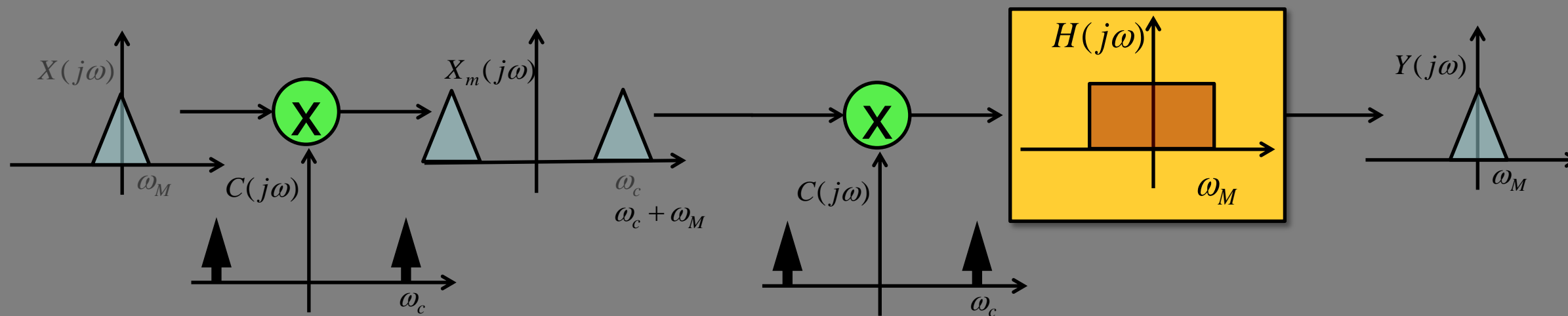


EEE304

Week 7: Communication Systems: Applications of Modulation



EEE304

Week 7: Communication Systems: Applications of Modulation

Learning Objectives:

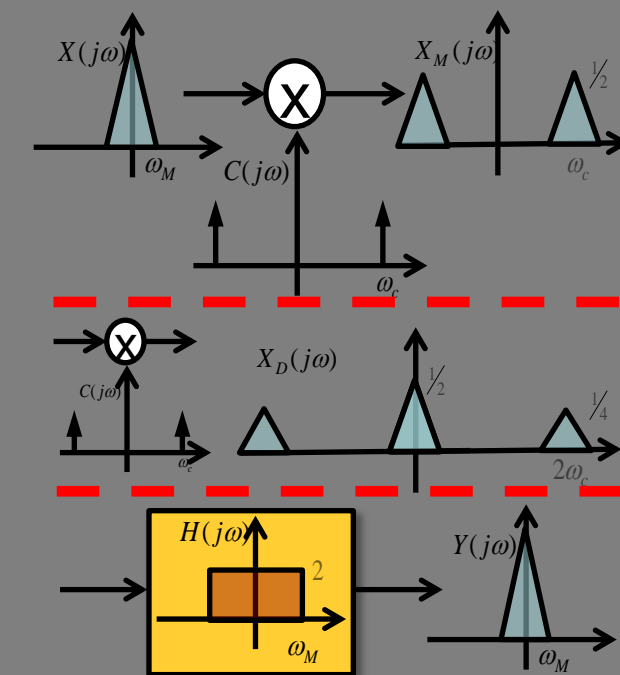
- Develop a general understanding of communications applications of modulation
- AM basics and derivations
- Asynchronous demodulation and envelope detection
- Multiplexing (Frequency Division, Time Division)



ARIZONA STATE UNIVERSITY

EEE304

Lecture 7.1: Modulation and Demodulation Generalities



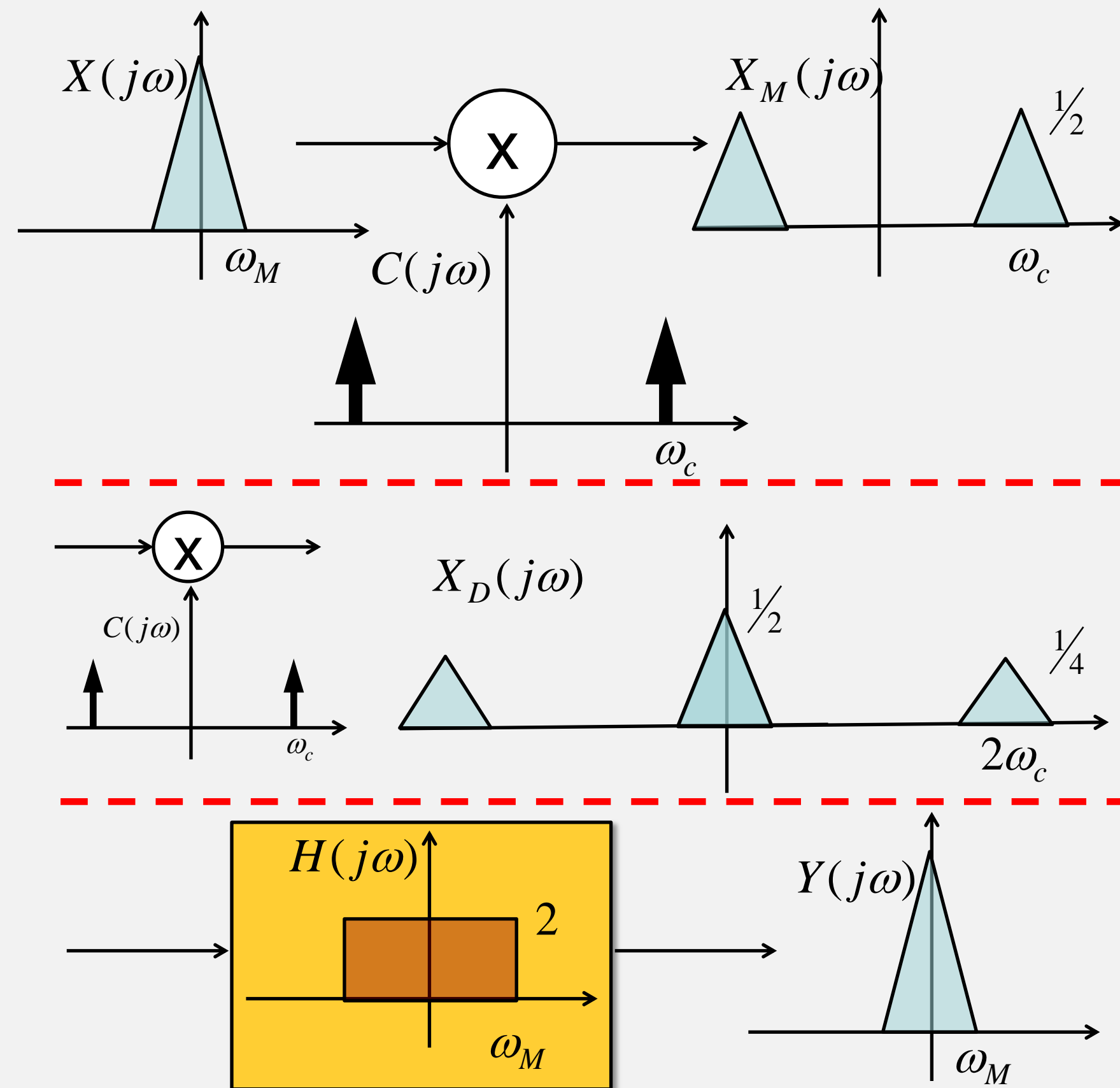
ARIZONA STATE UNIVERSITY

Benefits of Modulation

- Shift transmitted signal spectrum to a frequency inside the operating band of a communication channel.
 - Speech signal 200Hz-4kHz. AM modulation ~1MHz, Cellular radio 800-900MHz, Microwave Link 300MHz-300GHz
 - High-speed digital data (Mbps) using optical carrier frequencies (200THz) : Huge Bandwidth, low transmission losses, immune to EM interference, small size, rugged and flexible.
- Reduced susceptibility to noise and interference
 - Use of certain modulation forms can trade off bandwidth for noise immunity, e.g. FM, PCM
- Multiplexing
 - Simultaneous transmission of signals (frequency division, time division, code division)
- Physical size of equipment
 - Antenna size comparable to wavelength

Modulation and Demodulation

- A carrier wave (e.g., sinusoid) is modulated with a bandlimited signal
- The result contains frequency shifted signal replicas centered at the modulating frequency.
- The modulated signal is suitable for transmission over a communication channel. It is recovered by a “demodulation process” (modulation + lowpass, envelope detector).



