

## Part 1

arrays & linked lists  $\rightarrow$  order

trees  $\rightarrow$  hierarchy

root: top, no parent

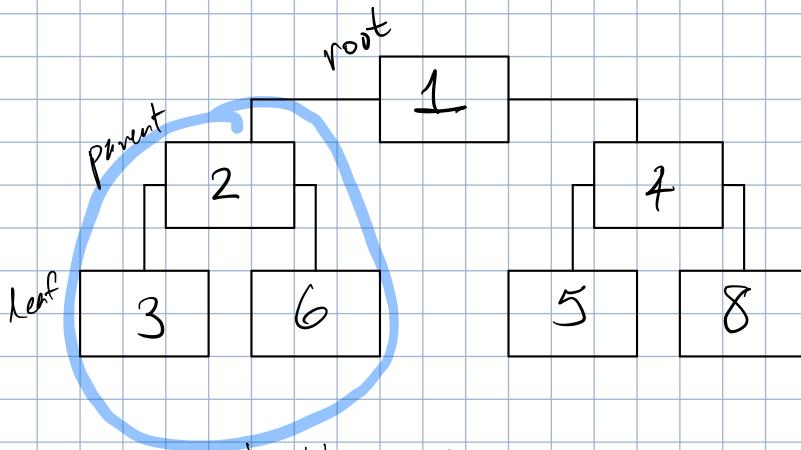
child

parent

leaf

binary tree

$\downarrow$   
up to 2  
children



trees are recursive

each node is a tree

pointer-based implementation

**typedef struct intree intree-t**

**struct intree**

int val

intree-t \*left

intree-t \*right

**intree-t \*make-node(int val, intree-t \*left, intree-t \*right)**

**intree-t \*t = (intree-t\*)malloc(sizeof(intree-t))**

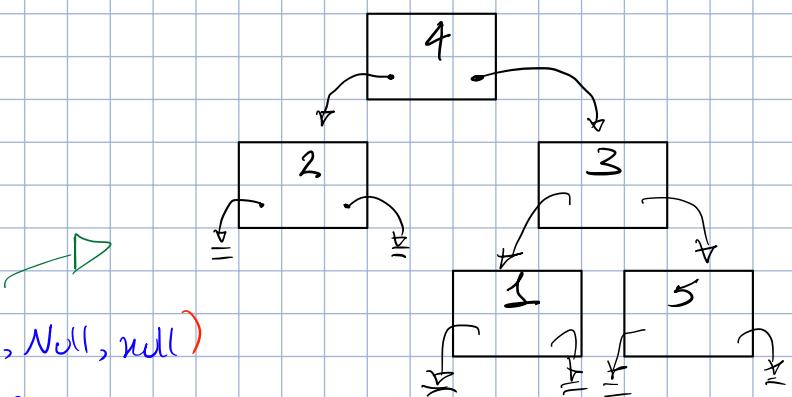
$t \rightarrow \text{val} = \text{val}$

$t \rightarrow \text{left} = \text{left}$

$t \rightarrow \text{right} = \text{right}$

return t

**intree-t \*t = make-node(4, make-node(2, Null, null), make-node(3, make-node(1, null, null), make-node(5, null, null)))**



empty?

bool is\_empty(intree t\*)  
return  $t == \text{null}$

leaf?

bool is\_leaf(intree t\*)  
return  $t \rightarrow \text{left} == \text{null} \wedge t \rightarrow \text{right} == \text{null}$

get value

int get\_val(intree t\*)  
assert(!is\_empty(t))  
return  $t \rightarrow \text{val}$

intree \*left(intree t\*)

assert(!is\_empty(t))

return  $t \rightarrow \text{left}$

intree \*right(intree t\*)

assert(!is\_empty(t))

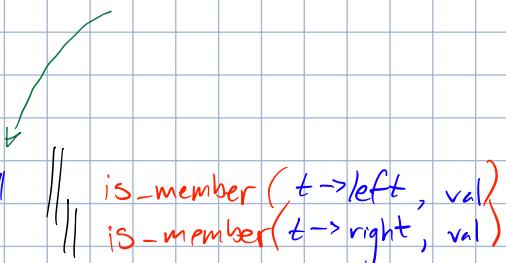
return  $t \rightarrow \text{right}$

bool is\_member(intree t\*, int val)

if(is\_empty(t))

return false

return  $t \rightarrow \text{val} == \text{val}$



||| is\_member( $t \rightarrow \text{left}, \text{val}$ )  
||| is\_member( $t \rightarrow \text{right}, \text{val}$ )

