## **ORBITAL MECHANICS - MIDTERM**

## **Ex.** 8

```
clear all
close all
%initial conditions
a1=12000;
                    %semi major axis [km]
e1=.2;
                    %eccentricity
i1=45*pi/180;
                    %inclination [rad]
                    %argument of perigee [rad]
w1=0;
                    %RAAN [rad]
omega1=0;
f1=0;
                    %true anomaly [rad]
p1=a1*(1-e1^2);
%final conditions
a2=13000;
e2=.1;
i2=45*pi/180;
w2 = 0;
omega2=0;
f2=120*pi/180;
p2=a2*(1-e2^2);
dt = 60*60;
                    %transfer time [sec]
mu=398600;
                    %gravitational parameter [km^3/s^2]
%position and velocity vectors from orbital elements
[rlvec,vlvec] = RVFromCOE( a1,i1,omega1,w1,e1,f1, mu );
[r2vec,v2vec] = RVFromCOE( a2,i2,omega2,w2,e2,f2, mu );
%calculation of chord vector
cvec=r2vec-r1vec;
r2=norm(r2vec);
r1=norm(r1vec);
%angle between the two position vectors
theta=acos(r1vec'*r2vec/r1/r2);
c = sqrt(r1^2 + r2^2 - 2*r1*r2*cos(theta));
%parameter "s"
s=(c+r1+r2)/2;
*picking max and min values for semi major axis of the transfer orbit
amin=s/2;
amax=100000*amin;
%minimum energy ellipse values
betamin=2*asin(sqrt((s-c)/s));
tmin=sqrt((amin^3/mu)*(pi-betamin+sin(betamin)));
%iterations to obtain the actual semi major axis of the transfer orbit
t=tmin;
```

## ORBITAL MECHANICS - MIDTERM

```
g=t-dt;
while abs(q)>1e-10
    a=(amin+amax)/2;
    alpha=2*asin(sqrt(s/(2*a)));
    beta=2*asin(sqrt((r1+r2-c)/(4*a)));
    t=sqrt((a^3/mu)*(alpha-sin(alpha)-(beta-sin(beta))));
    if t<dt</pre>
        amin=a;
    elseif t>dt
        amax=a;
    end
    q=t-dt;
end
*solving for deltaE and p given the semi major axis found with the
%iteration (according to the procedure in the "Fundamentals of
%Astrodynamics" notes)
syms x y
eqn1=1-(r2/x)*(1-\cos(theta))==1-(a/r1)*(1-\cos(y));
eqn2=(r1*r2*sin(theta))/sqrt(mu*x)==t-sqrt(a^3/mu)*(y-sin(y));
sol = vpasolve([eqn1, eqn2], [x, y]);
xSol = double(sol.x);
ySol = double(sol.y);
%lagrange coefficients
f2=1-(a/r1)*(1-cos(ySol));
g2=t-sqrt(a^3/mu)*(ySol-sin(ySol));
fdot2=sqrt(mu/xSol)*tan(theta/2)*((1-cos(theta))/xSol-1/r1-1/r2);
gdot2=1-(r1/xSol)*(1-cos(theta));
%velocity at point 1 and 2 for the transfer orbit
vf1=1/g2*(r2vec-f2*r1vec);
vf2=1/g2*(gdot2*r2vec-r1vec);
%delta v's
dv1=norm(vf1-v1vec);
dv2=norm(v2vec-vf2);
%Orbital elements for the transfer orbit
[at,it,omegat,wt,et] = OrbitalElementsFromRV( rlvec, vf1, mu );
fprintf('deltaV 1 = %.2f km/s \cdot deltaV 2 = %.2f km/s \cdot n \cdot n \cdot dv1, dv2)
fprintf('Orbital elements of the transfer orbit\n')
fprintf('Semi major axis: %.0f km\n',at)
fprintf('Inclination: %.0fo\n',it*180/pi)
fprintf('Right ascension of the ascending node: %.0f°\n',omegat*180/
pi)
fprintf('Argument of periapsis: %.1fo\n',wt*180/pi)
fprintf('Eccentricity: %.2f\n',et)
deltaV 1 = 0.38 \text{ km/s}
deltaV 2 = 0.44 \text{ km/s}
```

## ORBITAL MECHANICS - MIDTERM

Orbital elements of the transfer orbit

Semi major axis: 11978 km

Inclination: 45°

Right ascension of the ascending node: 0°

Argument of periapsis: 341.8°

Eccentricity: 0.21

Published with MATLAB® R2019b