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Outline

- Big images = mosaicing
- What is the zero-spacing problem?
 - Impacts on large-scale emission
 - Imaging artefacts
 - Total-power
- Solutions
 - Concept
 - Cross-calibration
 - Recipes



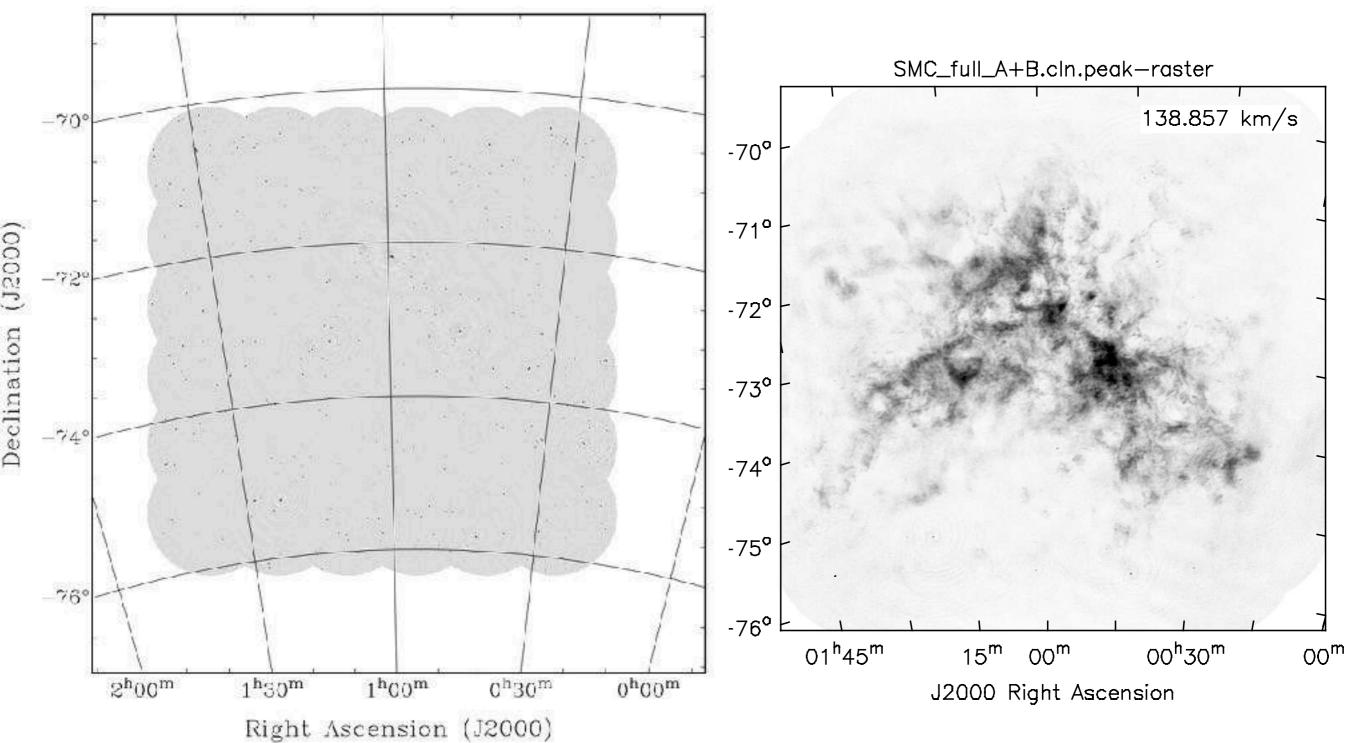
Why Mosaic?

- Wide-field imaging:
 - Interested in source that is larger than primary beam, θ > λ / D

- Large scale structure:
 - Interested in structure on scales larger than that sampled by the shortest baseline: θ > λ/ d_{min}



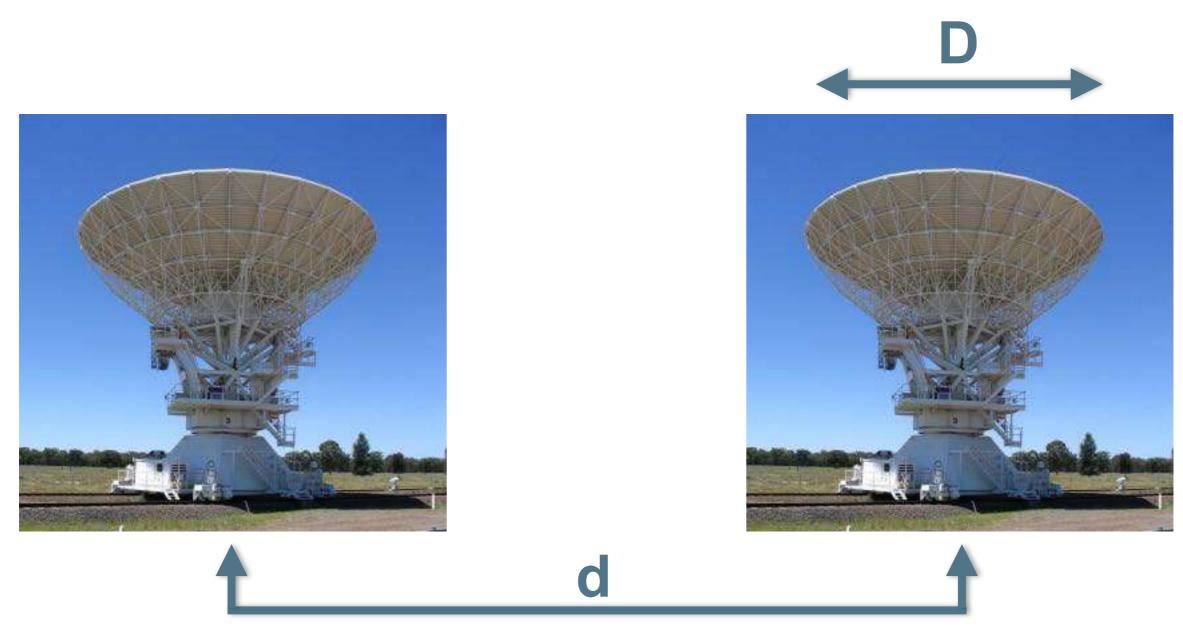
Two different reasons to mosaic:





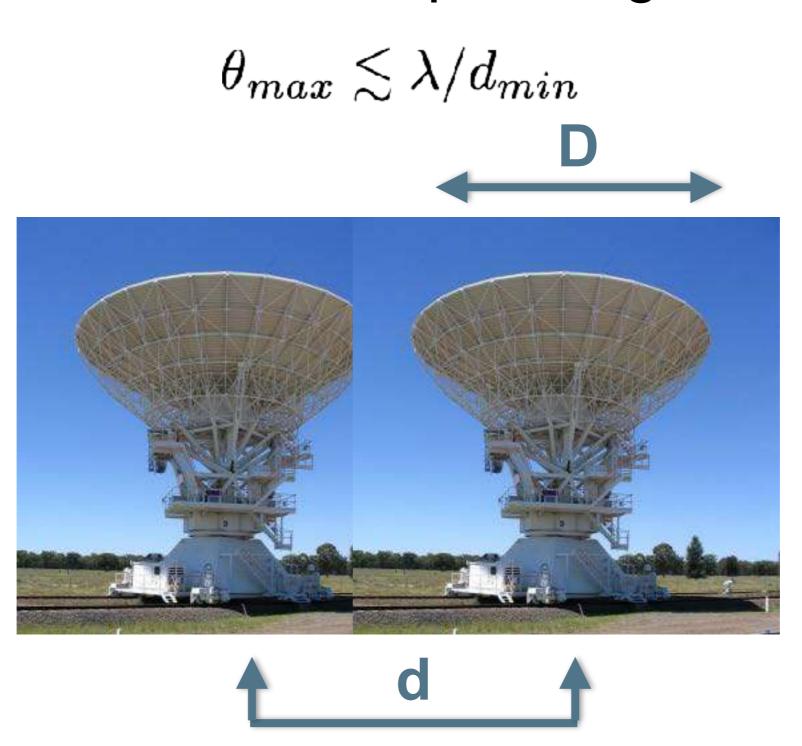
An Interferometer samples angular scales:

$$\theta_{max} \lesssim \lambda/d_{min}$$



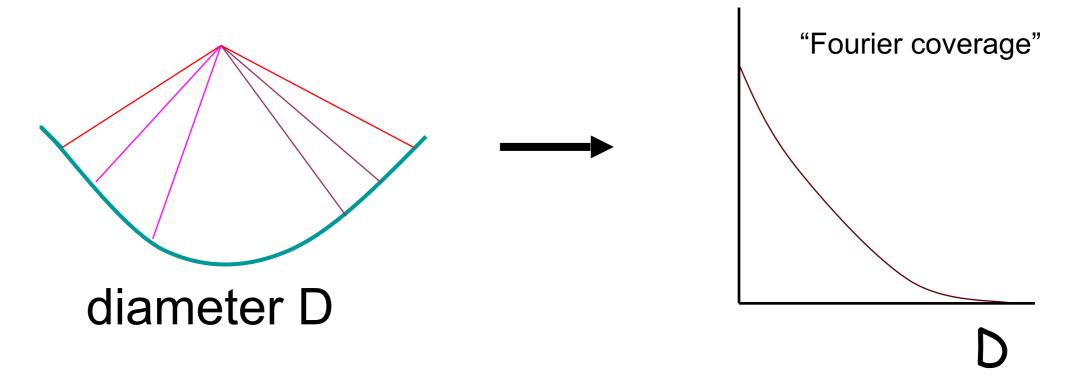


An Interferometer samples angular scales:



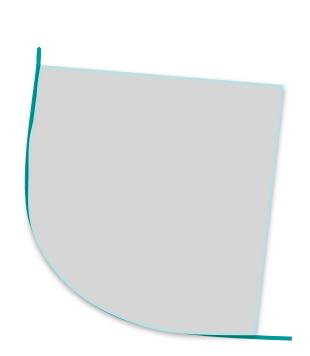
Mosaicing Fundamentals

- Background theory:
 - Ekers & Rots (1979) pointed out that one can think of a single dish as a collection of subinterferometers.