int count(intree t\*)

if(is\_empty(t))

return 0

int left = count( $t \rightarrow \text{left}$ )

int right = count( $t \rightarrow \text{right}$ )

return  $\text{left} + \text{right} + 1$

void free-tree(intree\_t \*t)

if (!is-empty(t))  
return

free-tree(t->left)  
free-tree(t->right)

free(t)

avoid reaching  
into children tree

void get\_depth(intree\_t \*t)

assert(!is-empty(t))

if (is-empty(t))  
return 0

longest path from root to subtree

int left\_depth = get\_depth(t->left)  
int right\_depth = get\_depth(t->right)

if (left > right)  
return left + 1  
else  
return right + 1

depth can be edge or nodes

Part 2

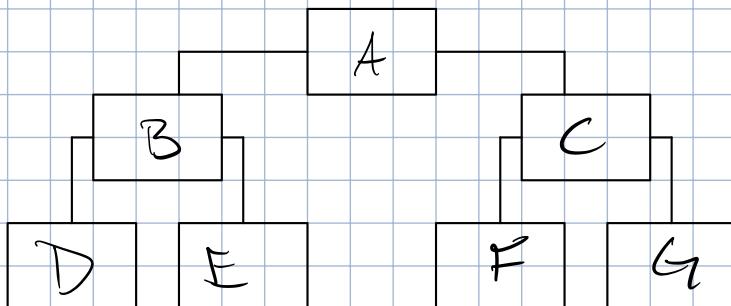
Tree traversal

Depth first: starting from root, visit all nodes in 1 branch

Breadth first: starting from root visit all nodes on current level

Depth

preorder A B D E C F G I  
in order D B E A F C G I  
post order D E B F G C A



void preorder-print(intree\_t \*t)

if (is-empty(t))  
return  
printf("%s -> %d", t->val)

pre\_order\_print(  $t \rightarrow \text{left}$  )

right type?  
closer to base case?

pre\_order\_print(  $t \rightarrow \text{right}$  )

void **inorderprint** ( intree\_t \* $t$  )

if ( is\_empty(  $t$  ) )  
return

pre\_order\_print(  $t \rightarrow \text{left}$  )

printf(  $t \rightarrow \text{val}$  )

pre\_order\_print(  $t \rightarrow \text{right}$  )

void **postorderprint** ( intree\_t \* $t$  )

if ( is\_empty(  $t$  ) )  
return

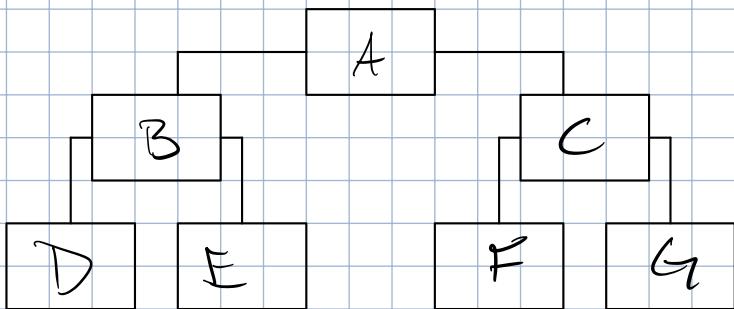
pre\_order\_print(  $t \rightarrow \text{left}$  )

pre\_order\_print(  $t \rightarrow \text{right}$  )

printf(  $t \rightarrow \text{val}$  )

Breadth

level order: A BC DE FG



Let's make a queue!

collection of elements w/ limited operations

- ① Create empty queue
- ② Enqueue element at back of queue
- ③ Dequeue element at front of queue



typedef struct queue queue\_t

struct queue {

intlist\_t \*front

intlist\_t \*back

}

intlist\_t \*newnode

queue\_t \*create\_queue

int dequeue

Now to implement

instead of a queue w/ int lists, we need one w/ int trees

after printing a tree, we enqueue its children, dequeue that tree

- t  
print t
- (A) B C  
print B
- (A) (B) C D E

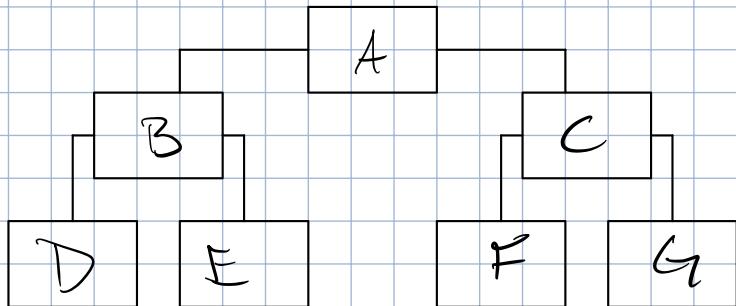
queue<sup>t</sup> \*q = create<sub>queue</sub>()

