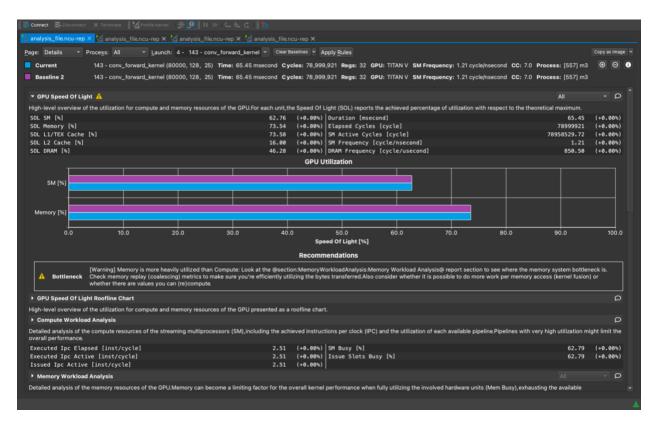
ECE 408 Final Project: Final Milestone

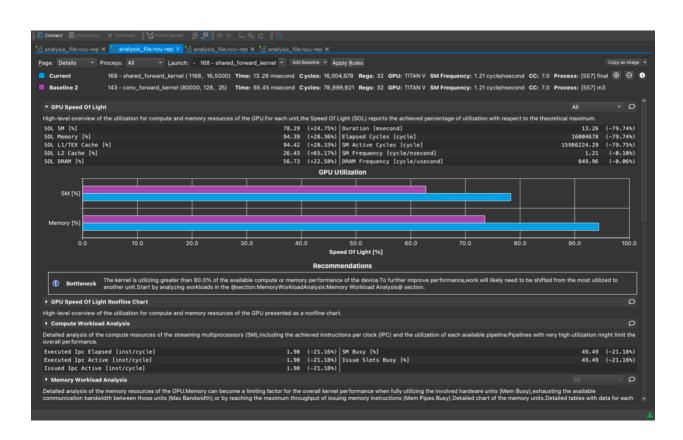
Vedant Vipul Jhaveri

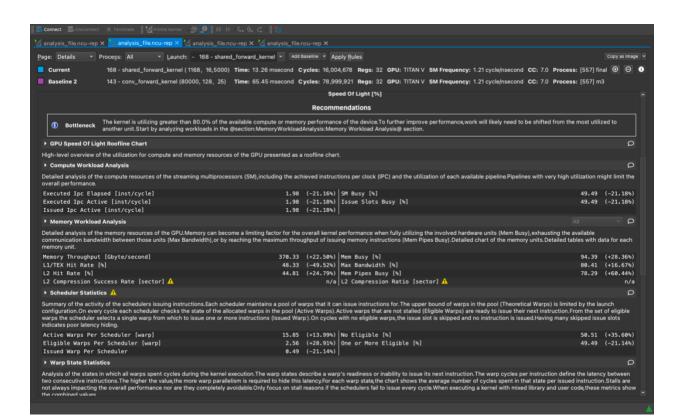
NetID: vedantj2

I used the Kernel code from PM2 with a tile width of 8 as the baseline to check against all the mentioned optimizations. All tests gave an Accuracy of 0.8714 meaning there was no compromise on the result by the optimizations made by me.