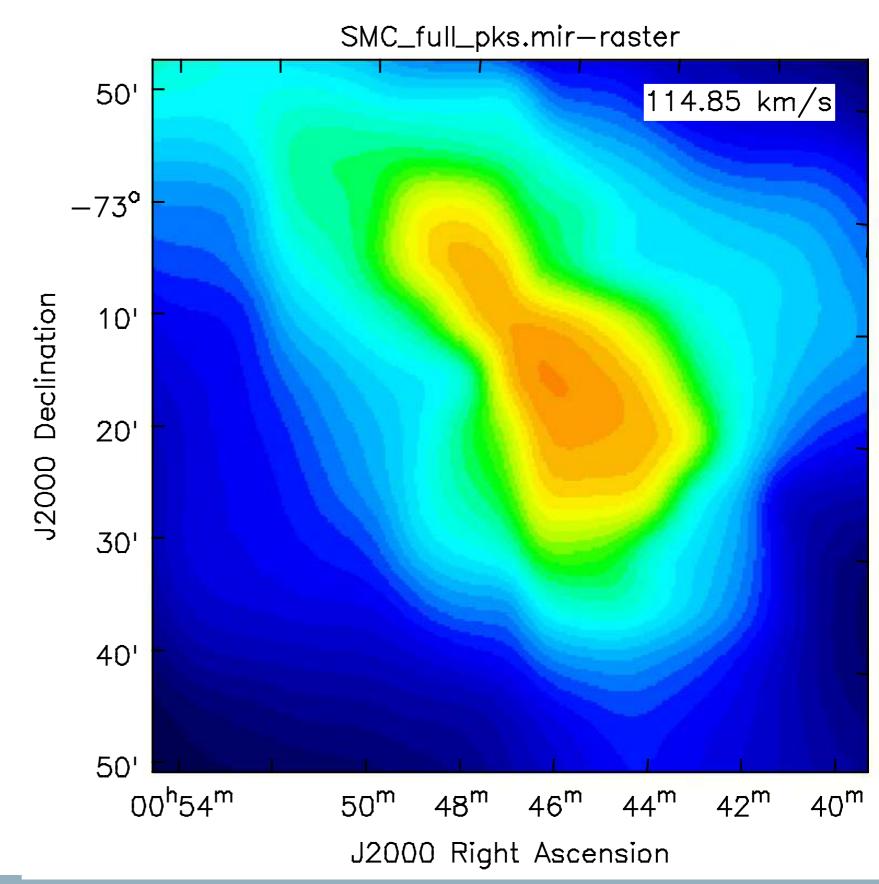


^{*}Ron showed us this in his first talk

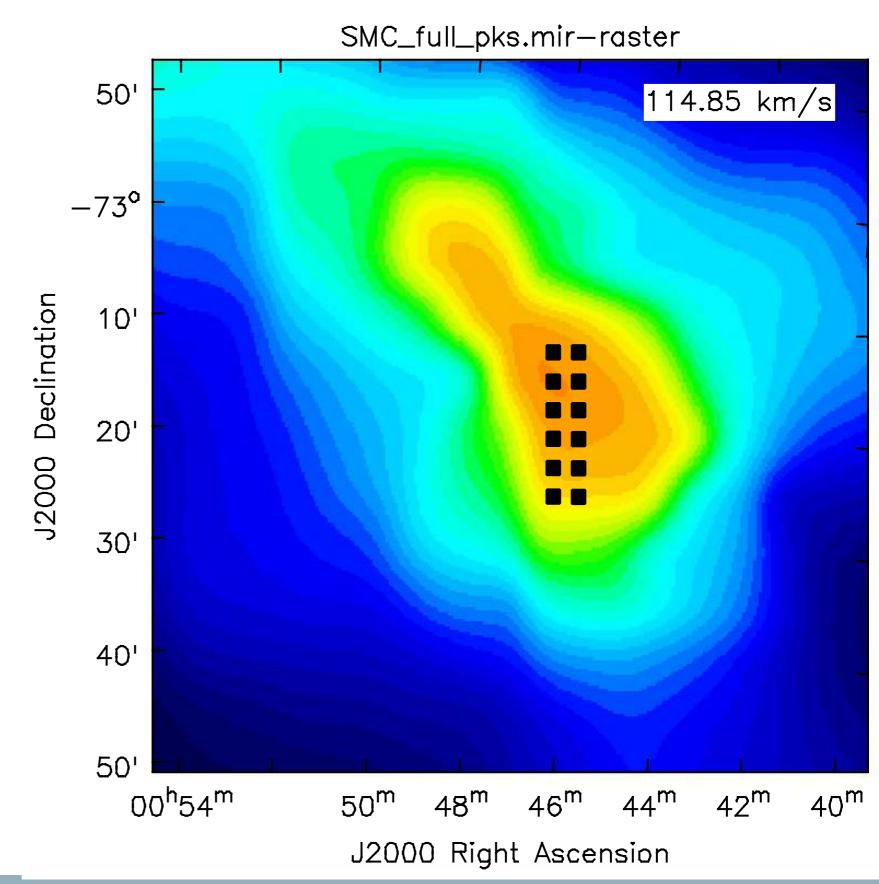




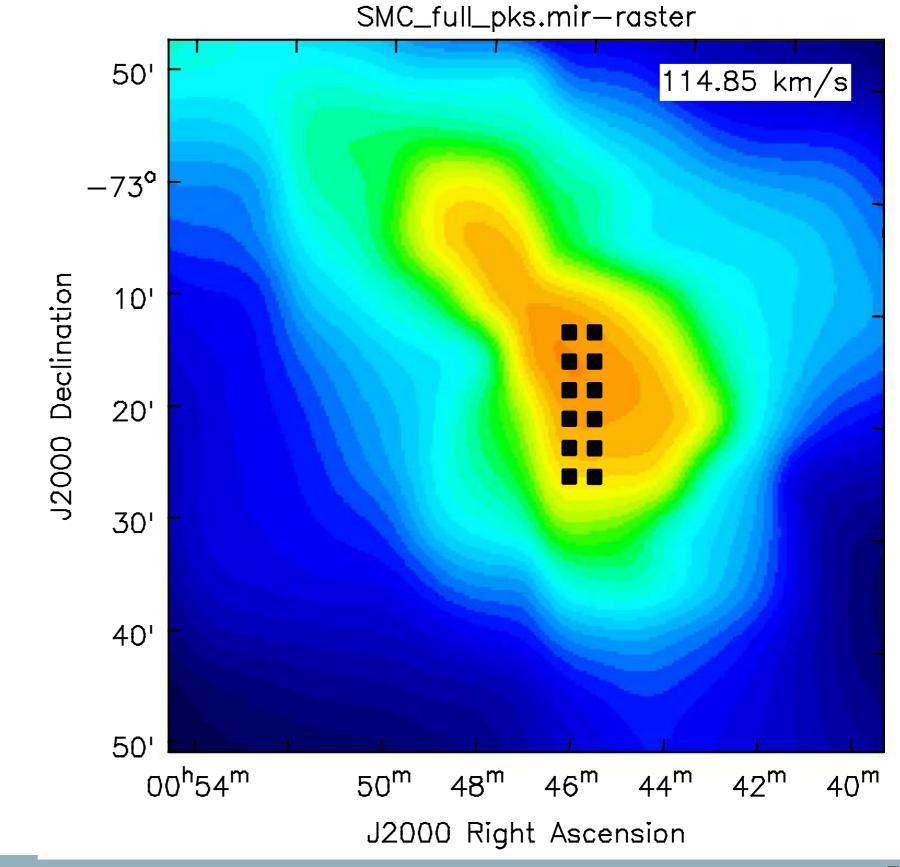


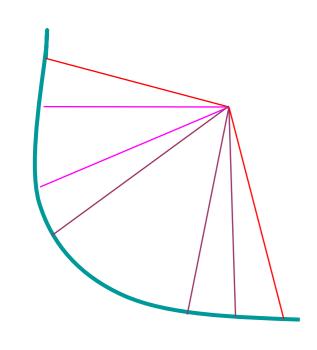








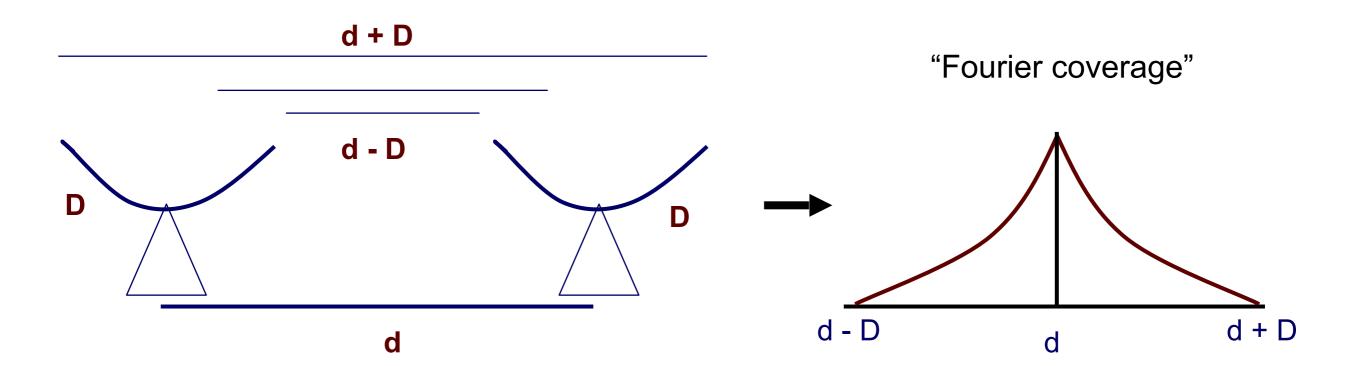






Mosaicing Fundamentals

• Extending this formalism to interferometers, we find that an interferometer doesn't just measure angular scales $\theta = \lambda / d$ it actually measures $\lambda / (d - D) < \theta < \lambda / (d + D)$





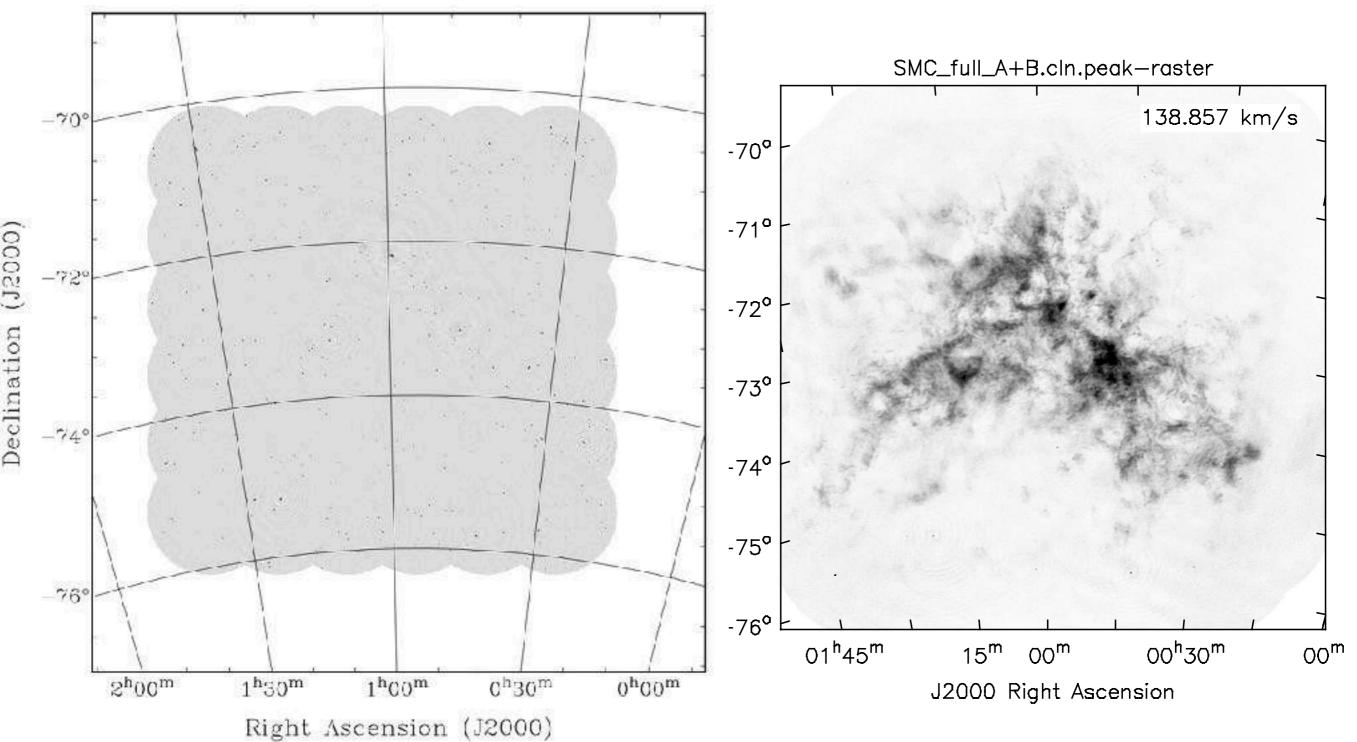
Mosaicing Fundamentals

- But you can't get all that extra info from a single pointing
 - As with a single dish, you have to scan to get the extra "spacings"
- Ekers & Rots showed that you can recover this extra information by scanning the interferometer
- The sampling theorem states that we can gather as much information by sampling the sky with a regular, Nyquist spaced grid (Cornwell 1988)



Linear mosaic

Joint deconvolution



Joint Deconvolution Approach

Form a linear combination of the individual pointings, p:

$$I_{LM}(\ell) = W(\ell) \frac{\Sigma_p A(\ell - \ell_p) I_p(\ell) / \sigma_p^2}{\Sigma_p A^2 (\ell - \ell_p) / \sigma_p^2}$$

- Here σ_p is the noise variance of an individual pointing and A(l) is the primary response function of an antenna
- W(l) is a weighting function that suppresses noise amplification at the edge of mosaic (amongst other things)

Mosaicing: Joint Approach

 Joint dirty beam depends on antenna primary beam:

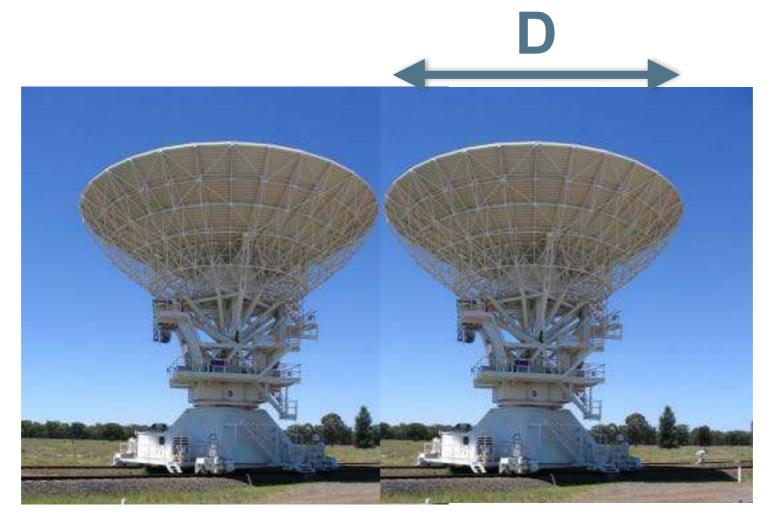
$$B_{LM}(\ell;\ell_0) = W(\ell) \frac{\sum_p A(\ell_0 - \ell_p) B_p(\ell - \ell_0) A(\ell - \ell_p) / \sigma_p^2}{\sum_p A^2(\ell - \ell_p) / \sigma_p^2}$$

- Use all u-v data from all points simultaneously
 - Extra info gives a better deconvolution



But...