inttree<sup>t</sup> \*curr = t

if (is<sub>empty</sub>( t ))  
return

printf( curr->val )  
if ( !is<sub>empty</sub>( curr->left ) )  
enqueue( q, curr->left )  
if ( !is<sub>empty</sub>( curr->right ) )  
enqueue( q, curr->right )

curr = dequeue( q )



Part?

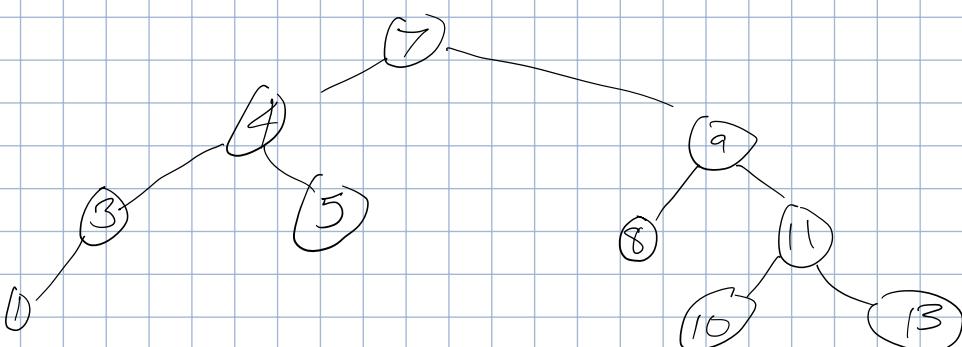
Binary Search Tree (BST)

values are unique

values in left subtree are strictly less than root

values in right subtree are strictly more than root

left & right are BSTs



How do we find if something is in tree?  
can now pick where to go if node != value-

can ask node  $\geq$  value or node  $\leq$  value

bool bst-lookup (infrreet \*t, int val)

if (is-empty(t))  
return false

if ( $t \rightarrow \text{val} == \text{val}$ )  
return true

if ( $t \rightarrow \text{val} > \text{val}$ )  
return bst-lookup( $t \rightarrow \text{left}$ , val)  
if ( $t \rightarrow \text{val} < \text{val}$ )  
return bst-lookup( $t \rightarrow \text{right}$ , val) → unnecessary

infrreet \*insert (infrreet \*t, int val)

if (is-empty(t))  
return makenode(val, null, null)

if ( $t \rightarrow \text{val} > \text{val}$ )  
 $t \rightarrow \text{left} = \text{insert}(t \rightarrow \text{left}, \text{val})$

else if ( $t \rightarrow \text{val} < \text{val}$ )  
 $t \rightarrow \text{right} = \text{insert}(t \rightarrow \text{right}, \text{val})$

else  
ayo, this shit already there doing  
return t

remove value

leaf?  $\rightarrow$  remove it

if value has only 1 child  $\rightarrow$  copy value from child & remove child

if value has 2 children  $\rightarrow$  copy value from in-order successor & delete in-order successor

infrreet \*remove-node (infrreet \*t, int val)

if (is-empty(t))  
return t

if ( $t \rightarrow \text{val} > \text{val}$ )  
 $t \rightarrow \text{left} = \text{remove-node}(t \rightarrow \text{left}, \text{val})$

else if ( $t \rightarrow \text{val} \geq \text{val}$ )  
 $t \rightarrow \text{right} = \text{remove\_node}(t \rightarrow \text{left}, \text{val})$

else {

if (  $\text{is\_empty}(t \rightarrow \text{left})$  )

inttree\_t \*temp =  $t \rightarrow \text{right}$

free( $t$ )

return temp

only 1 child, right . left is empty



if (  $\text{is\_empty}(t \rightarrow \text{right})$  )

inttree\_t \*temp =  $t \rightarrow \text{left}$

free( $t$ )

return temp

only 1 child, left . right is empty



inttree\_t \*temp = min\_value( $t \rightarrow \text{right}$ )

