof. By Claim 17, $\nu\left(p_{\rm SG}\right) \geq 1-25q^{\varepsilon/3}$. Since $p_{\rm SG} \leq 1$, Markov's Inequality implies the result.

FIGURE 4.1. Illustration of the proof of Proposition 21. We see here how an infected column could propagate in a good box. i stands for infected sites. Other sites could be either infected or healthy, according to their initial state.

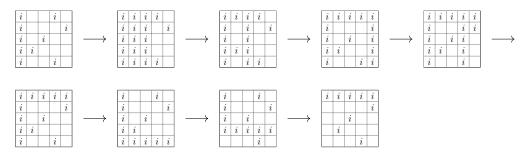


FIGURE 4.2. Illustration of the proof of Proposition 21. We see here how to rotate an infected column in a good box.

From now on we think of a fixed ω . Let

$$E = \{0 \text{ belongs to a super-good path of length } l \},$$

$$A = \{\eta_0 = 0\}.$$

Proposition 21. E, A satisfy the assumptions of Lemma 8 with $N = 4L^2l$, D = 3L, $V = 3L^2$.

Proof. The path is constructed by propagating an infected column (or row), as illustrated in Figures 4.1, 4.2, and 4.3. Figure 4.1 shows how an infected column could propagate to the right in a good box. Since the path may have corners, we will occasionally need to rotate the infected column and create an infected row, as explained in Figure 4.2. Finally, using these two basic moves, we may take the column or row that was initially infected by the assumption that the path is super-good, and then move it along the path until the origin is infected. This is illustrated in Figure 4.3.

This concludes the proof of the upper bound of τ_0 – for q small enough $N^2\binom{V}{D}2^Dq^{-D-2} \le e^{-q^{-1-\varepsilon}}$, and by Proposition 9

(4.5)
$$\mathbb{P}_{\mu}\left(\tau_{A} > e^{-q^{-1-\varepsilon}}\right) \leq 2q + p_{SG}\left(\omega\right) + \sqrt{p_{SG}\left(\omega\right)}.$$

In particular, if ω is low pollution $\mathbb{P}_{\mu}\left(\tau_{A}>e^{-q^{-1-\varepsilon}}\right)\leq 3q^{\varepsilon/12}$.

5. KCM on polluted \mathbb{Z}^3

The upper bound, just as the two dimensional case, is given by Lemma 11 and the results of [8].

For the lower bound, we will use the ideas of [11] in order to construct a path that infects the origin and satisfies the hypotheses of Lemma 8. In contrast to the infection mechanism in

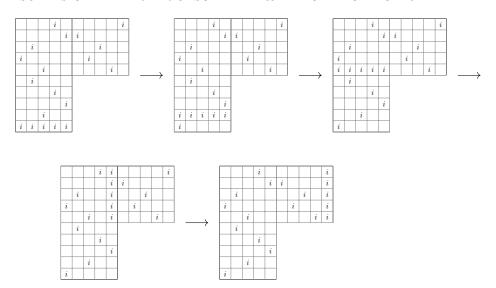


FIGURE 4.3. Illustration of the proof of Proposition 21. We see here how to propagate infection through a good path.

bootstrap percolation ([11]), we will need a finer path, that not only allows us to infect the origin, but also keeps the configuration close to the original one in order to avoid large energy barrier and entropic cost.

A move is denote by a pair (x, a) where $x \in \mathcal{S}$ and $a \in \{i, h\}$. A move is legal in η if $c_x(\eta) = 1$. A finite sequence of moves is given by $\Gamma = (x_i, a_i)_{i=1}^k$. Starting from the configuration η , we let $\Gamma_i(\eta)$ denote the configuration obtained by applying the first i moves in Γ . The sequence Γ is legal with respect to the initial configuration η if each move from $\Gamma_i(\eta)$ to $\Gamma_{i+1}(\eta)$ is legal. We let $\Gamma(\eta)$ denote the configuration obtained by applying the entire sequence of moves in Γ starting from η .

Note that if the change from η to η' is a legal move, then the change from η' to η is also a legal move. Similarly, if Γ is a legal sequence starting from η and ending at η' then the reverse of Γ , denoted $rev(\Gamma)$, is a legal sequence starting from η' and ending at η .

We denote the concatenation of two sequences, Γ and Γ' by $\Gamma + \Gamma'$. If Γ is a legal sequence of moves from η to η' , and Γ' is a legal sequence of moves from η' to η'' then $\Gamma + \Gamma'$ is legal sequence of moves from η to η'' .

Lemma 22. Let Γ denote a sequence of legal moves that starts at η and ends at η' . For any set of susceptible sites X, Let Γ^X denote the same set of moves as Γ except that any move that would cure a site in X is ignored. Then Γ^X is also a legal set of moves that start at η and ends at $\eta'' = \Gamma_k^X(\eta)$ where for all $i \leq k$ the only difference between $\Gamma_i(\eta)$ and $\Gamma_i^X(\eta)$ lies on the set X.

