

Presentation on Road Sign Detector and Driver Alert System Presented By

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Domain

- Road Safety: This project will focus driver's safety using Image processing techniques.
- Image Pre-Processing
- Deep Learning: The deep learning algorithm CNN is used due to its ability to recognize patterns in images.

List of Issues

- Bad lighting conditions make it harder to gather colour and contour information of traffic sign.
- Occluded Traffic sings with sunlight and dark.
- Motion blur and car vibration makes harder to retrieve images from the camera.
- Damaged traffic sign.

Issues to be focused

- Identify, categorize and warn to the driver for traffic signs.
- Safety of the drivers and the fellow travelers
- Clearer Diagnosis of road signs

Road Accident Statistics

During the calendar year 2020, there were close to 5lakh road accident in India, which resulted in more than 1.3lakhs death and inflicted injured on 5.2lakh persons. These numbers translate into one road accident every minute and a road accident death every 4 minute. More than half of these victims are in active age group of 25-65 years. Following graph gives percentage of the total number of accident took place and people killed from 2019-2020.



Introduction

Road traffic has been the major issue that most cities are facing these days. People neglect the importance of traffic signs which could prove deadly. Currently, the maps services assist us about some details of navigation, but it fails to provide essential information such as "U-turns, prohibited roads, speed-limits, speed breakers and diversions etc.", which are generally present on the signboards. These are of utmost importance for road safety but the drivers often miss out on them. There is urgent need for a mechanism which would be able to detect these signs and alert the drivers. So, an expert system based on CNN, will detect & recognize the signboards in real time.

- Traffic sign recognition system is a crucial research direction in computer vision and a significant section of Advanced Driver Assistance System (ADAS). It can be grouped into two technologies, traffic-sign detection and traffic-sign recognition. The correctness of detection will directly lead to the final identification results. Traffic signs contain necessary messages about vehicle safety and they show the latest traffic conditions, define road rights, forbid and allow some behaviors and driving routes, cue dangerous messages and so on. They can also help drivers identify the condition of the road, so as to determine the driving routes.
- Traffic signs have some constant characteristics that can be used for detection and classification, among them, color and shape are important attributes that can help drivers obtain road information. The image of traffic signs is often affected by some external factors, such as weather conditions. Therefore, traffic-sign recognition is a challenging subject and also a valuable subject in traffic engineering research.

Literature Survey

	J		
Author & Year	Adopted	Features	Challenges
	Scheme		
Md Tarequl Islam	Two	HSV Color space	Ability to label
(2020)	Convolutional	is used,	the signs,
	Neural Network	RGB to HSV	manually clicked
	using Classifier.	conversation,	pictures & online
		Moderate to high	downloaded.
		accuracy.	Classifier
			Challenges.
V.KOKILA,	(ADS) auto	Advanced	Image quality,
Mr.	driving	machine learning	Non-
N.VASUDEVAN(2020)	frameworks.	Classification.	informational
	Sign based	Image pre-	Pixel, Unwanted
	strategies, Shape-	processing	picture edges.
	based techniques.	methods.	
Chai K. Toh (2018)	Wireless digital	Wireless	Positioning of
	traffic signs	Transmission of	Traffic Signs
		traffic signs	Cost of
		Reduce complex	Installation is
		image	high
		recognition	
Ying Sun (2019)	Convolutional	Better Image	Need
	Neural Network	recognition	Consideration on
		Minimal Error	climatic factors.
Arturo de la	Image	Accuracy of	The highly
Escalera(1997)	processing,	image	probable sign
	Neural networks,	recognition.	regions are
	traffic signs		extracted. The
	recognition		most preferred
	Using Neural		are "pure" colors
	Network Model,		for better
	Keras.		visibility.

