# Hyperparameter Tuning

July 6, 2025

## What is Hyperparameter Tuning?

- Hyperparameters are "knobs" that control model training
- Examples: learning rate, max depth, number of estimators
- They are **not learned** from data must be set manually
- Tuning is the process of finding the best values for these settings

### Grid Search: Intuition

- Try all combinations of hyperparameters in a fixed grid
- Like a chef testing every recipe from a list of ingredients
- Works well when search space is small

## Grid Search: Math & Algorithm

### Objective:

$$\theta^* = \arg\min_{\theta \in \Theta} f(\theta)$$

#### Algorithm:

- **1** Define grid  $\Theta = \theta_1 \times \cdots \times \theta_d$
- **②** For each  $\theta \in \Theta$ , train model and evaluate  $f(\theta)$
- **3** Return best  $\theta^*$

### Random Search: Intuition

- Sample random combinations of hyperparameters
- Like spinning a roulette wheel to find good combos
- Often outperforms grid search in high dimensions

## Random Search: Math & Algorithm

### **Objective:**

$$heta^* = \arg\min_{ heta \sim p( heta)} f( heta)$$

### Algorithm:

- **①** Define sampling distributions  $p_1, \ldots, p_d$
- ② For i = 1 to N: sample  $\theta^{(i)}$ , train model, evaluate
- **3** Return best  $\theta^{(i)}$

## Particle Swarm Optimization: Intuition

- Inspired by birds or fish searching for food
- Each "particle" (solution) flies in search space
- Particles learn from their own and neighbors' best positions

## **PSO: Equations**

### **Velocity Update:**

$$v_i(t+1) = wv_i(t) + c_1r_1(p_i - x_i(t)) + c_2r_2(g - x_i(t))$$

#### **Position Update:**

$$x_i(t+1) = x_i(t) + v_i(t+1)$$

#### Where:

- w: inertia weight
- $c_1, c_2$ : cognitive/social coefficients
- $r_1, r_2 \sim \text{Uniform}(0, 1)$

# PSO: Personal Best p and Global Best g

### Personal Best $p_i$ :

$$p_i = \arg\min_{x \in \{x_i(1), \dots, x_i(t)\}} f(x)$$

Best position particle i has seen so far (based on validation loss).

### Global Best g:

$$g = \arg\min_{i} f(p_i)$$

Best position found by any particle in the swarm.

#### Intuition:

- Each particle remembers its own best solution p<sub>i</sub>
- ullet Particles share knowledge to follow the global best g
- ullet Movement balances exploration (randomness) and exploitation (toward  $p_i$  and g)

## PSO: Algorithm

- Initialize particles x<sub>i</sub> and velocities v<sub>i</sub>
- ② Evaluate  $f(x_i)$ , update personal best  $p_i$  and global best g
- Update velocity and position:

$$v_i \leftarrow \text{update formula}$$

$$x_i \leftarrow x_i + v_i$$

- Repeat for T iterations
- $\odot$  Return best g

## MoDeVa: Hyperparameter Tuning Overview

- MoDeVa supports 3 tuning strategies:
  - ModelTuneGridSearch
  - ModelTuneRandomSearch
  - ModelTunePSO
- Common arguments:
  - param\_distributions: hyperparameter search space
  - metric: e.g., "MSE", "ACC", "F1"
  - cv: number of cross-validation folds
  - $\bullet$  n\_iter: only for random search

## Example: Grid Search in MoDeVa

```
from modeva.models import ModelTuneGridSearch
model = mz.get_model("XGB-Depth2")
param_space = {
    "max_depth": [2, 4, 6],
    "learning_rate": [0.01, 0.1, 0.2]
hpo = ModelTuneGridSearch(dataset=ds, model=model)
result = hpo.run(param_distributions=param_space,
                 metric="MSE",
                 cv=5)
result.table
```

## Example: Random Search in MoDeVa

```
from scipy.stats import uniform, randint
from modeva.models import ModelTuneRandomSearch
model = mz.get_model("XGB-Depth2")
param_space = {
    "learning_rate": uniform(0.001, 0.3),
    "n_estimators": randint(100, 1000)
hpo = ModelTuneRandomSearch(dataset=ds, model=model)
result = hpo.run(param_distributions=param_space,
                 n_iter=10.
                 metric="MSE",
                 cv=5)
result.table
```

## Example: PSO Search in MoDeVa

```
from modeva.models import ModelTunePSO
model = mz.get_model("XGB-Depth2")
param_space = {
    "learning_rate": (0.001, 0.3).
    "max_depth": (2, 8)
hpo = ModelTunePSO(dataset=ds. model=model)
result = hpo.run(param_distributions=param_space,
                 metric="MSE",
                 cv=5)
result.table
```