

## 1 Simple Linear Example

Consider a simple driver-response system:

$$\begin{aligned} x_t &= \sin(t) \\ y_t &= x_{t-1} + \eta_t \\ &= \sin(t-1) + \eta_t \\ &= \sin(t) \cos(1) - \cos(t) \sin(1) + \eta_t \end{aligned}$$

with  $\eta_t \sim \mathcal{N}(0, 1)$ . Define

$$\delta x_t \equiv \frac{dx}{dt} \approx \frac{\Delta x}{\Delta t} = x_t - x_{t-1}$$

and

$$\delta y_t \equiv \frac{dy}{dt} \approx \frac{\Delta y}{\Delta t} = y_t - y_{t-1} .$$

It follows that

$$\begin{aligned} \delta x_t &= \sin(t) - \sin(t-1) \\ &= \sin(t) - (\sin(t) \cos(1) - \cos(t) \sin(1)) \\ &= \sin(t) (1 - \cos(1)) + \sin(1) \cos(t) \\ &\equiv \kappa_1 \sin(t) + \kappa_2 \cos(t) \end{aligned}$$

with  $\kappa_1 = 1 - \cos(1)$  and  $\kappa_2 = \sin(1)$ , and

$$\begin{aligned} \delta y_t &= x_{t-1} + \eta_t - x_{t-2} - \eta_{t-1} \\ &= \sin(t-1) - \sin(t-2) + \eta_t - \eta_{t-1} \\ &= (\sin(t) \cos(1) - \cos(t) \sin(1)) - (\sin(t) \cos(2) - \cos(t) \sin(2)) + \eta'_t \\ &= \sin(t) (\cos(1) - \cos(2)) + \cos(t) (\sin(2) - \sin(1)) + \eta'_t \\ &\equiv k_1 \sin(t) + k_2 \cos(t) + \eta'_t \end{aligned}$$

with  $\eta'_t = \eta_t - \eta_{t-1} \sim \mathcal{N}(0, 2)^1$ ,  $k_1 = (\cos(1) - \cos(2))$  and  $k_2 = (\sin(2) - \sin(1))$ .

The main idea of Local Impulse Response (LIR) causality inference is to use a subsetting procedure on some (or all) of the four time series  $x_t$ ,  $y_t$ ,  $\delta x_t$ , and  $\delta y_t$  to determine the causality of the system.

Consider a few extreme points in the driver cycle, e.g.  $t = n\pi$  with  $n = 0, 1, 2, 3, 4, \dots$ . The driver values are

$$x_{n\pi} = \sin(n\pi) = 0 ,$$

the response values are

$$y_{n\pi} = \sin(n\pi) \cos(1) - \cos(n\pi) \sin(1) + \eta_{n\pi} = \eta_{n\pi} + (-1)^n \sin(1) ,$$

the local change in the driver values are

$$\delta x_{n\pi} = \kappa_1 \sin(n\pi) + \kappa_2 \cos(n\pi) = (-1)^n \kappa_2 ,$$

and the local change in the response values are

$$\delta y_{n\pi} = k_1 \sin(n\pi) + k_2 \cos(n\pi) + \eta'_{n\pi} = \eta'_{n\pi} + (-1)^n k_2 .$$

Consider  $t = n\pi/2$  with  $n = 1, 2, 3, 4, \dots$ . The driver values are

$$x_{n\frac{\pi}{2}} = \sin\left(n\frac{\pi}{2}\right) = (-1)^n ,$$

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<sup>1</sup>The difference of two normal distributions with means  $\mu_1$  and  $\mu_2$  and variances  $\sigma_1^2$  and  $\sigma_2^2$  is another normal distribution with mean  $\mu_1 - \mu_2$  and variance  $\sigma_1^2 + \sigma_2^2$ .

the response values are

$$y_{n\frac{\pi}{2}} = \sin\left(n\frac{\pi}{2}\right) \cos(1) - \cos\left(n\frac{\pi}{2}\right) \sin(1) + \eta_{n\frac{\pi}{2}} = \eta_{n\frac{\pi}{2}} + (-1)^n \cos(1) ,$$

the local change in the driver values are

$$\delta x_{n\frac{\pi}{2}} = \kappa_1 \sin\left(n\frac{\pi}{2}\right) + \kappa_2 \cos\left(n\frac{\pi}{2}\right) = (-1)^n \kappa_1 ,$$

and the local change in the response values are

$$\delta y_{n\frac{\pi}{2}} = k_1 \sin\left(n\frac{\pi}{2}\right) + k_2 \cos\left(n\frac{\pi}{2}\right) + \eta'_{n\frac{\pi}{2}} = \eta'_{n\frac{\pi}{2}} + (-1)^n k_1 .$$

