AX=b min x x + 7 (Ax-b) XX 2x474 =0 0 AX=b@

SUB! × AT (AAT) b ZAX+AATX = 0, AX=b Assuming that AAT is Py, invertible (-26

4 (xTx+uTu) + Bu 8 K+ +X + at (Ax+Bu > U=-B/2

x) (x) (x) (x) (x) (traunversation) more (25 + H) 0 长 10 2x + (-27) Sxx =0

x (0) = 0, x(1) = [1;1] > 11 200 200 200 = d<sub>2</sub> かわ 11 0 0 20 422

0 00 ×2(1) X2(1)-0 TX() 300

0

0

0

Opt. Grenzy Hamiltonian Company Control. 兕 (+) w En, const En, opt 20 20 = ab 1 Ox+u 00 11 レニーーメン N/8 Ju de Sherey! = u2+ 2T 6-01 eae-ar 11 中田田 axtu 0 0 -cut > (6) 601 -20t dl = S S e u da = u = -2/2 分