$t \rightarrow \text{val} = \text{temp} \rightarrow \text{val}$

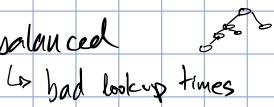
$t \rightarrow \text{right} = \text{remove\_node}(t \rightarrow \text{right}, \text{temp} \rightarrow \text{val})$

3

return  $t$

more

binary search tree (BST) can be unbalanced



vs balanced



In order traversal : 2 3 4 7 8 9 11

int count\_nodes (inttree\_t \*t)

if (  $\text{is\_empty}(t)$  )

return 0

int left = count\_nodes ( $t \rightarrow \text{left}$ )

int right = count\_nodes ( $t \rightarrow \text{right}$ )

return 1 + left + right

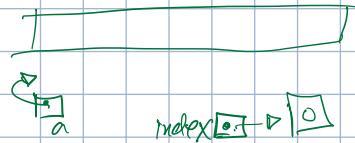
`int tree_t *balance(inttree_t *t)`

```

int count = count_nodes(t)
int *a = (int *) malloc(sizeof(int) * count)
int index = 0
make_array(t, a, &index)

return make_bst(a, 0, count - 1)

```



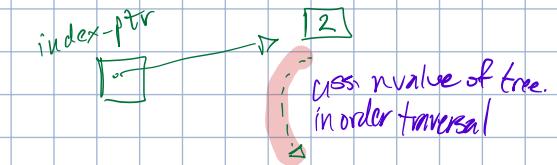
`void make_array(inttree_t *t, int *a, int *index_ptr)`

```

if (is_empty(t))
    return;

make_array(t->left, a, index_ptr)
a[*index_ptr] = t->val
*index_ptr += 1
make_array(t->right, a, index_ptr)

```



`inttree_t makebst(int *a, int start, int end)`

```

if (start > end)
    return null;

```

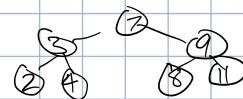
```

int middle = (start + end) / 2
inttree_t *t = make_node(a[middle], null, null)

```

$t \rightarrow \text{left} = \text{make\_bst}(a, \text{start}, \text{middle}-1)$  → 
  
 $t \rightarrow \text{right} = \text{make\_bst}(a, \text{middle}+1, \text{end})$  →

return t



full binary tree: all nodes not a leaf has 2 children

complete binary tree: all levels (except maybe last) filled & all nodes in last level are left justified

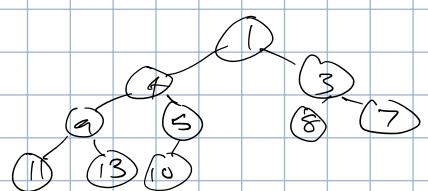
Min heaps: binary tree

complete

unique values

values in left & right subtrees strictly greater than root

left & right subtrees are min heaps



max heap

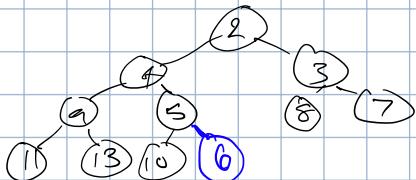
complete

unique values

values in left & right subtrees strictly less than root  
left & right subtrees are min heaps

cool operations: add min heap, remove min, is empty

let's add 6



bool \*is\_heap(introot \*t)

if (isleaf(t))  
return true

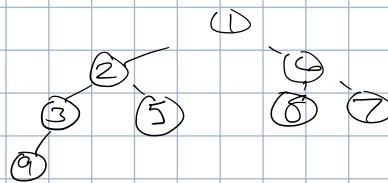
if (isempty(t->right))  
return (t->left->val) > (t->val)

no right kids, only need to check  
left value

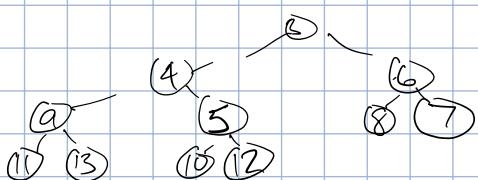
if ((t->left->val) > (t->val) && (t->right->val) > (t->val))  
return is\_heap(t->left) && is\_heap(t->right)