Proof. This is a consequence of the fact that more infected sites can only help the constraints to be satisfied. Let Y_i denote the subset of X that is infected for some $j \leq i$ in $\Gamma_i(\eta)$. For each i, $\Gamma_i^X(\eta) = (\Gamma_i(\eta))^{Y_i \leftarrow i}$, thus the infected sites in $\Gamma_i(\eta)$ are a subset of the infected sites in

 $\Gamma_i^X(\eta)$. Thus moves in Γ^X are legal if they are legal in Γ . Finally $\eta'' = (\eta')^{Y_k \leftarrow i} \in (\eta')^{(X)}$ and thus the last line in the lemma holds.

We repeat the definitions from [11] of the objects necessary for our work. Note that some of the details in the definitions are slightly modified to fit within the framework of our proof.

For $k \in \mathbb{Z}$ we let Λ_k denote $\mathbb{Z}^2 \times \{k\}$ and refer to this as the kth layer of \mathbb{Z}^3 . We let e_1 , e_2 , and e_3 denote the unit vectors in each of the cardinal directions.

The standard brick is a the collection of sites $[0,4L) \times [0,16L) \times [0,32L)$. The base of the standard brick is the bottom half $[0,4L) \times [0,16L) \times [0,16L)$. The top of the standard brick is the remaining half of the brick. The sections of the standard brick are the sets $[0,4L) \times [0,16L) \times [4jL,4(j+1)L)$ for $0 \le j \le 7$. The tip of the standard brick is the set $[0,4L) \times [0,4L), \times [16L,32L)$, and has the same dimensions as a section, though a different orientation. The anchor of the standard brick is the site (4L,16L,0) and the flag is the site (0,0,32L). Note that the standard brick contains neither its anchor nor flag, though the flag is on the boundary of the tip and the anchor is at the corner opposite to the flag on the boundary of the brick.

A proto-brick, \hat{B} , is the set of vertices $[0, 4L) \times [0, 4L) \times [0, 2L)$ that lies in a different \mathbb{Z}^3 from the standard brick. For each $\hat{x} = (\hat{x}_1, \hat{x}_2, \hat{x}_3) \in \hat{B}$ define $cell(x) = (x_1, 4x_2, 16x_3) + \{0\} \times [0, 4) \times [0, 16)$. The standard brick is related to the proto-brick by

$$B = \bigcup_{\hat{x} \in \hat{B}} cell(\hat{x}).$$

A site in the proto-brick is susceptible if every site in the corresponding cell is susceptible.

Definition 23. Let \hat{B} be a proto-brick with corresponding brick B in standard position. The brick B is good if there exists a set $\hat{S} \subseteq \hat{B}$ with the following properties

(1) All vertices in the following set are susceptible:

$$\sigma(\hat{S}) := \{\hat{x}, \hat{x} + \hat{e}_3, \hat{x} - \hat{e}_1 - \hat{e}_2 + \hat{e}_3 : \hat{x} \in \hat{S}\} \cap \hat{B};$$

(2) every $\hat{x} \in \hat{S}$, except for \hat{x} in the bottom layer of \hat{B} , satisfies either

$$\hat{x} - \hat{e}_3 \in \hat{S}$$
, or

$$\hat{x} + \hat{e}_1 + \hat{e}_2 - \hat{e}_3 \in \hat{S};$$

- (3) $\hat{S} \subseteq \{\hat{x}: 3L < \hat{x}_1 + \hat{x}_2 + \hat{x}_3 < 4L\};$
- (4) for $0 \le k \le 2L 1$, $\hat{S} \cap \Lambda_k$ is an oriented path from $\{\hat{x}_1 = 0\}$ to $\{\hat{x}_2 = 0\}$ with steps \hat{e}_1 or $-\hat{e}_2$ where no three consecutive steps are the same;
- (5) The site (L+1, 4L+4, 16L) is contained in S, where

$$S = \bigcup_{\hat{x} \in \hat{S}} cell(\hat{x});$$

(6) for $0 \le k < 32L - 1$, there is an infected site in $S \cap \Lambda_k + e_3$.

The first five conditions for a good brick depend only on the quenched random set S. The last condition also depends on the configuration on S.

The set S is called the sail of B. The set

$$\bar{S} = S \cup \{S + e_3\} \cap B$$

is called the thick sail of B.

For a fixed $\hat{x} \in \hat{B}$ and some value $0 \le j \le 15$ we call the set $(x_1, x_2, x_3) + \{0\} \times [0, 4) \times \{j\}$ the *j*th *unit* of $cell(\hat{x})$. Similarly, for fixed $0 \le j \le 3$, the set $(x_1, x_2, x_3) + \{0\} \times \{j\} \times [0, 16)$ is called a *strip*. A cell consists of 16 units or 4 strips.

