

# Astha Gupta

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INTERESTS	<b>Robot Locomotion, Machine Learning, Neurorobotics</b>	
EDUCATION	<b>European Master in Advanced Robotics Plus (EMARO+)</b>	<b>Sep 2018 - Aug 2020</b>
	Ecole Centrale de Nantes, France	GPA: 91/100
	University of Genoa, Italy	GPA: 97.64/100
	<b>Master of Science (Technology) in Information Systems</b>	<b>Aug 2012 - Jul 2016</b>
	Birla Institute of Technology and Science, Pilani, India	CGPA: 8.27/10
	<b>All India Senior School Certificate Examination (Class XII)</b>	<b>2012</b>
	Modern Vidya Niketan Sector-17, Faridabad, India	Percentage: 94.6%
PUBLICATIONS	<ul style="list-style-type: none"><li>• Zapf, M. P., <b>Gupta, A.</b>, Saiki, L. Y. M., &amp; Kawanabe, M. (2018, August). Data-Driven, 3-D Classification of Person-Object Relationships and Semantic Context Clustering for Robotics and AI Applications. In 2018 27th IEEE International Symposium on Robot and Human Interactive Communication (RO-MAN) (pp. 180-187). IEEE. <a href="#">🔗</a></li><li>• <b>Gupta, A.</b>, &amp; Goel, L. (2016, September). Heuristic Approach for Face Recognition using Artificial Bee Colony Optimization. In The International Symposium on Intelligent Systems Technologies and Applications (pp. 209-223). Springer, Cham. <a href="#">🔗</a></li></ul>	
WORK EXPERIENCE	<b>Biorobotics Laboratory, Ecole Polytechnique Fédérale de Lausanne, Switzerland</b>	
	<i>Assistant Researcher (affiliated with NCCR)</i>	<b>Sep 20 - Feb 21</b>
	<ul style="list-style-type: none"><li>• Integrated Krock, bio-inspired amphibious robot, with PyBullet, simulation platform</li><li>• Adapted Krock's low level controllers to be easily used and developed upon in python or cpp, and enabled it to be used with webots PyBullet</li><li>• Implemented simulation-to-real transfer feature to validate learnt Central Pattern Generator (CPG) based locomotion strategies, and demonstrated Krock walking as proof of concept</li><li>• Implemented real-to-simulation feature to identify system parameters such as drag coefficients for swimming</li></ul>	
	<b>Von Reventlow Robotics, Munich, Germany</b>	
	<i>Robotics Intern</i>	<b>Jul 2019 - Aug 19</b>
	<ul style="list-style-type: none"><li>• Evaluated the viability and adapted Octomap and Moveit for trajectory planning on a novel omni-drive service robot</li><li>• Worked on implementation of a pick-and-place routine following Object detection, Object extraction, Grasp prediction and Action execution</li></ul>	
	<b>Advanced Telecommunications Research Institute International, Japan</b>	
	<i>Research Engineer, Dynamic Brain Imaging (DBI)</i>	<b>Oct 2017 - Aug 2018</b>
	Artificial Consciousness towards Human Actions	
	<ul style="list-style-type: none"><li>• Implemented 3D framework for spatio-temporal analysis of person-object interaction using Point cloud extraction from images via RGB-Depth co-registration</li><li>• Modelled data into time-series occupancy map and person-object co-localization maps</li><li>• Clustered correlation patterns using K-means to obtain human-object interaction context</li><li>• Implemented Autoencoder and LSTM to predict changes in the environment in near future</li></ul>	
	<b>VMware, Bangalore, India</b>	
	<i>Member of Technical Staff, VMware Cloud Foundation (VCF)</i>	<b>Jul 2016 - Sep 2017</b>
	<ul style="list-style-type: none"><li>• Leveraged ITIL practices with the help of Servicenow APIs for efficient data center management</li><li>• Responsible for Configuration Management integration point between VCF and Servicenow</li><li>• Backup and Recovery: Written a python script to back-up data from Cassandra and ESXi host</li><li>• Photon Controller: Worked towards providing containers as Infrastructure as a part of VCF</li></ul>	
	<b>Inria, Lille - Nord Europe, France</b>	
	<i>Research Intern, MOdels for Data Analysis and Learning (MODAL)</i>	<b>May 2016 - Jul 2016</b>
	PAC Bayesian Non-Negative Matrix Factorisation using Block Gradient Descent	

- Implemented Probably Approximately Correct (PAC) Bayesian algorithm with optimised search for Non-Negative Matrix Factors using Block Gradient Descent
- Applied the algorithm to Handwriting Recognition and contributed to open source ([PACbayesian-NMF](#)) as a result of internship

#### **iLabs [24]7 Inc., Bangalore, India**

*Data Science Intern, Data Science Group (DSG)*

**Jul 2015 - Dec 2015**

- Worked on Advertisement Re-Targeting and Product Recommendation system
- Created product end to end for one of the customers using feature engineering and purchase propensity models

#### PROJECT EXPERIENCE

#### **Salamander Locomotion Analysis (Master thesis) [↗](#)**

**Mar 2020 - Aug 2020**

- Worked on multimodal controller design and characterization to replicate locomotion of Salamanders using somatosensory feedback with Central Pattern Generators (CPGs)
- Used multi-objective evolutionary algorithms (MOEA) for learning the control parameters
- Evaluated and compared state-of-the-art MOEA algorithms for performance
- Devised generic objective functions for learning and performance evaluations for locomotion
- Explored open loop versus closed loop control architectures for different types of connections between body and limb: body to limb, limb to body, bi-directional, and decoupled