return false

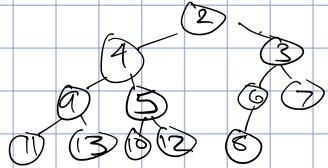
add 3



add 2



sift up until we  
have a heap



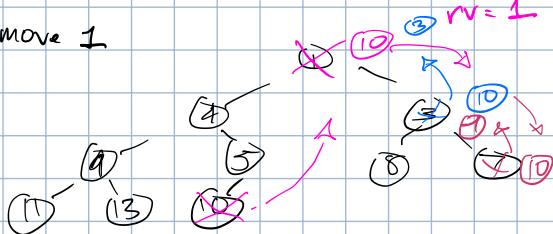
put into next open slot

## Heaps

min heap is a BST. complete & children greater than node

① ② ③

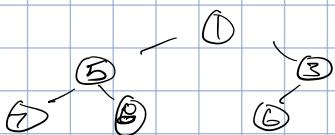
remove 1



Sift down to smallest value for 10 \$3  
again for 10 \$7

## Cool! Alert!

heaps stored in arrays  
level ordered



1	5	3	7	8	6
---	---	---	---	---	---

```
int val = a[i]
int parent = a[(i-1)/2]
int lchild = a[2*i+1]
int rchild = a[2*i+2]
```

truncation helps

val 8 w/index t: parent  $(4-1)/2 = \frac{3}{2} = 1$   
 $a[1]$  or 5 true

some helper fns

```
void swap(int *a, int *b)
int temp = *a
*a = *b
*b = temp
```

```
void print_heap(int heap[], int size)
for (int i=0; i<size; i++)
printf("%d", heap[i])
```

```
void sift_up(int heap[], int size, int index)
```

```
if (index == 0) {
    return;
}
int parent = (index-1)/2
if (heap[index] < heap[parent])
    swap(&heap[index], &heap[parent])
sift_up(heap, parent)
```

void insert(int heap[], int size, int index)

\*size = \*size + 1

heap[\*size - 1] = val  
sift-up(heap, \*size - 1)

insert @ end of array  
sift that up

void sift-down(int heap[], int size, int index)

int min-index = index

int left = 2 \* index + 1

int right = 2 \* index + 2

if (left < size)

if (heap[left] < heap[min-index])  
min-index = left

if (right < size)

if (heap[right] < heap[min-index])  
min-index = right

if (min-index != index)

make sure we got space in heap

② in earlier example



void remove-min(int heap[], int \*size)

int last = heap[\*size - 1]

heap[0] = last

\*size = \*size - 1

sift-down(heap, \*size, 0)

void build-heap

for (int i = size/2 ; i >= 0 ; i--)  
sift-down(a, size, i)

more heaps

void heap-sort(int heap[], int size)

for (int i = size - 1 ; i > 0 ; i--)  
swap(&heap[0], &heap[i])  
sift-down(heap, i, 0)

priority queue: queue with...  
every element has priority  
elements w/ high priority dequeued before elements w/ lower priority  
...

dictionaries: maps key to values  
↳ unique

Set: store collection of unique values

how to implement?

linked lists!

easy

but lookup time proportional to length of list

but adding key-value pairs takes time proportional to length of list

binary search tree!

easy

adding values is pretty good

but lookup time is proportional to height of tree

hash tables!

hash tables!

goal: add, remove, query in near constant time

idea: trade space for time

$A[\text{key}] = \text{item}$

space of array?

need slot for each possible value key could take

what if keys are integers? strings?

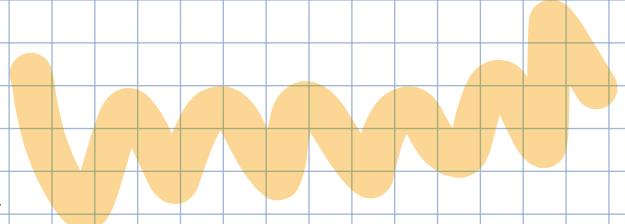
may need array larger than memory of computer

only need array large enough to hold max number of items stored at same time

$A[\text{hash}(\text{key})] = \text{item}$

$\text{hash}(\text{key}_1) \neq \text{hash}(\text{key}_2)$  if  $\text{key}_1 \neq \text{key}_2$   
 $0 \leq \text{hash}(\text{key}) < N$   $\rightarrow$  array length

collisions can happen w/ rare occurrence



Suppose we have 1000 spots in A

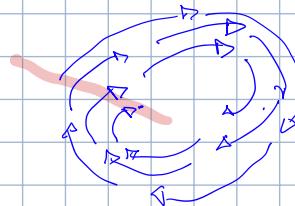
$$\text{hash}(\text{key}) = \text{key \% 1000}$$

nice if uniformly distributed

String keys w/ 1000 spots

hash code should depend on entire input key  
output should look "random"

```
int hash( char *s )  
    int h=0  
    while(*s) prime  
        h = h*37 + int(*s++)  
        h = h % HASH_SIZE
```



