

node-red-contrib-edgetpu-inference 1.0.0

This package contains Node-RED nodes taking advantage of Shenzhou TPU to inference using AI models. There are also nodes for GUI presentation of result and system performance.

Install

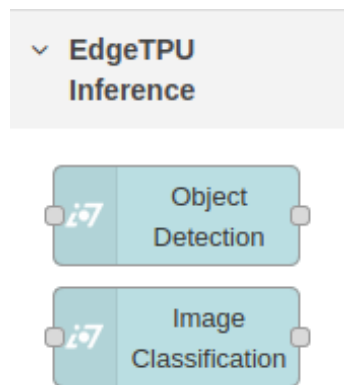
Run the following npm command in your Node-RED user directory (typically ~/.node-red):

```
npm install --prefix=~/.node-red node-red-contrib-edgetpu-inference
```

Category

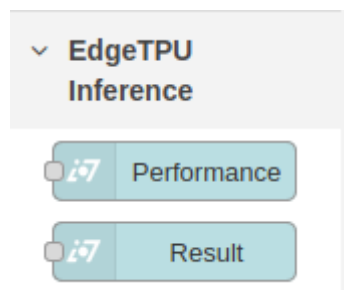
- Inference Node

Find the inference node in category " EdgeTPU Inference " as follow:



- Result Node and Performance Node

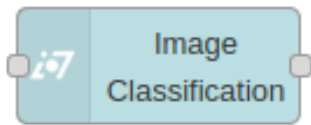
Find the inference node in category " EdgeTPU Inference " as follow:



Usage

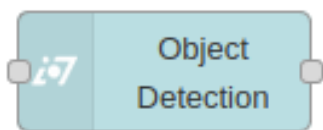
• Inference Node

> “Image Classification” node:



Run image classification models with specified TPUs

> “Object Detection” node:



Run object detection models with specified TPUs

- Node Properties:

The explanation about the items of Properties:

1. **Input Type:** The source input format, including the paths of image file, URL link, video file and camera device
2. **TPU Type:** Support M.2 edge TPU type at current
3. **TPU ID:** Select a number of edge TPU
4. **Model Path:** The edge TPU support model files path
5. **Label Path:** The label file path of model
6. **Image Classification API parameter:**
 - o threshold : Minimum confidence threshold for results.
 - o top_k : The maximum number of results

o resample : A resampling filter for image resizing.

Edit Image Classification node

Delete Cancel Done

Properties

Name: Name of the node

Input Type: URL

TPU Type: ShenZhou (PCIe)

TPU ID: 0

Model Path: modelpath with extension

Label Path: labelpath with extension

Image Classification API Parameters

threshold: 0.1

top_k: 3

resample: PIL.Image.NEAREST

Control

☒ Output Image

☒ Video Loop

☒ Parse Particular Label

Label Name: Person

7. Object Detection API parameter:

o threshold : Minimum confidence threshold for detected objects.

o top_k : The maximum number of detected objects to return.

o keep_ratio : If true, keeping the image aspect ratio the same when down-sampling the image. If false, resizing and reshaping the image (without cropping) to match the input tensor's dimensions.

o relative_coord : If true, providing coordinates as float values between 0 and 1, representing each position relative to the total image width/height. If false, providing coordinates as integers, representing pixel positions in the original image.

[0, 0] is always the top-left corner.

o resample : A resampling filter for image resizing.

Edit Object Detection node

Delete Cancel

Properties

Name

Input Type

TPU Type

TPU ID

Model Path

Label Path

☒ Object Detection API Parameters

threshold

top_k

keep_ratio

relative_coord

resample

Control

☒ Output Image

☒ Video Loop

☒ Parse Particular Label

Label Name

Note: The API parameter can reference the following link

- o <https://coral.ai/docs/edgetpu/api-intro/#edge-tpu-api-overview>
(<https://coral.ai/docs/edgetpu/api-intro/#edge-tpu-api-overview>)

8. Control

- o Output Image : Output base64 image
- o Video Loop : Play video looply

- Input and Output data Formats:

1. Input data format to inference node:

When the inference using a edgetpu model is performed, you need to pass the corresponding msg.payload to the inference node. The msg.payload would be a string of path about image or frame sources.