Problem Statement

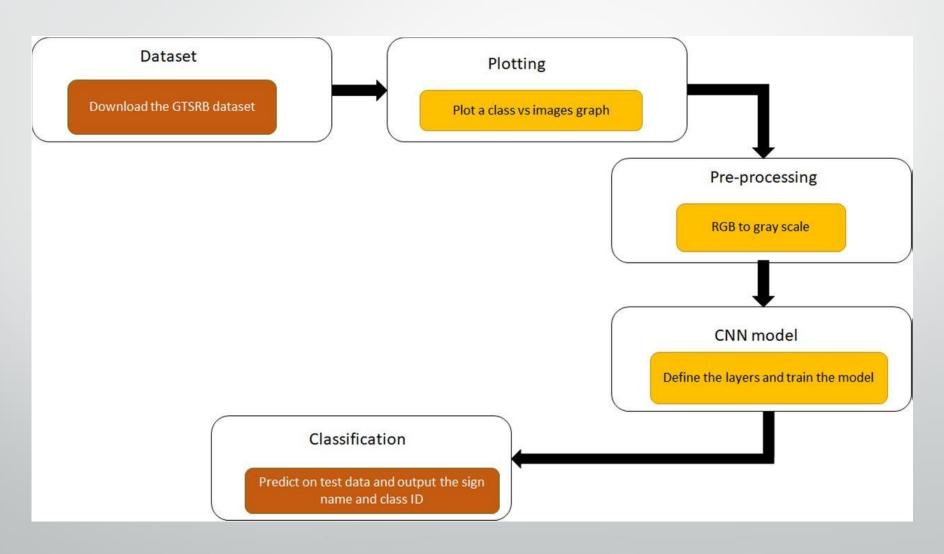
The objectives of the system is first to detect and then classify signs. This works well when we have lots of images as well as not clear ones.

For classifying images we are using Convolutional Neural Network Model

Why CNN is better than other Models

- CNN are hugely popular is because of their architecture the best thing is there is no need for feature extraction. The system learns to do feature extraction and the core concept of CNN is, it uses convolution of image and filters to generate invariant features which are passed on to the next layer. The features in next layer are convoluted with different filters to generate more invariant and abstract features and the process continues till one gets final feature / output (let say face of X) which is invariant to occlusions.
- another key feature is that deep convolutional networks are flexible and work well on image data. As one researcher points out, convolutional layers exploit the fact that an interesting pattern can occur in any region of the image, and regions are contiguous blocks of pixels. But one of the reasons why researchers are excited about deep learning is the potential for the model to learn useful features from raw data. Now, convolutional neural networks can extract informative features from images, eliminating the need of traditional manual image processing methods.

Proposed Solution



Methodology

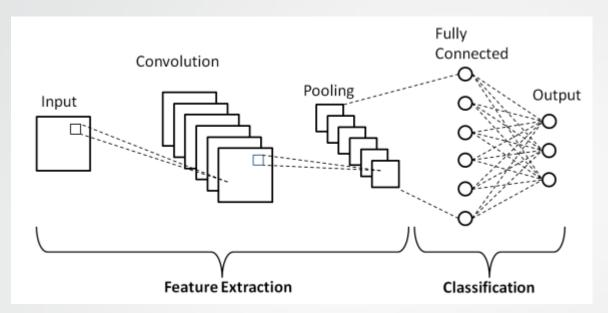
- Explore the Dataset
- The presence of a generalised dataset is crucial before moving on to the detection or classification.
- The GTSRB (German Traffic Sign Recognition Benchmark) dataset is the most popular of them.
- There are numerous images in it.
- The variety, backdrop, and colour variation of the traffic signs will aid in the model's performance accuracy.
- For this project, we are using the public dataset available at Kaggle:

Traffic sign Dataset

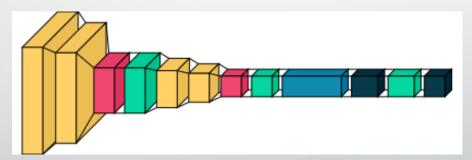
• The dataset contains more than 50,000 images of different traffic signs. It is further classified into 43 different classes the dataset is quiet varying, some of the classes have many images while some classes have few images. The size of the dataset is around 300MB. The dataset has a train folder which contains images inside each class and a test folder which we will use for testing our model.