Standard Amplitude Modulation: Basic Equations

- Fourier transform of signals and their operations to account for the lowpass filter at the end.

$$c(t) = \cos(\omega_c t) \Rightarrow C(j\omega) = \pi\{\delta(\omega - \omega_c) + \delta(\omega + \omega_c)\}$$

- Modulation property

$$X_M(j\omega) = \frac{1}{2\pi} X(j\omega) * C(j\omega)$$

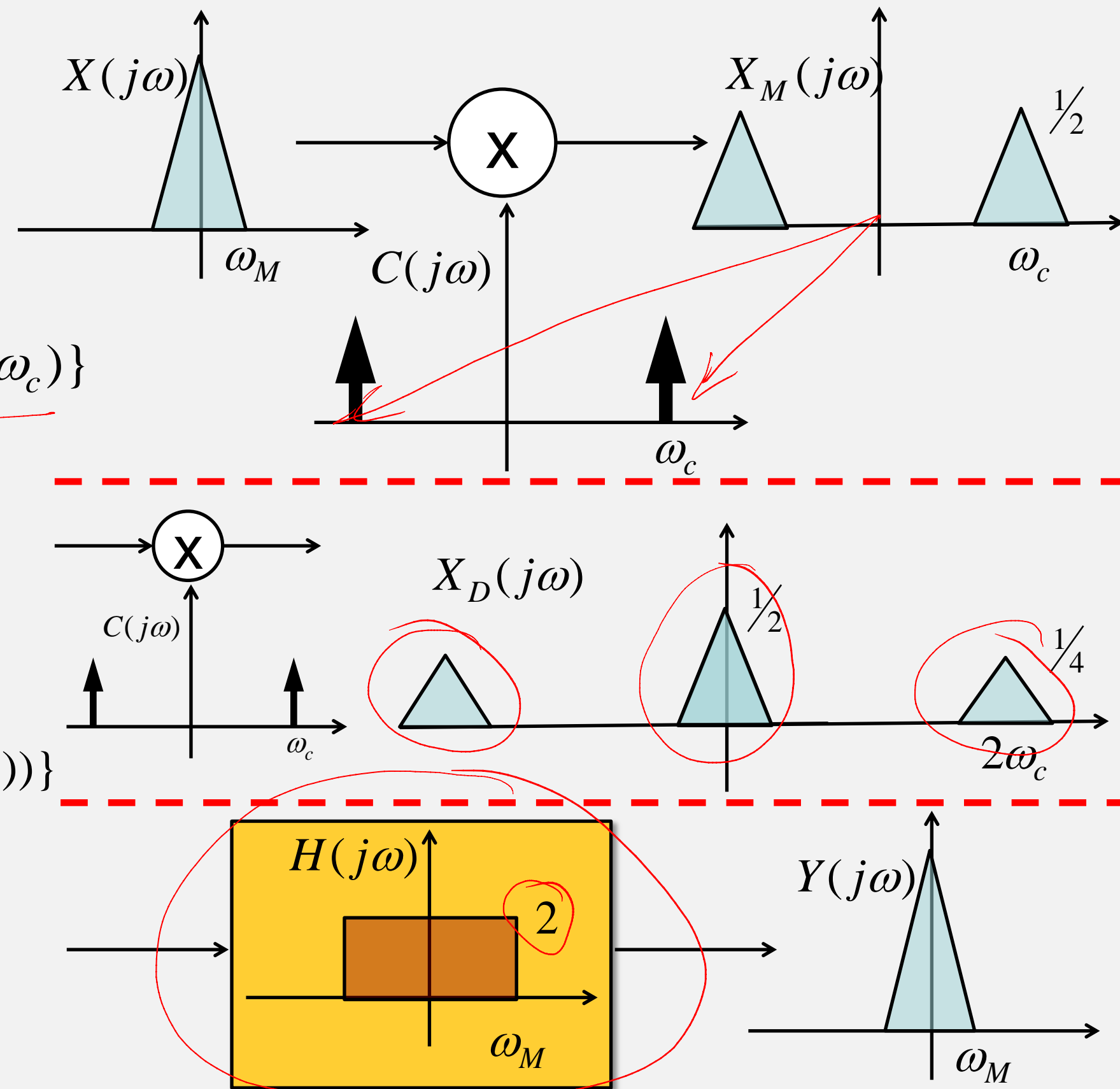
$$= \frac{1}{2} \{X(j(\omega - \omega_c)) + X(j(\omega + \omega_c))\}$$

- Demodulation: Second Modulation

$$X_D(j\omega) = \frac{1}{4} \{X(j(\omega - 2\omega_c)) + 2X(j\omega) + X(j(\omega + 2\omega_c))\}$$

- Lowpass Filtering

$$Y(j\omega) = H(j\omega)X_D(j\omega) = X(j\omega)$$



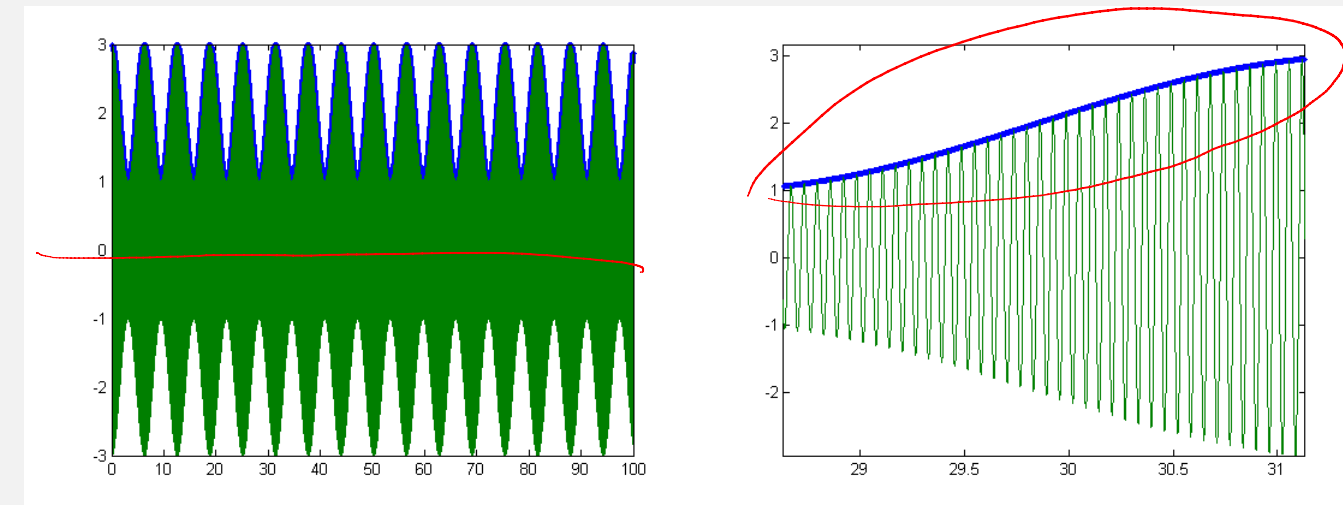
Standard Amplitude Modulation: Asynchronous Demodulation