The set $B_i = \Lambda_i \cap B$ is the *i*th *layer* of B. The sites in a unit of a cell all lie on the same layer, whereas the sites of a strip in a cell lie across 16 different layers.

If each of the units in a layer is the 15th unit in a cell, we say the layer is a *transition* layer. Otherwise it is an internal layer. Note the only sites in $\bar{S}\backslash S$ are (possibly) those that lie directly above a transition layer.

We denote the layers of a sail as the sets $S_i = \Lambda_i \cap S$. If S_i is in an internal layer, then $S_{i+1} = S_i + e_3$. The layer S_i is an oriented path of units with subsequent units differing by either e_1 or $-4e_2$. The path has two types of corner units: an exterior corner unit reached by e_1 from the previous unit and followed by $-4e_2$ to the next unit, and an interior corner unit reached by $-4e_2$ and followed by e_1 . For i < 32L - 1, if S_i is a transition layer then for every $u \in S_i$ either $u + e_3 \in S_{i+1}$ or $u + e_3 - e_1 - 4e_2 \in S_{i+1}$.

A general brick, B, is given by an anchor and flag in \mathbb{Z}^3 that differ by (d_1, d_2, d_3) given by some rearrangement of the vector $(\pm 4L, \pm 16L, \pm 32L)$. The base, top, sections, layers, and tip of a general brick is the reorientation of the those of the standard brick to fit with the new choice of anchor and flag. The definitions of sails, units, strips, etc. are also all modified according to the new orientation.

In [11] the authors essentially show that a good sail can become completely infected under the bootstrap percolation dynamics if the bottom layer is completely infected. We need a refinement of this result, as we do not wish to infect everything, but instead we wish to move the infection from some set to another in \mathbb{Z}^3 whilst not increasing the number of infected sites of the configurations restricted to a finite domain by too much.

The following series of lemmas will show how to propagate infection from certain sets of sites in the base of B to any collection of sites in the tip of B.

Lemma 24. Let η be an initial configuration on the brick B. Suppose B is good with respect to η and let S denote the sail of B. Fix i and consider the configuration $\eta' = \eta^{S_i \leftarrow i}$. Then there exists a sequence of legal moves from η' to η'' of length at most CL where every site in S_{i+1} becomes infected in η'' , and η'' agrees with η outside of S_{i+1} and possibly a set of sites consisting of at most 2 boundary sites in S_i and 16 sites in $S_i + e_3$ that lie on the boundary of B.

Proof. Without loss of generality assume B is the standard brick. By property 5 of a good brick there exists some infected site in $S_i + e_3$. We proceed unit by unit. Suppose u is a unit in $S_i + e_3$ that contains an infected site, z. First we may cure $z - e_3 \in S_i$. Then we may infect a site in $S_i + e_3$ connected to the already infected sites of $S_i + e_3$ and cure the corresponding site in S_i below the newly infected site. The set $S_i + e_3$ is connected so we may proceed until every site in $S_i + e_3$ is infected and all but one site in each of the boundary units of S_i are healthy.

If S_i is an internal layer then $S_{i+1} = S_i + e_3$ and we are done. Otherwise suppose S_i is a transition layer and let $P_0 = S_i + e_3$ be viewed as a path of units. For $l \geq 0$ we proceed inductively. Suppose P_l is a path of infected units consisting of steps e_1 and $-4e_2$ such that for every $u \in P_l$, either $u \in S_{i+1}$ or $u - e_1 - 4e_2 \in S_{i+1}$. If P_l contains S_{i+1} then it differs from $S_i + 1$ by at most four boundary units and we are done. Otherwise there exists some non-boundary external corner unit $u \in P_l$ such that $u \notin S_{i+1}$ and $u - e_1 - 4e_2 \in P_l$. Since u is an external corner unit, $u - e_1$ and $u - 4e_2 \in P_l$. Thus we infected every site in $u - e_1 - 4e_2$ and cure u. This creates a new path of units P_{l+1} that satisfies either $u' \in S_{i+1}$ or $u' - e_1 - 4e_2 \in S_{i+1}$ for every $u' \in P_{l+1}$. Continue until no external corner units exists. This final path of infected units will contain all of S_{i+1} plus at most 4 boundary units of $S_i + e_3$.

The following lemma generalizes the statement of Lemma 24.

Lemma 25. Let η be an initial configuration on the brick B. Suppose B is good with respect to η and let S denote the sail of B. Let V be a set of sites restricted to a single section in the base of B, such that V separates B into two connected components B^- and B^+ , where B^+ is the part containing the top of B. Let $X_1 = V \cap \bar{S}$ and X_2 be any subset of $B^+ \cap \bar{S}$. There is a sequence of legal moves of length $O(L^2)$, starting from $\eta^{X_1 \leftarrow i}$ and ending at $\eta^{X_1 \cup X_2 \leftarrow i}$, where at any time in the sequence the configuration differs from η on a set of at most $|X_1| + |X_2| + O(L)$ sites.

