

### **Review: Process synchronization**



- · Cooperating processes need to
  - share data
  - synchronize access to shared data
- · Accessing shared data needs to be in CS
- Other types of synchronization more complex
- Synchronization without OS help is hard
- Sync primitives supported by OS
  - Lock() is simple, but not powerful enough
  - More powerful ones were invented
    - Semaphore
    - Condition variables

# [lec4] Mutual exclusion & Critical Section



- Critical section a section of code, or collection of operations, in which only one process may be executing at a given time
- Mutual exclusion mechanisms that ensure that only one person or process is doing certain things at one time (others are excluded)

### [lec4] Lock (aka mutex)



```
Init: lock = 1; // 0 means held; 1 means free
```

- Each primitive is atomic
- In reality, lock is not implemented as above!
  - The waiting process is put to sleep

# [lec4] "Too much milk" problem with locks



```
Acquire(lock);

if (noMilk)

buy milk;

Release(lock);
```

• There is one problem with this solution?

## Often times, we have to wait for shared resources



- In "too much milk", we just needed to check
- Often times, before accessing shared resources, we have to wait ...

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# Producer & Consumer Problem (1-pool version)



- Producer: creates copies of a resource
- Consumer: uses up (destroys) copies of a resource. (may produce something else)
- Buffer: used to hold resource produced by producer before consumed by consumer
- Synchronization: keeping producer & consumer in sync
- Happens inside OS all the time (e.g. I/Os)
  - How about in real life?

while (buffer is full);
insert item into buffer

produce an item;

Producer

while (1) {

while (buffer is empty); remove an item;

Consumer

While (1) {

ert item into buffer consume the item

**Producer & Consumer -**

solution using locks?

## Often times, we have to wait for shared resources



- (Busy waiting is a bad idea)
- Checking resources needs to be in critical section
- Busy waiting & checking inside CS even worse!
  - No one else can check!
- → Need a more powerful sync. primitive!
- → Want the simplest primitive that can check & wait

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#### **Semaphore**



- A synchronization variable that takes on non-negative integer values
  - Invented by Edsger Dijikstra in the mid 60's
- Two primitve operations
  - wait(semaphore): an atomic operation that waits for semaphore to become greater than 0, then decrements it by 1
  - signal(semaphore): an <u>atomic</u> operation that increments semaphore by 1

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### **Semaphore**



- In reality, wait(S) is not implemented as above!
- Semaphore aren't provided by hardware (why not?)
   we'll discuss OS implementations next time

. .

### **Binary Semaphore**



- Binary semaphores: only take 0 or 1
- Sounds familiar?
  - S=0 → someone is holding the lock!

# semaphores vs. locks: fundamental difference?



### semaphore has built-in counting!



- signal(S) simply increments S
  - "just produced an item"
  - S value == how many items have been produced
- wait(S) will return without waiting only if S > 0;
  - Wait(S) is saying "waited until there is at least one item, and then just consumed an item"

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### Two usages of semaphores



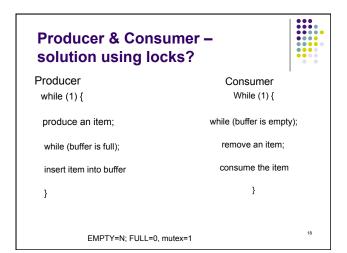
- For mutual exclusion:
  - to ensure that only one process is accessing shared info at a time.
  - · Semaphores or binary semaphores?
- For condition synchronization:
  - to permit processes to wait for certain things to happen
  - · Semaphores or binary semaphores?

