

数值算法 Homework 10

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Problem 1

([Reference 1](#)) & ([Reference 2](#))

Let A be a Hermitian matrix.

Describe how to transform A to a real tridiagonal matrix by unitary similarity, before applying the implicit QR algorithm.

Proof:

我们首先使用 Householder 变换将 A 约化为一个 Hermite 三对角阵.

要设计算法将 Hermite 三对角阵约化为对称三对角阵,

首先考虑如何将形如 $\begin{bmatrix} a_1 & b \\ \bar{b} & a_2 \end{bmatrix}$ (where $a_1, a_2 \in \mathbb{R}$, $b \in \mathbb{C}$) 的 2 阶 Hermite 阵化为实对称阵.

设 $b = re^{i\theta}$ (对应地 $\bar{b} = re^{-i\theta}$), 则我们可以构造如下的酉相似变换:

$$\begin{aligned} \begin{bmatrix} e^{-i\theta} & \\ & 1 \end{bmatrix} \begin{bmatrix} a_1 & b \\ \bar{b} & a_2 \end{bmatrix} \begin{bmatrix} e^{i\theta} & \\ & 1 \end{bmatrix} &= \begin{bmatrix} e^{-i\theta} \cdot a_1 \cdot e^{i\theta} & e^{-i\theta} \cdot b \cdot 1 \\ 1 \cdot \bar{b} \cdot e^{i\theta} & 1 \cdot a_2 \cdot 1 \end{bmatrix} \quad (\text{note that } \begin{cases} b = re^{i\theta} \\ \bar{b} = re^{-i\theta} \end{cases}) \\ &= \begin{bmatrix} a_1 & r \\ r & a_2 \end{bmatrix} \\ &= \begin{bmatrix} a_1 & |b| \\ |b| & a_2 \end{bmatrix} \end{aligned}$$

注意到 $e^{i\theta} = \frac{b}{r} = \frac{b}{|b|}$

因此我们只需取 $D = \text{diag}\{\frac{b}{|b|}, 1\}$ 即有 $D^{-1} \begin{bmatrix} a_1 & b \\ \bar{b} & a_2 \end{bmatrix} D = \begin{bmatrix} a_1 & |b| \\ |b| & a_2 \end{bmatrix}$

Matlab 代码:

```
rng(51);
A = diag(rand(2, 1));
A(1,2) = rand(1, 1) + 1i * rand(1, 1);
A(2,1) = A(1,2)';

disp("A:");
disp(A);

D = diag([A(1,2) / abs(A(1,2)), 1]);

disp("D_inv * A * D:");
disp((D \ A) * D);
```

运行结果:

```

A:
    0.6757 + 0.0000i    0.3433 + 0.6440i
    0.3433 - 0.6440i    0.0447 + 0.0000i

D_inv * A * D:
    0.6757 - 0.0000i    0.7298 + 0.0000i
    0.7298 - 0.0000i    0.0447 + 0.0000i

```

推广到 n 维情况:

我们可以将 Hermite 三对角阵 A 的超对角线提取出来得到 $b \in \mathbb{R}^{n-1}$

逐元素除以模长: $d = b ./ \text{abs}(b)$

为一次性构建对角矩阵 D , 我们需要不断将 d 中靠后的元素累乘到靠前的元素.

最终 $D = \text{diag}([d^T, 1]) \in \mathbb{C}^{n \times n}$, 使得 $D^{-1}AD$ 为对称三对角阵.

Matlab 代码为:

```

% Construct a Hermitian tridiagonal matrix `A`:
rng(51);
n = 5;
A = diag(rand(n, 1)) + diag( ...
    rand(n-1, 1) + 1i * rand(n-1, 1), 1) + diag( ...
    rand(n-1, 1) + 1i * rand(n-1, 1), -1);
A = 0.5 * (A + A');
disp("A:");
disp(A);

% Extract the superdiagonal elements of A
b = diag(A, 1);

% Compute "phase" information
d = b ./ abs(b);

% Loop over the vector `d` to accumulate the "phase" information
for i = n-2:-1:1
    d(i) = d(i) * d(i+1);
end

% Create a diagonal matrix `D` from the modified vector `d`
D = diag([d; 1]);

% Perform the unitary transformation `D_inv * A * D`
% changing the matrix `A` into a real and symmetric matrix `A_tilde`
A_tilde = (D \ A) * D;

% Display the transformed matrix `A_tilde`
disp("D_inv * A * D:");
disp(A_tilde);

```

运行结果:

```

A:
  0.6757 + 0.0000i   0.5996 + 0.0978i   0.0000 + 0.0000i   0.0000 + 0.0000i
0.0000 + 0.0000i
  0.5996 - 0.0978i   0.0447 + 0.0000i   0.2840 - 0.1355i   0.0000 + 0.0000i
0.0000 + 0.0000i
  0.0000 + 0.0000i   0.2840 + 0.1355i   0.3433 + 0.0000i   0.2178 + 0.0790i
0.0000 + 0.0000i
  0.0000 + 0.0000i   0.0000 + 0.0000i   0.2178 - 0.0790i   0.6440 + 0.0000i
0.4568 - 0.0539i
  0.0000 + 0.0000i   0.0000 + 0.0000i   0.0000 + 0.0000i   0.4568 + 0.0539i
0.2842 + 0.0000i

D_inv * A * D:
  0.6757 + 0.0000i   0.6075 + 0.0000i   0.0000 + 0.0000i   0.0000 + 0.0000i
0.0000 + 0.0000i
  0.6075 - 0.0000i   0.0447 + 0.0000i   0.3146 - 0.0000i   0.0000 + 0.0000i
0.0000 + 0.0000i
  0.0000 + 0.0000i   0.3146 - 0.0000i   0.3433 + 0.0000i   0.2317 - 0.0000i
0.0000 + 0.0000i
  0.0000 + 0.0000i   0.0000 + 0.0000i   0.2317 + 0.0000i   0.6440 + 0.0000i
0.4599 - 0.0000i
  0.0000 + 0.0000i   0.0000 + 0.0000i   0.0000 + 0.0000i   0.4599 + 0.0000i
0.2842 + 0.0000i

```

Problem 2

Let A and B be $n \times n$ real symmetric matrices.

Suppose that B is positive definite.

Show that AB is diagonalizable, and design an algorithm to compute all eigenvalues and eigenvectors of AB .

Solution:

注意到 B 是对称正定阵，故存在 Cholesky 分解 $B = LL^T$

其中 $L \in \mathbb{R}^{n \times n}$ 为具有正实数对角元的下三角阵 (因为是非奇异矩阵)

因此 $AB = ALL^T = L^{-T}(L^TAL)L^T$ ，相似于实对称阵 L^TAL

而 L^TAL 作为实对称阵 (自然是正规矩阵) 可正交相似对角化，于是 AB 可相似对角化。

欲计算 AB 的特征值和特征向量，只需先对 B 做 Cholesky 分解得到 $B = LL^T$

并对实对称阵 L^TAL 应用 Wilkinson 位移的对称隐式 QR 算法得到谱分解 $L^TAL = Q\Lambda Q^T$

最后使用回代法求解三角方程组 $L^TX = Q$ 得到 $X = L^{-T}Q$

根据 $AB = L^{-T}(L^TAL)L^T = L^{-T}Q\Lambda Q^TL^T = (L^{-T}Q)\Lambda(L^{-T}Q)^{-1}$

可知 Λ 的对角元即为 AB 的特征值， $X = L^{-T}Q$ 的列向量即为对应的特征向量。

Problem 3

Implement the scaling-and-squaring algorithm (with truncated Taylor series) for computing the matrix exponential.

Test the accuracy of your algorithm by a few diagonalizable matrices with known spectral decomposition.

- (optional) Implement the Schur–Parlett algorithm and compare the accuracy.

- **(H, optional)** Replace truncated Taylor series by Pade approximants and compare the accuracy.

(1) 秦九韶算法

在超越矩阵函数的逼近中经常涉及计算多项式.

考虑以下矩阵多项式:

$$p(A) = c_d A^d + c_{d-1} A^{d-1} + \cdots + c_1 A + c_0 I$$

其中 $c_0, c_1, \dots, c_{d-1}, c_d$ ($c_d \neq 0$) 是给定的实数.