- Translate signal into a positive envelope

$$x(t) \leftarrow x(t) + A > 0$$

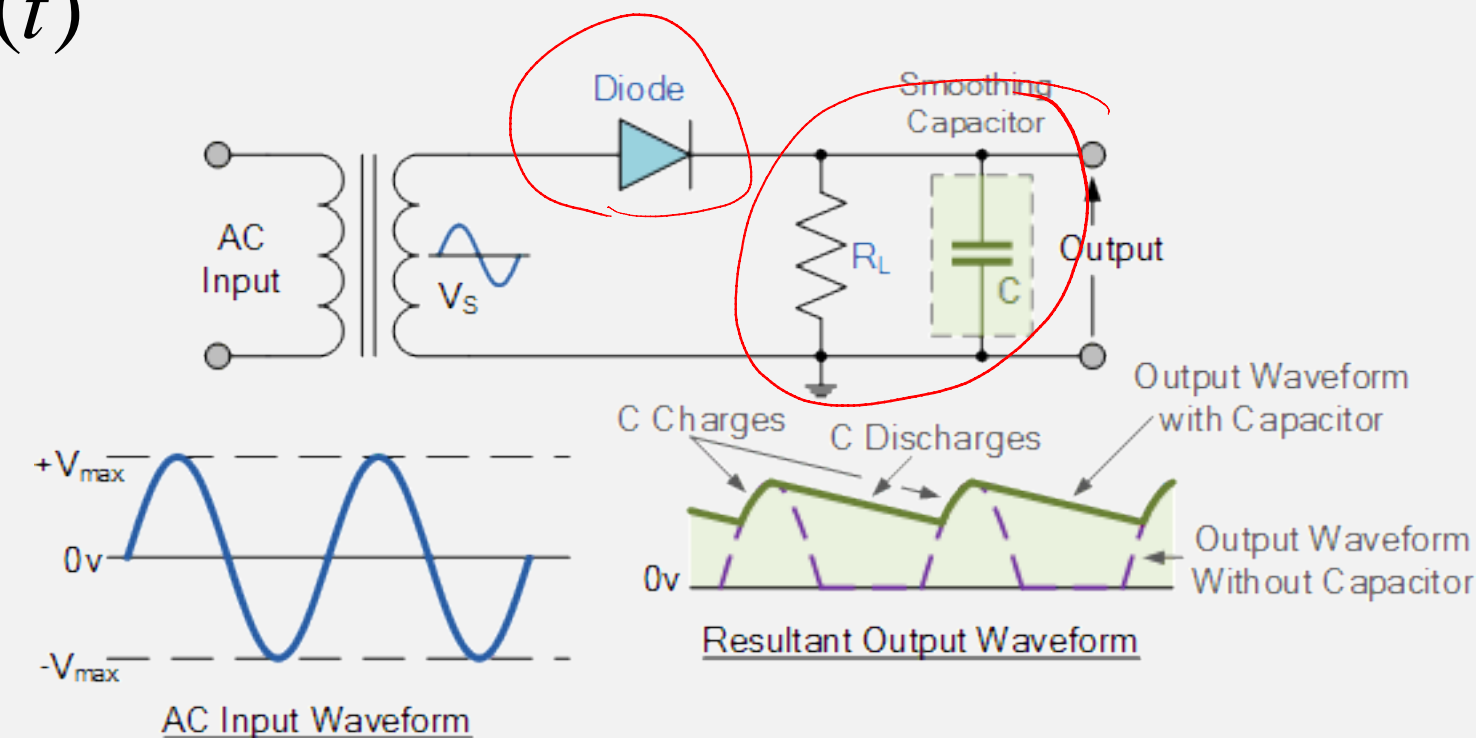
$$\frac{\max(|x|)}{A} = m = \text{Modulation Index}$$

- Modulate $y_M(t) = \cos(\omega_c t)x(t)$
- Use a half-wave rectifier $y_R(t) = \max(\cos(\omega_c t), 0)x(t)$
- and a smoothing filter $Y(j\omega) = H(j\omega)Y_R(j\omega)$
 - When $y(t) > y_R(t)$, $y(t) = e^{-(t-t_i)/RC} y(t_i)$
 - $1/RC \ll \text{carrier frequency}$
 - $1/RC \gg \text{signal frequency}$



Common app:
Wm ~ 1e3 Hz
Wc ~ 1e5 Hz

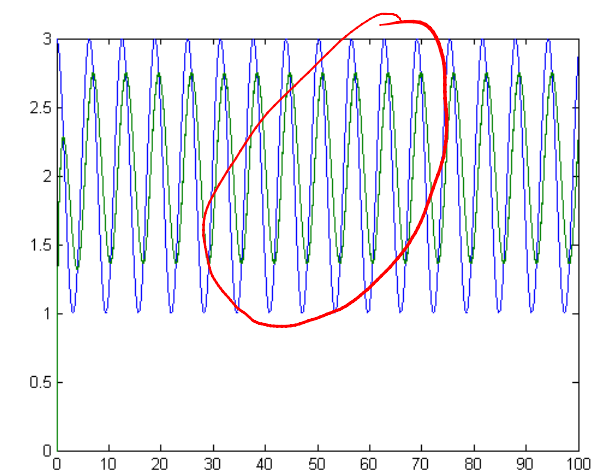
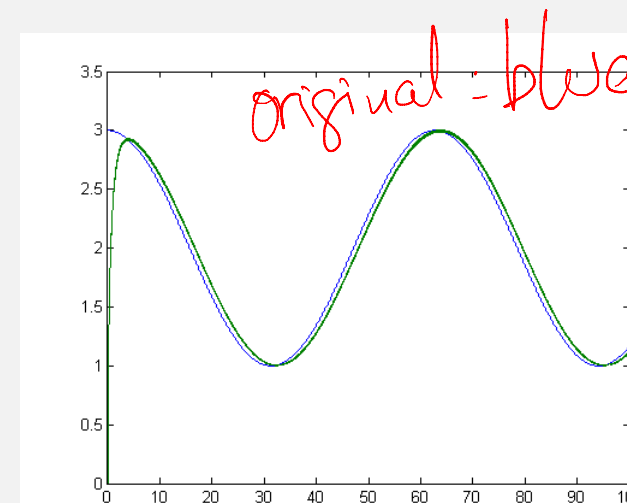
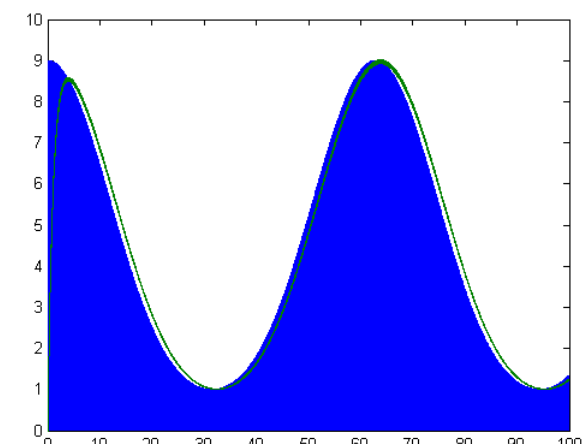
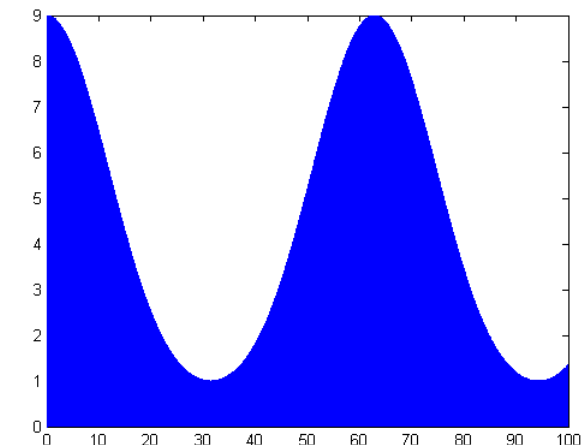
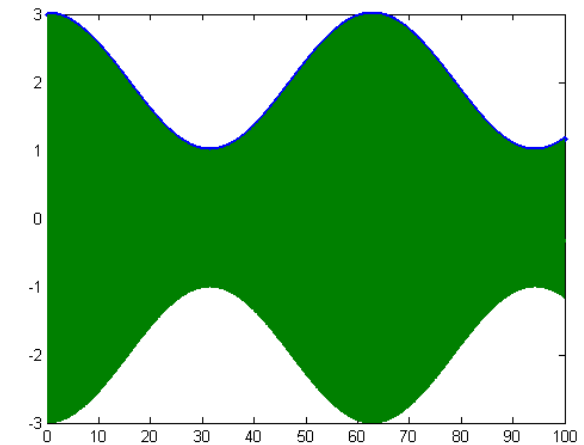
```
t=[0:0.001:100];  
x=cos(1*t);  
c=sin(100*t);  
plot(t,x+2,'.',t,(x+2).*c)
```