## 2 Subsetting for LIR variance

Consider  $\mathbf{X} = \{x_t\}$  and  $\mathbf{Y} = \{y_t\}$  given  $t \in [0, 4\pi]$ . Let  $L$  be the library length of  $\mathbf{X}$  and  $\mathbf{Y}$ . These systems have five points where  $t = n\pi$  for  $n = 0, 1, 2, 3$  and  $4$ . Thus, an  $m$ -binned histogram of  $\mathbf{X}$ , where  $m \geq L$ , would have a bin,  $b_0$ , centered at  $x_t = 0$  that contains the five points  $\mathbf{X}_0 = \{x_{n\pi}\}$ . (If  $m < L$ , then  $\mathbf{b}_0$  would contain at least five points but the total number of points in  $\mathbf{b}_0$  would be a function of the total number of bins, assuming bins of equal sizes.)

Consider the set of time steps  $\mathbf{T} = \{t = n\pi\} \forall n = 0, 1, 2, 3, 4$  for which the values in  $\mathbf{X}_0$  are achieved. The local impulses immediately preceding  $\mathbf{b}_0$  are  $\delta\mathbf{X}_{\mathbf{T}} = \{\delta x_{n\pi}\}$ , which also contains five points. However, those five points would not appear in a single bin of an  $m$ -binned histogram of  $\{\delta x_t\}$  (given  $m \geq L$ ). The set  $\delta\mathbf{X}_{\mathbf{T}}$  would actually be split into two separate bins in such a histogram, one for the three points equal to  $\kappa_2$  and one for the two points equal to  $-\kappa_2$ . Thus, the time steps associated all of the points in a given histogram bin of a given time series, e.g.  $\mathbf{b}_0$ , do not necessarily correspond to points in a single histogram bin of different (though related) times series, e.g.  $\delta\mathbf{X}_{\mathbf{T}}$ . This idea is straightforward but it is the basic idea underlying the subsetting method for calculating the LIR variance.

The subsetting is premised on the following:

- The local temporal response causally depends on the local temporal change in the driver; e.g.  $y_t$  causally depends on  $\delta x_t$
- The local temporal response causally depends on the immediately preceding response; e.g.  $y_t$  causally depends on  $y_{t-1}$
- The local temporal response does not causally depend on the immediately preceding driver except through the local temporal change in the driver; e.g.  $y_t$  does not causally depend on  $x_{t-1}$  except through  $\delta x_t$

Thus, the subsetting procedure is as follows:

1. Create an  $m$ -binned histogram of the response signal  $\mathbf{R} = \{r_t\}$ .
2. Given  $m$  bins  $\mathbf{b}_i$  where  $i$  denotes the center of the  $m$ th bin, create an  $m'$ -binned histogram of the change in the driver signal  $\delta\mathbf{D} = \{\delta d_t\} = \{d_t - d_{t-1}\}$  at the time steps  $\tau = \{t \mid r_t \in \mathbf{b}_i\}$ .
3. Given  $m'$  bins  $\mathbf{b}'_j$  where  $j$  denotes the center of the  $m'$ th bin, find the variance of the response at the time steps immediately following (i.e.  $t + 1$ ) the time steps  $\tau' = \{t \mid \delta d_t \in \mathbf{b}'_j\}$ .

As an example, consider  $\mathbf{R} = \mathbf{X}$  and  $\mathbf{D} = \mathbf{Y}$ . An  $m$ -binned histogram of  $\mathbf{X}$  would lead to a bin centered at zero,  $b_0$ , that contains at least five points evaluated at  $t = n\pi \forall n = 0, 1, 2, 3, 4$ . Thus, the change in the driver signal, i.e.  $\{\delta y_t\}$ , evaluated at  $\tau$  contains at least the five points  $\eta'_{n\pi} + (-1)^n k_2$ . The  $m'$ -binned histogram of step 2 would split these five points among different bins (depending on both the sign of  $k_2$  and the value of  $\eta'_{n\pi}$  for a given  $n$ ). If each of the points is placed into a bin alone, then the variance calculations of step 3 become  $\text{var}(\sin(n\pi + 1)) \forall n = 0, 1, 2, 3, 4$ , which is five zeros because the variance of a single point is zero. Suppose

all five points are placed into a single bin. The variance calculation of step 3 then becomes

$$\text{var}(\{\sin(n\pi + 1) \mid n = 0, 1, 2, 3, 4\}) = \text{var}(\{\sin(n\pi) \cos(1) + \cos(n\pi) \sin(1) \mid n = 0, 1, 2, 3, 4\}) \quad (1)$$