(秦九韶算法/Horner 技巧, Matrix Computation 算法 11.2.1)

给定 $A \in \mathbb{R}^{n \times n}$ 和 $c_0, c_1, \dots, c_{d-1}, c_d$ (用向量 $c \in \mathbb{R}^{d+1}$ 传入)

此算法计算多项式 $F = p(A) = c_d A^d + c_{d-1} A^{d-1} + \cdots + c_1 A + c_0 I$:

```
function: F = Qin_Jiushao(A, c)
    F = c_d A + c_{d-1} I
    for k = d - 2 : -1 : 0
        F = A F + c_k I
    end
end
```

上述算法需要 $d - 1$ 次矩阵乘法.

但和标量的情形不同的是, 上述求和过程并不是最优的, 我们可以适当增加 "步长".

以 $d = 4$ 为例 (只需要 2 次矩阵乘法):

$$\begin{aligned} p(A) &= c_4 A^4 + c_3 A^3 + c_2 A^2 + c_1 A + c_0 I_n \\ &= A^2 (c_4 A^2 + c_3 A + c_2 I_n) + c_1 A + c_0 I_n \\ A_1 &= A \\ A_2 &= A^2 \\ F_1 &= c_4 A_2 + c_3 A_1 + c_2 I_n \\ F &= A_2 F_1 + c_1 A_1 + c_0 I_n \end{aligned}$$

一般来说, 考虑计算 d 次矩阵多项式:

$$p(A) = c_d A^d + c_{d-1} A^{d-1} + \cdots + c_1 A + c_0 I$$

可取最优步长 $t = \lfloor \sqrt{d} \rfloor$ 并计算:

$$\begin{aligned} A_1 &= A \\ A_2 &= A A_1 \\ A_3 &= A A_2 \\ &\vdots \\ A_t &= A A_{t-1} \end{aligned}$$

这需要 $t - 1$ 次矩阵乘法.

记 $r = \lfloor \frac{d}{t} \rfloor$ 并执行以下迭代:

$$\begin{aligned} F &= c_d A_{d-rt} + c_{d-1} A_{d-rt-1} + \cdots + c_{rt+1} A_1 + c_{rt} I \\ \text{for } k &= r - 1 : -1 : 0 \\ F &= A_t F + (c_{kt+t-1} A_{t-1} + \cdots + c_{kt+1} A_1 + c_{kt} I) \\ \text{end} \end{aligned}$$

这需要 r 次矩阵乘法.

因此总共需要 $r + t - 1$ 次矩阵乘法.

Matlab 代码为:

```
function F = Qin_Jiushao(A, c)
    % A: Input matrix
    % c: A vector of coefficients for the polynomial, where c(i) corresponds to
    the coefficient for A^(d-i)

    d = length(c) - 1; % Degree of the polynomial
    t = floor(sqrt(d)); % Optimal step length based on the square root of the
    degree
    r = floor(d / t); % Number of iterations required

    % Step 1: Precompute the powers of A, namely A1, A2, ..., At
    A_powers = cell(t, 1); % Cell array to store powers of A
    A_powers{1} = A; % A1 = A
    for i = 2:t
        A_powers{i} = A_powers{i-1} * A; % Ai = A^i, iteratively calculate
        powers of A
    end

    % Step 2: Compute the polynomial value using the precomputed powers of A
    % Start by initializing F with the highest degree term
    % F=c_d A_{d-rt} + c_{d-1} A_{d-rt-1} + \dots + c_{rt+1} A_1 + c_{rt} I
    n = size(A, 1);
    F = zeros(n, n);
    for j = d-r*t:-1:1
        F = F + c(r*t+j+1) * A_powers{j};
    end
    F = F + c(r*t+1) * eye(n);

    % Iterate backwards to calculate the polynomial
    for k = r-1:-1:0
        % F = A_t F + (c_{kt} + t-1} A_{t-1} + \dots + c_{kt+1}A_1 + c_{kt}I)
        % Compute the sum term for the current iteration
        sum_term = zeros(n, n);
        for j = t-1:-1:1
            sum_term = sum_term + c(k*t+j+1) * A_powers{j}; % Add each term to
            the sum
        end
        sum_term = sum_term + c(k*t+1) * eye(n);
        % Update F using the sum of the current terms and the previous result
        F = A_powers{t} * F + sum_term;
    end
end
```

函数调用:

```
rng(51);
n = 100;
A = randn(n);
A = A / norm(A, 'inf');

% Define random polynomial coefficients
d = 50;
c = rand(1, d+1);
```

```

% Direct computation of the polynomial p(A) = c_d A^d + ... + c_0 I
direct_result = zeros(n, n);
A_powers = cell(d, 1); % Cell array to store powers of A
A_powers{1} = A; % A^1 = A
for i = 2:d
    A_powers{i} = A_powers{i-1} * A; % A^i = A^i, iteratively calculate powers
of A
end
for i = d:-1:1
    direct_result = direct_result + c(i+1) * A_powers{i};
end
direct_result = direct_result + c(1) * eye(n);

% Call the Qin_Jiushao function
qin_jiushao_result = Qin_Jiushao(A, c);

% Compare the results
disp('Difference (in Frobenius norm):');
disp(norm(direct_result - qin_jiushao_result, 'fro'));

```

运行结果:

```

Difference (in Frobenius norm):
5.3512e-16

```

(2) Taylor 逼近

计算 $\exp(A)$ 的缩放平方算法 (Scaling and Squaring)

```

m = max(0, 1 + floor(log2(norm(A, 'inf'))))
E_0 = the Taylor approximation of exp(A/2^m)
for j = 1 : m
    E_j = E_{j-1}^2
end

```

Matlab 代码为:

```

function E = scaling_and_squaring_Taylor(A, d)
    % Scaling and Squaring Algorithm to compute exp(A)
    % A: input matrix

    % Step 1: Compute m
    m = max(0, 1 + floor(log2(norm(A, 'inf')))); % Compute m based on the
infinity norm of A

    % Step 2: Compute the Taylor approximation of exp(A / 2^m)
    % The coefficients for the Taylor expansion of exp(z) are 1, 1, 1/2!, 1/3!,
...
    c = zeros(d+1, 1); % Coefficients for Taylor expansion
    c(1) = 1;
    for k = 2:d+1
        c(k) = c(k-1) / (k-1); % Compute the Taylor coefficients
    end

```

```

    % Use Qin_Jiushao to compute the Taylor approximation of exp(A / 2^m)
    E_0 = Qin_Jiushao(A / 2^m, c); % Apply Qin_Jiushao to compute the
    polynomial approximation

    % Step 3: Squaring E_0, m times
    E = E_0;
    for j = 1:m
        E = E * E; % Square E_0 for m times to get exp(A)
    end
end
end

```

函数调用:

```

rng(51);
n = 5;

% Generate diagonalizable matrix with known spectral decomposition
[Q, ~] = qr(rand(n, n));
Lambda = randn(n, 1);
A = Q * diag(Lambda) * Q';
disp("Max eigenvalue absolute value:");
disp(max(abs(Lambda)));

% Exact solution
% exact_solution = expm(A);
exact_solution = Q * diag(exp(Lambda)) * Q';
disp("Exact solution:");
disp(exact_solution);

% Taylor approximation
d = 10;
Taylor_approximation = scaling_and_squaring_Taylor(A, d);
disp("Taylor approximation:");
disp(Taylor_approximation);

% Display Difference
disp('Difference (in Frobenius norm):');
disp(norm(exact_solution - Taylor_approximation, 'fro'));

```

运行结果:

```

Max eigenvalue absolute value:
    1.0947

Exact solution:
    2.0455    0.1010   -0.7774   -0.1252    0.4095
    0.1010    1.0922    0.3790   -0.5317    0.6041
   -0.7774    0.3790    2.1706    0.2647    0.6328
   -0.1252   -0.5317    0.2647    2.0280   -0.6589
    0.4095    0.6041    0.6328   -0.6589    1.3701

Taylor approximation:
    2.0455    0.1010   -0.7774   -0.1252    0.4095
    0.1010    1.0922    0.3790   -0.5317    0.6041
   -0.7774    0.3790    2.1706    0.2647    0.6328
   -0.1252   -0.5317    0.2647    2.0280   -0.6589

```

0.4095 0.6041 0.6328 -0.6589 1.3701

Difference (in Frobenius norm):

1.9342e-13

(3) Padé 逼近

考虑矩阵指数函数 e^A 的计算.

