(iii)
$$\frac{dx}{dt} = kx$$
 (iii) $\frac{dx}{dt} = 1 - 8x$

(iiii) $\frac{dx}{dt} = k(t) \times (v) \frac{dx}{dt} = f(t) + hx$

$$x(t) = xg(t) + xp(t)$$
(o) $f(t) = tonst$, $x_p = C_2$ $x(t) = \frac{c_1e^{xt}}{xg} + \frac{c_2}{xp}$

(b) $\frac{dx}{dt} = kx + x \exp(\beta t)$ $\Rightarrow xp(t) = Ae$

$$\frac{dy}{dt} = ay + qx(t) \quad y(t) = ye^{at} \quad y = money \text{ in your bank}$$

$$\frac{dy}{dt} = ay \cdot e^{xp(at)} + \int e^{at} - g(s) \, ds$$

$$\frac{dy}{dt} = ay \cdot e^{at} + \frac{d}{dt} e^{at} \int e^{-as} q(s) \, ds$$

$$\frac{dy}{dt} = ay \cdot e^{at} + ae^{at} \int e^{-as} q(s) \, ds + e^{at} e^{-at} q(t)$$

$$\frac{dy}{dt} = a \left[y \cdot e^{at} + e^{at} \int e^{-as} q(s) \, ds \right] + q(t)$$

$$\frac{dy}{dt} = ay + q(t)$$

(i)
$$q(t) = const$$

(iii) $q(t) = cos(\omega t)$
(iv) $q(t) = H(t-T)$
(v) $q(t) = S(t-T)$
 $solution = f(T)$

3.2 Primer

linear 2nd order ODE constant coefficients.

$$a\frac{d^2x}{dt^2} + b\frac{dx}{dt} + cx = 0$$

$$\frac{d^2x}{dt^2} - \beta \frac{dx}{dt} + \delta x = 0 \qquad \beta = -\frac{b}{\alpha} , \quad x = \frac{c}{\alpha}$$

$$\beta = -\frac{b}{a} , \quad \gamma = \frac{c}{a}$$

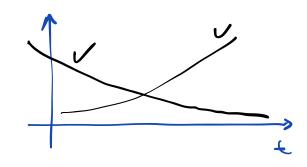
$$m^2 e^{mt} - \beta m e^{mt} + \gamma e^{mt} = 0$$

$$m^2 - \beta m + \gamma = 0$$
 — characteristic equation.

$$M_{1,2} = \frac{1}{2} \left[\beta \pm \sqrt{\beta^2 - 47} \right]$$

$$\beta = -\frac{1}{2}$$
, $Y = -\frac{1}{2}$
 $m_1 = -1$, $m_2 = \frac{1}{2}$

$$x(t) = c_1 e^{-t} + c_2 e^{t/2}$$



M1, M2 - real.

Complex roots
$$m_1 = p + iq$$
; $m_2 = p - iq$.

$$x_1(t) = e^{(p+iq)t} = e^{pt} e^{iq(t)}$$

$$x_2(t) = e^{(p-iq)t} = e^{pt} e^{-iq(t)}$$

De Moires theorem

$$\chi_{2}(t) = e^{pt} (los qe + i Sin qt)$$

 $\chi_{2}(t) = e^{pt} (los qt - i Sin qt)$

$$\frac{1}{2}(x_1(t) - x_2(t)) = iSing(t) e^{pt}$$

$$\frac{1}{2}(x_1(t) - x_2(t)) = cosq(t) e^{pt}$$

$$z(t) = c_1 e^{\rho t} cos(qt) + c_2 e^{\rho t} sin(qt)$$

$$\frac{d^2x}{dt^2} - \beta \frac{dx}{dt} + 8x = 0$$

$$y = \frac{dx}{dt}$$

$$\frac{dx}{dt} = y$$

$$\frac{dy}{dt} = \frac{d^2x}{dt^2} = \beta \frac{dz}{dt} - rx$$

$$\frac{dy}{dt} = \beta y - \gamma x$$

$$\frac{dn}{dt} = ax + by$$

$$\frac{dy}{Nf} = cx + dy$$

$$\frac{dy}{dt} = \beta y - \delta x$$

$$\frac{dx}{dt} = A x$$

$$\frac{dx}{dt} = ax + by$$

$$\frac{dx}{dt} = a + by$$

$$\frac{dx}{$$

$$A = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix}$$

$$A = \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \qquad e^A = 1 + A + \frac{A^2}{2!} \quad \dots$$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} + \frac{1}{2!} \begin{bmatrix} \lambda_1^2 & 0 \\ 0 & \lambda_2^2 \end{bmatrix} + \cdots$$

$$\begin{bmatrix} 1+\lambda_1+\frac{\lambda_1^2}{2!}+\cdots & 0 \\ 0 & 1+\lambda_2+\frac{\lambda_2^2}{2!}+\cdots \end{bmatrix}$$