Proof. Without loss of generality assume B is the standard brick. Any results here apply by changing the orientation of the moves.

Since V is a separating set for B, The paths (of units), S_j and $S_j + e_3$, are partitioned in to connected collections of sites are either entirely in B^+ or B^- .

Let i denote the lowest layer in B that contains a site in $V \cap \bar{S}$. No site in S_i is in B^+ , otherwise V would not separate B. Thus each $x \in S_i$ is either in V or B^- .

Consider the initial configuration $\eta' = \eta^{S_i \leftarrow i}$ obtained by infecting every site in S_i from η . By Lemma 24 there exists a sequence of legal moves starting from η' that infects every site in S_{i+1} while leaving healthy all but 20 sites in S_i and $S_i + e_3$. Repeat this process, infecting subsequent lines, except for the boundary points. Any time a site in X_2 is to become healthy, leave it infected. Eventually every site in X_2 will become infected as this process will at some point infect every site in S_i that lies above S_i , which includes all of $S_i \cap S_i$. Infecting each subsequent line and curing the previous takes at most CL steps and leaves behind at most 20

infected sites on each line that are not necessarily in X_2 . There are at most 32L layers that need to be infected in $\bar{S} \cap B$ before every site in X_2 has been infected. The most number of infected sites in this process is $|\eta| + |S_i| + |X_2| + O(L)$. Let Γ' denote this sequence of legal moves that starts at η' and ends with X_2 completely infected. The number of moves in Γ' is at most $O(L^2)$. If $V = B_i$, Γ' would be the sequence we are after. We will construct Γ by ignoring moves of Γ' that occur on or below V.

Each step in Γ' consists of curing or infecting a site x, or leaving it unchanged. Now consider the related censored sequence of moves, Γ , starting from $\eta' = \eta^{X_1 \leftarrow i}$ defined as follows. Suppose x is the site to be updated in Γ' at time t. If $x \in B^-$ or $x \in X_1$ then do nothing in Γ at time t. Otherwise act in the same way as Γ' . We claim that for each t the set of infected sites in $\Gamma'_t(\eta') \cap B^+$ is the same as the set of infected sites in $\Gamma_t(\eta^{S_i \leftarrow i}) \cap B^+$. Suppose for $t \geq 0$ the claim is true up to time t, and the move at time t is at a site t is a legal move, so there exists at least 2 neighbors of t that are in t. Those neighbors are either in t or t in which case they also must be infected in t in the claim therefore t in the claim remains true for t in the claim therefore t in the claim remains true for t in the claim remains true for t is legal and therefore t in the claim remains true for t in the claim remains true for

Thus every move in Γ is legal. Moreover, $X_2 \subseteq B^+$ and thus X_2 is infected in $\Gamma_t(\eta^{X_1 \leftarrow i})$ when it is infected in $\Gamma_t'(\eta')$. The configuration $\Gamma_t(\eta)$ differs from η on a set of size at most $|X_1| + |X_2| + O(L)$ and the length of Γ equals the length of Γ' .

Once X_2 is completely infected, reverse the sequence of moves, except that when a site in X_1 or X_2 is to be cured, ignore that move, thus leaving that site infected. The resulting configuration will have sites that are infected only if they are either in X_1 or X_2 or were infected in η . The full sequence will take at most twice the number of steps in Γ , $O(L^2)$.

The following corollary shows how to cure a collection of infected sites that lie further up the sail.

Corollary 26. Let B be a good brick with sail S for a configuration η on B. Let V be a set of sites that separates B into two connected components B^+ and B^- . Let X_2 be a set in $B^+ \cap \bar{S}$ and let $X_1 = V \cap \bar{S}$. There exists a sequence of moves of length at most CL^2 that begins at $\eta^{X_1 \cup X_2 \leftarrow i}$ and ends at $\eta^{X_1 \leftarrow i}$ where each configuration in the sequence differs from η on a set of size at most $|X_1| + |X_2| + O(L)$.

Proof. By Lemma 25, there is a sequence of moves that starting from $\eta^{X_1 \leftarrow i}$ and ending at $\eta^{X_1 \cup X_2 \leftarrow i}$. Apply the reverse of this sequence.

Starting from a brick B with some layer in the base of the sail completely infected, we will show how to propagate this infection to a translation of B, while curing most of the infected sites in the original brick B.

A brick, B, points to another brick, B', if the tip of B coincides exactly with one of the four sections in the base of B'. This is denoted by $B \triangleright_k B'$ where k is the corresponding section in B' which coincides with the tip of B.

Lemma 27. Let B be a good brick that points to a good brick B', with sails S and S' respectively. Then $|S \cap S'| = O(L)$.

Proof. Assume without loss of generality the cells of B have orientation given by (1, 4, 16) while the cells of B' have orientation (16, 1, 4).

