

PROBLEM

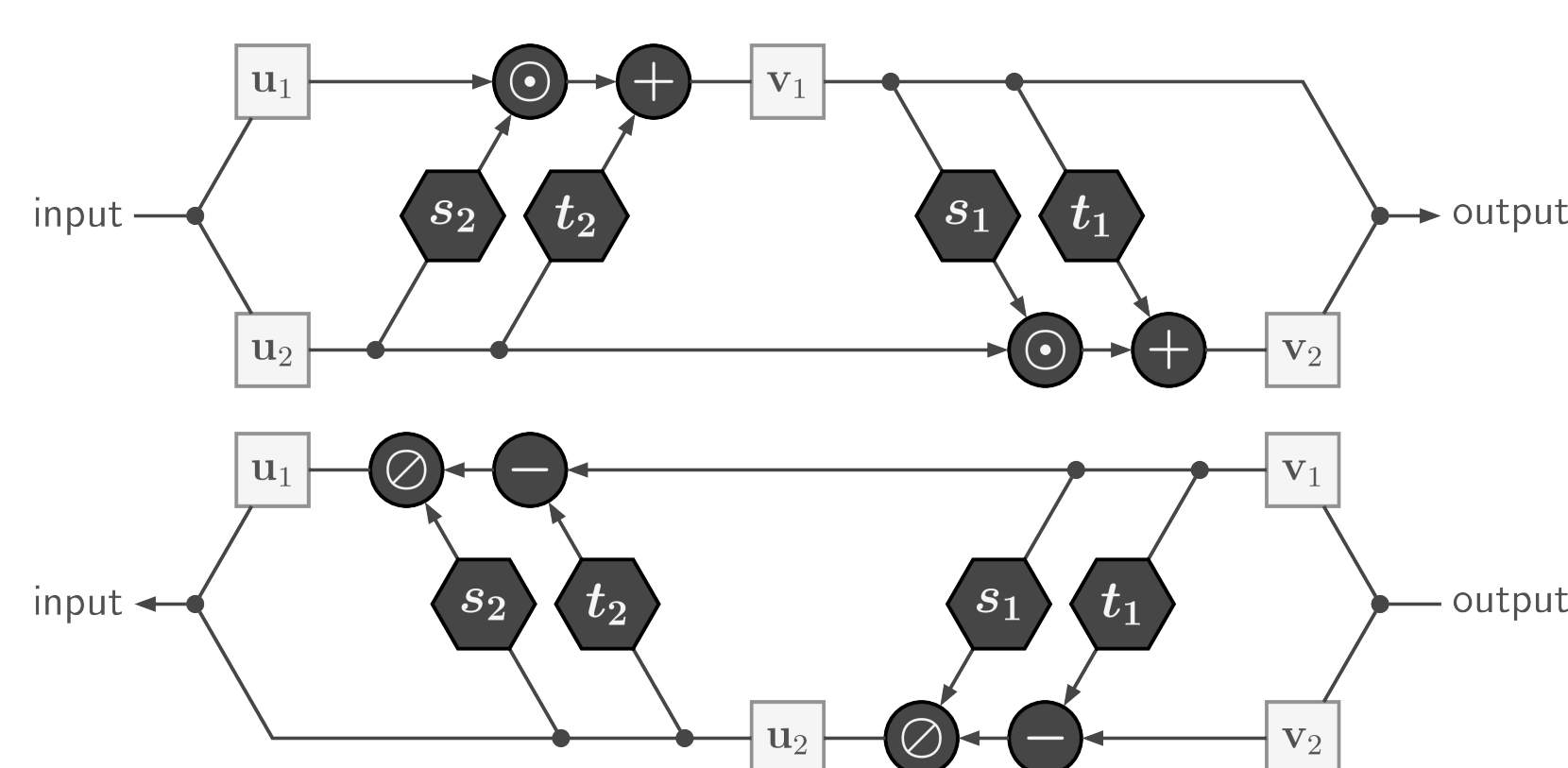
Thompson sampling (TS), a strategy to balance *exploration* and *exploitation* in multi-armed bandit problems, enjoys theoretical guarantees and strong empirical performance in a variety of domains. However, TS assumes causal relationships between selected actions and received rewards.

