ALEXANDER DAVID STYLER

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AREAS OF INTEREST

Autonomous Driving

- Prediction, planning, and machine learning
- System latency, architecture, and optimization

EDUCATION

Carnegie Mellon University

PhD Candidate in Robotics (Expected December 2018)

Carnegie Mellon University

M.S. in Robotics, QPA 3.89 (December 2012)

Carnegie Mellon University

B.S. in Computer Science, Robotics Minor; QPA 3.56, University Honors (May 2008)

EXPERIENCE

Prediction and System Latency, UBER Advanced Technologies Group, Pittsburgh Technical Lead/Manager (2016-present)

- Leader and developer for the System Latency working group:
 - o Rearchitected the core autonomy system to reduce response time by half
 - O Developed tools, monitoring, and metrics to prevent response time regressions
- Technical lead for Prediction team:
 - o Led core efforts for vehicle prediction, interaction, and feature computation
 - o Maintained interface contract and implementation, and handled consumer requests
- Managed four person Prediction Architecture and Software team

Various Projects, Mitsubishi Electric Research Labs, Cambridge Technical Intern (2015)

- Implemented unsupervised clustering techniques for vehicle trips to analyze similarity and prediction performance of energy usage (Python)
- Improved bounds of state-of-the-art time-series subsequence search to speed up pattern search in very large satellite sensor datasets

Predictive Optimization Project, Group Research and Innovation Center, BMW, Munich Visiting Student, (2014)

- Created routines to analyze, clean, and distill large driving dataset to be used in real-time for vehicle energy optimization and control (MATLAB)
- Deployed predictive optimization algorithm on prototype BMW i3 Plug-In Hybrid Vehicle

ChargeCar Project, CREATE Lab, Robotics Institute, Pittsburgh Researcher. PhD Candidate (2010-2015)

- Developed machine learning techniques for statistical prediction and optimization for control of a heterogeneous energy storage system for vehicles (Java, MATLAB, Python)
- Adapted data-driven approach to thermal optimization and control for an EV battery in collaboration with SBLiMotive and Bosch Automotive (MATLAB Simulink)

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PUBLICATIONS

Learned Optimal Control of a Range Extender in a Series Hybrid Vehicle, International Conference on Intelligent Transportation Systems, IEEE (2015)

Real-time Predictive Optimization for Energy Management in a Hybrid Electric Vehicle, Conference on Artificial Intelligence, AAAI (2015)

Model Predictive Control with Uncertainty in Human Driven Systems, Conference on Conference on Artificial Intelligence, AAAI (2013)

ChargeCar Community Conversions: Practical, Electric Commuter Vehicles Now, International Electric Vehicle Conference, IEEE (2012)

Active Management of a Heterogeneous Energy Store for Electric Vehicles, Integrated and Sustainable Transportation Systems, 2011 IEEE Forum (2011)

Close These Loopholes - Testing Database Modifications, Simple Talk (2007)

Close those Loopholes - Testing Stored Procedures, Simple Talk (2007)

PRESENTATIONS

Learned Optimal Control of a Range Extender in a Series Hybrid Vehicle, ITSC (2015), Electricity Industry Center Advisory Committee (2015)

Real-time Predictive Optimization for Energy Management in a Hybrid Electric Vehicle, AAAI (2015), Carnegie Mellon University (2015)

Model Predictive Control with Uncertainty in Human Driven Systems, Carnegie Mellon University (2012), AAAI (2013), University of Pennsylvania (2013)

Active Management of a Heterogeneous Energy Store for Electric Vehicles, IEEE FISTS 2011 (2011), SBLiMotive Research (2011)

TEACHING EXPERIENCE

Girls of Steel Robotics Team, Pittsburgh, PA

Volunteer Student Mentor (2012-2014)

- Taught, supervised, and mentored secondary students for programming and controlling robots for a national competition
- Helped students learn to design and rapidly prototype robots and quickly diagnose failures

Statistical Techniques in Robotics, Carnegie Mellon University, Pittsburgh, PA Teaching Assistant (2012)

- Presented a guest lecture on statistical filtering techniques for robotics
- Developed and graded coursework and exams, held recitation study sessions

General Robotics, Carnegie Mellon University, Pittsburgh, PA Teaching Assistant and Lab Supervisor (2006-2008)

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GRANTS AND HONORS

NSF Graduate Research Fellowship

Awarded September 2010 through September 2013

Program Committee, Main Track

Twenty-Ninth AAAI Conference on Artificial Intelligence, 2015

Session Chair

IEEE Forum on Integrated and Sustainable Transportation Systems, FISTS 2011

LEADERSHIP

- Managed three full-time direct reports and various interns (2016-present)
- Technical Lead (joint) for fifteen person software team (2017-present)
- Robotics Graduate Student Association President (2012)
- Faculty & Graduate Student Intramural Volleyball League Commissioner (2010-2012)
- School of Computer Science Student Advisory Council (2008)

REFERENCES

UBER, references available upon request

Dr. Illah Nourbakhsh, Robotics Institute, Carnegie Mellon University

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Dr. Daniel Nikovski, Mitsubishi Electric Research Labs

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