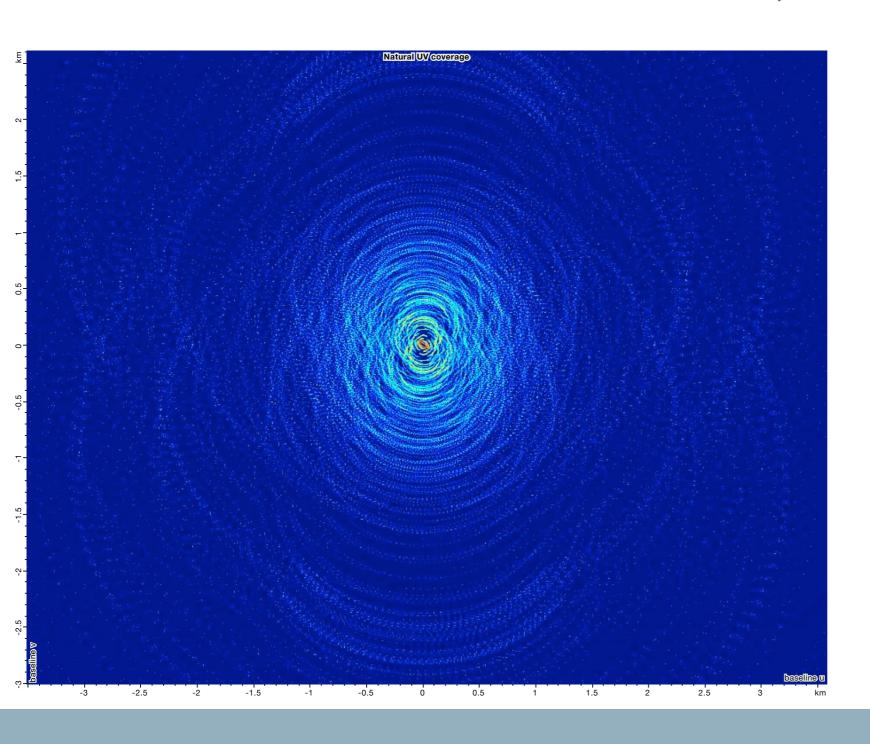
- Maximum angular scale even with misaiming is: $\theta_{max} \sim \lambda/(d_{\min}-D)$





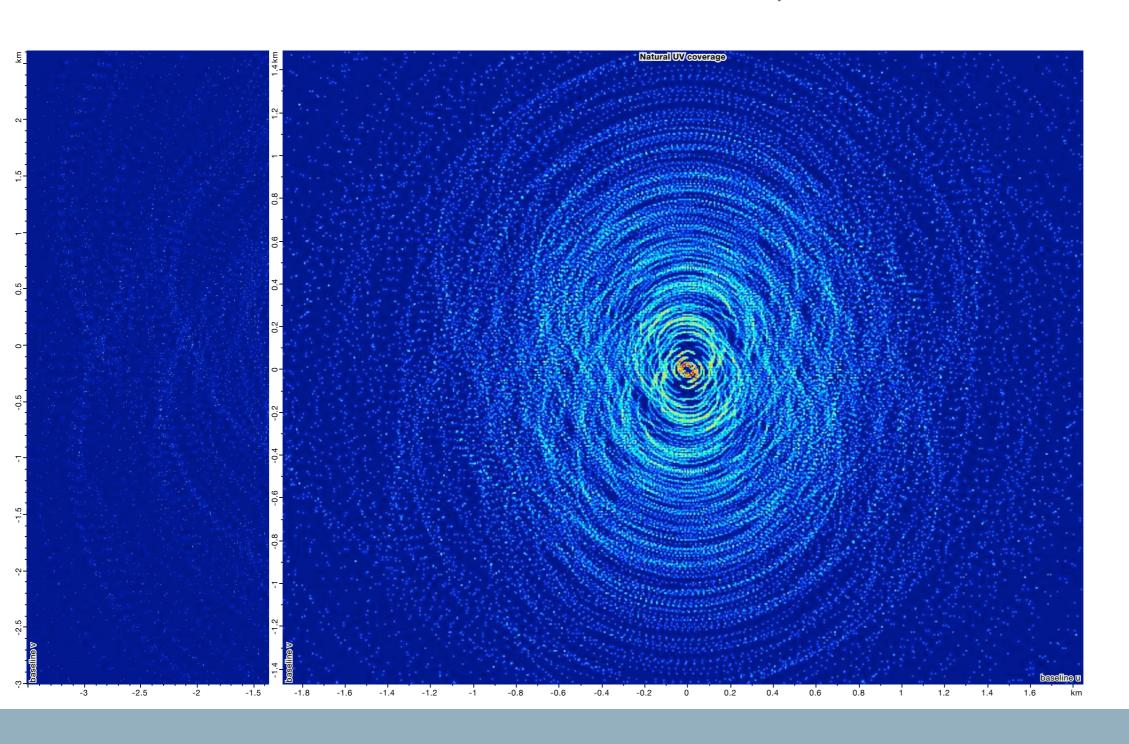


That's the zero-spacing problem ASKAP, 8h



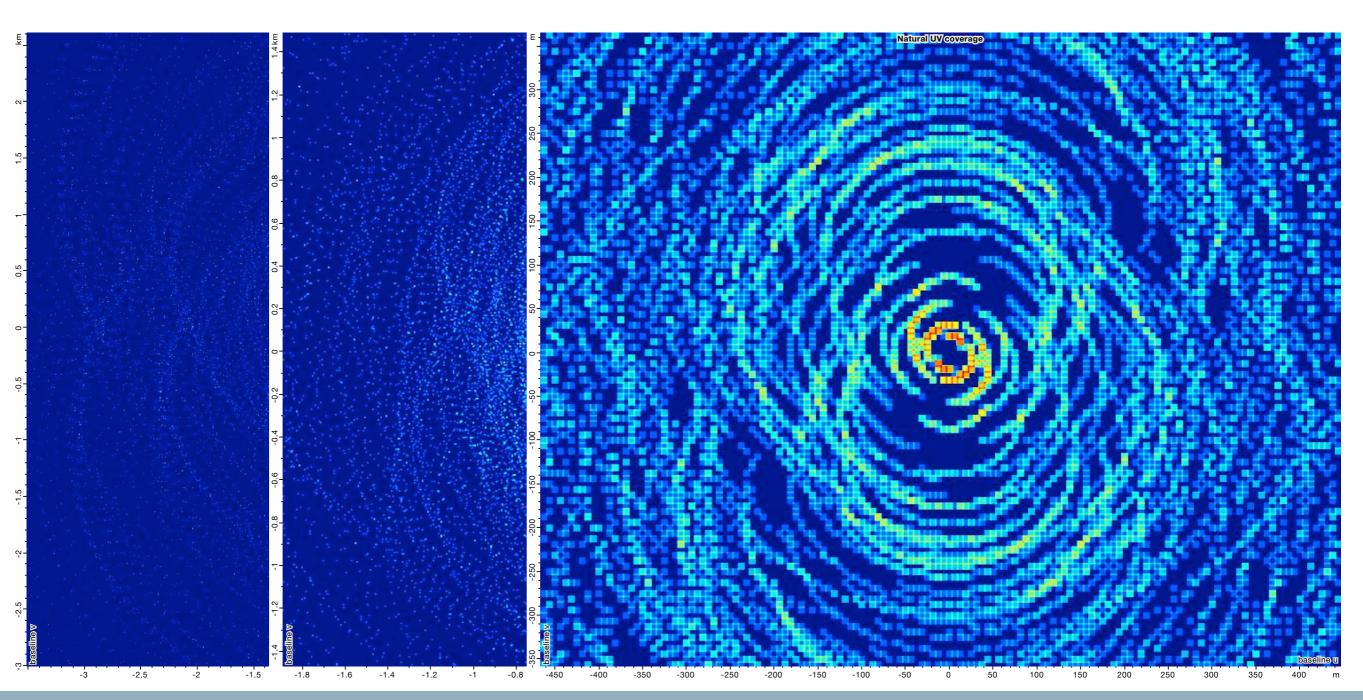


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That's the zero-spacing problem ASKAP, 8h



The zero-spacing problem

So if the source is large compared to

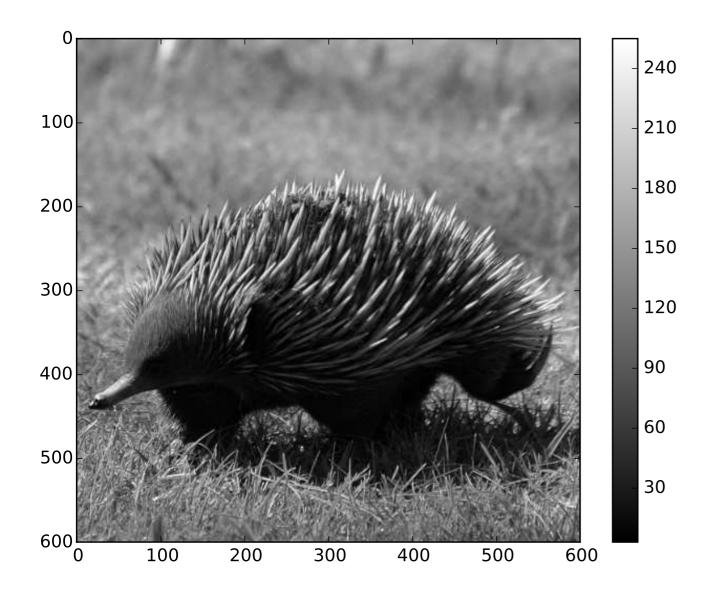
$$\theta_{max} \sim \lambda/d_{min}$$

there's a problem that:

- 1. Limits ability to recover large-scale structure
- Causes image artefacts around extended objects
- 3. Prevents total flux measurements

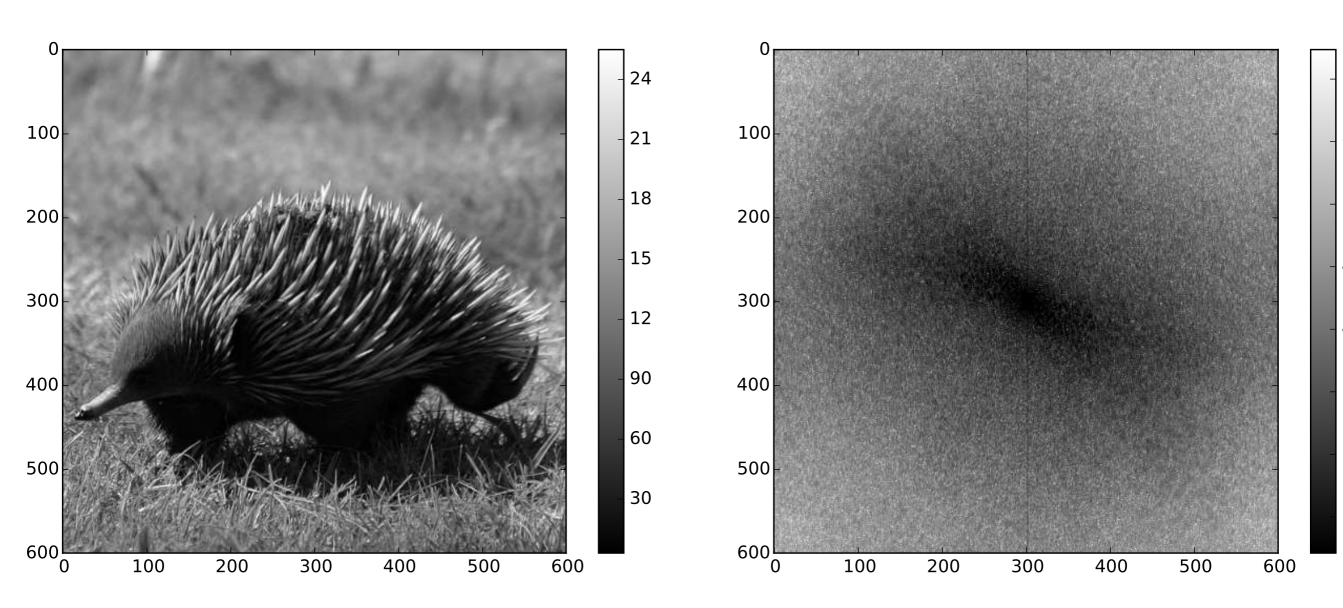




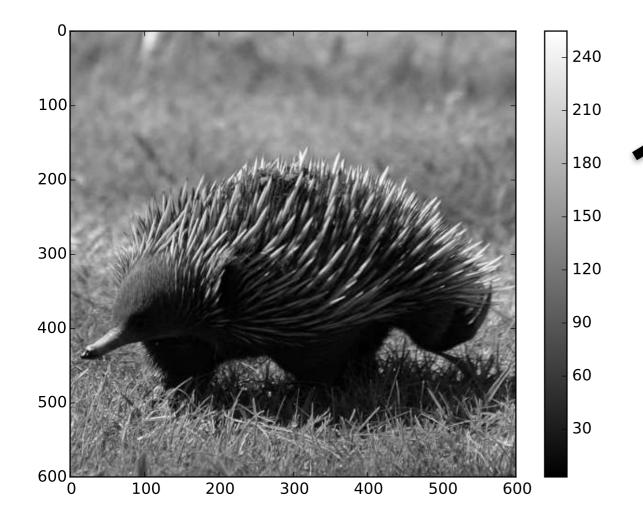




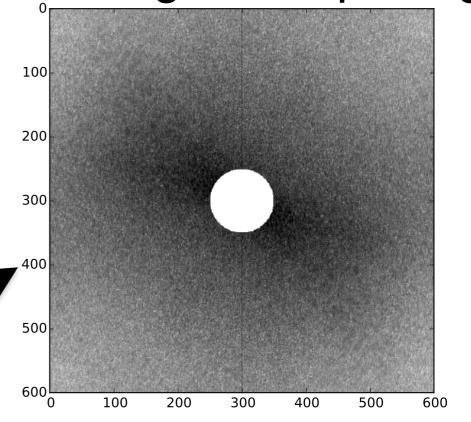
FT(Echidna)