2 handles of collisions

Linear probing: put item in next available slot if original slot is occupied

Separate chaining: keep list of items in each slot

0	1	2	3	4	5	6	7	8	9
B	C	X	W	Y	Z	D	E	F	A

insert W:  $\text{hash}(W)$   $\rightarrow 3$   
 $\text{hash}(X)$   $\rightarrow 2$   
 $\text{hash}(Y)$   $\rightarrow 4$   
 $\text{hash}(Z)$   $\rightarrow 2$       3? 4? 5? ✓

lookup Z:  $\text{hash}(Z)$   $\rightarrow 2$       ; what abt. 3? 4? 5? ✓

lookup H:  $\text{hash}(H)$   $\rightarrow 2$       3? 4? 5? 6? X  $\rightarrow$  H is not in hashtable

insert A:  $\text{hash}(A)$   $\rightarrow 9$   
 $\text{hash}(B)$   $\rightarrow 9$       ; add 1 & mod(size)  $\rightarrow 0$ ? ✓

insert rest:

Insert G:  $\text{hash}(G)$   $\rightarrow 6$       infinite loop! grows array or if we get back to 6, say no there

remove W!  $\text{hash}(W) \rightarrow 3$  but now can't find Z!  
don't remove, mark is dead !

limit collisions

move as lookup  
re-hash

## More hash tables

separate chaining  $\rightarrow$  buckets



insert W:  $\text{hash}(W) \rightarrow 3$   
 $\text{hash}(Y) \rightarrow 4$   
 $\text{hash}(X) \rightarrow Z$   
 $\text{hash}(Z) \rightarrow Z$

lookup F:  $\text{lookup}(F) \rightarrow 2$  F is not X or Z, either in bucket 2 or not

remove W:  $\text{hash}(W) \rightarrow 3$  take out W & put asterisk. bucket. don't need tombstone

how to implement bucket? linked list

long bucket? use good hash fn

rehashing:

define load factor as avg num of entries per slot  
if it reaches specified threshold, create larger table, hash all data into it, replace current

bonus option: keep old table for while, gradually move items to new table

## Graphs!

graphs have vertices, nodes representing entities

graphs have edges to represent relationships between 2 vertices

types

directed - links go one way, not reciprocated

undirected - all edges go both ways

source  $\rightarrow$  sink

weighted - each edge has weight signaling strength of relationship  
unweighted - relationship strengths are equal

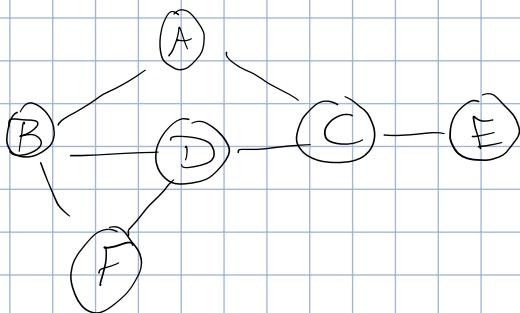
researchers co-authored at least 1 paper

undirected

can be weighted by # of papers

adjacency matrix

let's have an  $N \times N$  matrix

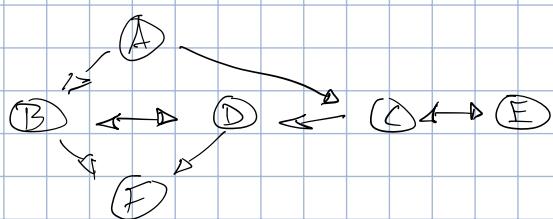


	A	B	C	D	E	F
A	0	1	1	0	0	0
B	1	0	0	1	0	1
C	1	0	0	1	1	0
D	0	1	1	0	0	1
E	0	0	1	0	0	0
F	0	1	0	1	0	0

table is symmetric

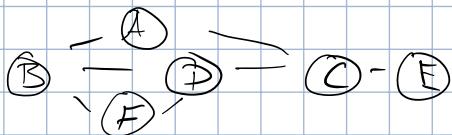
if it weighted, put value w

if directed, it is not symmetric



	A	B	C	D	E	F
A						
B						
C						
D	0	1	0	0	0	1
E						
F						

adjacency list



list

A : B, C

B : A, D, F

C : A, D, E

D : B, C, F

E: C  
F: B, D

for weighted, have tuples?

A: (B, 2), (C, 1)