Fix a layer in $B_i \subset B$ in the tip of B. By definition $X_i = B_i \cap S$ is a path of units, denote $\{u_i\}$ with steps $u_{i+1} - u_i \in \{e_1, 4e_2\}$ such that at most three consecutive steps are equal.

Similarly the set $X_i' = S' \cap B_i$ is a path of strips $\{s_i\}$. The step $s_{i+1} - s_i \in \{e_2, 16e_1, e_2 + 16e_1\}$ with at most three consecutive steps of type e_2 .

Let us consider the e_1 coordinates of $\{u_i\}$ and $\{s_i\}$. Every four steps the e_1 coordinate of $\{u_i\}$ grows by at most 3 while the e_1 coordinates of $\{s_i\}$ grows by at least 16. Thus, the size of the intersection of X_i and X'_i is O(1) and therefore the size of intersection of S and S' is O(L).

The next lemma is an extension of Lemma 25 which allows us to pass infection from the base of one brick to the tip of the next while staying within an O(L) Hamming distance from the original configuration.

Lemma 28. Let η be a configuration on $B \cup B'$ such that B and B' are good bricks with respect to η such that B points to B' with corresponding oriented sails S and S'. Let V be a separating set in a section of the base of B, and $X_1 = V \cap \bar{S}$. For any subset of sites X' in the tip of $B' \cap \bar{S}'$, there exists a sequence of $O(L^2)$ moves starting from $\eta^{X_1 \leftarrow i}$ and ending at $\eta^{X_1 \cup X' \leftarrow i}$ while each configuration in the sequence differs from η on a set of size at most $|X_1| + |X_2| + |X'| + O(L)$.

Proof. Let $X_2 = S \cap \bar{S}'$. From Lemma 25 there exists a sequence of length at most $O(L^2)$ of moves Γ starting at $\eta^{X_1 \leftarrow i}$ and ending at $\eta^{X_1 \cup X_2 \leftarrow i}$ such that the number of infected sites at any step in the sequence is at most $|I(\eta)| + |X_1| + |X_2| + O(L)$. By Lemma 27, the size of $S \cap S'$ is at most O(L), and the size of X_2 is at most double the size of $S \cap S'$. Moreover, S is a separating set for B' and thus, again by Lemma 25, there exists a sequence of moves, Γ' starting from $\eta^{X_1 \cup X_2 \leftarrow i}$ that ends in $\eta^{X_1 \cup X_2 \cup X' \leftarrow i}$ within Hamming distance $|X_1| + |X_2| + |X'| + O(L)$ if η . Finally, the sequence $rev(\Gamma)$ is a legal sequence of moves starting from $\eta^{X_1 \cup X_2 \cup X' \leftarrow i}$ and ending at $\eta^{X_1 \cup X' \leftarrow i}$ since $\eta^{X_1 \cup X_2 \leftarrow i}$ agrees with $\eta^{X_1 \cup X_2 \cup X' \leftarrow i}$ on B and the moves of Γ are contained entirely in B. The sequence of moves $\Gamma + \Gamma' + rev(\Gamma)$ satisfies conditions of the lemma and has The length of these three sequence is at most $O(L^2)$.

We specify a sequence of bricks $\mathcal{B} = \{B^i\}_{i=0}^3$.

- $\bullet \ B^0=((0,0,0);(4L,16L,32L)),$
- $\bullet \ B^1=((-12L,16L,32L);(20L,12L,16L)),$

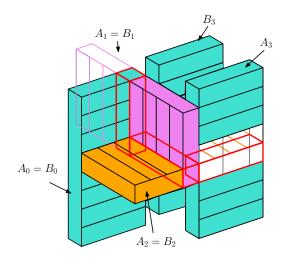


FIGURE 5.1. $B^0 = A^0$ is the left turquoise brick, B^1 and A^1 are represented by the pink brick, B^2 and A^2 are both represented by the orange brick (with different sail orientations), and B^3 and A^3 are the turquoise translations to the right of B^0 . The red outlines are where the tip of a brick coincides with the base othe another brick.

- $B^2 = ((20L, 0, 16L); (4L, 32L, 20L)),$
- $B^3 = ((4L, 16L, 4L); (8L, 32L, 36L)).$

Similarly define the sequence $\mathcal{B}' = \{A^i\}_{i=0}^3$ as:

- $\bullet \ A^0 = B^0,$
- $A^1 = B^1$.
- $A^2 = ((4L, 0L, 16L); (20L, 32L, 20L)),$
- $A^3 = ((16L, 16L, 4L); (20L, 32L, 36L)).$

The sequences satisfy

$$B^0 \triangleright_3 B^1 \triangleright_3 B^2 \triangleright_3 B^3$$

and

$$A^0 \triangleright_3 A^1 \triangleright_3 A^2 \triangleright_3 A^3.$$

and both B^3 and A^3 are translations of $B^0 = A^0$ See Fig. 5.