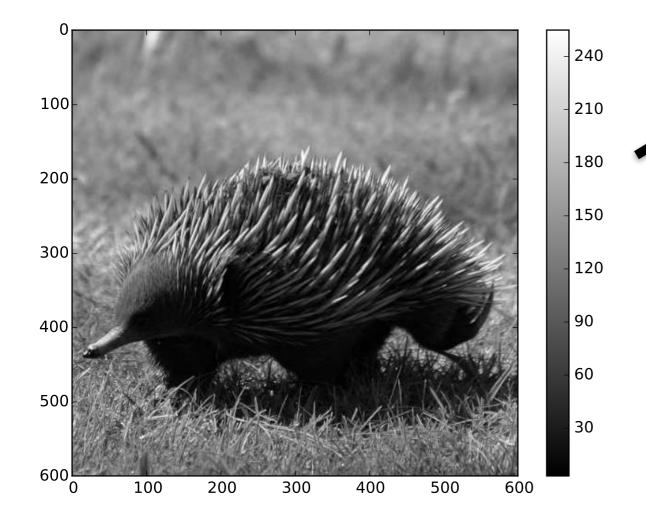




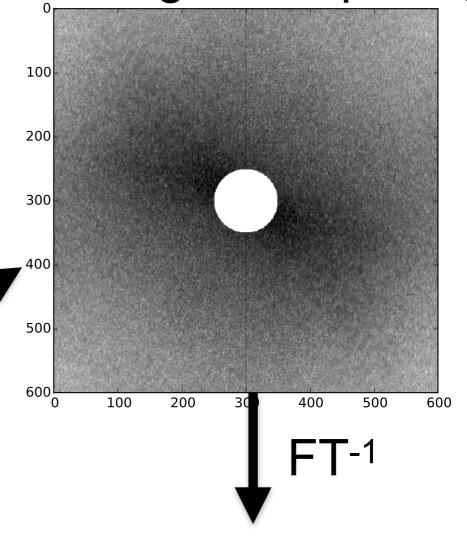
missing zero-spacing



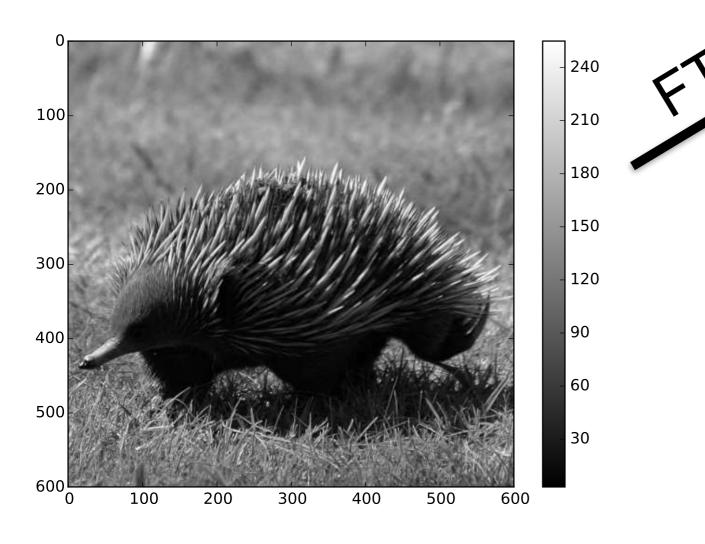




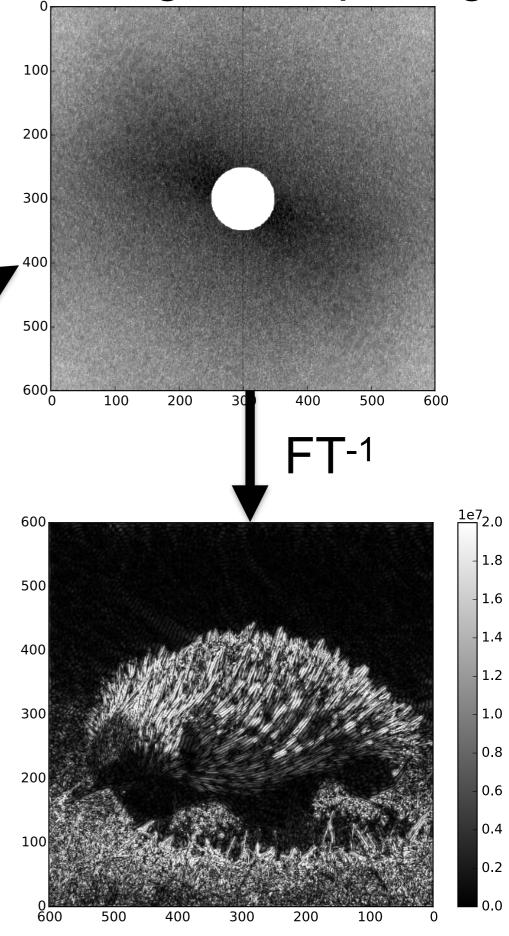
missing zero-spacing



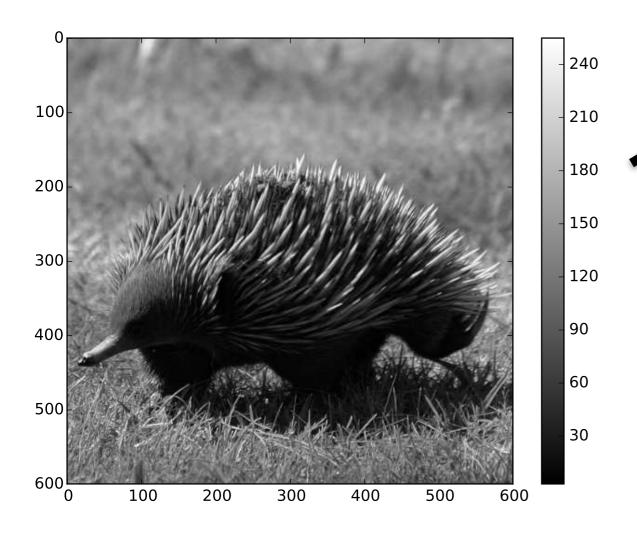


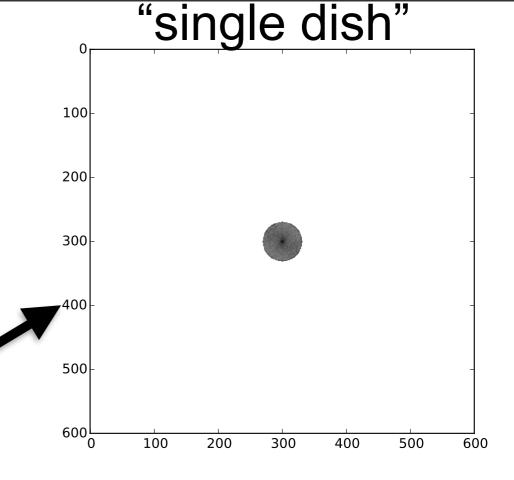


missing zero-spacing

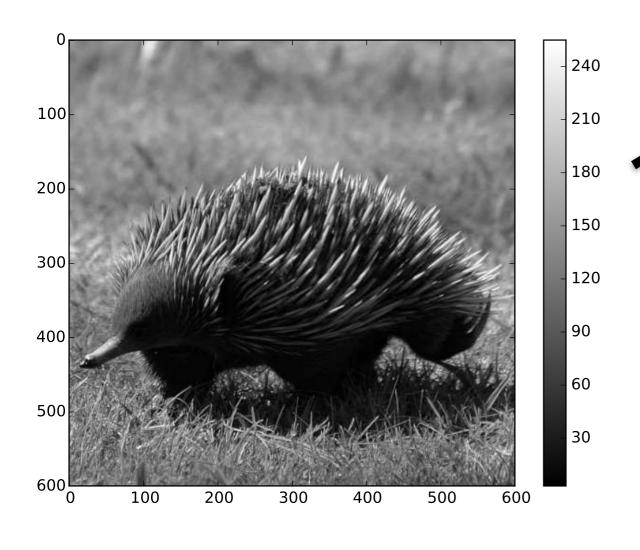


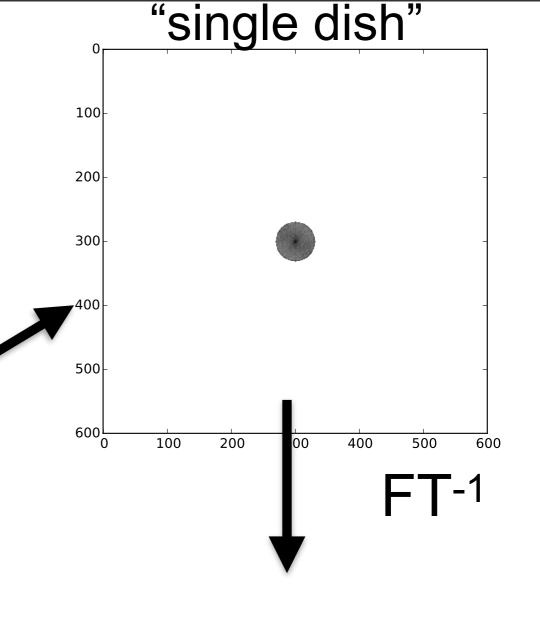




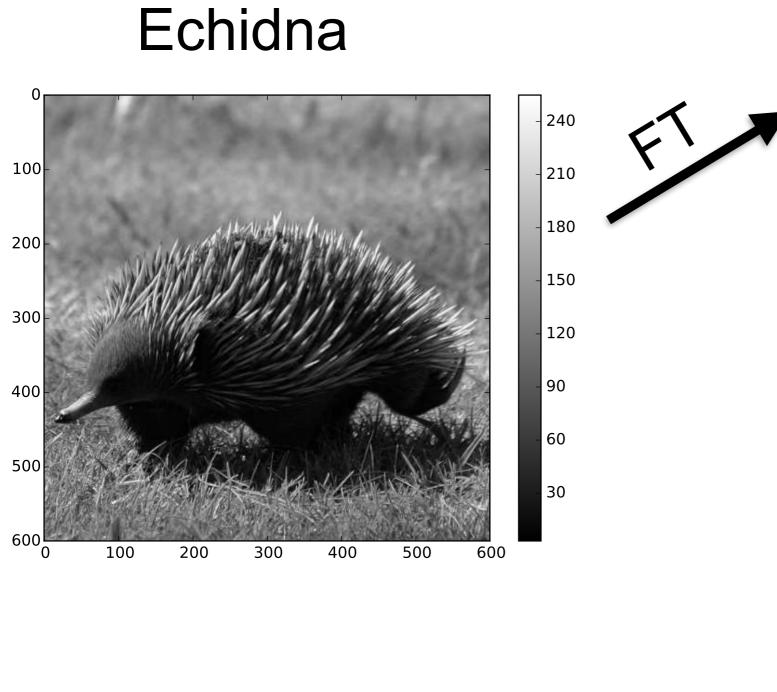












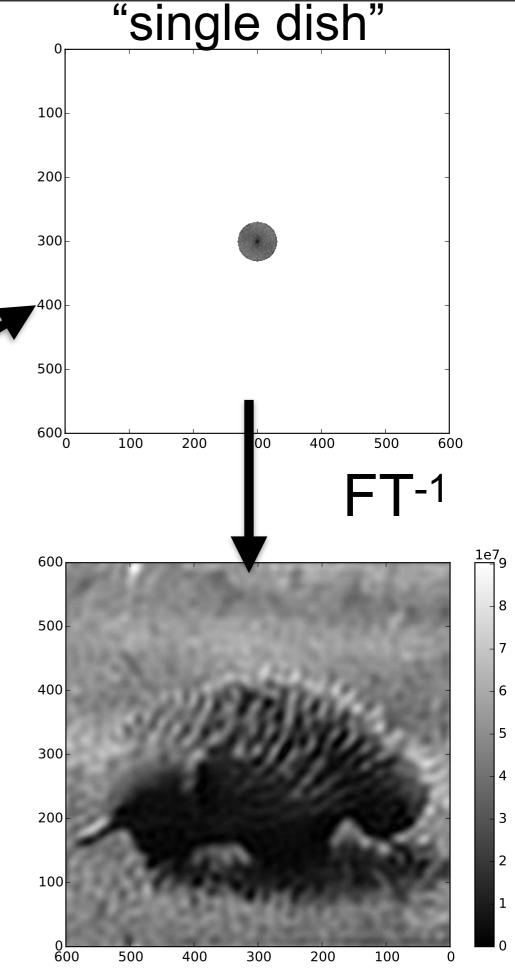
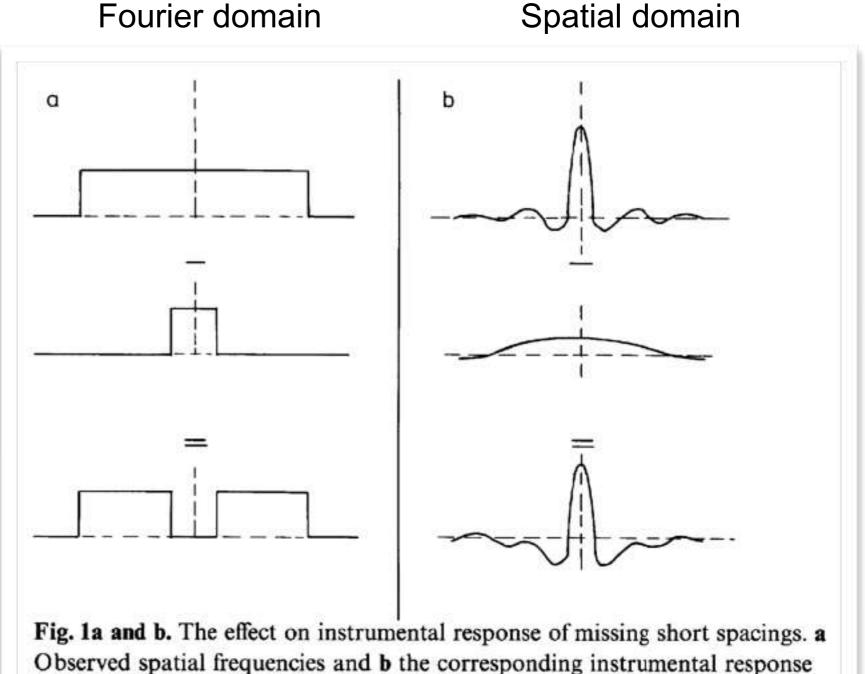