Source Type	Payload format	Example
Image	Strings	"/home/asus/Desktop/test.jpg"
URL Streaming server	Strings	"http://127.0.0.1:8080/?action=stream (http://127.0.0.1:8080/?action=stream)"
Video	Strings	"/home/asus/Desktop/test.mp4"
Local Camera	Strings	"0"
Stop Inference node	Strings	"STOP" or "stop"
Pause Inference node	Strings	"PAUSE" or "pause"

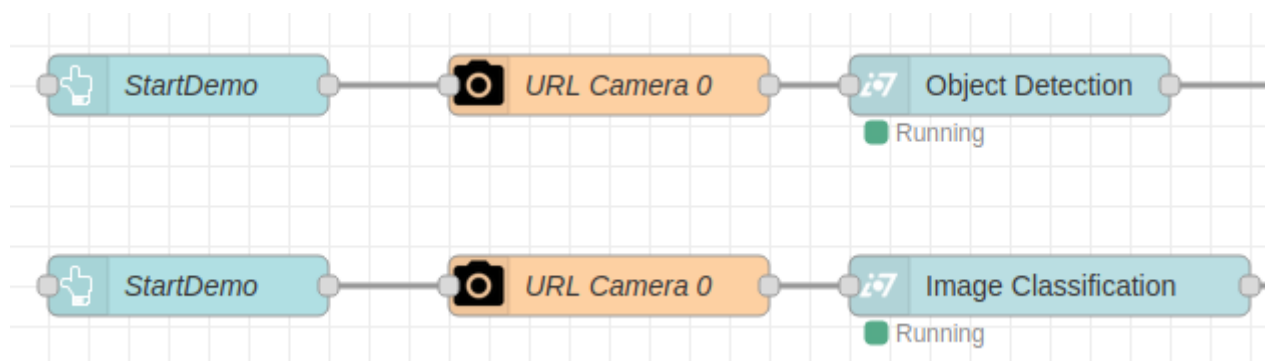
An example of input to inference node for url streaming server:

```
{  
  payload: "http://127.0.0.1:8080/?action=stream"  
}
```

You also need to select the "input type" item to URL on inference node:



1.1 Input data format to inference node:



2. Output data format from inference node::

2.1 SZ Image Classification node output json format:

Output	Format	Description
bbox	array	The coordinate about x1, y1, x2 and y2 return from the edgetpu object detection api.
className	Strings	Class Name category
score	Integer	The percent about the inference result
inf_fps	Integer	The FPS about TPU inference for a frame
starttime	Integer	Inference node start time(Millionseconds)
image	Strings	Base64 format strings (Output Image item is selected and then the image would be transfer)
model	Strings	Inference node import the model's filename
tpu	Strings	TPU node be used by inference node

The screenshot displays the TensorFlow Lite Studio interface. At the top, a workflow is visualized with four nodes connected in sequence: 'Start Demo' (light blue), 'URL Camera 0' (orange), 'Object Detection' (light blue), and 'msg' (green). The 'Object Detection' node is marked with a green dot and the text 'Running'. Below the workflow, the console output for the 'msg' node is shown as a JSON object:

```
msg : Object
{
  "object": {
    "payload": {
      "objects": [
        {
          "bbox": [
            79.41669940948486,
            359.08682584762573,
            109.76783752441406,
            417.1435832977295
          ],
          "className": "person",
          "score": 0.7890625
        },
        {
          "bbox": [
            79.41669940948486,
            359.08682584762573,
            109.76783752441406,
            417.1435832977295
          ],
          "className": "person",
          "score": 0.7890625
        }
      ]
    }
  }
}
```

i7 Result

- Node Properties:

1. Group: Select which group on dashboard and show the widgets
2. Size : sets the basic geometry of the grid layout in pixels
3. Resolution : Reconfig the resolution of frames
4. Label : Show the topic on the dashboard
5. Name : Config and show the name on the node