Note that B^2 and A^2 share the same set of sites but have flipped orientations. Both \mathcal{B} and \mathcal{B}' are called translation sequences. Given certain conditions on the bricks in \mathcal{B} or \mathcal{B}' , certain infected sites in B can propagate to infected sites in B^3 or A^3 .

We also define another sequence of bricks called a cleaning sequence, denoted $C = \{C^i\}_{i=0}^7$ such that $B^3 \triangleright_0 C^0$, $A^3 \triangleright_3 C^0$ and

$$C^0 \triangleright_0 C^1 \triangleright_0 C^2 \triangleright_3 C^3 \triangleright_3 C^4 \triangleright_2 C^5 \triangleright_3 C^6 \triangleright_0 C^7 \triangleright_0 B^0.$$

This sequence of bricks is used to return the sites in \mathcal{B} or \mathcal{B}' outside B^3 or A^3 to some original state. We will not specify the cleaning sequence as it is not unique. Figure 5.2 gives an example.

Our goal will be to show that we can infect sites in either B^3 or A^3 given a specific infected set of sites X in section 3 of $B = B^0 = A^0$ and conditions on the bricks B^i or A^i for i = 0, 1, 2, 3.

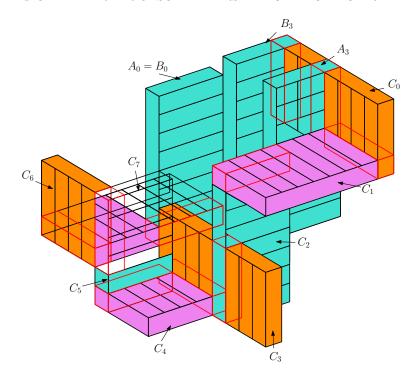


FIGURE 5.2. A sequence of eight bricks $\{C^i\}$, that facilitate cleaning outside A^3 or B^3 . The tips of B^3 and A^3 point to the bottom section and 3rd section, respectively, of C^0 . Starting from B^3 this example satisfies, $B^3 \triangleright_0 C^0 \triangleright_0 C^1 \triangleright_0 C^2 \triangleright_3 C^3 \triangleright_3 C^4 \triangleright_2 C^5 \triangleright_3 C^6 \triangleright_0 C^7 \triangleright_0 B^0$. The colors correspond to orientation. Some unused sections of bricks were removed or made transparent to show hidden bricks. Intersections of tips with sections in the base of subsequent bricks are highlighted in red.

Moreover, once we have spread the infected set of sites from B to either B^3 or A^3 we can return the configuration outside of B^3 or A^3 back to its original state but with the sites at X no longer infected.

Lemma 29. Let η be a configuration on the sites of the bricks in $\mathcal{B} \cup \mathcal{C}$. Let the bricks in \mathcal{B} and \mathcal{C} be good and have sails pointing in the appropriate direction, denoted by S^i and R^i , respectively, for the sails of the corresponding brick in \mathcal{B} or \mathcal{C} .

Let V be some a separating set in section 3 of B^0 and $X = V \cap \bar{S}^0$. Let $X' = S^2 \cap \bar{S}^3$. There exists a sequence of legal moves, Γ , starting from $\eta^{X \leftarrow i}$ and ending at $\eta^{X' \leftarrow i}$. The length of Γ is at most $O(L^2)$ and each configuration in the sequence differs from η on a set of size O(L). A similar statement holds for \mathcal{B}' .

Proof. This is simply an extension of Lemma 28. For i=0,1,2 each of the sails, S^i , are separating sets in the section 3 of the subsequent brick B^{i+1} . For i=0,1,2, let $X^i=S^i\cap \bar{S}^{i+1}$ and Γ^i be a sequence of legal moves from $\eta^{X^i\leftarrow i}$ that ends at $\eta^{X^i\cup X^{i+1}\leftarrow i}$. Then $\Gamma^0+\Gamma^1+\Gamma^2$ is a legal sequence of moves starting from $\eta^{X^0\leftarrow i}$ that ends at $\eta^{X^0\cup X^1\cup X^2\cup X^3\leftarrow i}$. The reverse of $\Gamma^0+\Gamma^1$ is legal starting from this configuration, ending at $\eta^{X^0\cup X^3\leftarrow i}$.

Repeat a similar argument through the bricks \mathcal{C} . For $i=0,\cdots,6$, let $Y^i=R^i\cap \bar{R}^{i+1}$ and let $Y^7=R^7\cap S^0$. There is a legal sequence starting from $\eta^{X^0\cup X^3\leftarrow i}$ that ends at $\eta^{X^0\cup X^3\cup Y^7\leftarrow i}$. The sail R^7 is a separating set that lies in section 0 of B^0 . By Corollary 26, there exists a sequence of legal moves restricted to the sites in B^0 that begins at $\eta^{X^0\cup X^3\cup Y^7\leftarrow i}$ and ends at $\eta^{X^3\cup Y^7\leftarrow i}$. The reverse of the sequence that infected Y^7 from X^3 can now be applied to $\eta^{X^3\cup Y^7\leftarrow i}$ to end at the desire configuration $\eta^{X^3\leftarrow i}$.