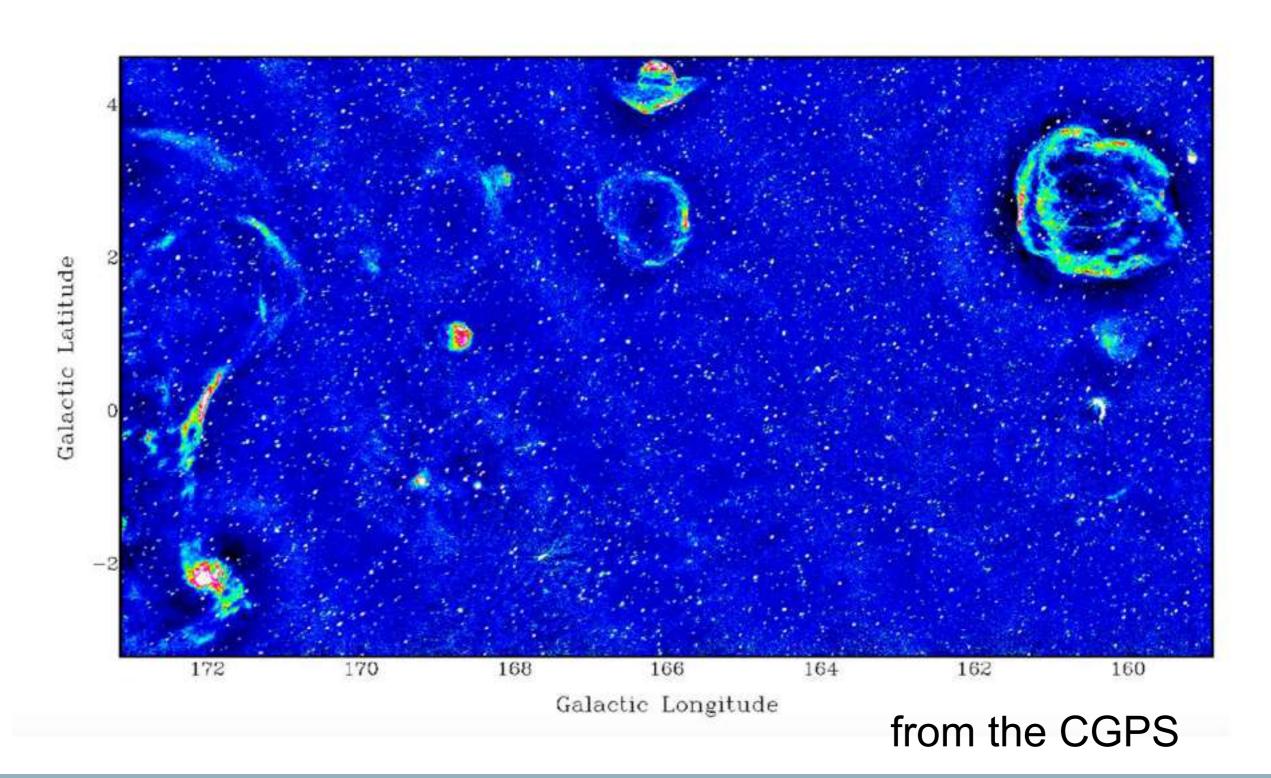
Image Artefacts

- Cause of "negative bowls"
- Cleaning algorithms try to recover this without information