Standard Amplitude Modulation: Asynchronous Demodulation

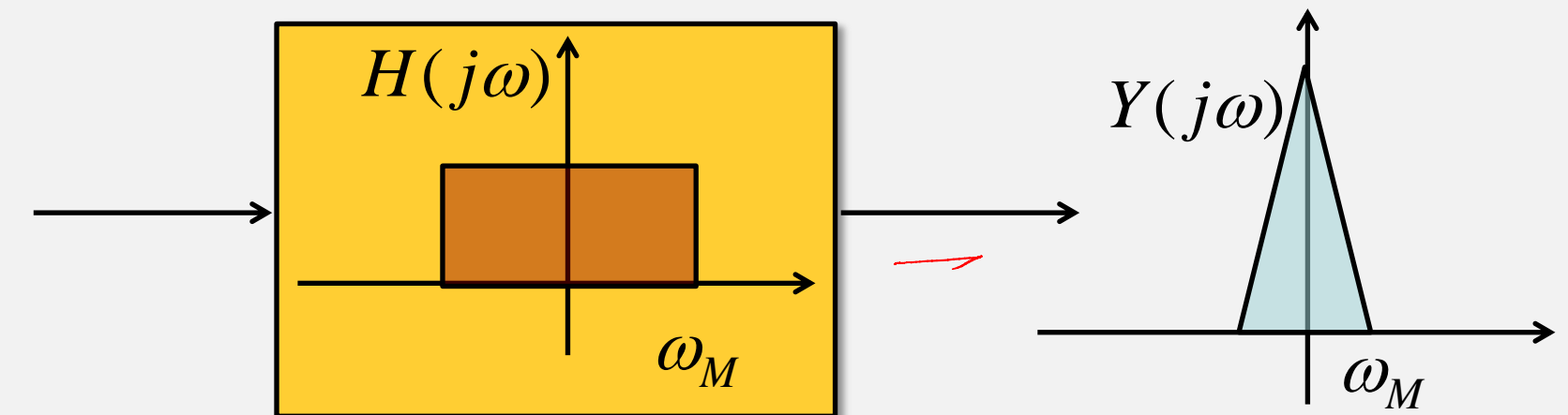
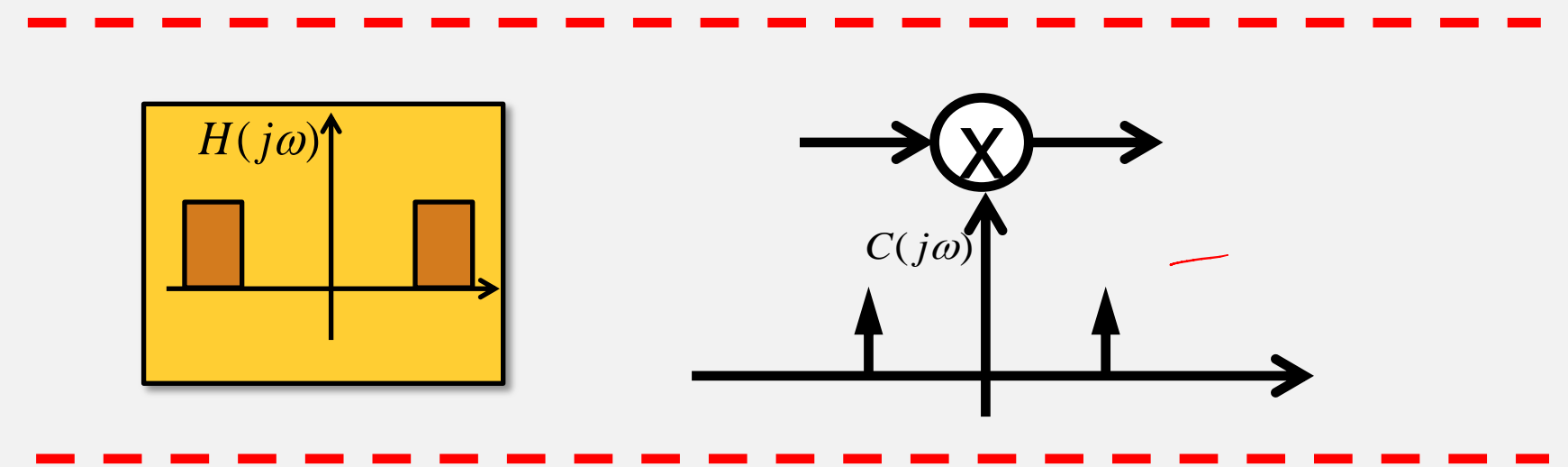
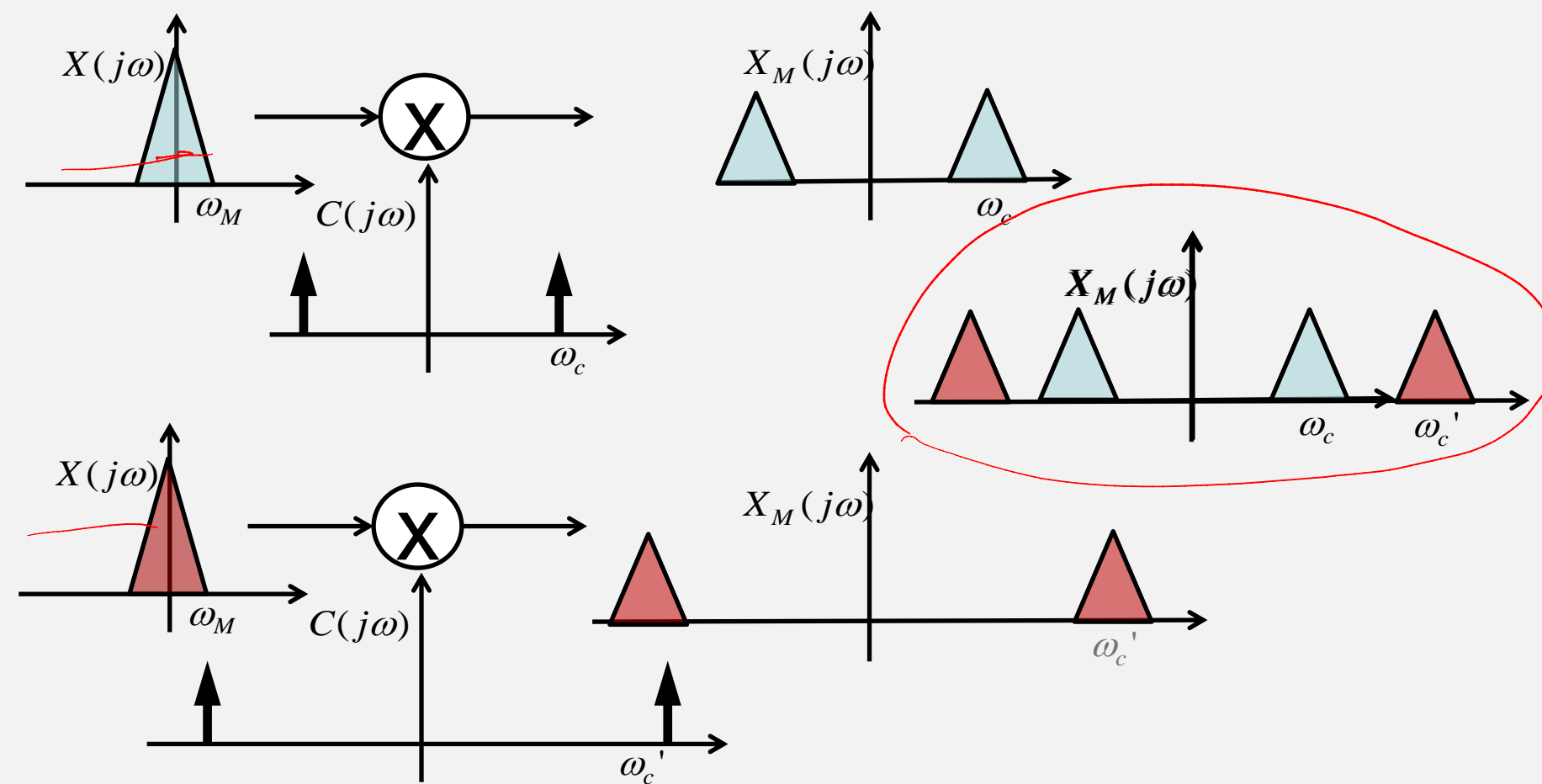
Alternative scheme for a rectifier:

- Modulate $y_M(t) = \cos(\omega_c t)x(t)$
- Use a square nonlinearity $y_D(t) = \cos^2(\omega_c t)x^2(t) = \frac{1}{2}x^2(t) + \frac{1}{2}\cos(2\omega_c t)x^2(t)$
- Then a lowpass filter $Y(j\omega) = H(j\omega)Y_R(j\omega)$ *Band limited to $2\omega_m$* *$\approx 2\omega_c$*
- And a square-root nonlinearity to recover $x(t)$ *Lowpass cutoff $> 2\omega_m$*
- Note: the observed difference is the same as filtering x with H . Left: $x(t) = \cos(0.1t)$, Right: $x(t) = \cos(1t)$.
 $H(s) = 1/(s+1)$



Multiplexing

- Signals modulated with different carrier frequencies and simultaneously transmitted (Frequency Division Multiplexing –carefully regulated BW)
- Bandpass filter and Demodulation for recovery of a specific signal.
- Practical inexpensive systems include an Intermediate Frequency stage where the selected signal is shifted to a fixed frequency where it is bandpass-filtered and demodulated by a fixed-frequency demodulator.



EEE304

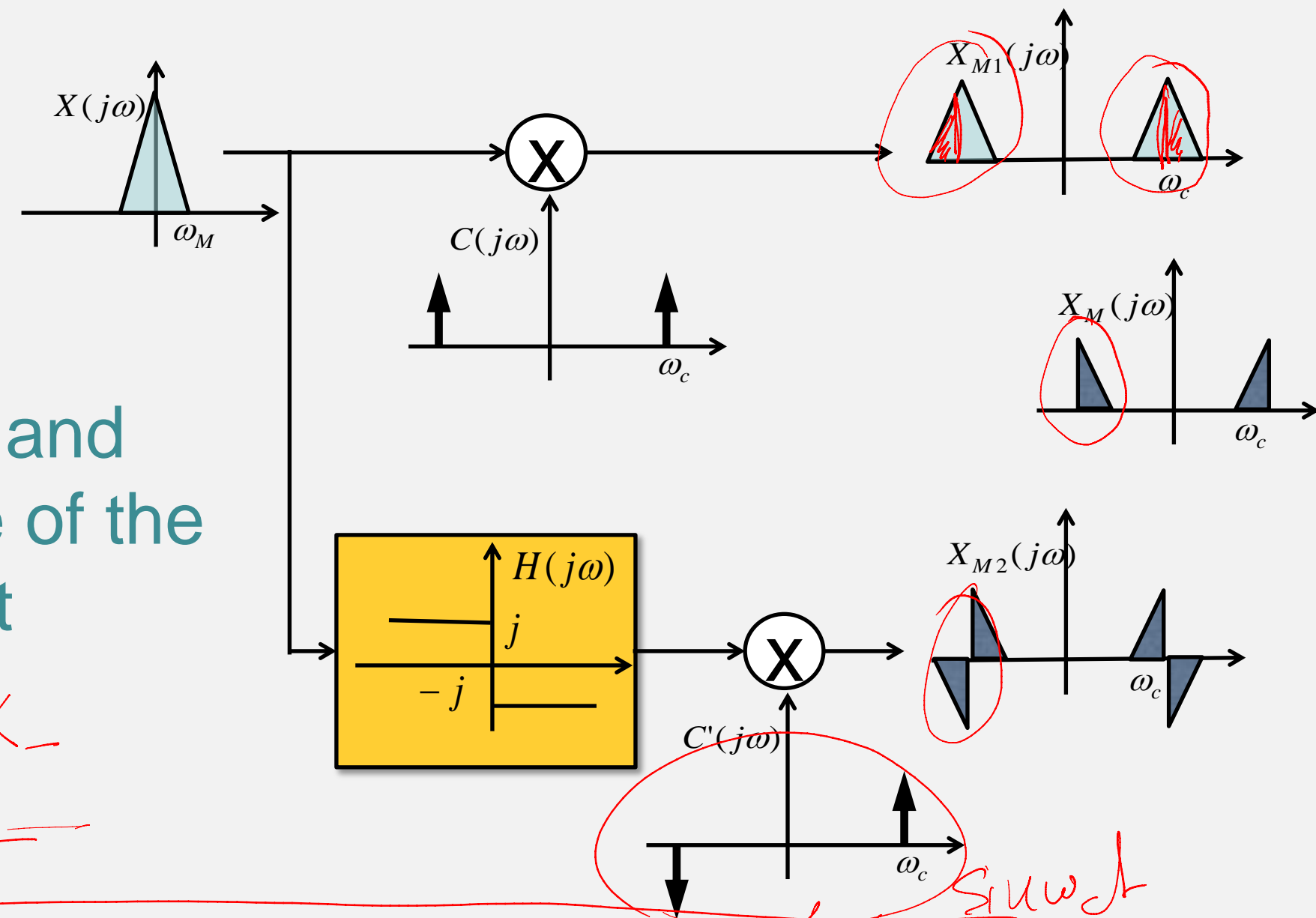
Lecture 3.2: Other Modulation Schemes



ARIZONA STATE UNIVERSITY

Single-Side Band AM

- Use of a 90 deg. phase shifting filter and sin/cos modulation to retain only one of the sidebands and make a more efficient bandwidth utilization.



$$X(j\omega) = X_+(j\omega) + X_-(j\omega)$$

$$X_{M1}(j\omega) = \frac{1}{2\pi} X(j\omega) * C(j\omega) = \frac{1}{2} \{ X_+(j(\omega - \omega_c)) + X_-(j(\omega - \omega_c)) + X_+(j(\omega + \omega_c)) + X_-(j(\omega + \omega_c)) \}$$

$$X_H(j\omega) = H(j\omega)[X_+(j\omega) + X_-(j\omega)] = -jX_+(j\omega) + jX_-(j\omega)$$

$$X_{M2}(j\omega) = \frac{1}{2\pi} X(j\omega) * C'(j\omega) = \frac{1}{2j} \{ X_H(j(\omega - \omega_c)) - X_H(j(\omega + \omega_c)) \}$$

$$= \frac{1}{2j} \{ -jX_+(j(\omega - \omega_c)) + jX_-(j(\omega - \omega_c)) + jX_+(j(\omega + \omega_c)) - jX_-(j(\omega + \omega_c)) \}$$

$$= \frac{1}{2} \{ X_-(j(\omega - \omega_c)) - X_+(j(\omega - \omega_c)) + X_+(j(\omega + \omega_c)) - X_-(j(\omega + \omega_c)) \}$$

$$X_M(j\omega) = X_{M1}(j\omega) + X_{M2}(j\omega) = X_-(j(\omega - \omega_c)) + X_+(j(\omega + \omega_c))$$