若 $g(z) \approx e^z$, 则 $g(A) \approx e^A$

为达到这一目的, 有一类非常有用的逼近函数——Padé 函数:

$$R_{p,q}(z) := (D_{p,q}(z))^{-1} N_{p,q}(z)$$

其中:

$$N_{p,q}(z) = \sum_{k=0}^p \frac{(p+q-k)!}{(p+q)!} \binom{p}{k} z^k = \sum_{k=0}^p \frac{(p+q-k)! p!}{(p+q)! k! (p-k)!} z^k$$
$$D_{p,q}(z) = \sum_{k=0}^q \frac{(p+q-k)!}{(p+q)!} \binom{q}{k} (-z)^k = \sum_{k=0}^q \frac{(p+q-k)! q!}{(p+q)! k! (q-k)!} (-z)^k$$

特殊地, 当 $q = 0$ 时即为 p 阶 Taylor 多项式:

$$R_{p,0}(z) = \sum_{k=0}^p \frac{z^k}{k!}$$

不幸的是, Padé 逼近仅在原点附近才非常好, 下面的等式说明了这一点:

$$e^A = R_{p,q}(A) + \frac{(-1)^q}{(p+q)!} A^{p+q+1} (D_{p,q}(A))^{-1} \int_0^1 u^p (1-u)^q e^{A(1-u)} du$$

不过我们可以利用缩放平方算法 $e^A = (e^{\frac{A}{2^m}})^{2^m}$ 来克服这一困难.

整个算法的好坏取决于以下逼近的精度:

$$F_{p,q} = \left(R_{p,q} \left(\frac{A}{2^m} \right) \right)^{2^m}$$

可以证明:

若 $\frac{\|A\|_\infty}{2^m} \leq \frac{1}{2}$, 则存在矩阵 $\Delta A \in \mathbb{R}^{n \times n}$ 使得:

$$F_{p,q} = e^{A+\Delta A}$$
$$A\Delta A = \Delta A A$$
$$\|\Delta A\|_\infty \leq \varepsilon(p, q) \|A\|_\infty$$
$$\varepsilon(p, q) = 2^{3-(p+q)} \frac{p!q!}{(p+q)!(p+q+1)!}$$

进而可以证明不等式:

$$\frac{\|e^A - F_{p,q}\|_\infty}{\|e^A\|_\infty} \leq \varepsilon(p, q) \|A\|_\infty \exp\{\varepsilon(p, q) \|A\|_\infty\}$$

参数 p, q 可根据所需的相对精度来确定.

鉴于计算 $F_{p,q}$ 大约需要 $m + \max(p, q)$ 次矩阵乘法, 故我们最好令 $p = q$

上述结果构成了有效计算 e^A 并控制误差的方法的基础.

(Matrix Computation 算法 11.3.1)

给定矩阵 $A \in \mathbb{R}^{n \times n}$ 和 $\tau > 0$, 此算法计算 $F = e^{A+\Delta A}$ (其中 $\|\Delta A\|_\infty \leq \tau \|A\|_\infty$)

```
m = max(0, 1 + floor(log2(||A||_inf)))
A = A/2^m
Let q be the smallest nonnegative integer such that ε(q, q) ≤ τ
N = I
D = I
X = I
c = 1
for k = 1 : q
    c = c(q - k + 1)/[(2q - k + 1)k]
    X = AX
    N = N + cX
    D = D + (-1)^k cX
end
solve DF = N for F = D^{-1}N using Gaussian elimination
for k = 1 : m
    F = F^2
end
```

上述算法大约需要 $2(q + m + \frac{1}{3})n^3$ 的计算量.

此外我们还可利用**秦九韶算法**来加快矩阵多项式 $D = D_{q,q}(A)$ 和 $N = N_{q,q}(A)$ 的计算.

Matlab 代码:

```
function F = scaling_and_squaring_Pade(A, q)
% Calculate the matrix exponential exp(A) using scaling and squaring method.
% A: input matrix (n x n)
% q: number of terms for the Pade series

% Step 1: Compute m based on the infinity norm of A
m = max(0, 1 + floor(log2(norm(A, 'inf')))); % Compute m based on the
infinity norm of A
A = A / 2^m; % Scale A by 2^m

% Step 2: Initialize N, D, X, and c
n = size(A, 1); % Size of matrix A
N = eye(n); % Identity matrix for N
D = eye(n); % Identity matrix for D
X = eye(n); % Identity matrix for X
c = 1; % Initial coefficient for Pade expansion

% Step 3: Iterate q times to compute N and D
for k = 1:q
    % Update coefficient c
    c = c * (q - k + 1) / ((2 * q - k + 1) * k);

    % Update X = A * X
    X = A * X;

    % Update N = N + c * X
    N = N + c * X;
end
```

```

        % Update D = D + (-1)^k * c * X
        D = D + (-1)^k * c * X;
    end

    % Step 4: Solve D * F = N for F, using Gaussian elimination
    F = D \ N; % Use MATLAB's backslash operator for solving the system

    % Step 5: Square F m times to apply the scaling and squaring
    for k = 1:m
        F = F * F; % Square F m times
    end
end
end

```

函数调用:

```

rng(51);
n = 5;

% Generate diagonalizable matrix with known spectral decomposition
[Q, ~] = qr(rand(n, n));
Lambda = randn(n, 1);
A = Q * diag(Lambda) * Q';
disp("Max eigenvalue absolute value:");
disp(max(abs(Lambda)));

% Exact solution
% exact_solution = expm(A);
exact_solution = Q * diag(exp(Lambda)) * Q';
disp("Exact solution:");
disp(exact_solution);

% Taylor approximation
q = 13;
Pade_approximation = scaling_and_squaring_Pade(A, q);
disp("Pade approximation:");
disp(Pade_approximation);

% Display Difference
disp('Difference (in Frobenius norm):');
disp(norm(exact_solution - Pade_approximation, 'fro'));

```

运行结果:

```

Max eigenvalue absolute value:
    1.0947

Exact solution:
    2.0455    0.1010   -0.7774   -0.1252    0.4095
    0.1010    1.0922    0.3790   -0.5317    0.6041
   -0.7774    0.3790    2.1706    0.2647    0.6328
   -0.1252   -0.5317    0.2647    2.0280   -0.6589
    0.4095    0.6041    0.6328   -0.6589    1.3701

Pade approximation:
    2.0455    0.1010   -0.7774   -0.1252    0.4095

```

0.1010	1.0922	0.3790	-0.5317	0.6041
-0.7774	0.3790	2.1706	0.2647	0.6328
-0.1252	-0.5317	0.2647	2.0280	-0.6589
0.4095	0.6041	0.6328	-0.6589	1.3701

Difference (in Frobenius norm):
2.8114e-15

(4) Schur-Parlett 递推

(Parlett 递推, Matrix Computation 算法 11.1.1)

给定对角元互不相同的上三角阵 $T \in \mathbb{C}^{n \times n}$, 计算 $F = f(T)$:

```
function: F = Parlett_Recursion(T)
    for i = 1 : n    (diagonal)
        fii = f(tii)
    end
    for p = 1 : n - 1    (p-th superdiagonal)
        for i = n - p    (from bottom to top)
            j = i + p
            sum = (fii - fij)tij
            for k = i + 1 : j - 1    (from left to right)
                sum = sum + fiktkj - tikfkj
            end
            fij =  $\frac{1}{t_{ii} - t_{jj}}$ sum
        end
    end
end
```

上述算法所需的计算量为 $\frac{2}{3}n^3$

Matlab 代码:

```
function F = Parlett_Recursion(T)
    % Given upper triangular matrix T, compute F = exp(T) using Parlett
    Recursion

    n = size(T, 1); % Size of the matrix T
    F = zeros(n, n); % Initialize the result matrix F

    % Step 1: Compute the diagonal elements of F
    for i = 1:n
        F(i, i) = exp(T(i, i)); % Apply f to each diagonal element
    end

    % Step 2: Compute the off-diagonal elements of F using the recursion
    for p = 1:n-1 % Iterate over superdiagonals
        for i = 1:n-p % Iterate over rows for the p-th superdiagonal
            j = i + p; % j is the column index in the p-th superdiagonal

            % Start computing the sum for f_{ij}
```

```

        sum = (F(i, i) - F(i, j)) * T(i, j);

        % Sum over the elements in between (i+1 to j-1)
        for k = i+1:j-1
            sum = sum + F(i, k) * T(k, j) - T(i, k) * F(k, j);
        end

        % Compute the final off-diagonal element f_{ij}
        F(i, j) = sum / (T(i, i) - T(j, j));
    end
end
end