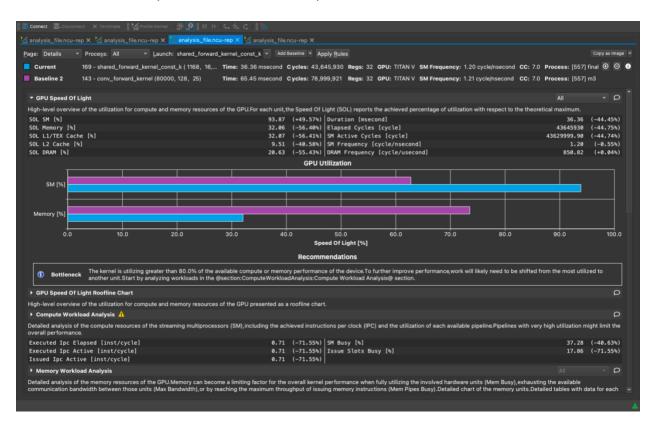
First, I implemented the required shared memory matrix multiplication with GPU loop unrolling. Despite being a challenge to understand how to unroll for GPU works I was able to figure it out. I have used a Tile width of 16 for this kernel and the reasoning is I found it to work the best by using sweeping parameters mentioned later for Extra credit. As you can see from the figure below, we use more memory, by about 28.36%, and SMs but the benefit far outweighs the higher memory usage since it runs about 79.74% faster than the baseline and uses about 79.74% less overall cycles and active SM cycles. Due to larger processing powers required we had to launch the kernel twice hence there was less processing power needed per kernel, but it overall still beats the baseline. The main bottleneck is the number of threads that can be processed for 10k images since each kernel launch makes us allocate and free memory for x_unrolled and the kernel launch itself takes a standard minimum time. There is a much better L2 cache hit rate which is usually more import. The shared memory matrix multiply is faster than convolution mainly because of lower number of for loops resulting in a lower time complexity of processing.



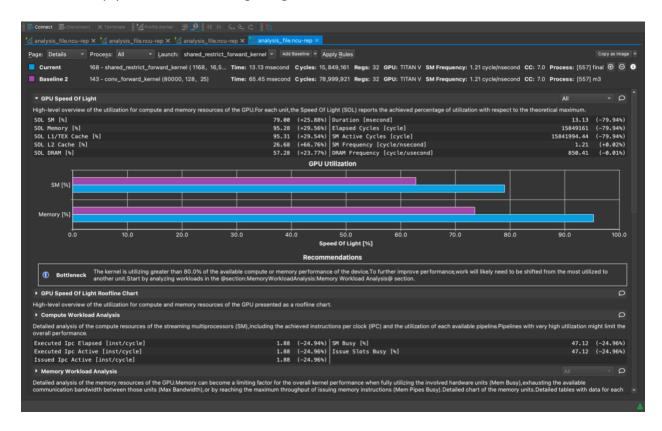


Extra Credit:

1. On top of the final milestone optimization, I decided to put k in constant memory to reduce the memory usage which it greatly did. While the final milestone optimization used 28% more memory than the baseline, this uses 56.4% LESS memory than the baseline which is shocking at first but with huge batch sizes and tiling for better memory performance storing k in constant memory proved to be a great improvement memory wise. Both kernels combined took ever so slightly more time than the baseline but the better memory utilization makes this optimization a win for us.



Restrict and loop unroll ever so slightly improved the time running time over x_unroll +
matrix multiply and used slightly more memory. If runtime and calculation time is of
utmost importance, then this is a decent optimization otherwise x_unroll + matrix
multiply is more than enough to give the needed boost.



3. By sweeping parameters I changed the tile width which changed the block sizes and how the computation for the convolution proceeds. The baseline shown above on Page 1 implements the basic convolution with a Tile Width of 8. Now I will post the results for tile widths of 16, 4, and 32 respectively to show the difference in performance and why on page 2 and my final milestone implementation onward I used tile width of 16.

For a very small increase in memory usage compared to the baseline, 7.9%, we get a better utilization of the DRAM as it reduces by 37.35% and an even better utilization of the L2 cache by about 39.39% less usage compared to the baseline with a tile width of 8. To put a cherry on top, we also get a faster runtime by about 4.8%.

The time taken increases by 207% for a tile width of 4 which is enough to reject this tile width.

For tile width of 32 we use about 22% less memory compared to baseline but the runtime is slower by 33% which is not a good enough tradeoff hence the best parameter by sweeping was tile width of 16.