CONTRIBUTIONS

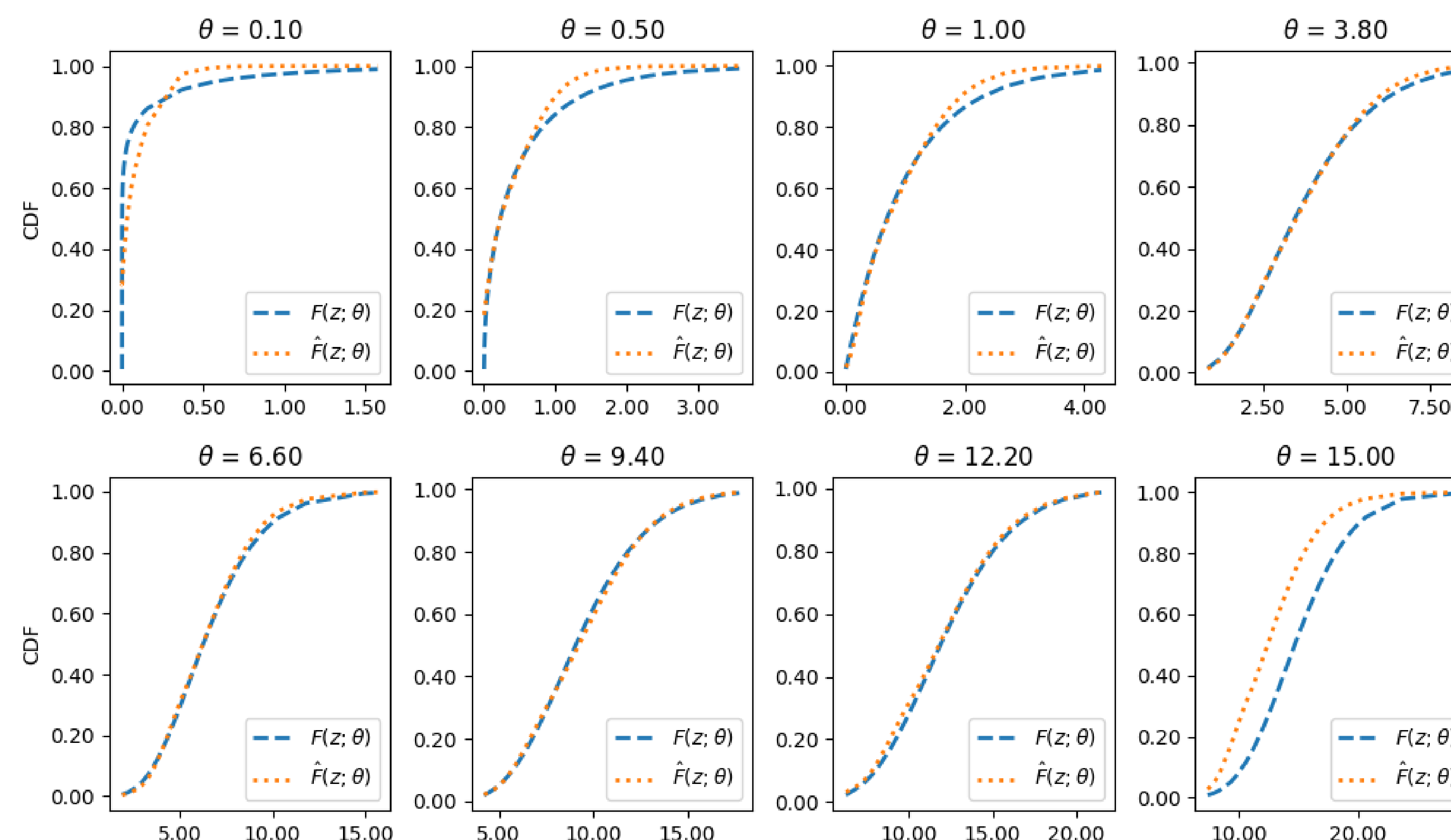
This article relaxes those assumptions by considering the *noncompliance* setting where a chosen action is not necessarily the implemented action. We formalize TS for both *observed noncompliance* and *latent noncompliance*. Further, we empirically demonstrate the performance benefit of our approach for a variety of environments with differing levels of stochastic noncompliance.

