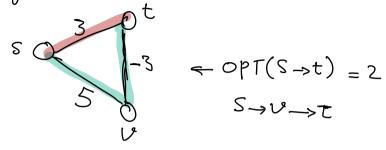
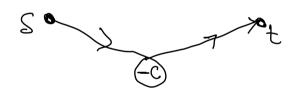
Bellman - ford

Shortest Path on weighted Graphs. Wit neg. edge weights



 $\Rightarrow$  Neg. Cycle: if there exists a cycle w/t neg. Snm af edges  $\Rightarrow$  OPT(S $\Rightarrow$ t) =  $-\infty$ 



\* Assumption: The graph does not have neg. Cycles >> optimal Path is Simple.

S->v OPT (i, v): The optimal Solution from S to v that Contains at a most i edges.

OPT (N-1, t): The shortest path to t, Godailatily at most n-1 edges

OPT(
$$i, v$$
) =  $\begin{cases} \infty & i=0, v \neq s \\ \text{Min}(OPT(i-1, v), \\ \text{Min}(OPT(i-1, w) + Cwv) \\ \text{(}v,w) \in E \end{cases}$ 



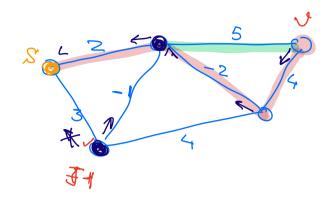
Vertices > U, ... Un > Bellman-bord

O(m)

Bellman-bord

Space: O(n2) Time: O(nm)

for  $v \in V$ :  $M[\varnothing, v] = \varnothing$   $M[o, s] = \varnothing$ for i = 1 to n-1for  $v \in V$ : Chy O(n) ty = min(M[i-1, w] + Cwv)  $f(v,w) \in E$  M[i,v] = min(ty), M[i-1, v]return M[n-1, \*]



Observation: Only the neighbors of the nodes that get updated in the Current iteration may get updated into the next iteration

for VEV: M[U] = \infty; Successor = Null

M[S] = 0; U = (S)

for i = 1 to n - 1

Por (U, W) E :

if (M[W] + Cw < M[U])

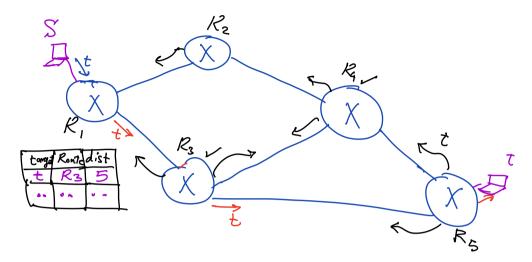
M[V] < M[V] + Cw

Successor [U] < W

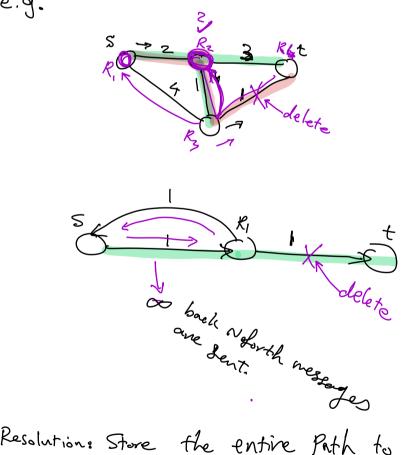
and u to Utmp

return M, Successor

## Distance Vector Protocal



e.g.



Resolution: Store the entire Path to t at every intermediate node.

Path Vector Protocol

Detect the Neg. Cycle:

If JU, S.t. OPT(N, U) < OPT(N-1, N)

There exists a neg. Cycle
otherwise

No neg. Cycle.