```

函数调用:

```

rng(51);
n = 5;

% Generate diagonalizable matrix with known spectral decomposition
[Q, ~] = qr(rand(n, n));
Lambda = randn(n, 1);
A = Q * diag(Lambda) * Q';

% Minimum difference between eigenvalues
sorted_Lambda = sort(Lambda);
differences = diff(sorted_Lambda);
min_diff = min(differences);
disp('Minimum difference between eigenvalues:');
disp(min_diff);

% Exact solution
% exact_solution = expm(A);
exact_solution = Q * diag(exp(Lambda)) * Q';
disp('Exact solution:');
disp(exact_solution);

% Calculate Schur decomposition
[Q_schur, T] = schur(A);
exp_T = Parlett_Recursion(T);
parlett_solution = Q_schur * exp_T * Q_schur';
disp('Schur-Parlett solution:');
disp(parlett_solution);

% Display Difference
disp('Difference (in Frobenius norm):');
disp(norm(exact_solution - parlett_solution, 'fro'));

```

运行结果:

```

Minimum difference between eigenvalues:
    0.0187

Exact solution:
    2.0455    0.1010   -0.7774   -0.1252    0.4095
    0.1010    1.0922    0.3790   -0.5317    0.6041
   -0.7774    0.3790    2.1706    0.2647    0.6328

```

-0.1252	-0.5317	0.2647	2.0280	-0.6589
0.4095	0.6041	0.6328	-0.6589	1.3701

Schur-Parlett solution:

2.0455	0.1010	-0.7774	-0.1252	0.4095
0.1010	1.0922	0.3790	-0.5317	0.6041
-0.7774	0.3790	2.1706	0.2647	0.6328
-0.1252	-0.5317	0.2647	2.0280	-0.6589
0.4095	0.6041	0.6328	-0.6589	1.3701

Difference (in Frobenius norm):

1.0243e-14

Problem 4

Let A and E be Hermitian matrices with $AE = EA$.

Try to give an upper bound on $\|\exp(A + E) - \exp(A)\|_2$

Make sure your upper bound tends to zero when $\|E\|_2 \rightarrow 0$

Solution:

考虑初值问题:

$$\begin{aligned}\dot{X}(t) &= AX(t) \\ X(0) &= I\end{aligned}$$

其中 $A, X(t) \in \mathbb{R}^{n \times n}$

它具有唯一解 $X(t) = e^{At}$

于是我们有:

$$\begin{aligned}e^{(A+E)t} - e^{At} &= e^{At}(e^{Et} - 1) \\ &= e^{At} \int_0^t E e^{Es} ds \\ &= \int_0^t e^{A(t-s)} E e^{(A+E)s} ds\end{aligned}$$

根据上式可知:

$$\|e^{(A+E)t} - e^{At}\|_2 \leq \|E\|_2 \int_0^t \|e^{A(t-s)}\|_2 \|e^{(A+E)s}\|_2 ds$$

注意到 $A \in \mathbb{C}^{n \times n}$ 为 Hermite 阵 (自然是正规矩阵), 因而存在谱分解 $A = U\Lambda U^H$

其中 $U \in \mathbb{C}^{n \times n}$ 为酉矩阵, $\Lambda := \text{diag}\{\lambda_1, \dots, \lambda_n\}$ 为对角阵.

于是我们有:

$$\begin{aligned}e^{At} &= e^{U\Lambda U^H t} \\ &= U e^{\Lambda t} U^H \\ &= U \text{diag}\{e^{\lambda_1 t}, \dots, e^{\lambda_n t}\} U^H\end{aligned}$$

进而有:

$$\begin{aligned}
\|e^{At}\|_2 &= \|U \text{diag}\{e^{\lambda_1 t}, \dots, e^{\lambda_n t}\} U^H\|_2 \\
&= \|\text{diag}\{e^{\lambda_1 t}, \dots, e^{\lambda_n t}\}\|_2 \\
&\leq \exp\{\max\{\text{Re}(\lambda_i) : 1 \leq i \leq n\} \cdot t\} \\
&\leq e^{\rho(A)t} \quad (\text{note that } A \text{ is Hermitian, so that } \|A\|_2 = \sigma_{\max}(A) = \rho(A)) \\
&= e^{\|A\|_2 t}
\end{aligned}$$

其中 $\rho(A) = \max_{1 \leq i \leq n} |\lambda_i|$ 代表 A 的谱半径.

注意到 E 也为 Hermite 阵, 且 $AE = EA$, 因此它们可以同时酉对角化.

类似地, 可推得 $\|e^{(A+E)t}\|_2 \leq e^{\|A+E\|_2 t} \leq e^{(\|A\|_2 + \|E\|_2)t}$

因此我们有:

$$\begin{aligned}
\|e^{(A+E)t} - e^{At}\|_2 &\leq \|E\|_2 \int_0^t \|e^{A(t-s)}\|_2 \|e^{(A+E)s}\|_2 ds \\
&\leq \|E\|_2 \int_0^t e^{\|A\|_2(t-s)} e^{(\|A\|_2 + \|E\|_2)s} ds \\
&= \|E\|_2 e^{\|A\|_2 t} \int_0^t e^{\|E\|_2 s} ds \\
&= \|E\|_2 e^{\|A\|_2 t} \frac{1}{\|E\|_2} (e^{\|E\|_2 t} - 1) \\
&= e^{\|A\|_2 t} (e^{\|E\|_2 t} - 1)
\end{aligned}$$

取 $t = 1$ 即有:

$$\|e^{(A+E)} - e^A\|_2 \leq e^{\|A\|_2} (e^{\|E\|_2} - 1)$$

当 $\|E\|_2 \rightarrow 0$ 时, 上界 $e^{\|A\|_2} (e^{\|E\|_2} - 1)$ 趋于 0

Problem 5

Have a quick glance at the paper "From Random Polygon to Ellipse: An Eigenanalysis"

by A. N. Elmachout and C. F. Van Loan (available on eLearning).

Reproduce the experiments in this paper.

(0) Helper Functions

生成元素和分别为 0 的单位向量 $x, y \in \mathbb{R}^n$ 的函数:

```
function [x, y] = generate_unit_vectors(n)
    % Step 1: Generate two random vectors of length n
    x_raw = randn(n, 1); % Random vector for x
    y_raw = randn(n, 1); % Random vector for y

    % Step 2: Adjust to make the sum of components zero
    x_raw = x_raw - mean(x_raw); % Ensure sum(x) = 0
    y_raw = y_raw - mean(y_raw); % Ensure sum(y) = 0

    % Step 3: Normalize the vectors to have unit 2-norm
    x = x_raw / norm(x_raw); % Normalize x
    y = y_raw / norm(y_raw); % Normalize y
end
```

生成平均矩阵的函数:

```
% Function to create the Averaging Matrix M_n
function M = averaging_matrix(n)
    % Create an n x n matrix of zeros
    M = 0.5 * (diag(ones(n,1), 0) + diag(ones(n-1,1), 1));
    M(n, 1) = 0.5;
end
```

绘制多边形的函数:

```
% Function to display the polygon given two vectors
function display_polygon(x, y, k, ax)
    % Ensure the polygon is closed by connecting the first and last points
    x = [x; x(1)];
    y = [y; y(1)];

    % Plot the polygon in the specified subplot axis
    plot(ax, x, y, 'b-o', 'Linewidth', 2, 'MarkerFaceColor', 'b');
    title(ax, ['Iteration: ', num2str(k)]);
    axis(ax, 'equal');
    grid(ax, 'on');
end
```

(1) A First Try

Averaging matrix M_n is defined as:

$$M_n := \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 1 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & & \vdots \\ \vdots & \vdots & & \ddots & 1 & \vdots \\ 0 & 0 & \cdots & \cdots & 1 & 1 \\ 1 & 0 & \cdots & \cdots & 0 & 1 \end{bmatrix}_{n \times n}$$

Denote $\mathcal{P}(x, y)$ as the initial polygon, where $x, y \in \mathbb{R}^n$ are unit l_2 -norm vectors. After k averaging steps we have the polygon $\mathcal{P}(M_n^k x, M_n^k y)$

Algorithm 1:

```
Input: unit vectors  $x^{(0)}, y^{(0)} \in \mathbb{R}^n$  whose components sum to zero
Display  $\mathcal{P}(x^{(0)}, y^{(0)})$ 
for  $k = 1 : \text{max\_iter}$ 
     $x^{(k)} = M_n x^{(k-1)}$ 
     $y^{(k)} = M_n y^{(k-1)}$ 
    Display  $\mathcal{P}(x^{(k)}, y^{(k)})$  for some  $k$  that we are interested in
end
```