Edit result node

Delete Cancel Done

Properties

Group [List] Default

Size auto

Resolution 720p

Label

Name

- Output

Reference the following image about the node outputs:

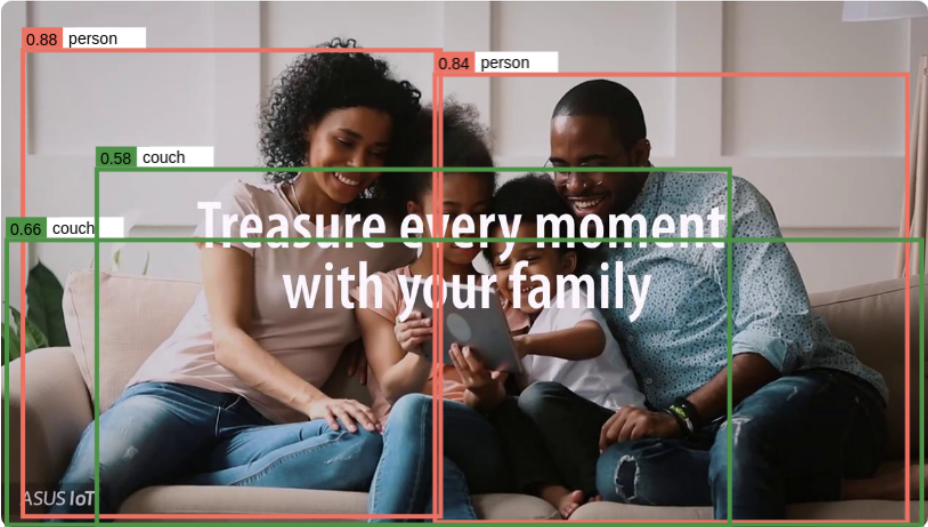
1. Default mapping to Group
2. Size set "auto" and the video source is 720p
3. Label mapping to the Label config of properties
4. The colors of bounding-box are classified with people and not people:
 - people : Orange
 - not people : Blue

5. The right filed (Total): show the quantity of classification object

Result Node

Model Name :
edgetpu/test_data/efficientnet-edgetpu-M_quant_embadding_extractor_edgetpu.tflite

Resolution: 1280*720 Inference Time: 150 fps Total Process Time: 26 fps



0.88 person 0.84 person 0.58 couch 0.66 couch

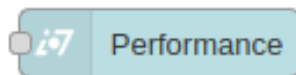
Treasure every moment
with your family

ASUS IoT

Result

- person 2
- couch 2

• Performance node



Show the following system information:

1. The temperature of edge TPUs
2. CPU usage
3. RAM usage

- Node Properties:

1. Group: Select which group on dashboard and show the widgets
2. Size : sets the basic geometry of the grid layout in pixels