Pulse-Train Carrier Modulation

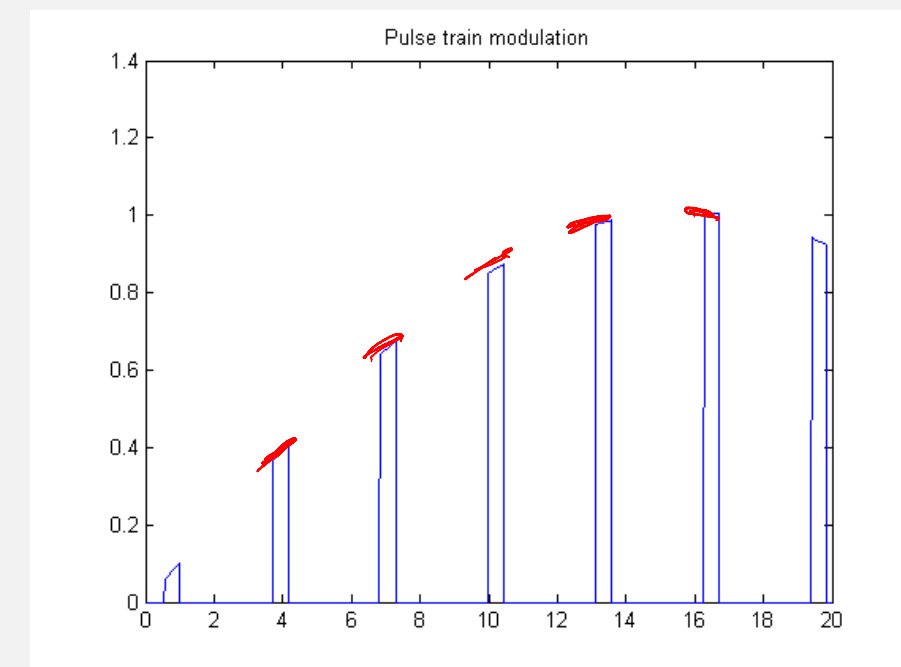
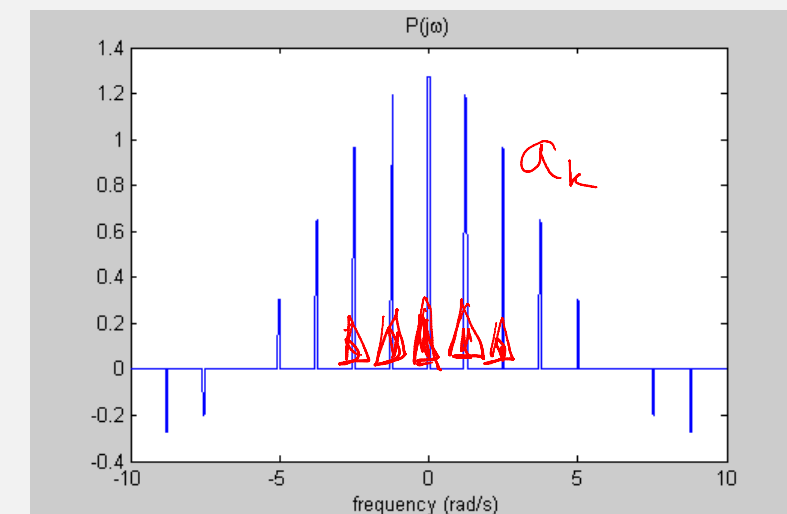
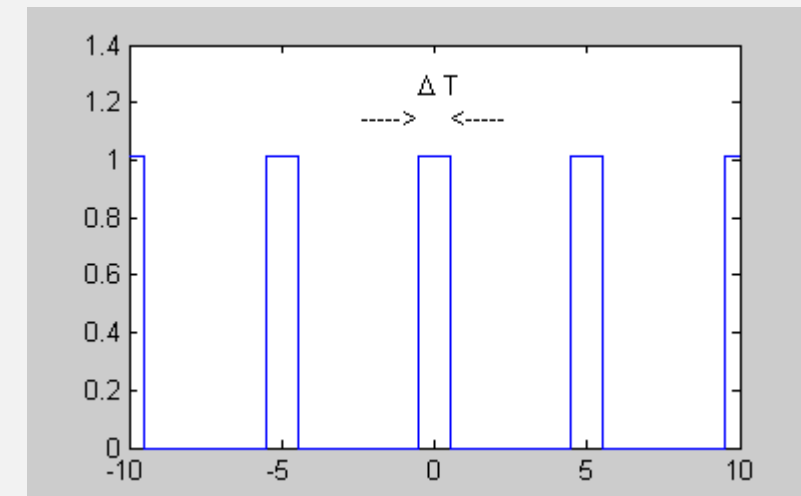
- Use of a pulse train to transmit snapshots of the signal. As long as the Nyquist theorem is satisfied, reconstruction of the signal is possible.

$$p(t) = \sum_n s_{\Delta}(t - nT); \text{ where } s_{\Delta} \text{ is a pulse of duty cycle } \Delta$$

$$P(j\omega) = 2\pi \sum_k a_k \delta(\omega - k\omega_s); \quad \omega_s = \frac{2\pi}{T}, \quad a_k = \mathcal{FS}\{s_{\Delta}\}$$

$$X_M(j\omega) = \frac{1}{2\pi} P(j\omega) * X(j\omega) = \sum_k a_k X(j(\omega - k\omega_s))$$

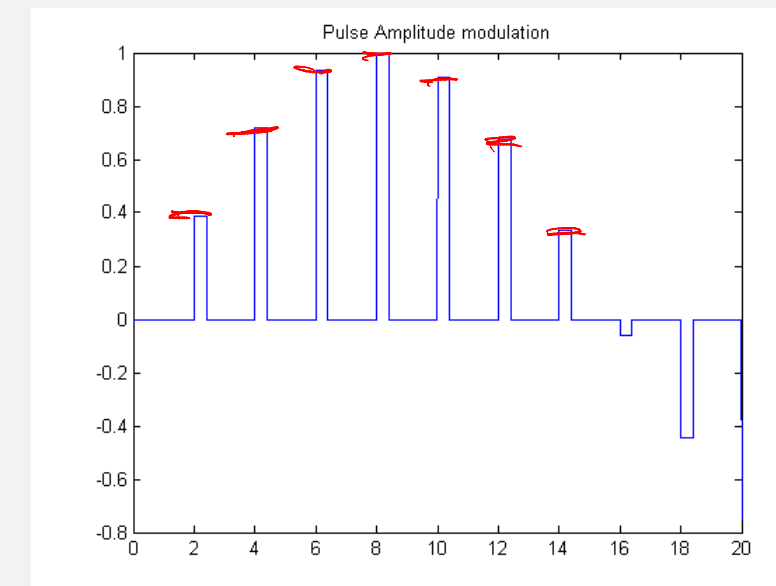
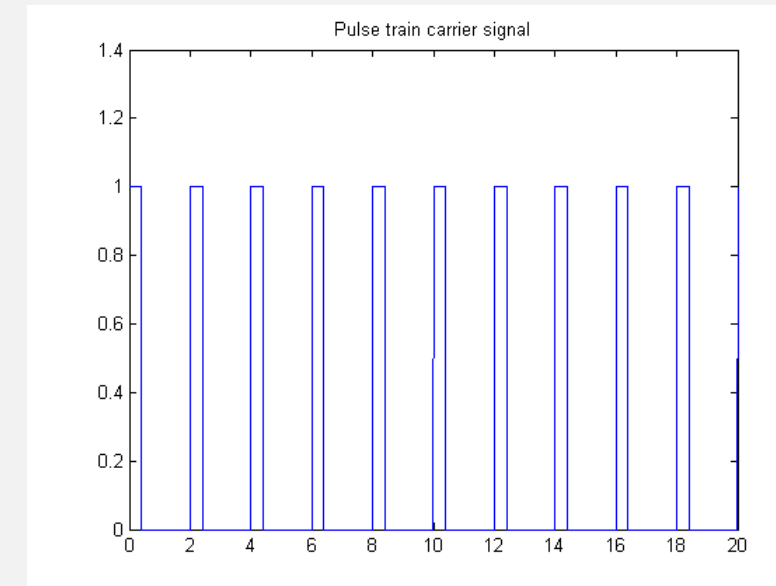
$$a_k = \frac{\sin\left(k \frac{2\pi}{T} \cdot \frac{\Delta T}{2}\right)}{k\pi} = \frac{\sin(k\pi\Delta)}{k\pi}$$



- Reconstruction is possible from the center replica as long as the DC coefficient is nonzero, or any harmonic using a bandpass filter and sinusoidal demodulation, regardless of the duty cycle value.

