Algorithms Final Cheat Sheet

Processes and DB

Probability of any success = $p*(1-p)^n-1$... $p=\Theta(1/n)$... t=t; prob of fail $\leq 1/e$... t=en*cln(n); prob of fail $\leq n^{-c}$... How long until succeeding at least once: n^{-1}

The Union Bound

Prob
$$\left[\bigcup_{i=1}^{\infty} F_i\right] <= \sum_{n=1}^{\infty} Prob[F_i]$$

Verifying AB=C

 $B\bar{r}->A(B\bar{r})$ and $C\bar{r}$. if $A(B\bar{r})!=C\bar{r}$ then AB!=C

Principle of Deferred Decisions

If AB! = C and \bar{r} is chosen uniformly at random with r_n at 0-1 then $\operatorname{Prob}(AB\bar{r} = C\bar{r}) <= 1/2$

Law of Total Probability

Let $E_1...E_n$ be mutually disjoint events in the sample space Ω and let $\bigcup_{i=1}^n E_i$ then $\sum_{i=1}^n Prob[B|E_i]Prob[E_i]$

Repeated trials increase the runtime to $\Theta(kn^2)$ If it returns false, then it this is right, but if it returns true, then it returns so with some probability of mistake.

Median Value

$$\sum_{j=1}^{\infty} j * Prob[X=j] = (n+1)/2$$
 while Prob $[X=j] = 1/n$

To take exactly j steps: Prob $[X = j] = (1 - p)^{j-1} p \ 1/p$ for the first success

Median Value

Linearity of Expectation: Given 2 random vars X and Y in the same probability space, E[X+Y]=E[X]+E[Y]

Memoryless guessing

Expected correct: 1, independent of n

Memory guessing

 $H(n) = \Theta(log(n))$ [harmonic series]

Coupon collection:

 $E[X_j] = n/(n-j); n$ = number of; j = collected; (n-j)/n of getting a new one $E[X] = nH(n) = \Theta(nlog(n))$

Conditional Probability

$$E[X|\alpha] = \sum_{j=0}^{\infty} j * \text{Prob } [X = j|\alpha]$$

Max 3-SAT

There is a randomized algo with polynomial expected run time that is guaranteed to produce a truth assignment satisfying at least a 7/8 fraction of all clauses. We would need 8k trials to get the satisfying assignment.

```
1: function Select(S, k)
       a_i \leftarrow random varinS
       for each element a_i of S do
3:
           S^-.append(a_i) if a_i < a_i
4:
           S^+.append(a_i) if a_i > a_i
5:
       end for
6:
       if S^- = k - 1 then
7:
8:
           return a_i
       else if S^- > k then
           Select(S^-, k)
10:
11:
           Select(S^+, k - 1 - |S^-|)
12:
13:
       end if
14: end function
```

Quicksort ExpectedComparisons

 $2nln(n) + O(n), \Omega(nlogn)$

Uniform

Prob [h(x) = i] = 1/m for all x and all i

Universal

Prob [h(x) = h(y)] = 1/m for all x! = y

Near-universal

Prob $[h(x) = h(y)] \le 2/m$ for all x! = y; $\mathbb{E}[chainLen] \le 2 * \alpha$; Runtime: $\Theta(1 + \alpha)$

k-uniform

Load Factor

 $\alpha = n/m$

Balanced Binary Tree Search

 $O(1 + \log(chainLen))$ with any hash $O(1 + \log(\alpha))$ for uniform

Recursively Hash

 $O(log_m n)$

Expected Search w/ binary probe

O(1)

Formula Satisfiability/SAT

$$(a \vee b \vee c \vee \bar{d}) \mathrel{\mathsf{<=>}} ((b \wedge \bar{c}) \vee \overline{(\bar{a} \mathrel{\mathsf{=>}} d)} \vee (c \neq a \wedge b))$$

CNF

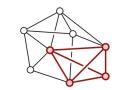
conjunction/AND of several clauses which use OR inside these clauses.