Matlab 代码:

```
% Implementing Algorithm 1
function averaging_algorithm(x, y, max_iter)
    % Step 1: Create the averaging matrix M_n
```

```

n = size(x, 1);
M = averaging_matrix(n);

% Create a figure for the subplots
figure;
subplot(2, 3, 1);
display_polygon(x, y, 0, gca);

% Define the set of iterations where we are interested in displaying the
polygon
interested_set = [5, 8, 14, 20, 50];
plot_index = 2;

% Step 2: Iterate through the algorithm
for k = 1:max_iter
    % Apply the averaging matrix to x and y
    x = M * x;
    y = M * y;

    % Check if the current iteration is in the interested set
    if ismember(k, interested_set)
        subplot(2, 3, plot_index); % Create a subplot (2x3 grid)
        display_polygon(x, y, k, gca); % Plot in the current axis
        plot_index = plot_index + 1;
    end
end
end
end

```

函数调用:

```

rng(51);
n = 10; % Size of the averaging matrix
max_iter = 200; % Number of iterations

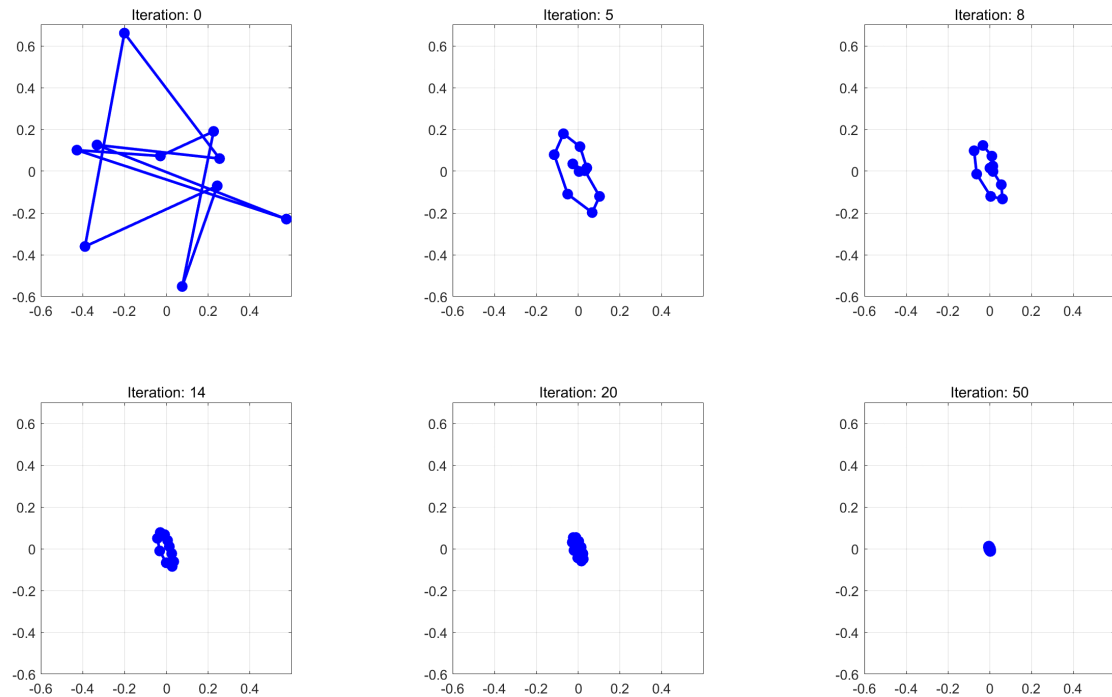
% Generate initial unit vectors
[x, y] = generate_unit_vectors(n);

% Run the averaging algorithm
averaging_algorithm(x, y, max_iter);

```

运行结果:

可以观察到多边形的各个顶点趋近于中心点 (即原点, 因为 $x, y \in \mathbb{R}^n$ 做了中心化)



(2) A Second Try

We introduce a normalization step to keep the polygon $\mathcal{P}(x^{(k)}, y^{(k)})$ from collapsing down to a point,

Specifically, at each iteration k , we rescale the vectors $x^{(k)}$ and $y^{(k)}$ to ensure that they remain unit vectors.

Algorithm 2:

```

Input: unit vectors  $x^{(0)}, y^{(0)} \in \mathbb{R}^n$  whose components sum to zero
Display  $\mathcal{P}(x^{(0)}, y^{(0)})$ 
for  $k = 1 : \text{max\_iter}$ 
     $u = M_n x^{(k-1)}$ 
     $x^{(k)} = u / \|u\|_2$ 
     $v = M_n y^{(k-1)}$ 
     $y^{(k)} = v / \|v\|_2$ 
    Display  $\mathcal{P}(x^{(k)}, y^{(k)})$  for some  $k$  that we are interested in
end
  
```

```

% Implementing Algorithm 2 (i.e. Algorithm 1 with normalization)
function averaging_algorithm(x, y, max_iter)
    % Step 1: Create the averaging matrix M_n
    n = size(x, 1);
    M = averaging_matrix(n);

    % Create a figure for the subplots
    figure;
    subplot(2, 3, 1);
    display_polygon(x, y, 0, gca);

    % Define the set of iterations where we are interested in displaying the
    polygon
    interested_set = [5, 20, 50, 100, 200];
  
```

```

plot_index = 2;

% Step 2: Iterate through the algorithm
for k = 1:max_iter
    % Apply the averaging matrix to x and y, and normalize them
    x = M * x;
    x = x / norm(x);
    y = M * y;
    y = y / norm(y);

    % Check if the current iteration is in the interested set
    if ismember(k, interested_set)
        subplot(2, 3, plot_index); % Create a subplot (2x3 grid)
        display_polygon(x, y, k, gca); % Plot in the current axis
        plot_index = plot_index + 1;
    end
end
end
end

```

函数调用:

```

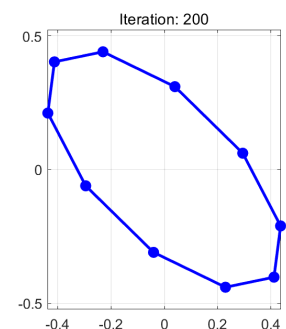
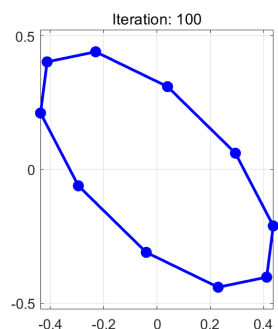
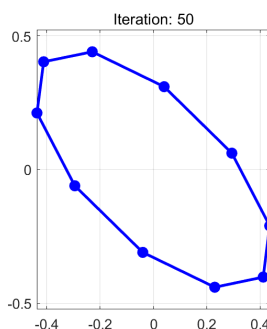
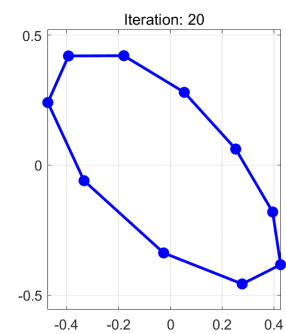
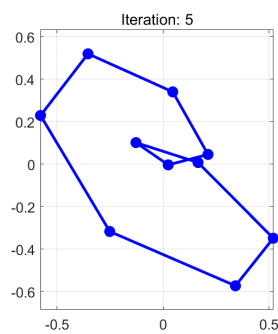
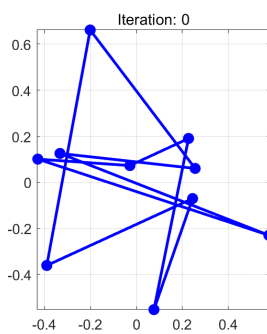
rng(51);
n = 10; % Size of the averaging matrix
max_iter = 200; % Number of iterations

% Generate initial unit vectors
[x, y] = generate_unit_vectors(n);

% Run the averaging algorithm
averaging_algorithm(x, y, max_iter);

```

运行结果:



猜想 (Conjecture):

No matter how random the initial $\mathcal{P}(x^{(0)}, y^{(0)})$, the edges of the $\mathcal{P}(x^{(k)}, y^{(k)})$ eventually "uncross",

and in the limit the vertices appear to arrange themselves around an ellipse that is tilted 45 degrees from the coordinate axes.