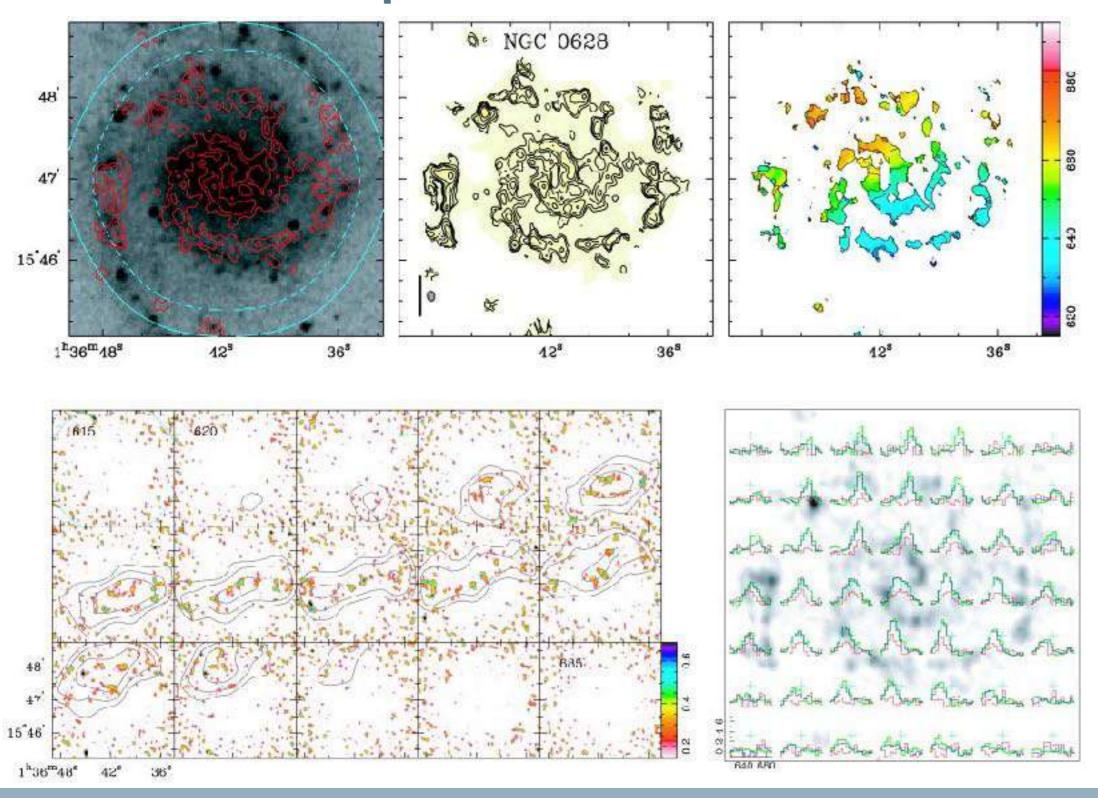


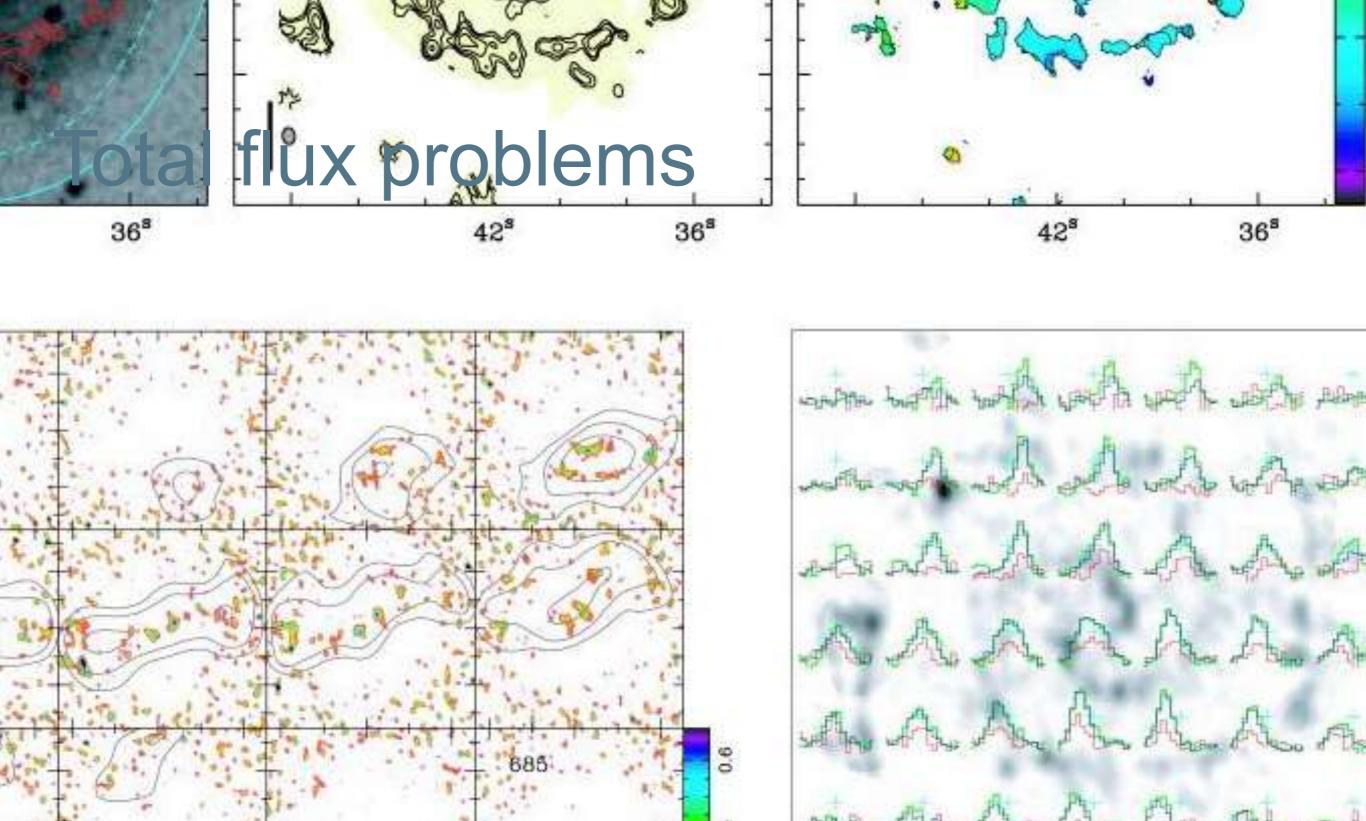
Negative bowls



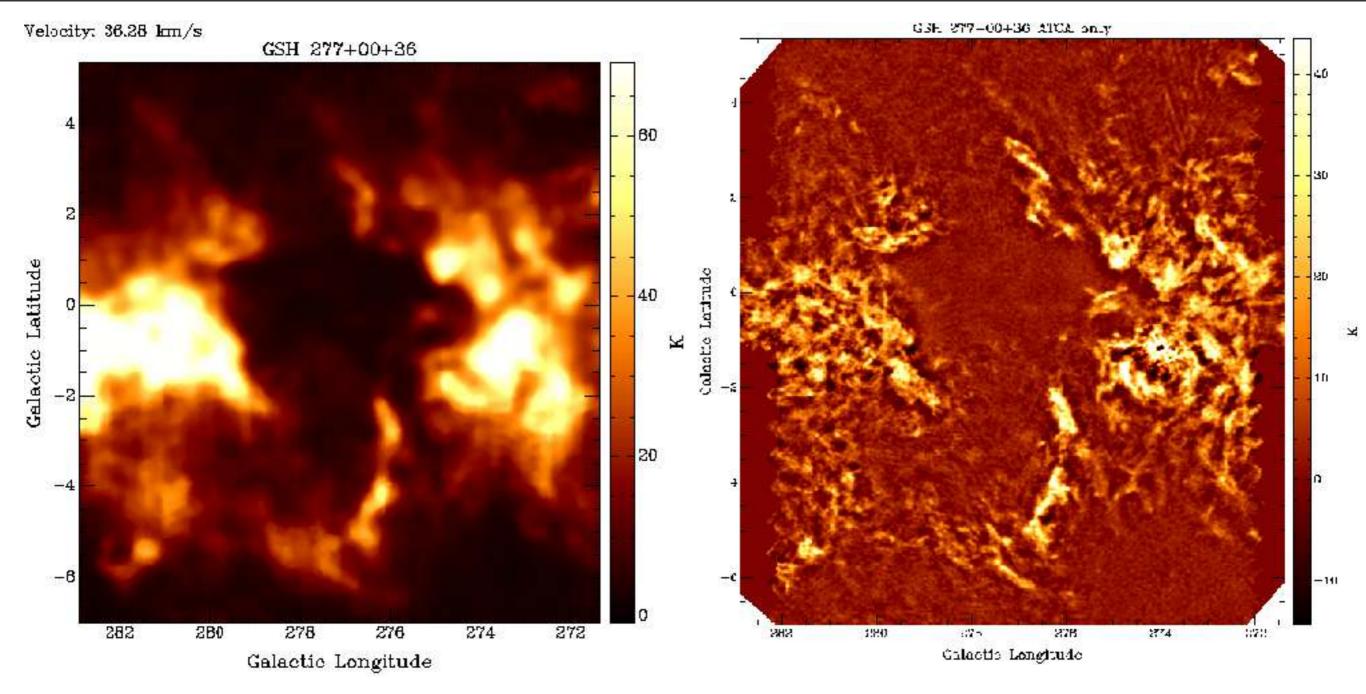


Total flux problems





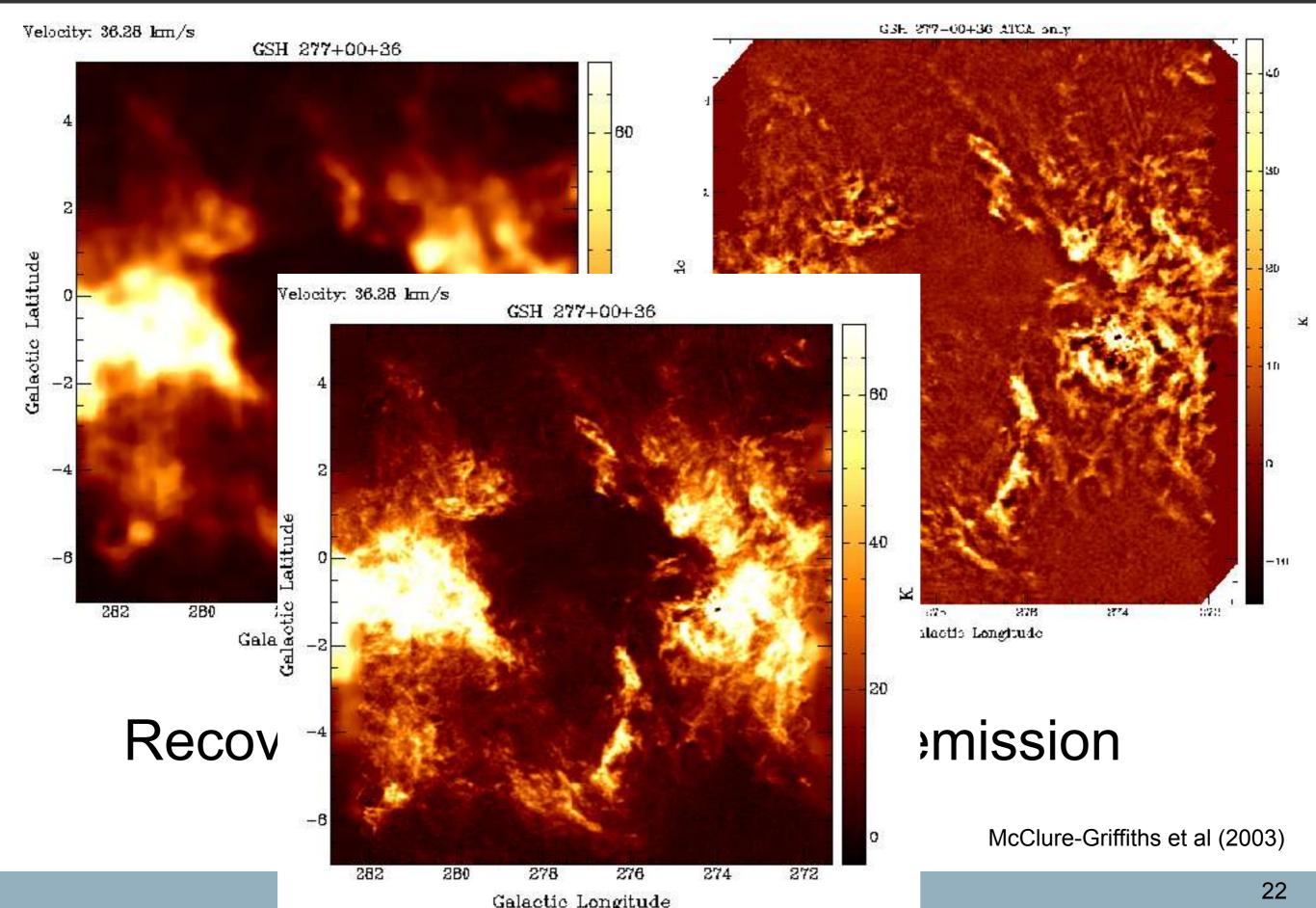




Recovering large-scale diffuse emission

McClure-Griffiths et al (2003)







Solution Methods:

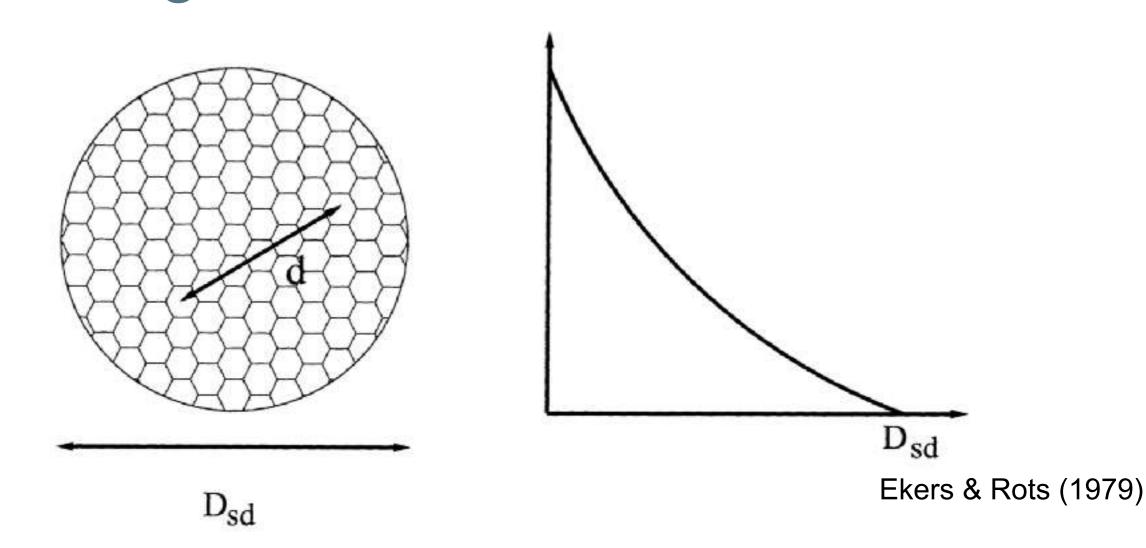
Basic methods:

- Combine dirty data in u-v plane then image and deconvolve
- Image, deconvolve, then combine

Variants:

- Combine during maximum entropy ("joint" deconvolution)
- Combine during deconvolution with single-dish as model ("default" method)

Using a single-dish as an interferometer



Single dish gives "visibilities" from zero-spacing to D

$$I_{sd}^{D}(l,m) = I(l,m) * B_{sd}(l',m')$$

 $V_{sd}'(u,v) = V(u,v) \times b_{sd}(u,v)$



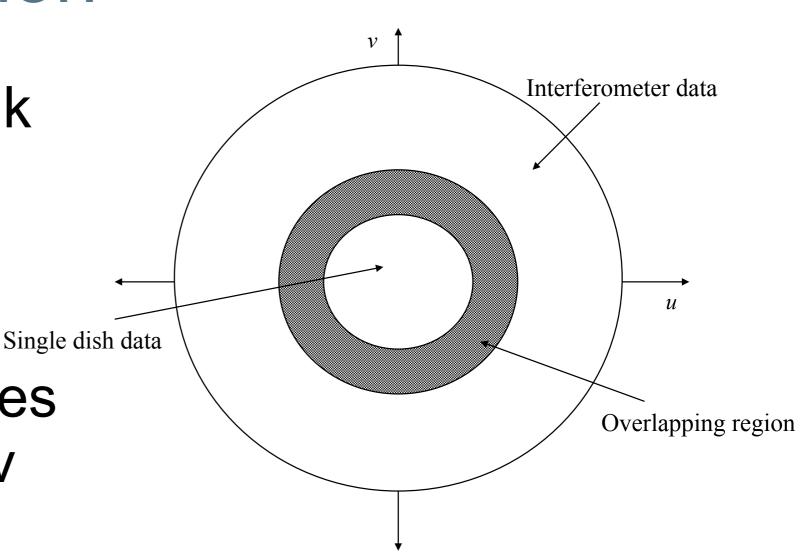
Cross-calibration

 Scale factor to link flux scales:

$$f_{cal} = \frac{S_{int}}{S_{sd}}$$

 Measure intensities in overlapping u-v space

$$f_{cal} = rac{I_{int}}{I_{sd}}$$



Combine Dirty Images, then Deconvolve

- Combine the dirty images, I_{int}^{D} and I_{sd}^{D}

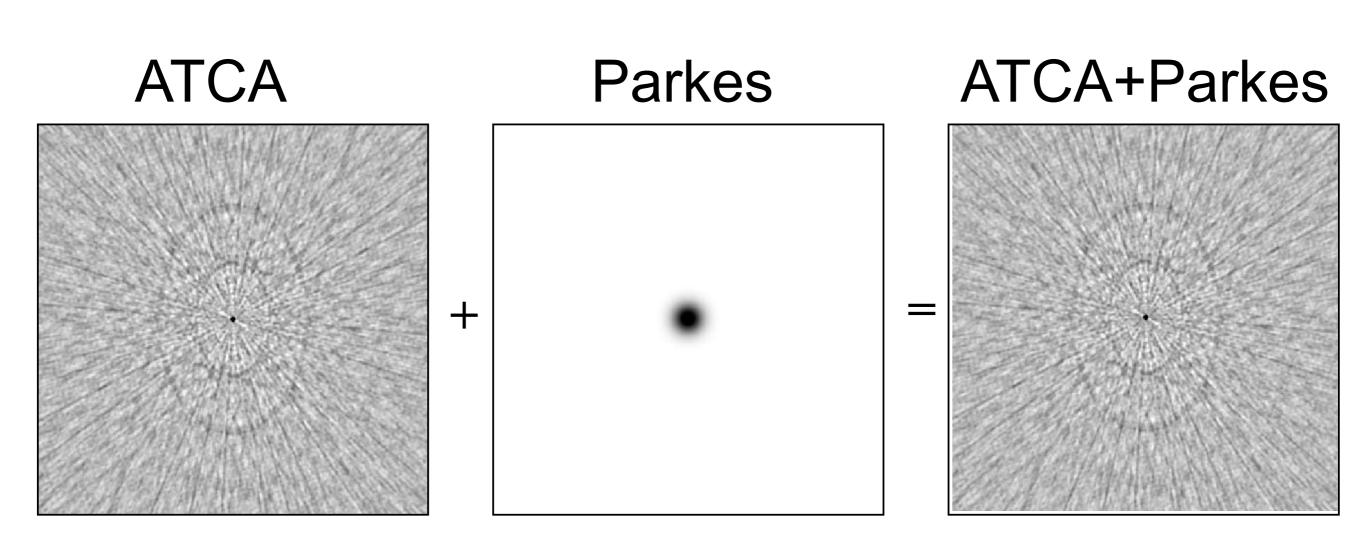
$$I_{comb}^{D} = \frac{I_{int}^{D} + \alpha f_{cal} I_{sd}^{D}}{1 + \alpha}$$

• where the ratio of beam solid angles gives $\alpha = \frac{\Omega_{int}}{\Omega_{sd}}$

Implemented in miriad's mosmem, casa clean(?)



Beam combination



$$B_{comb} = \frac{B_{int} + \alpha B_{sd}}{1 + \alpha}$$

Combination after deconvolution

 "Feathering" technique combines deconvolved image in Fourier space

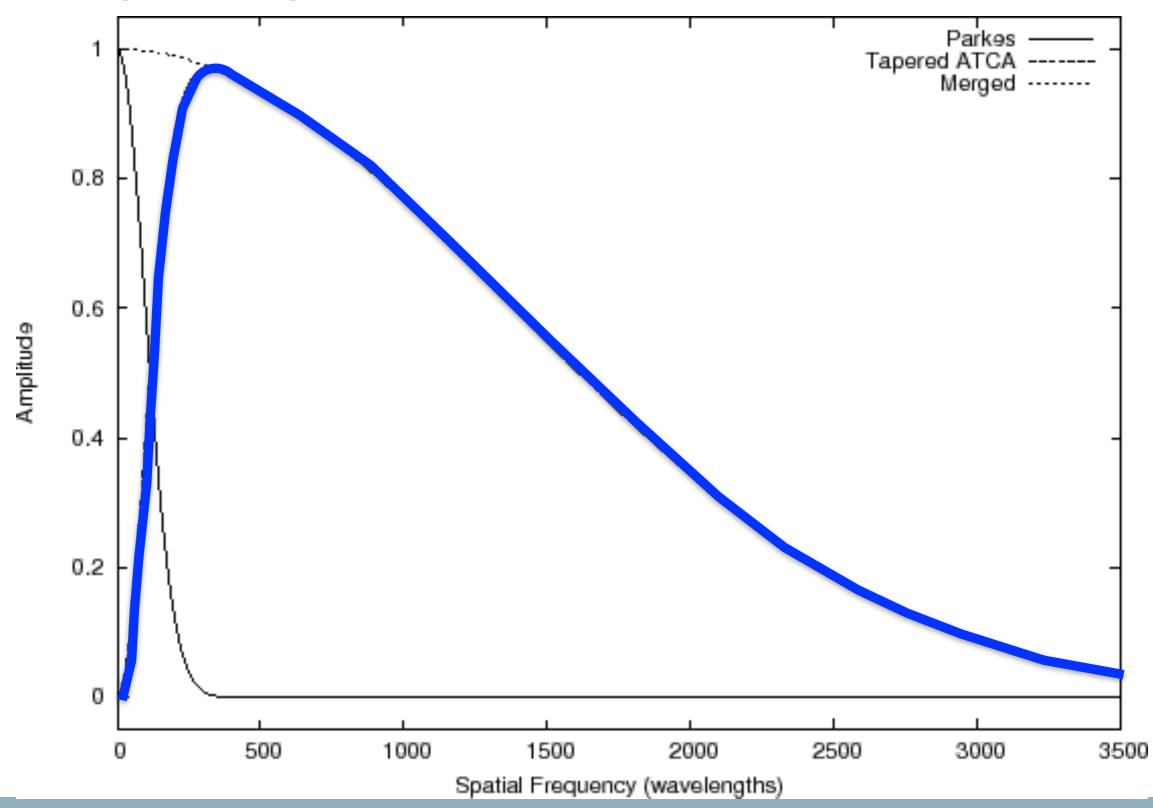
$$V_{comb}(k) = \omega'(k) V_{int}(k) + f_{cal} \omega''(k) V'_{sd}(k)$$

where

$$\omega'(k) + \omega''(k) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{\theta_{int}^2 k^2}{4 \ln 2}\right)$$