Pulse Amplitude Modulation

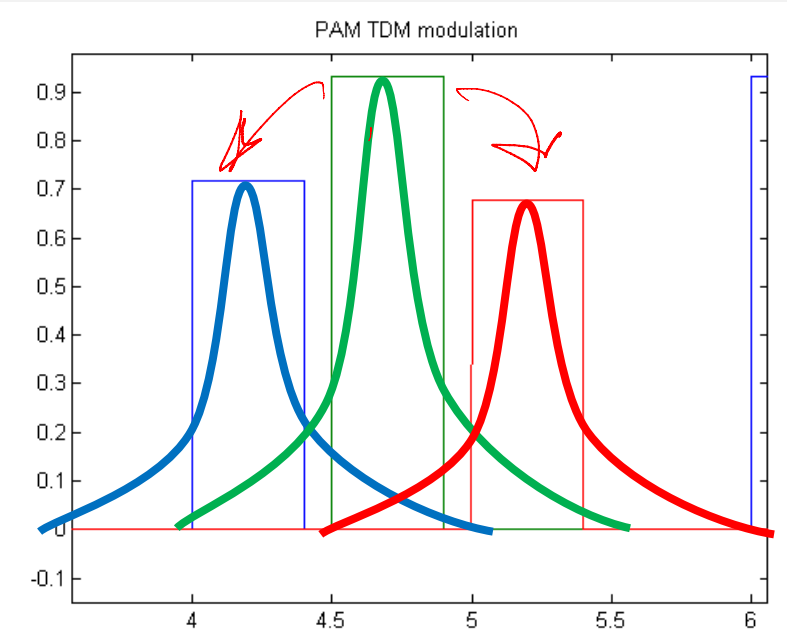
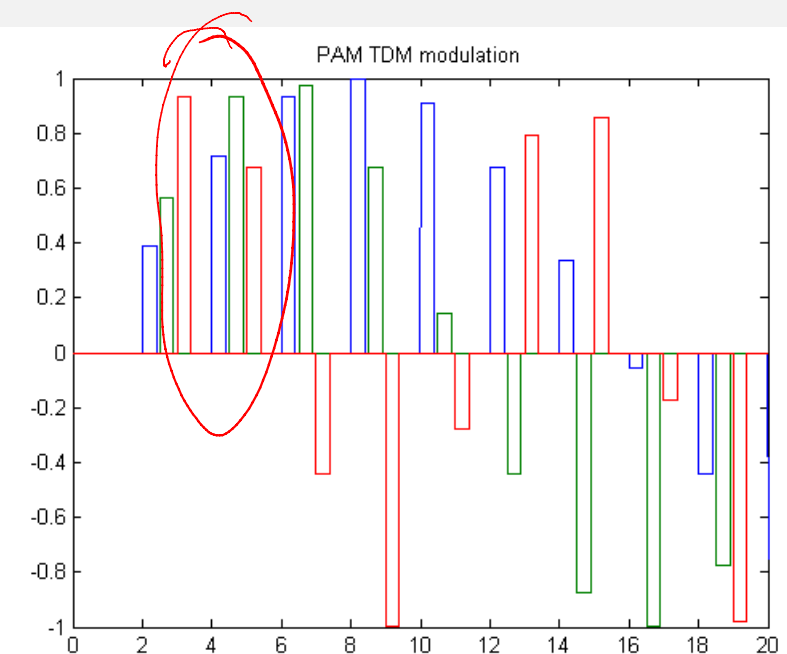
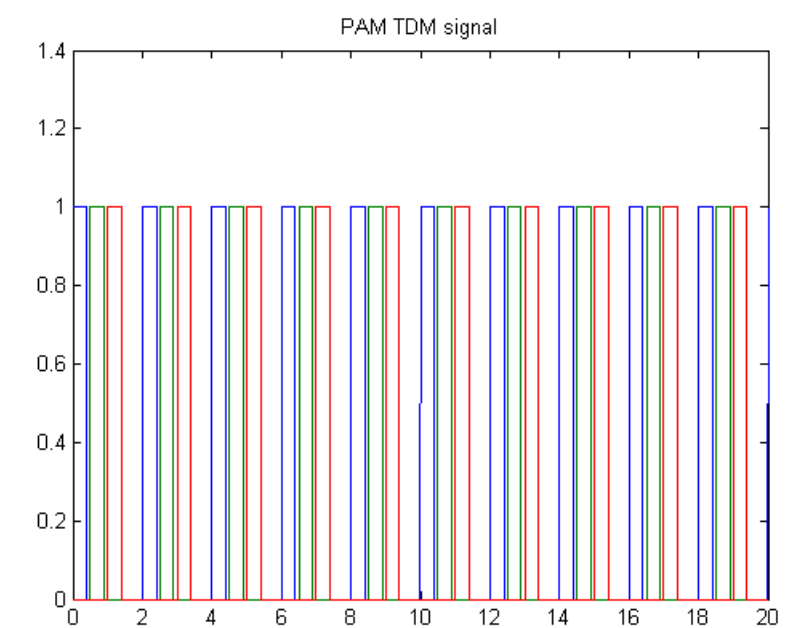
- Similar to Pulse Train Carrier but sending only the sampled values of the signal, $x(nT)$.
- Here, instead of an impulse with weight $x(nT)$, we transmit a ZOH-pulse with the value $x(nT)$.
- The reconstruction is again similar, through lowpass filtering or bandpass filtering and sinusoidal demodulation.
- Requires a timing sequence to identify the correct sampling instants
- Quantization offers some noise immunity trading off accuracy



Pulse Amplitude Modulation

Time Division Multiplexing in PAM systems

- Each time slot allocated to one signal, deciphered by a timing sequence (using additional bandwidth)
- Each pulse is affected by channel distortion (smearing effect) causing “Intersymbol Interference”
- Digital Pulse Amplitude Modulation
 - Sending only quantized values, e.g. 0-1 reduces intersymbol interference but increases the bandwidth of the transmission
- Pulse Code Modulation
 - Encoding the transmitted binary signal with error correction and encryption codes. Transmitted code can be a vector selected to reduce susceptibility to noise.