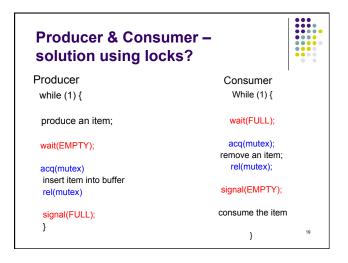
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# Producer & Consumer (1-pool version)



- Define constraints (what is "correct")
  - Consumer must wait for producer to fill buffer (mutual excl. or condition sync?)
  - Producer must wait for consumer to empty buffer, if all buffer space is in use (mutual excl. or condition sync?)
  - Only one process must manipulate buffer at once (mutual excl. or condition sync?)
- Use a separate semaphore for each constraint
  - Full = 0
  - Empty = N
- Mutex = 1



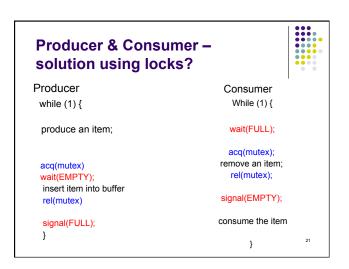


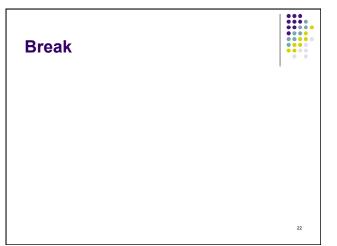
```
Deep thinking

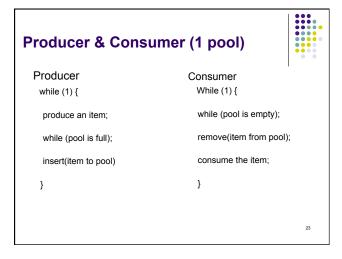
Why does producer wait(empties) but signal(fulls)?
Explain in terms of creating / destroying resources

Is the order of signal()'s important?
Is the order of wait()'s important?

How would this be extended to have >1 consumers?
```

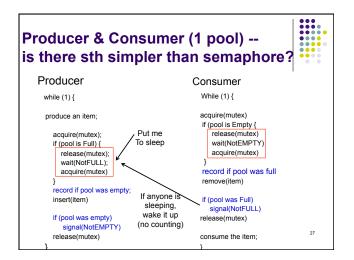


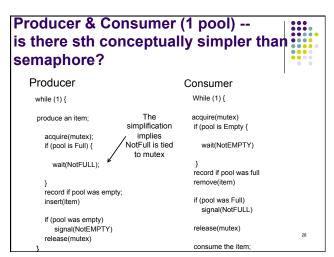


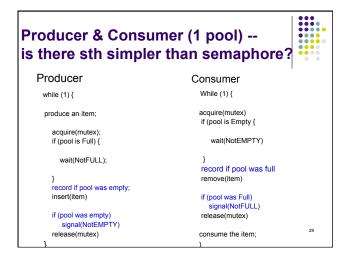


```
Producer & Consumer (1 pool) --
needs mutual excl, try lock
  Producer
                                    Consumer
   while (1) {
                                     While (1) {
    produce an item;
                                      while (pool is empty);
    flag = 0;
                                      remove(item from pool);
    while (flag == 0) {
     acq(lock)
                                      consume the item;
    if (pool is not full) {
         flag = 1;
         insert(item to pool)
     rel(lock)
                                    }
  }
```

```
Producer & Consumer (1 pool) --
try semaphore; counting is tricky
   Producer
                                   Consumer
    while (1) {
                                     While (1) {
     produce an item;
                                     wait(FULL);
     wait(EMPTY);
                                    acq(lock)
                                    remove(item from pool);
     acq(lock);
                                    rel(lock)
     insert(item to pool)
     rel(lock);
                                     sginal(EMPTY);
     signal(FULL)
                                     consume the item;
    }
                             EMPTY=N; FULL=0;
```