Pre-Processing

```
for i in range(classes):
       path = os.path.join(cur_path,'train',str(i))
       images = os.listdir(path)
       for a in images:
           try:
               image = Image.open(path + '\\'+ a)
               image = image.resize((30,30))
               image = np.array(image)
               data.append(image)
               labels.append(i)
           except Exception as e:
               print(e)
 ✓ 10m 14.8s
cannot identify image file 'D:\\Traffic_Sign_Recognition\\train\\0\\archive - Shortcut.lnk'
```



Schematic diagram of a basic convolutional neural network (CNN) architecture.

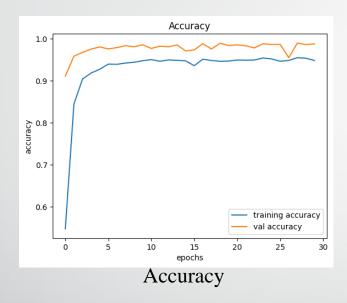


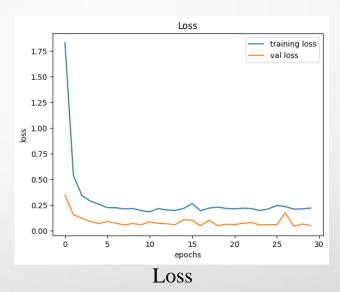
Visualization CNN model with its layers

• Test the model with test dataset

```
def testing(testcsv):
    y_test = pd.read_csv(testcsv)
    label = y_test["ClassId"].values
    imgs = y_test["Path"].values
    data=[]
    for img in imgs:
        image = Image.open(img)
        image = image.resize((30,30))
        data.append(np.array(image))
    X_test=np.array(data)
    return X_test,label
```

Accuracy and Loss Graph for testing data:





Accuracy Score for testing Data

```
# Score
score = model.evaluate(X_test, y_test, verbose=0)
print('Test Loss', score[0]*100)
print('Test accuracy', score[1]*100)

    8.1s

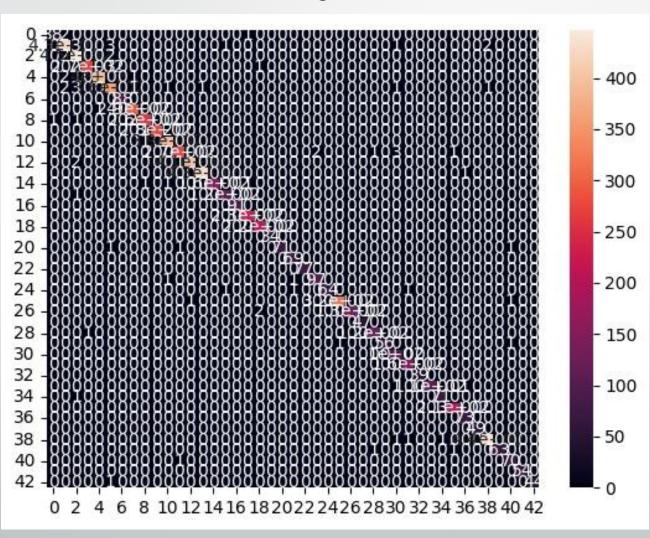
Test Loss 4.988387227058411
Test accuracy 98.81407618522644
```