3. Name : Config and show the name on the node

Edit performance node

Delete Cancel Done

Properties

Group [List] Default1

Size auto

Name

- Output

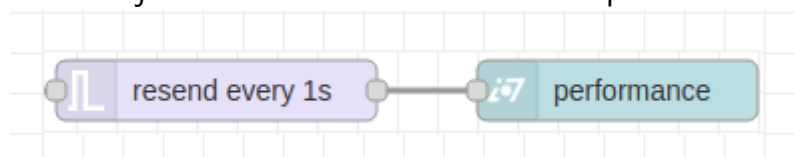
1. Default1 mapping to Group

2. The following informaion : CPU usage, RAM usage and TPU temperature

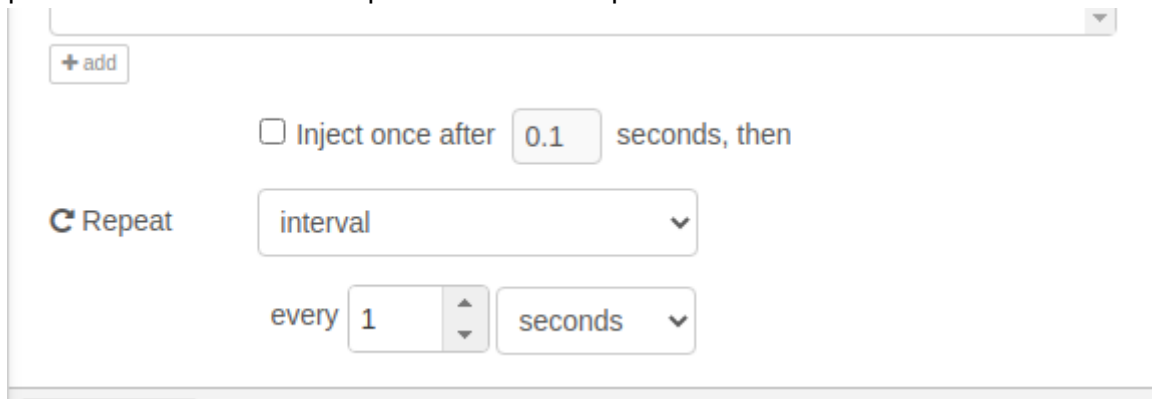


- Exmample flow

Get a "inject node" and then connect to performance node:



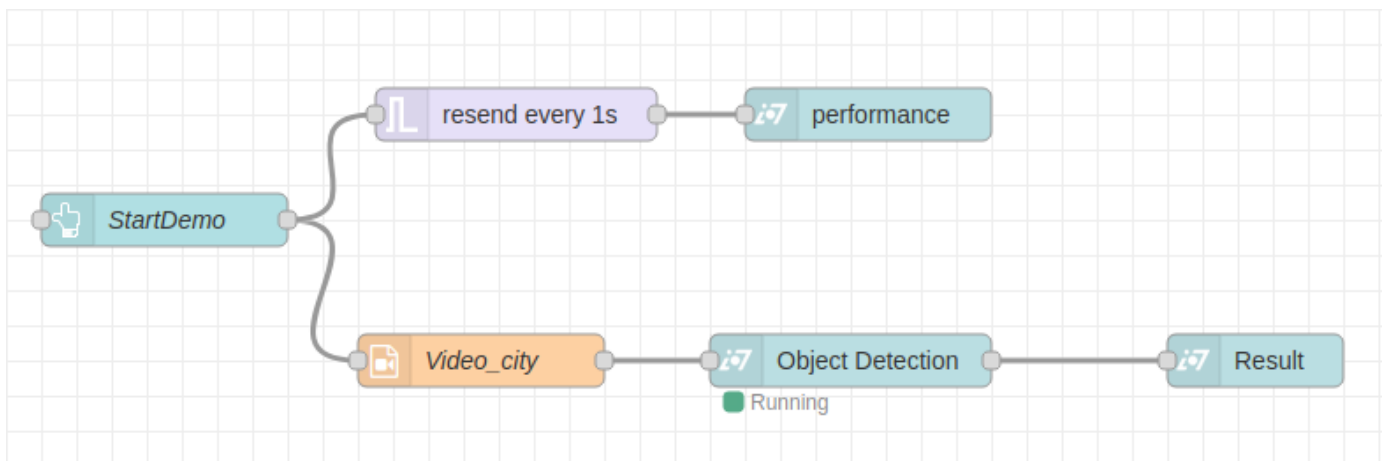
Set the "Repeat" filed of "inject node" to "interval" every 1 seconds and then the performance node will update the result per second



Configuration for the inject node:

- ☐ Inject once after 0.1 seconds, then
- Repeat: interval
- every 1 seconds

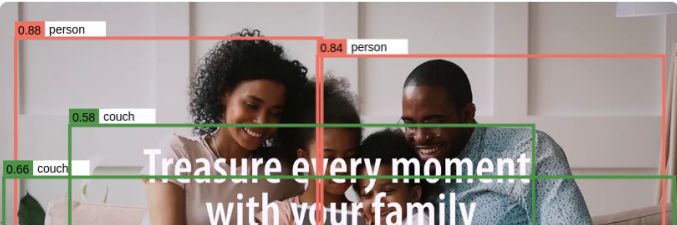
node-red-contrib-edgetpu-inference Example Flow



Result Node

Model Name :
edgetpu/test_data/efficientnet-edgetpu-M_quant_embedding_extractor_edgetpu.tflite