The same argument applies to \mathcal{B}' , using the same set \mathcal{C} .

Altogether the translation of infection to $\eta^{X^3 \leftarrow i}$ took at most $O(L^2)$ where each step in the configuration differed from η on a set of size O(L).

Analogous to the two-dimensional case, we define good paths of bricks and super-good paths of bricks along which infections will propagate.

Definition 30. Fix a configuration η . Consider a possible bi-infinite sequence in \mathbb{Z}^3 , denoted by $\cdots z_{-1}, z_0, z_1, \cdots$. We say that this sequence defines a *good path of bricks* if the following hold:

- (1) $z_i + B$ is good,
- (2) for all $C \in \mathcal{C}$, $z_i + C$ is good
- (3) one of the two following conditions hold:
 - either $z_{i+1} + B = z_i + B^3$ and $z_i + B^j$ are good for j = 0, 1, 2, 3.
 - or $z_{i+1} + B = z_i + A^3$ and $z_i + A^j$ are good for j = 0, 1, 2, 3.

Definition 31. Fix a configuration η and a good path of bricks $z_{-l}, \dots z_0$. We say this path is super-good if for some i, the brick $z_i + B$ has a sail whose bottom layer is completely infected.

Proposition 32. Fix a configuration η . Let $z_{-l} \cdots z_0 = -(L+1, 4L+4, 16L)$, be a super good path. Then there exists a sequence legal moves Γ of length $N = O(L^2 l)$ such that

- (1) $\Gamma^N(\eta)(0) = 0$, i.e. the origin is infected the final configuration,
- (2) for all $i \leq N$, $\Gamma^{i}(\eta)$ differs from η on a set of size is at most O(L),
- (3) for all $i \leq N$, $\Gamma^i(\eta)$ agrees with η on all sites outside $x_i + [O(L)]^2$, where x_i is the location of the ith move.

Proof. This follows from Lemma 29 by propagating the infected line guaranteed by the path being super-good. \Box

Similar to the two-dimensional case, we need to define the scaling. Let $L = 2\log(1/q)/q$, $l = q^{-L-1}$. We also define the following events:

- $E := \{ \text{ there exists super-good path } z_{-l} \cdots z_0 = -(L+1, 4L+4, 16L) \}$
- $A := \{ \eta(0) = 0 \}.$

All that remains is to show that E has high probability.

Lemma 33. The probability that there exists a bi-infinite good path containing $z_0 = -(L + 1, 4L + 4, 16L)$ tends to 1 as $(\pi, q) \to (0, 0)$.

Proof. The probability for a fixed brick to be good tends to 1 as $(\pi, q) \to (0, 0)$. Properties 1-5 in the definition of a good brick a satisfied with high probability according to [11, Proposition 6] while the last property holds with high probability through an argument similar to that found in the proof of Claim 13.

Construct the lattice of bricks that are translates of $z_0 + B$. Two bricks, z + B and z' + B, will be connected by an edge if z, z' is a good path of bricks of size two. This induces an directed edge-percolation process on a two dimensional lattice. This process has finite range dependencies, thus by LSS [18] and the fact that oriented percolation contains an infinite cluster when the percolation parameter is large enough, there exists a bi-infinite good path containing z_0 with probability that tends to 1 as $(\pi, q) \to (0, 0)$.

Lemma 34. The probability that there exists a super-good path of length l ending at $z_0 = -(L+1, 4L+4, 16L)$ tends to 1 as $(\pi, q) \to (0, 0)$.

Proof. This follows the same argument as in the proof of Claim 16. \Box

The proof of Theorem 3 is direct application of Proposition 9, Lemma 34, and Proposition 29. \Box

6. Questions

- Match the upper and lower bound in Theorem 3.
- Can the methods of [12] be used in order to analyze the FA3f model on polluted \mathbb{Z}^3 ? More generally, what can we say about the Fredrickson-Andersen model with general threshold in general dimension?
- The methods introduced above are rather soft, in the sense that they only require some high probability event from which a path that infects the origin could be constructed. It is therefore plausible that they could be applied for models in which other, stronger techniques, fail, e.g., KCMs on finite graphs (whose dynamics is not ergodic).
- Can we analyze other time scales of the system, and in particular the typical scale in which correlation of local functions is lost (see, e.g., [26, section 3.6])?

ACKNOWLEDGEMENTS

We would like to Cristina Toninelli for intoducting us to this problem and to each other, as well as for the useful discussions.

