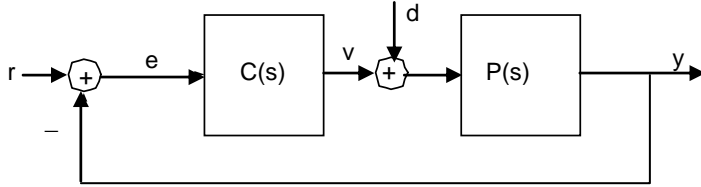


**Problem 1:**

For the feedback system shown below, compute the transfer functions from  $r$  to  $e$  ( $e/r$ ) and from  $d$  to  $e$  ( $e/d$ ).



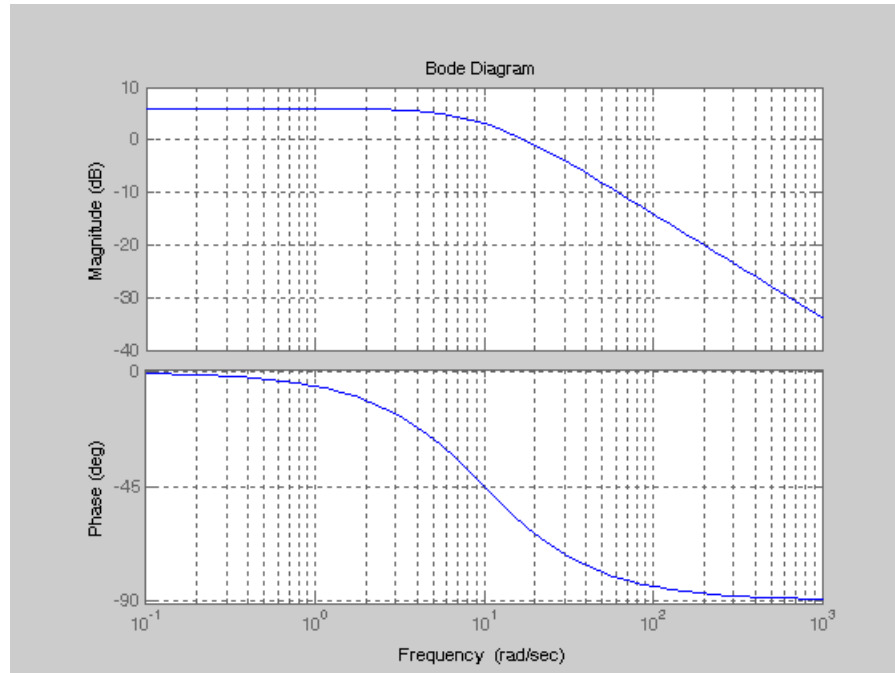
$$\frac{e(s)}{r(s)} = \frac{1}{1 + P(s)C(s)}, \quad \frac{e(s)}{d(s)} = \frac{-P(s)}{1 + P(s)C(s)}$$

**Problem 2:**

For the feedback system of Problem 1, suppose  $P(s) = 2/(0.1s + 1)$  and  $C(s) = K(Ts + 1)/s$ . Determine  $K, T$  so that the crossover frequency is 10 and the Phase Margin is at least  $60^\circ$ .

(You may use the given Bode plot to compute the necessary quantities graphically.)

At  $\omega = 10$  rad/s,  $\arg(P)$  is  $-45^\circ$ . Adding the controller integrator will produce an angle  $-135^\circ$ . We, therefore, need  $+15^\circ$  from the controller zero to obtain the desired  $-120^\circ$  (PM = 60). Thus,



$$\arg(Tj\omega_{GC} + 1) = 15^\circ \Rightarrow 10T = \tan\left(\frac{15\pi}{180}\right) \Rightarrow T = 0.027$$

Next, we compute  $K$  so that

$$|C(j\omega_{GC})P(j\omega_{GC})| = 1 \Rightarrow K = \frac{\omega_{GC}|0.1j\omega_{GC} + 1|}{|Tj\omega_{GC} + 1|2} = 6.8$$

The final controller is

$$C(s) = \frac{6.8(0.027s + 1)}{s}$$