

Supernova Model Evidence Extractor as Applied to BBH Waveforms

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October 7, 2013

What is SMEE?

- ▶ Written by Josh Logue *et al.* at the University of Glasgow
- ▶ Nested Sampling algorithm used to reconstruct waveforms in GW data
- ▶ The goal was to distinguish between physical models of SN based on GW signal measured
- ▶ Utilizes principle component analysis (PCA) to reconstruct signal

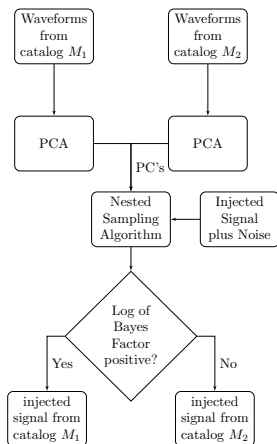


Figure: Graphical representation of SMEE

Principle Component Analysis

- ▶ Converts a data set into linearly independent principle components (PCs)
- ▶ The original data is now a linear combination of PCs (eigenvectors)
- ▶ The first PC holds the most variance in the data and the last holds the least

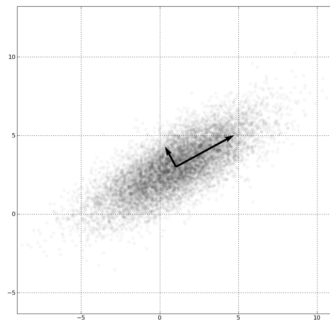


Figure: PCA of multivariate gaussian data. Source: Wikipedia

How Does SMEE Work?

- ▶ Calculates principle components (PCs) from catalogue of waveforms that share similar physics
- ▶ In principle the PCs will contain the morphology of signals and can accurately reconstruct a signal with a small number of PCs

$$\text{▶ } h_i \approx \sum_{j=1}^k U_j \beta_j$$

- ▶ Model preference is determined by the Bayes factor which is the ratio of the marginalized likelihoods for the two models:
$$B_{12} = \frac{p(D|M_1)}{p(D|M_2)}$$
 - ▶ If $B_{12} > 1$, then Model 1 is preferred and if $B_{12} < 1$ Model 2 is preferred.

- ▶ The evidence is obtained by using a nested sampling algorithm

to calculate:
$$p(D|M_s) = \int_{\beta_{\min}}^{\beta_{\max}} p(\beta|M_s) p(D|\beta, M_s) d\beta$$

Principle Component Analysis

- ▶ $\mathbf{M} = \mathbf{USV}^T$
 - ▶ \mathbf{M} is an $n \times m$ matrix containing the data
 - ▶ \mathbf{U} and \mathbf{V} are matrices of the eigenvectors of \mathbf{MM}^T and $\mathbf{M}^T\mathbf{M}$, respectively
 - ▶ \mathbf{S} is a diagonal matrix containing the square roots of the eigenvalues
- ▶ Step #1: Calculate the covariance matrix \mathbf{C} , of \mathbf{M}
- ▶ Step #2: Calculate the eigenvalues (\mathbf{S}^2) and eigenvectors (\mathbf{V}) of \mathbf{C}
- ▶ Step #3: Organize \mathbf{S} in descending order of eigenvalues along with the corresponding eigenvectors in \mathbf{V}

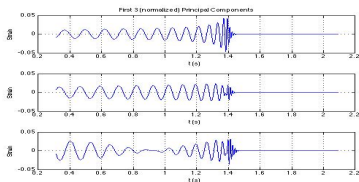
Principle Component Analysis

- ▶ Step #4: Compute the eigenvectors of the real covariance matrix \mathbf{U} (the PCs)
 - ▶ $\mathbf{U} = \mathbf{M} \times \mathbf{V}$
- ▶ Step #5: Calculate the β values by projecting \mathbf{M} onto \mathbf{U}
 - ▶ $\beta = \mathbf{M} \cdot \mathbf{U}$
- ▶ The reconstructed waveform is thus given by $\mathbf{D} = (\beta \cdot \mathbf{U}^T)^T$

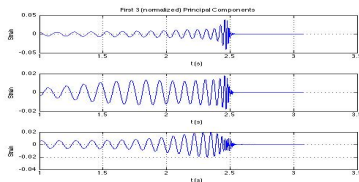
Waveform Catalogues

- ▶ NR waveforms made at GATech
- ▶ Q-series Waveforms
 - ▶ 13 waveforms of increasing mass ratio
- ▶ HR-series Waveforms
 - ▶ 15 waveforms of increasing mass ratio and spin magnitudes
- ▶ RO3-series
 - ▶ 20 waveforms of increasing mass ratio, spin, and system precession

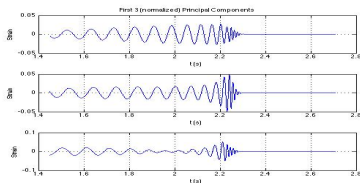
Principle Components



(a) First 3 Q-series principle components



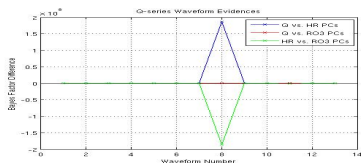
(b) First 3 HR-series principle components



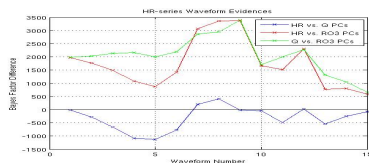
(c) First 3 RO3-series principle components

Preliminary Results

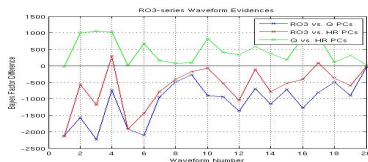
- The plots below show the results of SMEE. They are labeled as M_1 vs. M_2 for each catalogue ($\log(B_1) - \log(B_2)$)



(d) Q-series Evidences



(e) HR-series Evidences



(f) RO3-series Evidences

The Next Step

- ▶ Investigate why SMEE's reconstruction of the HR and RO3-series waveforms are so off
- ▶ Expand to using more sophisticated BBH catalogues from GATech