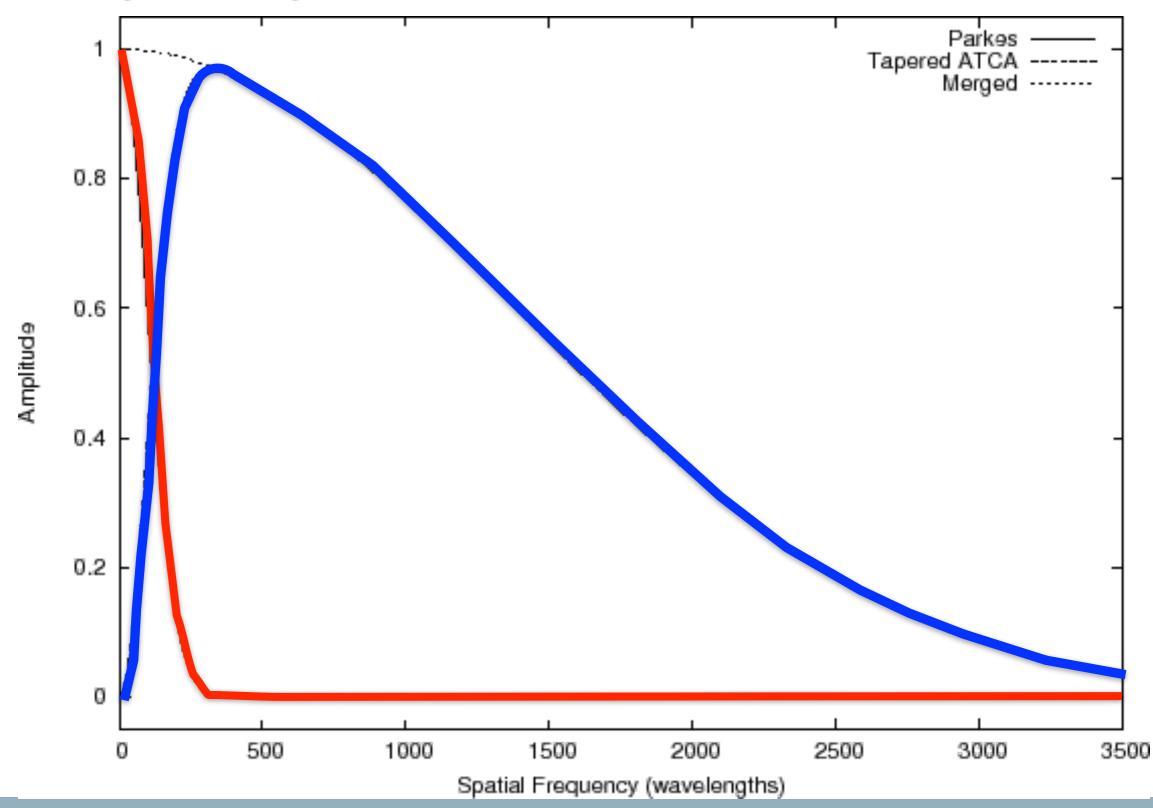


Weighting functions



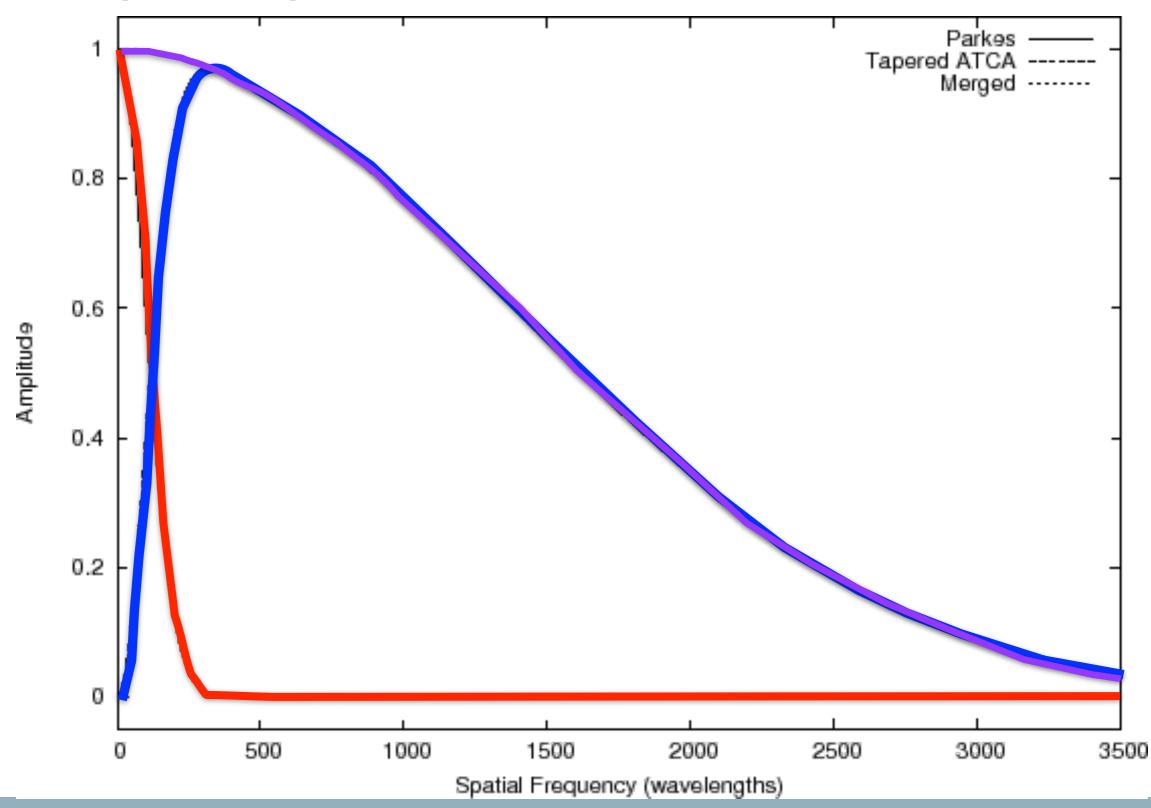


Weighting functions

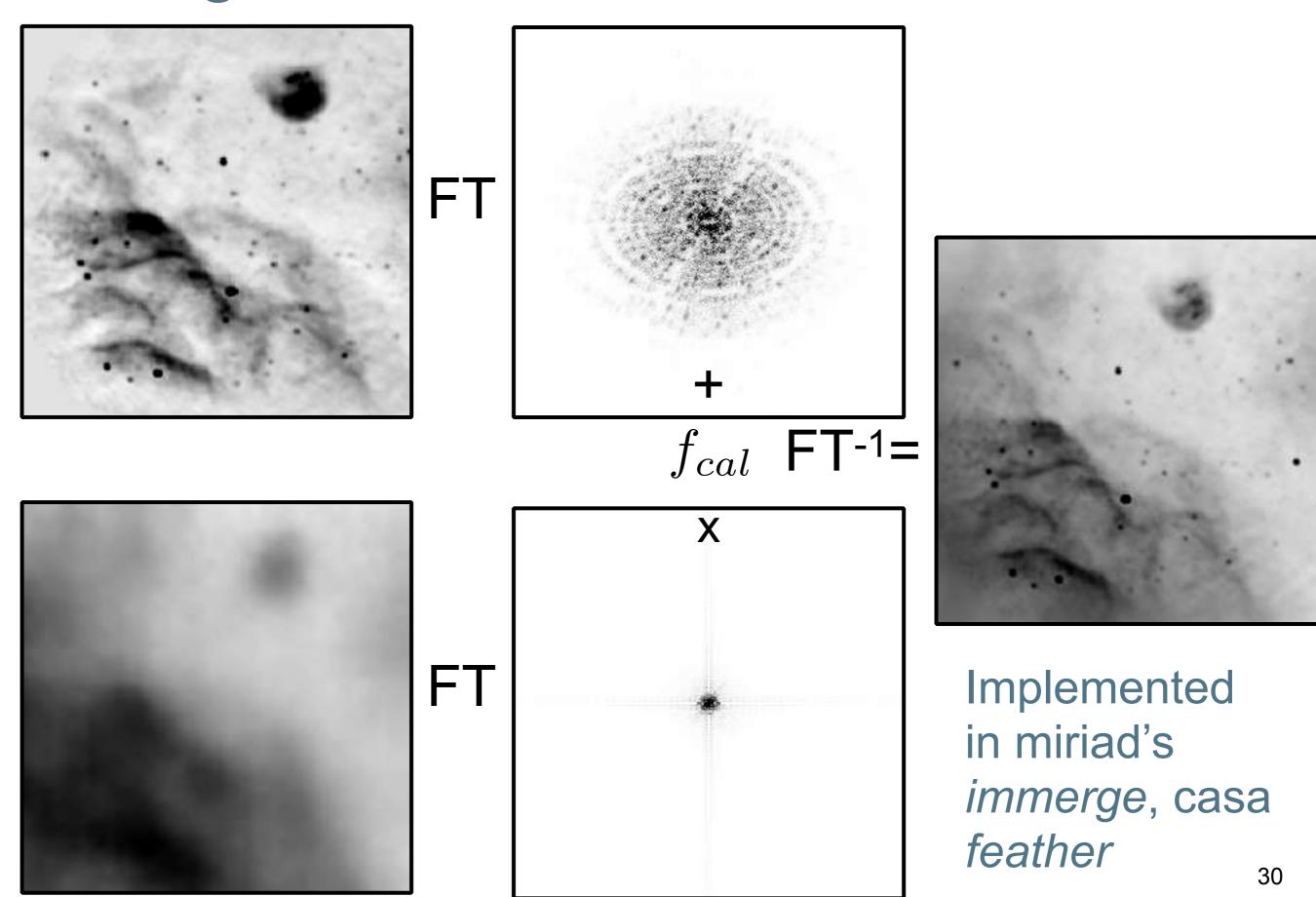




Weighting functions



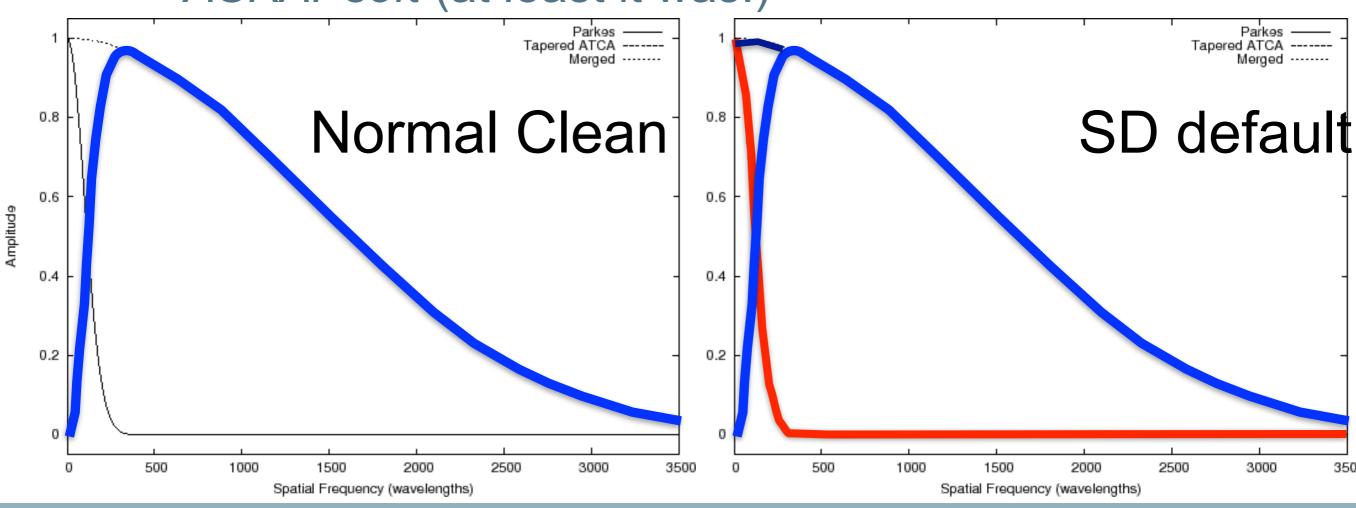
Image, deconvolve, then combine





Combination during Deconvolution: I

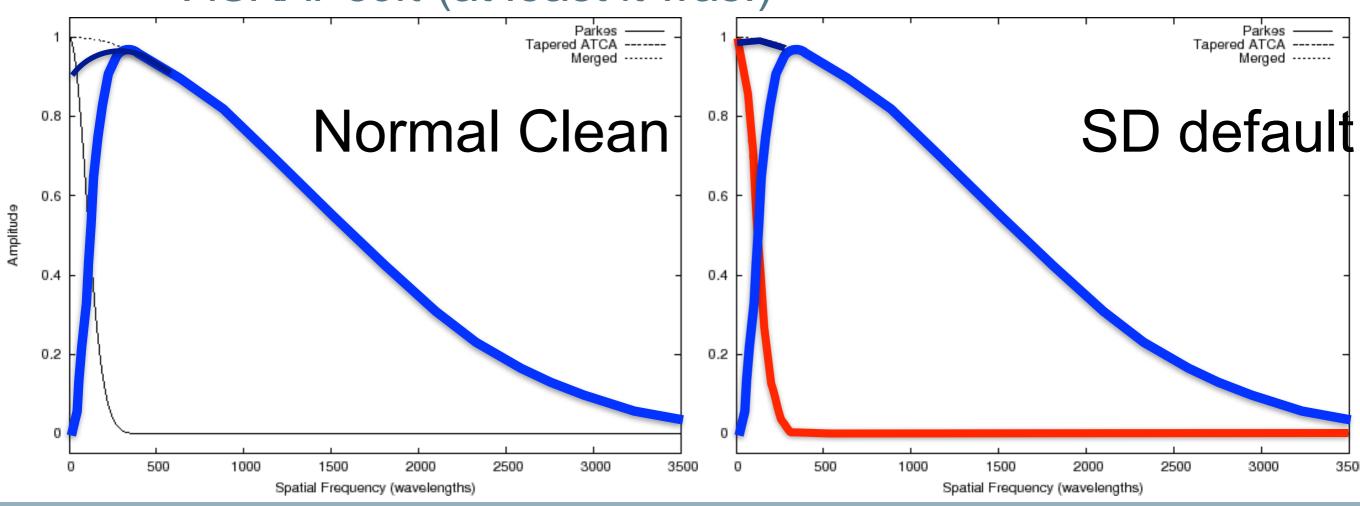
- Use the SD image as a "default" in deconvolution
 - Implemented in miriad's mosmem, casa's clean and ASKAPsoft (at least it was!)