(3) A Third Try

Consider the eigenvalues and eigenvectors of M_n :

$$M_n := \frac{1}{2} \begin{bmatrix} 1 & 1 & 0 & \cdots & 0 & 0 \\ 0 & 1 & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \ddots & \ddots & & \vdots \\ \vdots & \vdots & & \ddots & 1 & \vdots \\ 0 & 0 & \cdots & \cdots & 1 & 1 \\ 1 & 0 & \cdots & \cdots & 0 & 1 \end{bmatrix}_{n \times n}$$

(注意到 M_n 是一个 Frobenius 友阵加上单位阵最后乘以 $\frac{1}{2}$, 而这个 Frobenius 友阵的特征值和特征向量我们是知道的)

记 $\omega = \exp\left(\frac{2\pi}{n}\right)$, 则 M_n 的特征值和特征向量为:

$$\lambda_k = \frac{1}{2}(1 + \omega^{k-1})$$

$$x_k = \begin{bmatrix} 1 \\ \omega^{k-1} \\ \omega^{2(k-1)} \\ \vdots \\ \omega^{(n-1)(k-1)} \end{bmatrix} \quad (k = 1, \dots, n)$$

Algorithm 3:

Input: $\theta_x, \theta_y \in \mathbb{R}$

$$\tau = \begin{bmatrix} 0 \\ 2\pi/n \\ 4\pi/n \\ \vdots \\ 2(n-1)\pi/n \end{bmatrix}, \quad c = \sqrt{2/n} \cos(\tau), \quad s = \sqrt{2/n} \sin(\tau)$$

$$x^{(0)} = \cos(\theta_x)c + \sin(\theta_x)s$$

$$y^{(0)} = \cos(\theta_y)c + \sin(\theta_y)s$$

Display $\mathcal{P}(x^{(0)}, y^{(0)})$

for $k = 1 : \text{max_iter}$

$$u = M_n x^{(k-1)}$$

$$x^{(k)} = u / \|u\|_2$$

$$v = M_n y^{(k-1)}$$

$$y^{(k)} = v / \|v\|_2$$

Display $\mathcal{P}(x^{(k)}, y^{(k)})$ for some k that we are interested in

end

```

% Implementing Algorithm 3
function averaging_algorithm(x, y, max_iter)
    % Step 1: Create the averaging matrix M_n
    n = size(x, 1);
    M = averaging_matrix(n);

    % Create a figure for the subplots
    figure;
    subplot(2, 3, 1);
    display_polygon(x, y, 0, gca);

    % Define the set of iterations where we are interested in displaying the
    polygon
    interested_set = [2, 4, 5, 7, 9];
    plot_index = 2;

    % Step 2: Iterate through the algorithm
    for k = 1:max_iter
        % Apply the averaging matrix to x and y, and normalize them
        x = M * x;
        x = x / norm(x);
        y = M * y;
        y = y / norm(y);

        % Check if the current iteration is in the interested set
        if ismember(k, interested_set)
            subplot(2, 3, plot_index); % Create a subplot (2x3 grid)
            display_polygon(x, y, k, gca); % Plot in the current axis
            plot_index = plot_index + 1;
        end
    end
end
end

```

绘制多边形的函数修改为:

```

function display_polygon(x, y, k, ax)
    % Ensure the polygon is closed by connecting the first and last points
    x = [x; x(1)];
    y = [y; y(1)];

    % Identify even and odd indices
    even_indices = 2:2:length(x); % Even indices (2, 4, 6, ...)
    odd_indices = 1:2:length(x); % Odd indices (1, 3, 5, ...)

    % Plot even-indexed points in red
    plot(ax, x(even_indices), y(even_indices), 'ro', 'Linewidth', 2,
'MarkerFaceColor', 'r');
    hold(ax, 'on'); % Hold on to the current plot

    % Plot odd-indexed points in blue
    plot(ax, x(odd_indices), y(odd_indices), 'bo', 'Linewidth', 2,
'MarkerFaceColor', 'b');

    % Connect the points with a dashed line
    plot(ax, x, y, 'k--', 'Linewidth', 1); % Dashed line (k-- for black dashed)

    % Add the title and adjust the grid and axis

```

```

title(ax, ['Iteration: ', num2str(k)]);
axis(ax, 'equal');
grid(ax, 'on');

% Add index labels next to each point
for i = 1:length(x)-1 % Exclude the last repeated point for closing the
polygon
    text(ax, x(i), y(i), num2str(i), 'VerticalAlignment', 'bottom',
'HorizontalAlignment', 'right', 'FontSize', 8);
end

hold(ax, 'off'); % Release the hold
end

```

函数调用:

```

rng(51);
n = 10; % Size of the averaging matrix
max_iter = 200; % Number of iterations

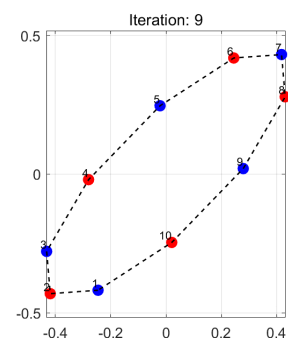
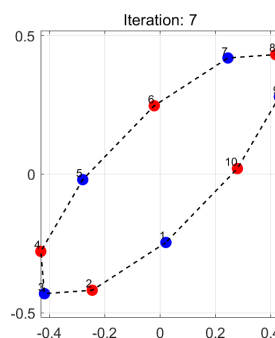
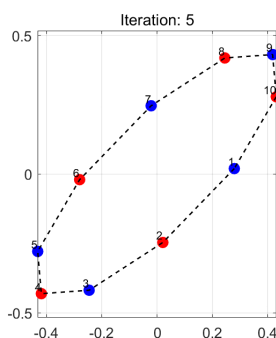
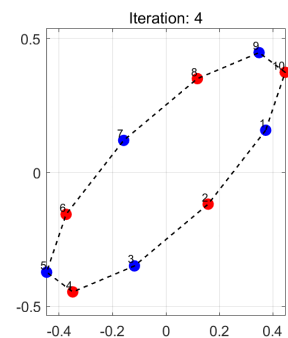
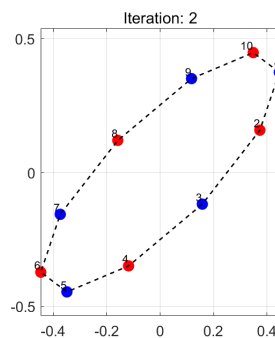
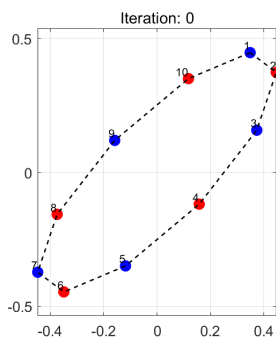
% Generate initial unit vectors
tau = 0:n-1;
tau = (2 * pi / n) * tau';
c = sqrt(2/n) * cos(tau);
s = sqrt(2/n) * sin(tau);

theta_x = rand(1);
theta_y = rand(1);
x = cos(theta_x) * c + sin(theta_x) * s;
y = cos(theta_y) * c + sin(theta_y) * s;

% Run the averaging algorithm
averaging_algorithm(x, y, max_iter);

```

运行结果:



猜想 (Conjecture):

For any input values $\theta_x, \theta_y \in \mathbb{R}$ in Algorithm 3, the even indexed polygons $\mathcal{P}(x^{(2k)}, y^{(2k)})$ are all the same and the odd-indexed polygons $\mathcal{P}(x^{(2k+1)}, y^{(2k+1)})$ are all the same.

(4) A Fourth Try

It is natural to ask what happens to the normalized polygon averaging process, if we use an alternative to the l_2 -norm for normalization.

A change in norm will only affect the size of the vertex vectors, not their direction.

