

The Torsors

Exercise 01 :

Considering the following vectors $\overrightarrow{OA} = 3a\vec{i}$, $\overrightarrow{OB} = 4a\vec{j}$ and $\overrightarrow{OC} = 5a\vec{k}$,

Determine the torsor at O of the vectors \overrightarrow{AB} and \overrightarrow{CB} .

Exercise 02 :

Let the torsor $[T_1]_O$ be defined at point O , the origin of a direct orthonormal frame $R(O, \vec{i}, \vec{j}, \vec{k})$, by the three following vectors:

$\vec{V}_a = -2\vec{i} + 3\vec{j} - 7\vec{k}$ defined at point $A(1,0,0)$

$\vec{V}_b = 3\vec{i} - \vec{j} - \vec{k}$ defined at point $B(0,1,0)$

$\vec{V}_c = -\vec{i} - 2\vec{j} + 8\vec{k}$ defined at point $C(0,0,1)$

Let $[T_2]_O$ be a torsor defined at point O by its reduction elements \vec{R}_2

and \vec{M}_{2O} such that: $[T_2]_O = \begin{cases} \vec{R}_2 = 2\vec{i} + \vec{j} + 3\vec{k} \\ \vec{M}_{2O} = -3\vec{i} + 2\vec{j} - 7\vec{k} \end{cases}$

- 1) Determine the reduction elements of $[T_1]$ at point O .
- 2) Determine the pitch and the central axis of the torsor $[T_2]$
- 3) Calculate the sum of the two torsors.
- 4) Calculate the comoment of the two torsors.
- 5) Calculate the scalar invariant of the sum torsor $[T] = [T_1] + [T_2]$.

Exercise 03 :

Let A be a point in space in $R(O, \vec{i}, \vec{j}, \vec{k})$, with

$\overrightarrow{OA} = \frac{21}{9}\vec{i} - \frac{4}{9}\vec{j} - \frac{12}{9}\vec{k}$ and a vector $\vec{V}_1 = -3\vec{i} + \vec{j} + 3\vec{k}$ whose axis passes through point A .

Let $[T_2]_O$ be a torsor defined at point O by its reduction elements \vec{R}_2 and \vec{M}_{2O} such that:

$$[T_2]_O = \begin{cases} \vec{R}_2 = (\alpha - 4)\vec{i} + \alpha\vec{j} + 3\alpha\vec{k} \\ \vec{M}_{2O} = (2\alpha + 9)\vec{j} + (-3\alpha - \frac{2}{3})\vec{k} \end{cases}$$

Exercise 05 :

1. Determine the reduction elements of the torsor $[T_1]_O$ whose resultant is the vector \vec{V}_1 .
2. For what value of α are the two torsors equal;
3. Deduce the pitch and the central axis of the torsor $[T_2]_O$ for this value of α .
4. Calculate the product of the two torsors for $\alpha = 2$.

In a direct orthonormal frame $R(O, \vec{i}, \vec{j}, \vec{k})$ we consider the vector field $\vec{V}(M)$ whose components are defined as a function of the coordinates (x, y, z)

of M by:

$$\begin{cases} V_x = 1 + 3y - tz \\ V_y = -3x + 2tz \\ V_z = 2 + tx - t^2y \end{cases}$$

Exercise 04 :

In the reference frame $R(O, \vec{i}, \vec{j}, \vec{k})$, consider the points $A(3,0,0)$ and $B(-1,2,1)$ in the affine space.

Let $\vec{V}(M)$ be an equiprojective vector field defined as follows:

$$\vec{V}(O) = \begin{pmatrix} 1 \\ 1 \\ 4 \end{pmatrix}, \vec{V}(A) = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \vec{V}(B) = \begin{pmatrix} 2 \\ -1 \\ 9 \end{pmatrix}$$

1. Determine the resultant vector \vec{R} of the torsor associated with the field $\vec{V}(M)$.
2. Deduce the expression of the vector field $\vec{V}(M)$ at any point $M(x, y, z)$ in the space.
3. Determine the central axis Δ of the torsor.

1. Calculate the vector $\vec{V}(M)$ at point O .
2. For which values of t is this field antisymmetric?
3. For each value of t found, determine the reduction elements of the torsor (resultant and moment at O).
4. Decompose the torsor associated with $\vec{V}(M)$ into a sum of a couple and a slider, and indicate the reduction elements.
5. Determine the position of the central axis of the torsor for $t = 0$ and $t = 2$.