Combination during Deconvolution: I

- Use the SD image as a "default" in deconvolution
 - Implemented in miriad's mosmem, casa's clean and ASKAPsoft (at least it was!)

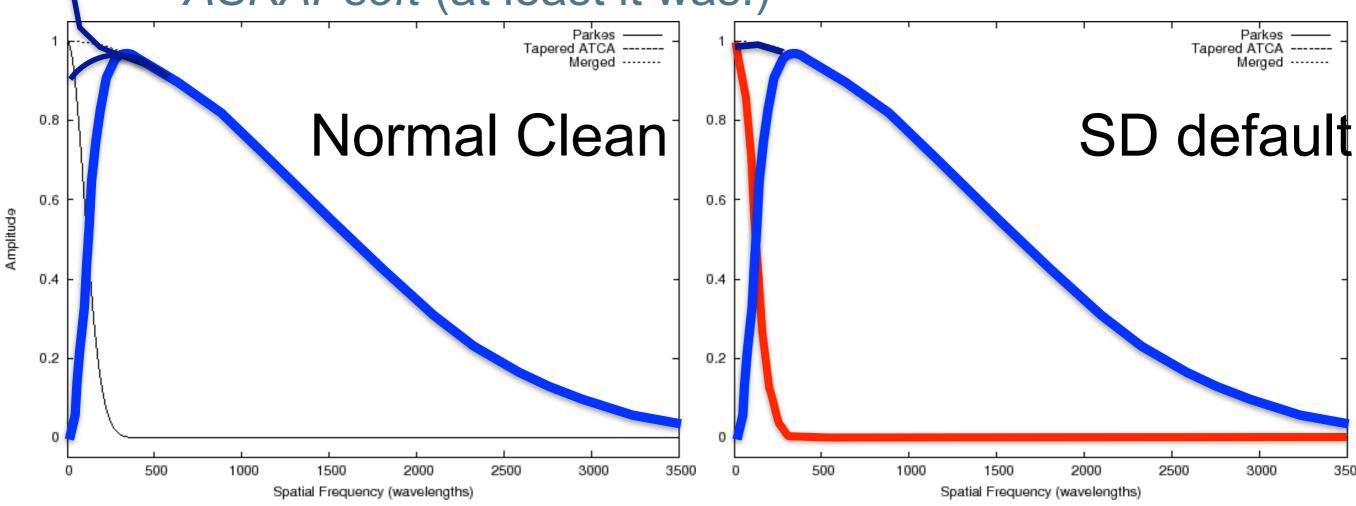




Combination during Deconvolution: I

 Use the SD image as a "default" in deconvolution

 Implemented in miriad's mosmem, casa's clean and ASKAPsoft (at least it was!)





Combination during Deconvolution: II

- Jointly deconvolve both images using a maximum entropy technique
- Where we maximise

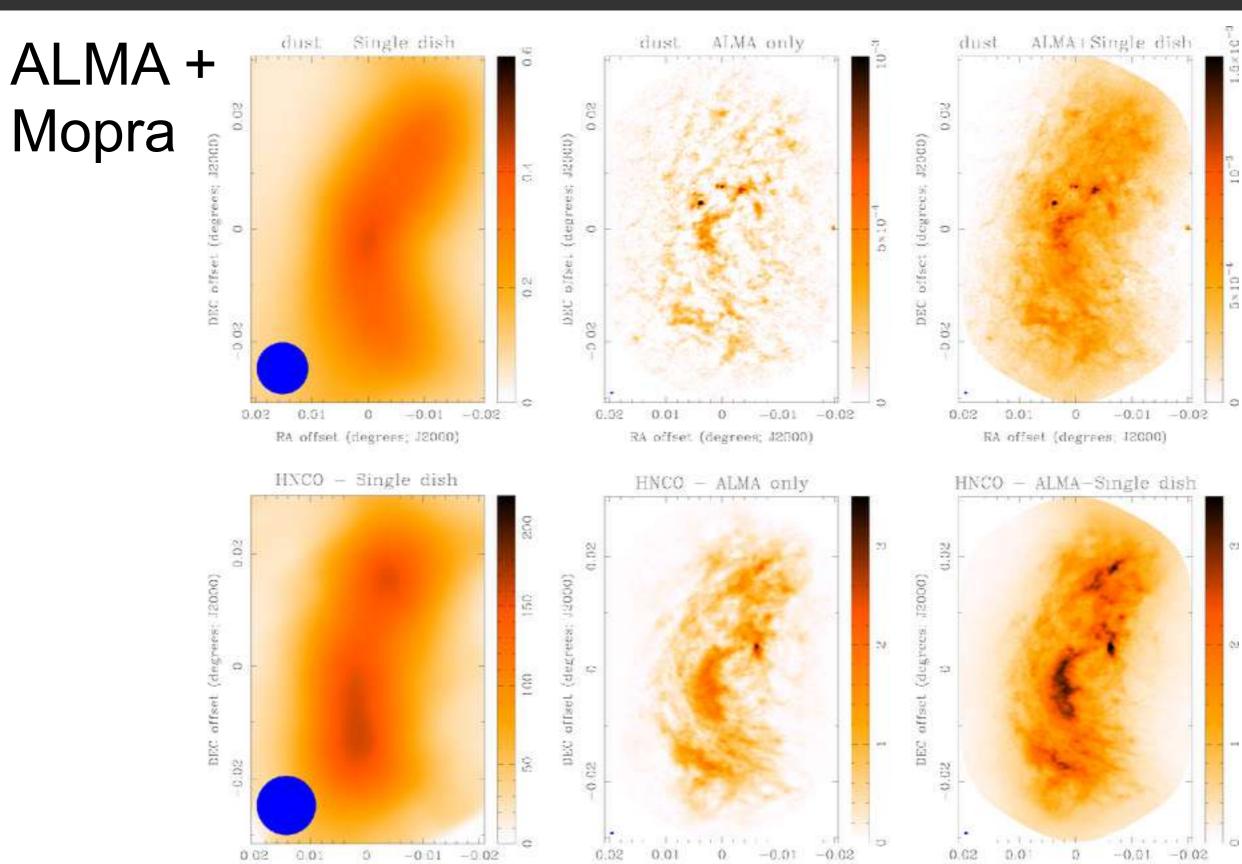
$$\varkappa = -\sum_{i} I_{i} \ln \left(\frac{I_{i}}{M_{i}e} \right)$$

subject to:

$$\sum_{i} \{I_{int}^{D} - B_{int} * I\}_{i}^{2} < N \sigma_{int}^{2}$$

$$\sum_{i} \{I_{sd}^{D} - \frac{B_{sd} * I}{f_{sd}}\}_{i}^{2} < M \sigma_{sd}^{2}$$

Implemented in miriad's mosmem



RA offset (degrees; J2000)

RA offset (degrees, J2000)

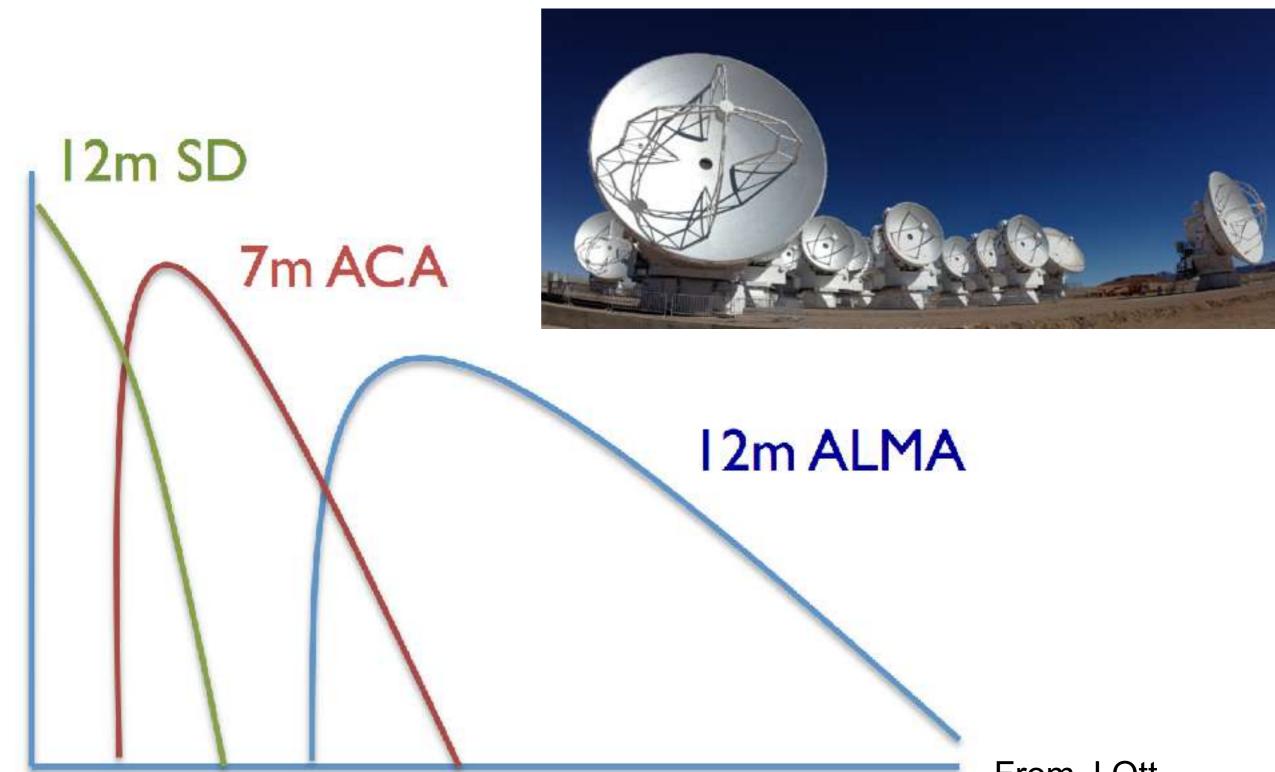
RA offset (degrees: J2000)

Some Complications

- Noise matching
- Need big single dish for overlapping u-v coverage:
 - rule-of-thumb D_{sd}~2*d_{min}
- Cross-calibration very-much subject to ratio of beam sizes
- Single dish image not larger than interferometer or aliasing
- Single dish is not well-defined:
 - elevation effects, sidelobes (<70% efficiency)
 - certainly not a perfect Gaussian beam so any method that deconvolves SD suffers, e.g. joint deconvolution
 - Brightness temperatures vs Jy/Bm



The ALMA + ACA solution





Summary

- Widefield imaging can include the desire to recover extended emission
 - Mosaic-ing can help with this
- Lack of "zero"-spacing in interferometers leads to:
 - lack of sensitivity to large scale emission
 - imaging artefacts (negative bowls)
 - inability to measure total flux
- Can be solved by combining interferometer with single dish data via
 - "joint" or "default" deconvolution
 - "feathering"
 - combination then deconvolution

Some useful literature

- Stanimirovic (2002) ASP Conf. Series 278
- Sault & Killeen (2003) Miriad Users Manual
- Holdaway (1999) ASP Conf. Series 180
- Ekers & Rots (1979) Image Formation, IAU Coll 49, 61.
- Cornwell (1988) A&A, 202, 316.
- Cornwell (1989) ASPC 6.
- Cornwell, Holdaway & Uson (1993) A&A, 271, 697.
- Sault, Staveley-Smith & Brouw (1996) A&A Suppl., 120, 375.
- Holdaway (1998) ASPC 180, ch.20.
- Subrahmanyan (2004) MNRAS, 348, 1208.
- Bhatnagar, Golap & Cornwell (2005) ASPC 347, 96