Experiments

Building the front-end for the Model

```
rom flask im
                                                                    model = load_model('model/TSR2.h5')
from werkzeug.utils import secure_filename
from keras.models import load_model
                                                                    def test on img(img):
   ort numpy as np
from PIL import Image
                                                                         data=[]
                                                                        image = Image.open(img)
app = Flask(__name__)
                                                                        image = image.resize((30,30))
                                                                        data.append(np.array(image))
# Classes of trafic sians
classes = { 0:'Speed limit (20km/h)',
                                                                        X test=np.array(data)
           1: 'Speed limit (30km/h)',
                                                                        Y pred = model.predict(X test)
           2: 'Speed limit (50km/h)',
                                                                        return image, Y_pred
           3: 'Speed limit (60km/h)',
           4: 'Speed limit (70km/h)',
                                                                    def image processing(img):
           5: 'Speed limit (80km/h)',
           6: 'End of speed limit (80km/h)',
                                                                        plot,prediction = test_on_img(img)
           7: 'Speed limit (100km/h)',
                                                                        s = [str(i).strip().replace("\n","") for i in prediction][0][1:-1]
           8: 'Speed limit (120km/h)',
                                                                        s=[float(b) for b in s.split(" ")]
           9: 'No passing',
                                                                        a=[[index, num] for index, num in enumerate(s) if (num == max(s))][0]
           10: 'No passing veh over 3.5 tons',
           11: 'Right-of-way at intersection',
           12: 'Priority road',
                                                                        # print(type(s), type(s[0]), s)
           13: 'Yield',
           14: 'Stop',
                                                                        return [a[1], classes[a[0]]]
           15: 'No vehicles',
           16: 'Vehicle > 3.5 tons prohibited'.
           17: 'No entry',
                                                                    @app.route('/', methods=['GET', 'POST'])
           18: 'General caution'.
                                                                    def index():
           19: 'Dangerous curve left',
                                                                        return render template('index.html')
           20: 'Dangerous curve right',
           21: 'Double curve',
           22: 'Bumpy road',
                                                                    @app.route('/predict', methods=['GET', 'POST'])
           23: 'Slippery road',
                                                                    def upload():
           24: 'Road narrows on the right',
                                                                        if request.method == 'POST':
           25: 'Road work',
           26: 'Traffic signals',
                                                                             # Get the file from post request
           27: 'Pedestrians',
                                                                             f = request.files['file']
           28: 'Children crossing',
                                                                             f.save(secure filename(f.filename))
           29: 'Bicycles crossing',
                                                                             file path = os.path.abspath(secure filename(f.filename))
           30: 'Beware of ice/snow',
           31: 'Wild animals crossing',
                                                                             # Make prediction
           32: 'End speed + passing limits'.
                                                                             result = image_processing(file_path)
           33: 'Turn right ahead',
                                                                             result = '{0} ({1:02} %)'.format(result[1], round((result[0] * 100), ndigits=3))
           34: 'Turn left ahead',
                                                                             os.remove(file_path)
           35: 'Ahead only',
           36: 'Go straight or right',
                                                                             return result
           37: 'Go straight or left',
                                                                        return None
           38: 'Keep right',
           39: 'Keep left',
                                                                    if __name__ == '__main__':
           40: 'Roundabout mandatory',
           41: 'End of no passing',
                                                                        app.run(debug=True)
           42: 'End no passing vehicle > 3.5 tons' }
```

Model Evaluation through Confusion Matrix



Result

The trained CNN's test results reveal that the model is 98.81% accurate at identifying and detecting traffic signs. The experimental finding demonstrates the CNN model's strong recognition accuracy for detecting and identifying road signs.





Conclusion and Future Work

- This project presents a method for recognizing traffic signs using deep learning. This approach is efficient in identifying and recognizing traffic signs by utilizing image preprocessing, road sign detection, and classifying. Results of the testing show that the accuracy of this method is 98.81%.
- In future, we will keep extending our datasets to cover all classes of our traffic signs. Meanwhile, more newly developed models for visual object recognition, such as Mask R-CNN, CapsNet, and Siamese neural network would be included. Capsule neural network (CapsNet) has been employed for effectively identifying a class of traffic signs which have spatial relationships. Compared with the well-known deep neural networks, capsule networks tackle the topological relationship between visual objects. In addition, we will adopt professional evaluation metrics to assess the performance of our models from multiple aspects in future.

References

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