INVERTIBLE NEURAL NETWORK

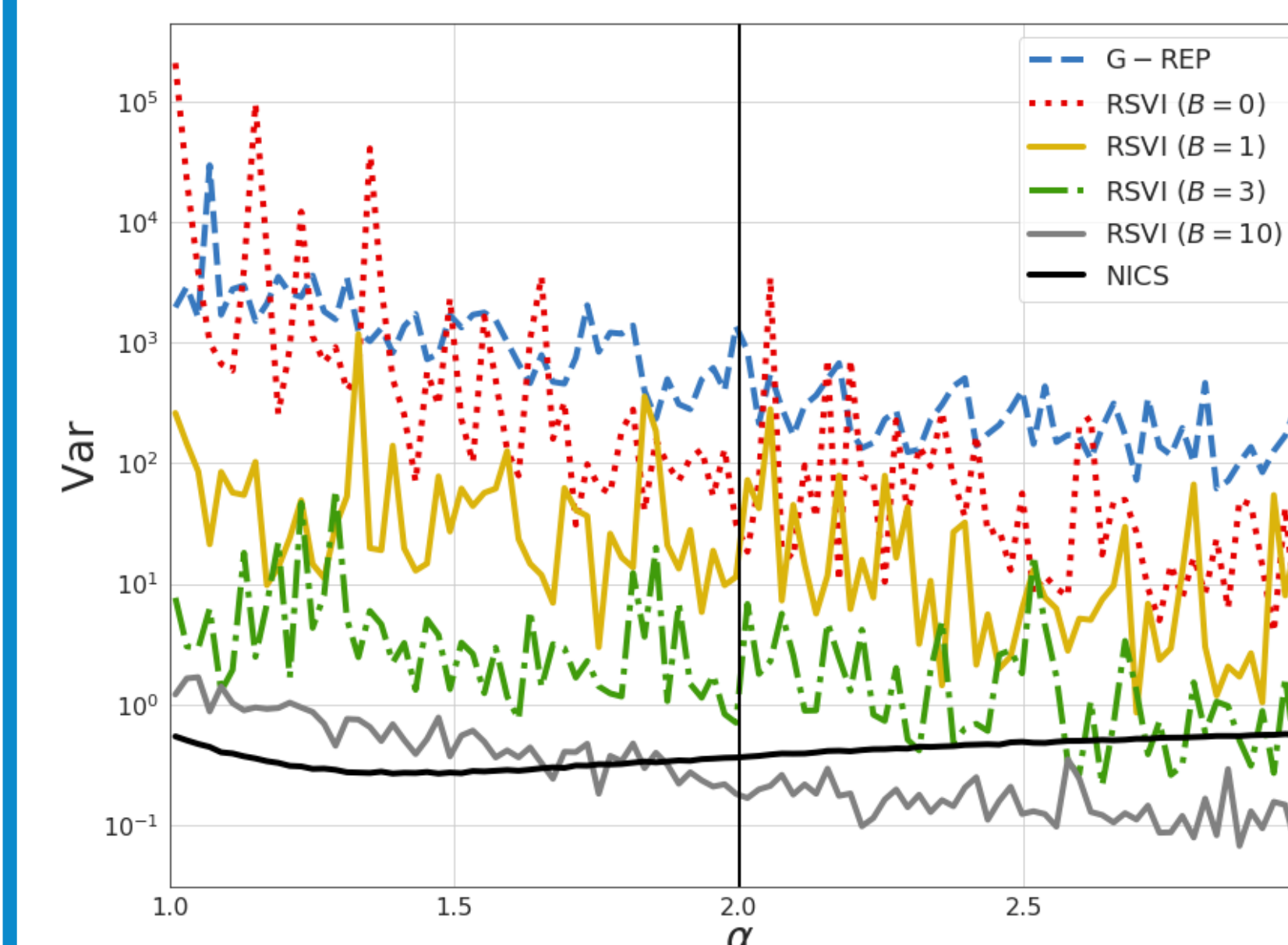
Affine coupling layer [1]



CDF APPROXIMATION FOR GAMMA DISTRIBUTION



REPARAMETERIZE



RESULTS

	Perplexity Scores	
	Softmax	NGS
NVLDA	???	1103.77
ProDLDA	???	???

REFERENCES & CODE

[1] Laurent Dinh, Jascha Sohl-Dickstein, and Samy Bengio. Density estimation using real NVP. *CoRR*, abs/1605.08803, 2016.

Source code available at:
github.com/astirn/neural-inverse-cdf-sampling