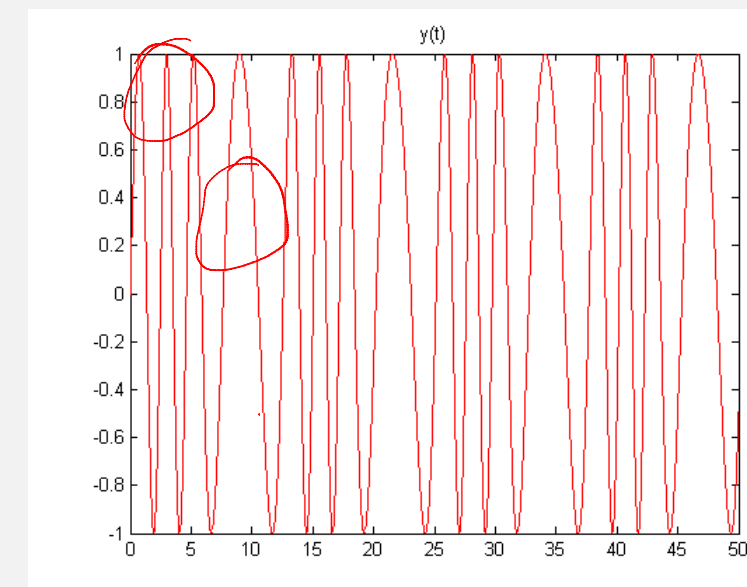
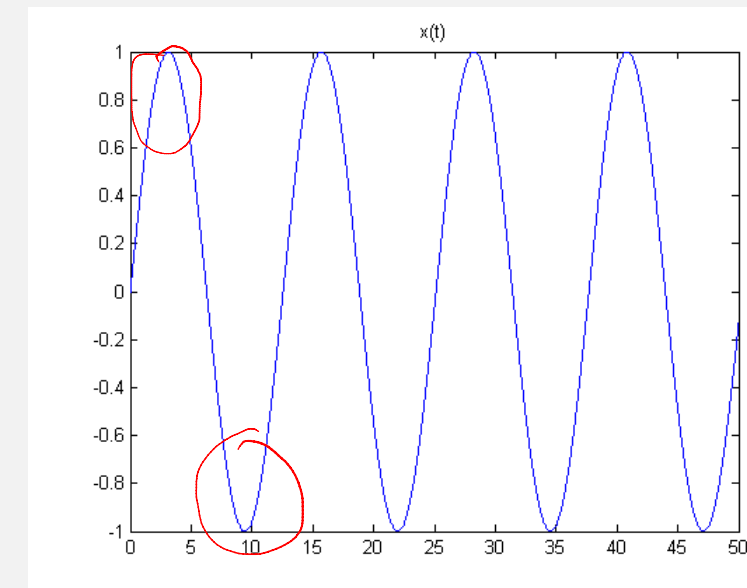


TDM-FDM Example

- 4 voice signals with bandwidth 4kHz are transmitted over a TDM and an FDM communication system. How much bandwidth is required by each system?
- The TDM system multiplexes 4 signals using PAM plus synchronizing pulse train sampled at $4\text{kHz} \times 2 = 8\text{kHz}$ minimum rate. The sampling time is $1/8\text{kHz} = 125\mu\text{s}$. The samples of the five signals must be included in this interval, implying that each is allocated $125/5 = 25\mu\text{s}$. Therefore, the channel bandwidth should be $1/25\mu\text{s} = 40\text{kHz}$.
- The FDM system uses 4kHz for each signal in adjacent frequency intervals. The total bandwidth used is $4 \times 4 = 16\text{kHz}$.
- Notes: Practical PAM would typically use more code for error correction. FDM would also require a fraction of the bandwidth for filter roll-off.

Sinusoidal Frequency Modulation

- Angle Modulation schemes: $c(t) = A\cos(\omega_c t + \theta_c) = A\cos(\theta(t))$
- Modulate the angle or frequency of the sinusoid with the signal.
- Have the advantage of constant amplitude transmission, which allows the transmitter to operate at peak efficiency.
- Use more bandwidth than AM but with better quality
- Phase Modulation $\theta_c(t) = \theta_0 + K_p x(t)$
- Frequency Modulation $\frac{d\theta}{dt} = \omega_c + K_f x(t)$
- Phase and Frequency modulation are related: PM of $x(t)$ is equivalent to FM of $\frac{dx(t)}{dt}$, and FM of $x(t)$ is equivalent to PM of $\int x(t)$



Frequency Modulation details

- Instantaneous frequency: $y(t) = A \cos(\theta(t)) \Rightarrow \omega_i = \frac{d\theta(t)}{dt}$

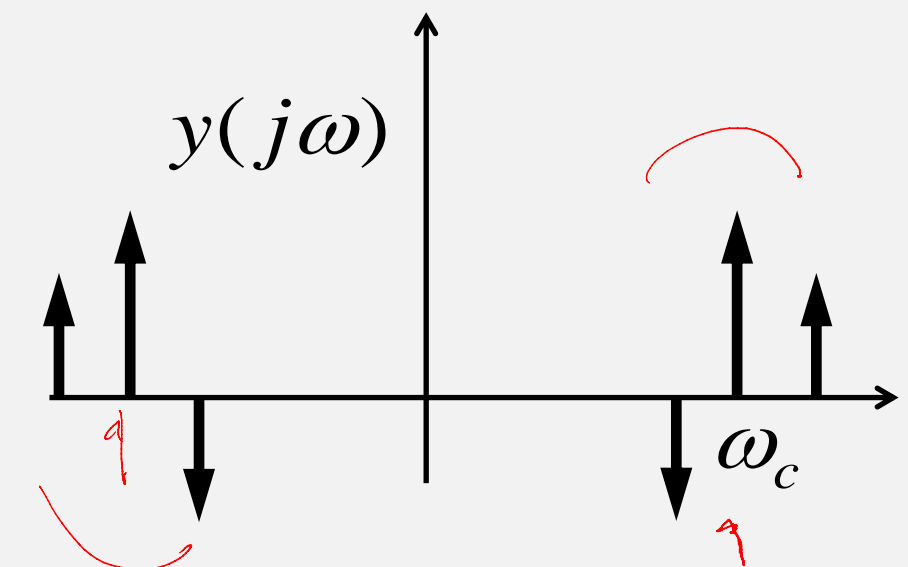
- Narrowband FM

$$\omega_i = \omega_c + K_f \underbrace{A \cos \omega_m t}_{x(t)}$$

$$\Delta\omega = K_f A, \quad m = \frac{\Delta\omega}{\omega_m} = \text{modulation index}$$

$$\begin{aligned} y(t) &= \cos\left[\omega_c t + \int x\right] = \cos\left[\omega_c t + \frac{\Delta\omega}{\omega_m} \sin \omega_m t\right] \\ &= \cos[\omega_c t] \cos[m \sin \omega_m t] - \sin[\omega_c t] \sin[m \sin \omega_m t] \\ &\approx \cos[\omega_c t] \times 1 - \sin[\omega_c t] m \sin \omega_m t \end{aligned}$$

- Looks like AM but modulated signal has constant amplitude



Frequency Modulation details

- Wideband FM

$$\omega_i = \omega_c + K_f \underbrace{A \cos \omega_m t}_{x(t)}$$

$$\Delta\omega = K_f A, \quad m = \frac{\Delta\omega}{\omega_m} = \text{modulation index}$$

$$\begin{aligned} y(t) &= \cos\left[\omega_c t + \int x\right] = \cos\left[\omega_c t + \frac{\Delta\omega}{\omega_m} \sin \omega_m t\right] \\ &= \cos[\omega_c t] \cos[m \sin \omega_m t] - \sin[\omega_c t] \sin[m \sin \omega_m t] \\ &\Rightarrow \text{Bessel functions} \end{aligned}$$

- The communication system bandwidth is much larger than the carrier frequency and depends on the amplitude of the signal.

Modulation Applications

- Implementation of Modulation $x_m(t) = \cos(\omega_c t)x(t)$

$$x_1(t) = \cos(\omega_c t) + x(t)$$

$$x_2(t) = x_1^2(t) = (\cos(\omega_c t) + x(t))^2 = \underbrace{\frac{1}{2}\cos(2\omega_c t)}_{\text{Hi-freq}} + \underbrace{\frac{1}{2} + x^2(t)}_{\text{Low-freq}} + 2\cos(\omega_c t)x(t)$$

$$H_{bandpass}[x_2] = \cos(\omega_c t)x(t)$$



- Chopper Amplifier: AC amplification is easier. With $s(\cdot)$ square wave, e.g., from a switching transistor (common in modulation/demodulation)

$$x_m(t) = s(\omega_c t)x(t)$$



$$H_{\text{amplify-bandpass}}[x_m] = Ax_m(t)$$

$$x_d(t) = s(\omega_c t)Ax_m(t)$$

$$x_a(t) = H_{lowpass}[x_d]$$