REFERENCES

- [1] Michael Aizenman and Joel L Lebowitz. Metastability effects in bootstrap percolation. *Journal of Physics A: Mathematical and General*, 21(19):3801, 1988.
- [2] József Balogh, Béla Bollobás, Hugo Duminil-Copin, and Robert Morris. The sharp threshold for bootstrap percolation in all dimensions. *Transactions of the American Mathematical Society*, 364(5):2667–2701, 2012.
- [3] József Balogh and Boris G Pittel. Bootstrap percolation on the random regular graph. Random Structures & Algorithms, 30(1-2):257–286, 2007.

- [4] Béla Bollobás, Hugo Duminil-Copin, Robert Morris, and Paul Smith. Universality of two-dimensional critical cellular automata. arXiv preprint arXiv:1406.6680, 2016.
- [5] Béla Bollobás, Karen Gunderson, Cecilia Holmgren, Svante Janson, and Michał Przykucki. Bootstrap percolation on Galton-Watson trees. Electronic Journal of Probability, 19, 2014.
- [6] Anton Bovier and Frank Den Hollander. *Metastability: a potential-theoretic approach*, volume 351. Springer, 2016.
- [7] N. Cancrini, F. Martinelli, C. Roberto, and C. Toninelli. Kinetically constrained spin models. *Probab. Theory Related Fields*, 140(3-4):459–504, 2008.
- [8] R. Cerf and F. Manzo. The threshold regime of finite volume bootstrap percolation. *Stochastic Process*. *Appl.*, 101(1):69–82, 2002.
- [9] Hugo Duminil-Copin and Vincent Tassion. A new proof of the sharpness of the phase transition for Bernoulli percolation and the Ising model. *Comm. Math. Phys.*, 343(2):725–745, 2016.
- [10] Glenn H Fredrickson and Hans C Andersen. Kinetic Ising model of the glass transition. *Physical review letters*, 53(13):1244, 1984.
- [11] Janko Gravner and Alexander E Holroyd. Polluted bootstrap percolation with threshold two in all dimensions. arXiv preprint arXiv:1705.01652, 2017.
- [12] Janko Gravner, Alexander E Holroyd, and David Sivakoff. Polluted bootstrap percolation in three dimensions. arXiv preprint arXiv:1706.07338, 2017.
- [13] Janko Gravner and Elaine McDonald. Bootstrap percolation in a polluted environment. *Journal of Statistical Physics*, 87(3):915–927, 1997.
- [14] Geoffrey Grimmett. Percolation. Springer, 1999.
- [15] Alexander E Holroyd. Sharp metastability threshold for two-dimensional bootstrap percolation. *Probability Theory and Related Fields*, 125(2):195–224, 2003.
- [16] Svante Janson. On percolation in random graphs with given vertex degrees. *Electronic Journal of Probability*, 14:86–118, 2009.
- [17] Svante Janson, Tomasz Luczak, Tatyana Turova, and Thomas Vallier. Bootstrap percolation on the random graph $G_{n.p.}$ Ann. Appl. Probab., 22(5):1989–2047, 2012.
- [18] T. M. Liggett, R. H. Schonmann, and A. M. Stacey. Domination by product measures. *Ann. Probab.*, 25(1):71–95, 1997.
- [19] Thomas M. Liggett. Interacting particle systems. Classics in Mathematics. Springer-Verlag, Berlin, 2005. Reprint of the 1985 original.
- [20] Laure Marêché, Fabio Martinelli, and Cristina Toninelli. Exact asymptotics for Duarte and supercritical rooted kinetically constrained models. arXiv preprint arXiv:1807.07519, 2018.
- [21] Fabio Martinelli. Lectures on Glauber dynamics for discrete spin models. In *Lectures on probability theory* and statistics (Saint-Flour, 1997), volume 1717 of *Lecture Notes in Math.*, pages 93–191. Springer, Berlin, 1999.
- [22] Fabio Martinelli, Robert Morris, and Cristina Toninelli. Universality results for kinetically constrained spin models in two dimensions. *Communications in Mathematical Physics*, pages 1–49, 2018.
- [23] Fabio Martinelli and Cristina Toninelli. Towards a universality picture for the relaxation to equilibrium of kinetically constrained models. arXiv preprint arXiv:1701.00107, 2016.
- [24] Assaf Shapira. Metastable behavior of bootstrap percolation on Galton-Watson trees. arXiv preprint arXiv:1706.08390, 2017.
- [25] Assaf Shapira. Kinetically constrained models with random constraints. arXiv preprint arXiv:1812.00774, 2018.

- [26] Assaf Shapira. Bootstrap percolation and kinetically constrained models in homogeneous and random environments. 2019. Ph.D. thesis.
- [27] Aernout C. D. van Enter. Proof of Straley's argument for bootstrap percolation. J. Statist. Phys., 48(3-4):943–945, 1987.

 $E ext{-}mail\ address: assafshap@gmail.com}$

LPSM UMR 8001, Université Paris Diderot, CNRS, Sorbonne Paris Cité

 $E ext{-}mail\ address: eslivken@gmail.com}$

LPSM UMR 8001, Université Paris Diderot, CNRS, Sorbonne Paris Cité