Algorithm 4:

```
% Implementing Algorithm 4
function averaging_algorithm(x, y, max_iter, p, q)
    % Step 1: Create the averaging matrix M_n
    n = size(x, 1);
    M = averaging_matrix(n);

    % Create a figure for the subplots
    figure;
    subplot(2, 3, 1);
    display_polygon(x, y, 0, gca);

    % Define the set of iterations where we are interested in displaying the
    polygon
    interested_set = [2, 4, 5, 7, 9];
    plot_index = 2;

    % Step 2: Iterate through the algorithm
    for k = 1:max_iter
        % Apply the averaging matrix to x and y, and normalize them
        x = M * x;
        x = x / norm(x, p);
        y = M * y;
        y = y / norm(y, q);

        % Check if the current iteration is in the interested set
        if ismember(k, interested_set)
            subplot(2, 3, plot_index); % Create a subplot (2x3 grid)
            display_polygon(x, y, k, gca); % Plot in the current axis
            plot_index = plot_index + 1;
        end
    end
end
```

函数调用:

```
rng(51);
n = 10; % Size of the averaging matrix
max_iter = 200; % Number of iterations
p = 'inf';
q = 1;

% Generate initial unit vectors
```

```

tau = 0:n-1;
tau = (2 * pi / n) * tau';
c = sqrt(2/n) * cos(tau);
s = sqrt(2/n) * sin(tau);

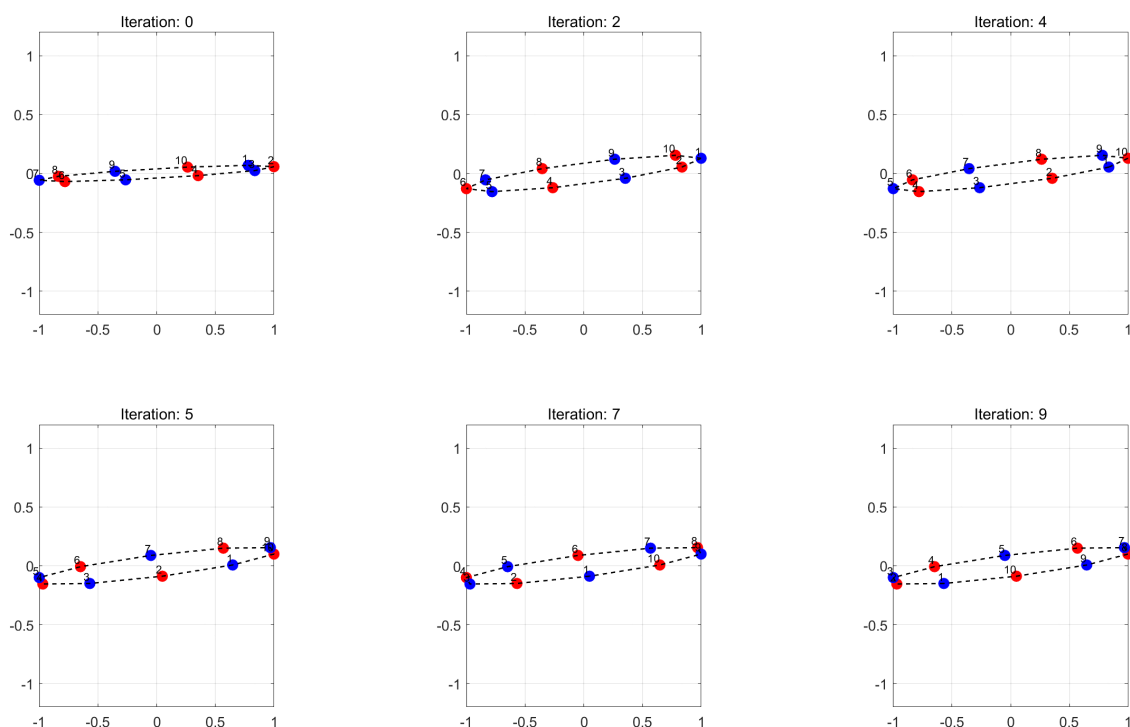
theta_x = rand(1);
theta_y = rand(1);
x = cos(theta_x) * c + sin(theta_x) * s;
x = x / norm(x, p);
y = cos(theta_y) * c + sin(theta_y) * s;
y = y / norm(x, q);

% Run the averaging algorithm
averaging_algorithm(x, y, max_iter, p, q);

```

运行结果: A more "rapid" look

(对 x 使用 $\|\cdot\|_\infty$ 范数标准化, 对 y 使用 $\|\cdot\|_1$ 范数标准化)



Problem 6 (optional)

In the lecture we have discussed how to solve Sylvester matrix equation $AX - XB = C$ using the Bartels-Stewart algorithm (through Schur decompositions).

What happens the matrices are real, and if only real Schur decompositions are permitted?

Solution:

给定 $A \in \mathbb{C}^{m \times m}$, $B \in \mathbb{C}^{n \times n}$, $C \in \mathbb{C}^{m \times n}$

Sylvester 方程组 $AX - XB = C$ 可以等价表示为 $\text{vec}(X) = (I_n \otimes A - B^T \otimes I_m)^{-1} \text{vec}(C)$

$$AX - XB = C$$

$$\Leftrightarrow$$

$$(I_n \otimes A - B^T \otimes I_m) \text{vec}(X) = \text{vec}(C)$$

(Sylvester 定理, Matrix Analysis 定理 2.4.4.1)

Sylvester 方程组有唯一解, 当且仅当系数矩阵 $(I_n \otimes A - B^T \otimes I_m)$ 非奇异, 即当且仅当 A, B 没有公共特征值.

假设 $A \in \mathbb{C}^{m,m}$ 和 $B \in \mathbb{C}^{n,n}$ 没有公共特征值.

直接求解 $(I_n \otimes A - B^T \otimes I_m)\text{vec}(X) = \text{vec}(C)$ 的代价是 $O(m^3n^3)$, 难以接受.

我们可以对 A 做 Schur 分解 $A = U_1 T_1 U_1^H$ (代价为 $O(m^3)$), 得到:

$$\begin{aligned} AX - XB &= U_1 T_1 U_1^H X - XB = C \\ &\Leftrightarrow \\ T_1(U_1^H X) - (U_1^H X)B &= U_1^H C \\ &\Leftrightarrow \\ T_1 Y - YB &= \tilde{C} \text{ where } \begin{cases} Y = U_1^H X \in \mathbb{C}^{m \times n} \\ \tilde{C} = U_1^H C \in \mathbb{C}^{m \times n} \end{cases} \end{aligned}$$

我们也可以对 B 做 Schur 分解 $B = U_2 T_2 U_2^H$ (代价为 $O(n^3)$), 得到:

$$\begin{aligned} AX - XB &= AX - XU_2 T_2 U_2^H = C \\ &\Leftrightarrow \\ A(XU_2) - (XU_2)T_2 &= CU_2 \\ &\Leftrightarrow \\ AY - YT_2 &= \tilde{C} \text{ where } \begin{cases} Y = XU_2 \in \mathbb{C}^{m \times n} \\ \tilde{C} = CU_2 \in \mathbb{C}^{m \times n} \end{cases} \end{aligned}$$

因此 Schur 分解预处理代价是 $O(\min(m^3, n^3))$

我们可以比较 A, B 的阶数, 哪个阶数小就对哪个做 Schur 分解.

不失一般性, 假设 $m > n$, 对 $B \in \mathbb{C}^{n,n}$ 做 Schur 分解 $B = UTU^H$:

$$\begin{aligned} AX - XB &= AX - XUTU^H = C \\ &\Leftrightarrow \\ A(XU) - (XU)T &= CU \\ &\Leftrightarrow \\ AY - YT &= \tilde{C} \text{ where } \begin{cases} Y = XU \in \mathbb{C}^{m \times n} \\ \tilde{C} = CU \in \mathbb{C}^{m \times n} \end{cases} \end{aligned}$$

我们可以首先解出 Y 的第 1 列 Ye_1 :

(记 $T = [t_{ij}]_{i,j=1}^n$, 则 $Te_1 = t_{11}e_1$)

$$\begin{aligned} AY_{e_1} - YT_{e_1} &= \tilde{C}e_1 \\ &\Leftrightarrow \\ A(Ye_1) - t_{11}Ye_1 &= \tilde{C}e_1 \end{aligned}$$

这相当于求解一个线性方程组, 得到 Y 的第 1 列 (Ye_1)

然后利用回代法的思想求解 Y 的剩余各列即可.