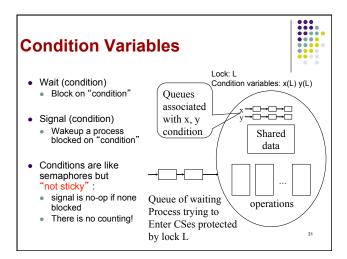


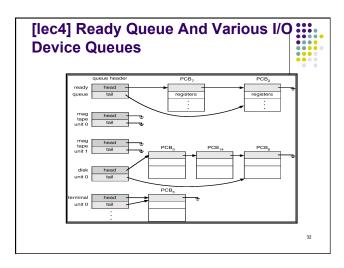


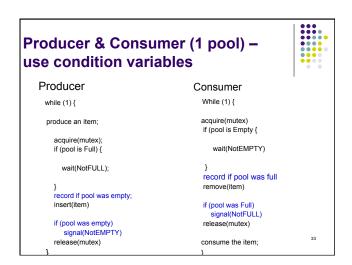
#### **Condition Variables**

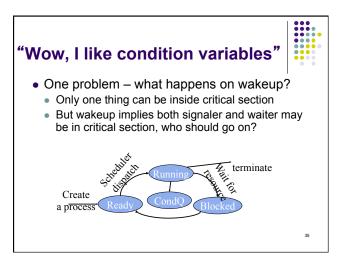


- · Used in conjunction with locks
- Used inside critical section to wait for certain conditions
- Contrast with Semaphore:
  - Has no counting bundled
  - More intuitive to many people
- Usage
  - On creation, has to specify which mutex it is associated with









### Two Options of the Signaler



- Relinquishes control to the awaken process; suspend signaler (Hoare-style, early time)
  - Signaler gives up lock, waiter runs immediately
  - Waiter gives back lock and CPU to signaler after critical sec.
  - Complex if the signaler has other work to do
  - In general, easy to prove things about system (e.g. fairness)

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#### Producer & Consumer (1pool) use condition variables Producer Consumer while (1) { While (1) { acquire(mutex) if (pool is Empty { produce an item: release(mutex) wait(NotEMPTY) acquire(mutex): if (pool is Full) { acquire(mutex) release(mutex); record if pool was full wait(NotFULL): acquire(mutex) remove(item) rel(mutex) signal(NotFull) record if pool was empty; if (pool was Full) signal(NotFULL) some other work if (pool was empty) release(mutex) signal(NotEMPTY) release(mutex) consume the item:

#### **Two Options of the Signaler**



- Relinquishes control to the awaken process; suspend signaler (Hoare-style, early time)
  - · Signaler gives up lock, waiter runs immediately
  - · Waiter gives back lock and CPU to signaler after critical sec.
  - Complex if the signaler has other work to do
  - In general, easy to prove things about system (e.g. fairness)
- Continues its execution (Mesa-style, modern)
  - Signaler keeps lock and CPU
  - Waiter put on ready queue
  - Easy to implement (e.g., no need to keep track of signaler)
  - But, what can happen when the awaken process gets a chance to run?
    - E.g. pool is full, producer 1 wait; consumer signals it; p1 in ready Q<sup>8</sup>, consumer rel (lock); p2 comes along...

#### Producer & Consumer (1 pool) -use condition variables - problem? Producer Consumer While (1) { while (1) { acquire(mutex) produce an item; if (pool is Empty { release(mutex) wait(NotEMPTY) acquire(mutex); if (pool is Full) { acquire(mutex) release(mutex): wait(NotFULL); record if pool was full acquire(mutex) record if pool was empty; signal(NotFULL) some other work insert(item) if (pool was empty) signal(NotEMPTY) release(mutex) release(mutex) consume the item;

#### **Monitors**

- Monitors are high-level data abstraction tool combining three features:
  - Like an object in OO programming language
    - Shared data
    - All procedure operate on the shared data
  - Except the procedures are all mutually exclusive!
  - Java has monitors
- Convenient for synchronization involving lots of shared state (manipulating shared data)
- Monitors hide locks, but still need condition variables

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# **Producer-Consumer with Monitors**



```
record pool[100];
condition nfull, nempty;
begin
procedure Enter(item);
begin
if (pool is full)
wait(nfull);
put item into pool;
if (pool was empty)
wakeup_someone();
end;

procedure Remove;
begin
if (pool is empty)
wait(nempty);
remove an item;
if (pool was full)
wakeup_someone();
end;
```

procedure Producer
begin
while true do
begin
produce an item
ProdCons.Enter(item);
end;
end;
procedure Consumer
begin
while true do
begin
ProdCons.Remove();
consume an item;
end;

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# Mutual Exclusion provided by OS or language/compiler



- Lock
  - Alone is not powerful enough
- Semaphore (incl. binary semaphore)
   binary semaphore alone not enough
- Lock and condition variable
- Monitor (hide lock, still use condition variables)

### Reading assignment



• Read Chapter 6