#### **Task Priority Control for Underwater Intervention [↗](#)**

**Sep 2019 - Jan 2020**

- Worked on Task Priority Control approach for Underwater Vehicle-Manipulator System (UVMS) based on theory presented by [Simetti E. et al](#)
- Implemented safe way point navigation, landing, tool-frame manipulation, and safety objectives - horizontal altitude control and minimum altitude control

#### **Modeling and Analysis of CloPeMa Gripper [↗](#)**

**Sep 2019 - Jan 2020**

- Carried out position and velocity analysis of [CloPeMa](#) mechanism using Screw Theory
- Modelled and Simulated the mechanism via Simscape Multibody Matlab Toolbox

#### **Navigation in Social Environment for NAO [↗](#)**

**Dec 2019 - Jan 2020**

- Compared different approaches for Navigating in Social Environment
- Developed a plugin to integrate the Human Aware Navigation package with NAO framework

#### **Omni-Directional Mobile Robot for Playing Soccer [↗](#)**

**Dec 2019 - Jan 2020**

- Created an omni-directional mobile robot to play soccer autonomously
- Implemented and tested algorithm in Gazebo with ROS

#### **Nonholonomic Path Planning using A-star Algorithm [↗](#)**

**May 2019 - Jun 2019**

- Worked on path planning of a (2,0) mobile robot in a maze using A\* algorithm
- The approach involved discretization of the control inputs instead of the conventional approach to discretize the environment space
- Implemented multiple variations of the base algorithm to evaluate their effect

#### **Sentiment Analysis for Review Spam Detection [↗](#)**

**Jan 2016 - May 2016**

- Devised four-step procedure along Semi-Supervised approach for dataset annotating
- Implemented dichotomous classification of spams into definitive and likely categories
- Extracted and analysed effect of Sentiment Features for Review Spams predictions in multiple ML algorithms

#### **Optimizing Join operation on Clusters [↗](#)**

**Jan 2015 - May 2015**

- Devised strategies and successfully implemented the proposed design using MPI and OpenMP.

#### **Creation of a Keyword Index using Map-Reduce in Hadoop [↗](#)**

**Jan 2015 - May 2015**

- Implemented TFIDF analysis using Hadoop's Map-Reduce framework

#### TECHNICAL SKILLS

- **Programming languages:** C, C++, Python, Cython, MATLAB, Java,
- **Libraries:** jMetalPy, Pymoo, Keras, OpenCV, OpenGL, OctoMap, Point Cloud (PCL)
- **Simulation & Frameworks:** Robot Operating System (ROS), Simulink, PyBullet, Gazebo, Keras, Tensorflow, Docker, Git
- **Single-Board Computer & Microcontrollers** RaspberryPi 3 model A+, Odroid-XU4, Arduino Due, Nvidia Jetson xavier

	<ul style="list-style-type: none"> <li>• <b>Technical Writing</b> Latex, Microsoft Office</li> <li>• <b>Operating Systems</b> Linux/Ubuntu, Windows</li> </ul>	
HONORS & AWARDS	<ul style="list-style-type: none"> <li>• Research Thesis Scholarship'20 by Università degli studi di Genova</li> <li>• Erasmus Mobility Scholarship'19 by Ecole Centrale de Nantes, France</li> <li>• <a href="#">Charpak Allocation Mensuelle d'Entretien (AME)</a> Scholarship 2018</li> <li>• <i>Bravo Award</i> for exceptional performance at iLabs[24]7 Inc.</li> <li>• Finished undergraduate degree within <i>Top 10%</i> in class at BITS Pilani</li> <li>• Ranked within <i>top 1%</i> of the <i>All India Senior School Certificate Examination</i> (AISSCE)</li> </ul>	
LEADERSHIP & ACTIVITIES	<p><b>Member, Master Inventors</b>, VMware <b>Jun 2017 - Sep 2017</b></p> <ul style="list-style-type: none"> <li>• Facilitating and encouraging research activities with university collaborations and patent filing</li> </ul> <p><b>Member, Student-Faculty Council</b>, BITS Pilani <b>Jan 2016 - May 2016</b></p> <ul style="list-style-type: none"> <li>• Providing feedback and communicating issues regarding academic matters</li> </ul> <p><b>Professional Assistant, Computer Programming Course</b> <b>Jan 2016 - May 2016</b></p> <ul style="list-style-type: none"> <li>• Responsible for conducting labs and evaluation components for Computer Programming Course under Department of Computer Science &amp; Information Systems (CSIS)</li> </ul> <p><b>Coordinator, Department of Art, Design and Publicity</b> <b>Aug 2014 - Jul 2015</b></p> <ul style="list-style-type: none"> <li>• Led 50+ member team for on-campus art, decoration and online publicity of all India inter-college cultural and technical festival</li> </ul>	
REFERENCES	<p><a href="#">Dr. Auke Jan Ijspeert</a>  Full Professor  École Polytechnique Fédérale de Lausanne  Email: <a href="mailto:auke.ijspeert@epfl.ch">auke.ijspeert@epfl.ch</a>  Phone No: (+41) 2169 32658</p>	<p><a href="#">Dr. Fulvio Mastrogiovanni</a>  Associate Professor  University of Genoa  Email: <a href="mailto:Fulvio.Mastrogiovanni@unige.it">Fulvio.Mastrogiovanni@unige.it</a>  Phone No: (+39) 010353 - 2324</p>
CONTACT INFORMATION	<p><a href="#">G astha736</a> <a href="#">in astha736</a> <a href="#">@alphabeginner.com</a> <a href="#">@astha736</a> <a href="#">astha736</a></p>	