上述算法称为 **Bartels-Stewart 算法**

(Bartels-Stewart 算法, Matrix Computation 算法 7.6.2)

给定矩阵 $A \in \mathbb{C}^{m \times m}, C \in \mathbb{C}^{m \times n}$ 和上三角阵 $T \in \mathbb{C}^{n \times n}$ (其中 $m < n$, 且 A, T 没有公共特征值)

本算法用方程 $AY - YT = C$ 的解覆盖 C :


```

function:  $Y = \text{Bartels-Stewart}(T, B, C)$ 
    for  $k = 1 : n$ 
         $C(1 : m, k) = C(1 : m, k) + C(1 : p, 1 : k - 1)T(1 : k - 1, k)$ 
        solve  $(A - T(k, k)I_m)y = C(1 : m, k)$  to get  $y$ 
         $C(1 : m, k) = y$ 
    end
     $Y = C$ 
end

```

对于实 Schur 型，要解决 2×2 对角块的问题只需使用 Gauss 消去法将两列放在一起解。
(或者使用复运算，它可以拆成实部和虚部的实运算)

Problem 7 (optional)

Use truncated SVD to compress some grayscale images.

If you only have colored images, you can convert them to grayscale using:

$$\text{gray} = \alpha \cdot \text{red} + \beta \cdot \text{green} + \gamma \cdot \text{blue}$$

Common choices of the constants are $(\alpha, \beta, \gamma) = (0.299, 0.587, 0.114)$ and $(\alpha, \beta, \gamma) = (0.2126, 0.7152, 0.0722)$.

You are also encouraged to think about how to compress colored images.

(1) Grayscale Image

SVD 压缩灰度图像的函数:

```

def svd_compress(image, k):
    """
    Compress an image using Singular Value Decomposition (SVD).
    Only the first `k` singular values are kept.

    Parameters:
    - image: 2D numpy array representing the grayscale image.
    - k: The number of singular values to retain for compression.

    Returns:
    - compressed_image: The compressed image as a 2D numpy array.
    - num_singular_values: The number of singular values used.
    - compression_rate: The compression rate for the compressed image.
    """
    # Perform SVD decomposition
    U, S, Vt = np.linalg.svd(image, full_matrices=False)

    # Keep only the first k singular values
    U_k = U[:, :k]
    S_k = np.diag(S[:k]) # Create a diagonal matrix with the first k singular
    values
    Vt_k = Vt[:k, :]

    # Reconstruct the compressed image using the reduced SVD matrices
    compressed_image = np.dot(U_k, np.dot(S_k, Vt_k))

    # Calculate compression rate
    m, n = image.shape

```

```

compression_rate = (k * (m + n + k)) / (m * n)

# Return the compressed image, number of singular values used, and the
compression rate
return compressed_image, k, compression_rate

```

函数调用:

```

if __name__ == "__main__":
    # Open the image, convert it to grayscale, and then convert it to a numpy
    array
    image_path = 'DIP_Fig02.41(c)(einstein high contrast).tif'
    image_name = 'Einstein'
    image = Image.open(image_path).convert('L') # Convert the image to
    grayscale ('L' mode)
    image = np.array(image) # Convert the grayscale image to a numpy array

    # Choose the number of singular values to use for compression
    k_values = [5, 10, 20, 30, 40] # Example k-values to test
    compressed_images = []
    singular_values_list = []
    compression_rates_list = []

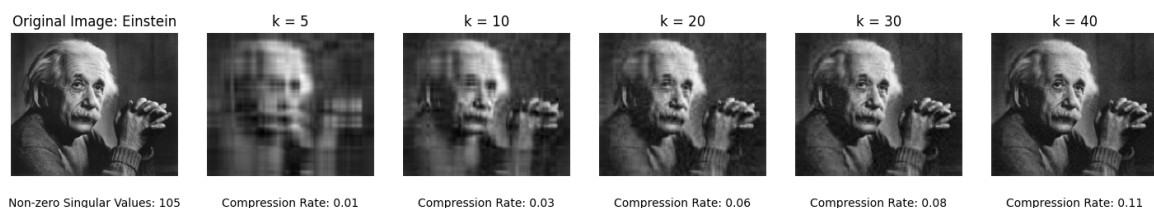
    # Generate compressed images for each k value
    for k in k_values:
        compressed_image, num_singular_values, compression_rate =
        svd_compress(image, k)
        compressed_images.append(compressed_image)
        singular_values_list.append(num_singular_values)
        compression_rates_list.append(compression_rate)
        print(f"Number of singular values used for k={k}:
        {num_singular_values}")
        print(f"Compression rate for k={k}: {compression_rate:.2f}")

    # Plot the original image and all compressed images
    plot_compressed_images(image, compressed_images, k_values, image_name,
    sum(singular_values_list), compression_rates_list)

```

运行结果:

(图片来源: Digital Image Process (3rd Edition, R. Gonzalez) Figure 2.41)



(2) RGB Image

SVD 压缩彩色图像的函数:

```

def svd_compress_color(image, k):
    """
    Compress a color image using Singular Value Decomposition (SVD).

```

Only the first `k` singular values are kept for each RGB channel.

Parameters:

- image: 3D numpy array representing the color image (height, width, 3).
- k: The number of singular values to retain for compression.

Returns:

- compressed_image: The compressed color image as a 3D numpy array.
- num_singular_values: The number of non-zero singular values used for each channel.

- compression_rate: The compression rate for each channel.

"""

Get image dimensions

m, n, _ = image.shape

Initialize the compressed image

compressed_image = np.zeros_like(image)

List to store compression rates for each channel

compression_rates = []

total_non_zero_singular_values = 0

Apply SVD compression on each RGB channel

for i in range(3): # Loop through each channel (0 = Red, 1 = Green, 2 = Blue)

channel = image[:, :, i]

U, S, Vt = np.linalg.svd(channel, full_matrices=False)

Number of non-zero singular values

num_singular_values = np.sum(S > 1e-10) # Consider values larger than a small threshold as non-zero

Keep only the first k singular values

U_k = U[:, :k]

S_k = np.diag(S[:k]) # Create a diagonal matrix with the first k singular values

Vt_k = Vt[:, :k]

Reconstruct the compressed channel using the reduced SVD matrices

compressed_channel = np.dot(U_k, np.dot(S_k, Vt_k))

Store the compressed channel back into the image

compressed_image[:, :, i] = compressed_channel

Update total number of non-zero singular values

total_non_zero_singular_values += num_singular_values

Calculate the compression rate for this channel

compression_rate = (k * (m + n + k)) / (m * n)

compression_rates.append(compression_rate)

Return the compressed image, number of singular values, and compression rates

return compressed_image, total_non_zero_singular_values, compression_rates

函数调用:

```

if __name__ == "__main__":
    # Open the image, convert it to RGB, and then convert it to a numpy array
    image_path = 'DIP_Fig06.46(a)(lenna_original_RGB).tif'
    image_name = 'Lenna'
    image = Image.open(image_path).convert('RGB') # Ensure the image is in RGB
mode
    image = np.array(image) # Convert the image to a numpy array

    # Choose the number of singular values to use for compression
    k_values = [10, 100, 200, 300, 500] # Example k-values to test
    compressed_images = []
    singular_values_list = []
    compression_rates_list = []

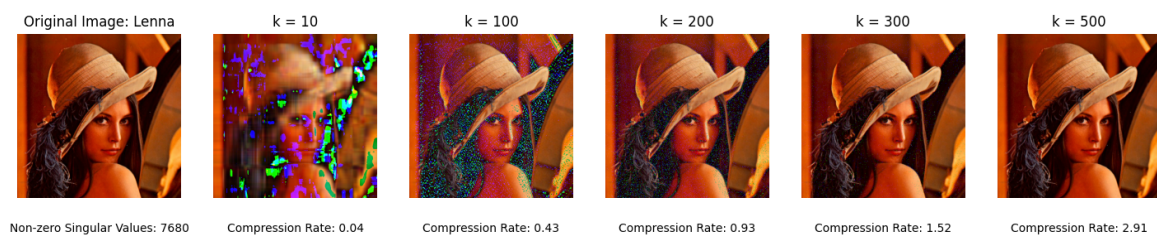
    # Generate compressed images for each k value
    for k in k_values:
        compressed_image, num_singular_values, compression_rates =
svd_compress_color(image, k)
        compressed_images.append(compressed_image)
        singular_values_list.append(num_singular_values)
        compression_rates_list.append(np.mean(compression_rates)) # Mean
compression rate for all channels
        print(f"Number of singular values used for k={k}:
{num_singular_values}")
        print(f"Average compression rate for k={k}:
{np.mean(compression_rates):.2f}")

    # Plot the original image and all compressed images
    plot_compressed_images_color(image, compressed_images, k_values, image_name,
sum(singular_values_list), compression_rates_list)

```

运行结果:

(图片来源: Digital Image Process (3rd Edition, R. Gonzalez) Figure 6.46)



Poor girl.