$$= \text{var}(\{(-1)^n \kappa_2 \mid n = 0, 1, 2, 3, 4\}) \quad (2)$$

$$= \text{var}(\{\kappa_2, -\kappa_2, \kappa_2, -\kappa_2, \kappa_2\}) \quad (3)$$

$$= \frac{1}{5} ((\kappa_2 - \mu)^2 + (-\kappa_2 - \mu)^2 + (\kappa_2 - \mu)^2 + (-\kappa_2 - \mu)^2 + (\kappa_2 - \mu)^2) \quad (4)$$

$$= \frac{1}{5} \left( \frac{16}{25} \kappa_2^2 + \frac{36}{25} \kappa_2^2 + \frac{16}{25} \kappa_2^2 + \frac{36}{25} \kappa_2^2 + \frac{16}{25} \kappa_2^2 \right) \quad (5)$$

$$= \frac{1}{5} \frac{120}{25} \kappa_2^2 \quad (6)$$

$$= \frac{24}{25} \kappa_2^2 \quad (7)$$

where  $\mu = \kappa_2/5$ . Thus, the LIR variance depends strongly on the number of bins used to construct the histograms in steps 1 and 2.

In this particular example,  $\mathbf{Y}$  is known to be the response and  $\mathbf{X}$  is known to be the driver. It may be assumed that our assignment of  $\mathbf{R} = \mathbf{X}$  and  $\mathbf{D} = \mathbf{Y}$  may proven “false” by comparing the variances given this assignment and its complement, i.e.  $LIRvar \mid \mathbf{R} = \mathbf{X}, \mathbf{D} = \mathbf{Y}$  and  $LIRvar \mid \mathbf{R} = \mathbf{Y}, \mathbf{D} = \mathbf{X}$ . It may be assumed that the lower LIR variance is indicative of a stronger causal inference, i.e. if  $LIRvar \mid \mathbf{R} = \mathbf{X}, \mathbf{D} = \mathbf{Y}$  is greater than  $LIRvar \mid \mathbf{R} = \mathbf{Y}, \mathbf{D} = \mathbf{X}$ , then it may be assumed  $\mathbf{R} = \mathbf{Y}, \mathbf{D} = \mathbf{X}$  is the more “correct” assignment. Notice, however, that we have already shown that the incorrect assignment of  $\mathbf{R} = \mathbf{X}$  and  $\mathbf{D} = \mathbf{Y}$  can lead to an LIR variance of variance. The correct assignment of  $\mathbf{R} = \mathbf{Y}$  and  $\mathbf{D} = \mathbf{X}$  cannot lead to an LIR variance less than zero (variances are nonnegative). Thus, it seems that comparing LIR variances is not a robust method for causal inference.

### 3 LIR Approach to Probabilistic Causality

Probabilistic causality is centered on the definition that a cause  $C$  is said to *cause* (or *drive*) an effect  $E$  if

$$P(E|C) > P(E|\bar{C}) ,$$

i.e.  $C$  causes  $E$  if the probability of  $E$  given  $C$  is higher than the probability of  $E$  given not  $C$ . The LIR causal inference method involves using e.g.  $\{x_t\}$ ,  $\{y_t\}$ ,  $\{\delta x_t\}$ , and  $\{\delta y_t\}$  to determine the direction of causal influence in a system of two times series  $\{x_t\}$  and  $\{y_t\}$ . It follows that applying LIR causal inference to probabilistic causality involves evaluating the above inequality given e.g.  $C = \{x_t\}$ ,  $\{y_t\}$ ,  $\{\delta x_t\}$ , or  $\{\delta y_t\}$  and  $E = \{x_t\}$ ,  $\{y_t\}$ ,  $\{\delta x_t\}$ , or  $\{\delta y_t\}$  given  $E \neq C$  and for different temporal offsets.

The conditional probabilities are estimated using histograms of the time series data as follows:

$$P(E|C) \approx \frac{1}{L} H(E|C) = \frac{H(E \cap C)}{H(C)}$$

where  $H(A)$  is an  $m$ -binned histogram of  $A$ ,  $L$  is the library length of the  $E$  and  $C$  time series (which are assumed to be the same length). Similarly,

$$P(E|\bar{C}) \approx \frac{1}{L} H(E|\bar{C}) = \frac{H(E \cap \bar{C})}{H(\bar{C})} .$$

Define the *causal penchant*

$$\rho_{EC} = P(E|C) - P(E|\bar{C}) \approx \frac{H(E \cap C)}{H(C)} - \frac{H(E \cap \bar{C})}{H(\bar{C})} .$$

If  $C$  causes  $E$ , then  $\rho_{EC} > 0$ . Otherwise, i.e.  $\rho_{EC} \leq 0$ , the causal influence of the system is *undefined(?)*. Causal influence between a pair of time series is accomplished by comparing penchants.