Resolution: 1280*720 Inference Time: 150 fps Total Process Time: 26 fps



Treasure every moment
with your family

0.88 person
0.84 person
0.58 couch
0.66 couch

Result

- person 2
- couch 2

Performance Node

CPU : 67%

High 100%
Low 60s 0s

RAM : 37%

High 100%
Low 60s 0s

```
[
  {
    "id": "484a4066.57495",
    "type": "tab",
    "label": "result flow",
    "disabled": false,
    "info": ""
  },
  {
    "id": "b62b54bc.47f5b8",
    "type": "function",
    "z": "484a4066.57495",
    "name": "Video_city",
    "func": "\nmsg.payload=\`./node_modules/node-red-contrib-edgetpu-inference/tes
    "outputs": 1,
    "noerr": 0,
    "initialize": "",
    "finalize": "",
    "x": 330,
    "y": 460,
    "wires": [
      [
        "9ddba8c7.d7aa58"
      ]
    ],
    "icon": "font-awesome/fa-file-video-o"
  },
  {
    "id": "9ddba8c7.d7aa58",
    "type": "SZ Object Detection",
    "z": "484a4066.57495",
    "name": "",
    "intype": "2",
    "tputype": "0",
    "tpunum": "0",
    "modelpath": "./node_modules/node-red-contrib-edgetpu-inference/test_data/ssd_
    "labelpath": "./node_modules/node-red-contrib-edgetpu-inference/test_data/coco
    "threshold": "0.5",
    "topk": "5",
    "keepratio": "0",
    "relativecoord": "0",
    "resample": "0",
    "outimage": true,
    "loop": true,
    "x": 540,
    "y": 460,
    "wires": [
      [
        "eb2c99f7.87bd78"
      ]
    ]
  },
  {
    "id": "eb2c99f7.87bd78",
```

```

        "type": "ui_result",
        "z": "484a4066.57495",
        "group": "365bb82b.fd8d18",
        "name": "",
        "title": "Label",
        "order": 1,
        "resolution": "1",
        "width": "21",
        "height": "14",
        "x": 770,
        "y": 460,
        "wires": []
    },
    {
        "id": "d3960755.7f39d8",
        "type": "ui_performance",
        "z": "484a4066.57495",
        "group": "365bb82b.fd8d18",
        "name": "",
        "title": "",
        "order": 2,
        "width": "9",
        "height": "14",
        "x": 550,
        "y": 300,
        "wires": []
    },
    {
        "id": "24bc2238.e885be",
        "type": "ui_button",
        "z": "484a4066.57495",
        "name": "StartDemo",
        "group": "365bb82b.fd8d18",
        "order": 1,
        "width": 0,
        "height": 0,
        "passthru": false,
        "label": "StartDemo",
        "tooltip": "",
        "color": "",
        "bgcolor": "",
        "icon": "",
        "payload": "",
        "payloadType": "str",
        "topic": "",
        "x": 150,
        "y": 380,
        "wires": [
            [
                "b62b54bc.47f5b8",
                "44161e7.d23cbe"
            ]
        ]
    },
    {
        {

```

```

    "id": "44161e7.d23cbe",
    "type": "trigger",
    "z": "484a4066.57495",
    "name": "",
    "op1": "1",
    "op2": "0",
    "op1type": "str",
    "op2type": "str",
    "duration": "-1",
    "extend": false,
    "units": "s",
    "reset": "",
    "bytopic": "all",
    "topic": "topic",
    "outputs": 1,
    "x": 350,
    "y": 320,
    "wires": [
      [
        "d3960755.7f39d8"
      ]
    ]
  },
  {
    "id": "365bb82b.fd8d18",
    "type": "ui_group",
    "z": "",
    "name": "Default1",
    "tab": "36b75a6f.51b2c6",
    "order": 3,
    "disp": true,
    "width": "30",
    "collapse": false
  },
  {
    "id": "36b75a6f.51b2c6",
    "type": "ui_tab",
    "z": "",
    "name": "List",
    "icon": "dashboard"
  }
]

```