3CNF

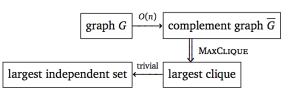
cnf with exactly 3 literals per clause

Maximum Independent Set (from 3Sat)

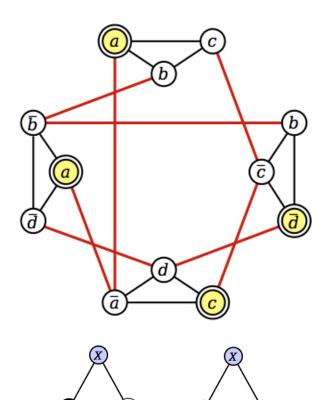
input is a simple, unweighted graph, get the size of the largest/smallest subgraph Make the formula into a graph or vice versa, if it has an independent set of size k, its possible Any graph has an edge-complement with the same vertices but the opposite set of edges if its not an edge in G. Its independent in G if and only if the same vertices define a clique in \overline{G} (a complete graph). The largest independent is thus the largest clique in the compliment of the graph.

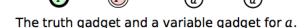


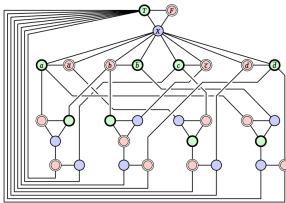
A graph with maximum clique size 4.



3Color [From 3SAT]







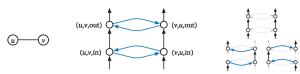
A 3-colorable graph derived from the satisfiable 3CNF formula $(a \lor b \lor c) \land (b \lor \bar{c} \lor \bar{d}) \land (\bar{a} \lor c \lor d) \land (a \lor \bar{b} \lor \bar{d})$

Truth gadget: T, F, and X for true/false/other, variable

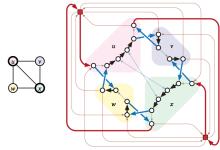
gadget for variable a connecting and \bar{a} which must be opposite bools. Clause gadget joining three literal nodes to node T in the truth gadget using give new unlabeled nodes and ten edges.

Hamiltonian Cycle [From Vertex Cover]

For each vertex u, all the edge gadgets are connected in H into a single directed path, a vertex chain. H has d-1 additional edges for each i. H also contains k cover vertices, 1-k, with a directed edge to the first vertex in each vertex chain and a directed edge from the last vertex in each vertex chain. Start at cover vertex 1 and traverse vertex chain for vu_2 , then visit cover vertex 2 and so on and so forth before returning to 1. If v is a part of the vertex cover, follow the edge from (u_i, v, in) to (u_i, v, out) , else, detour from $(u_i, v, in) > (v, u_i, in) > (v, u_i, out) > (u_i, v, out)$. G contains a vertex cover of size K if and only if H contains a Hamiltonian cycle



An edge gadget for uv and its only possible intersections with a Hamiltonian cycle



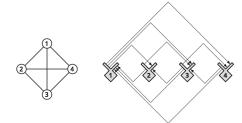
A vertex cover $\{u,x\}$ in G and the corresponding Hamiltonian cycle in H.

Subset Sum

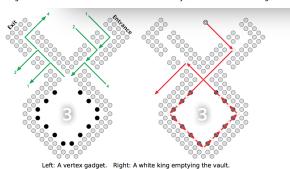
number edges from 0 to m-1; set X contains the integer $b_i:=f^i$ for each edge i, and the integer $a_v:=f^m+\sum_{i\delta v}4^i$ where $\delta(v)$ is the set of edges that have v as an endpoint. [X is a (m+1) digit number written in base 4). The mth digit is 1 if vertex, 0 otherwise. $t:=k*4^m+\sum_{i=0}^{m-1}2*4^i$

Draughts

White can capture a certain number of black pieces in a single move if and only if G has a Hamiltonian cycle. Replace edges uv with u->v and v->u. If there is a path you can capture them all, if there isn't, you can capture at most 1/2 of them.



A high level view of the reduction from Hamiltonian cycle to international draughts.



Gray circles are black pieces that cannot be captured.

LIS -> DAG

Every number will be a node.Number-node A has an edge to number-node B iff 1. B comes after A in the sequence, 2. B is greater than A in value. There's a special node end. Every node has an edge to end. Every path on this graph is a valid increasing subsequence. The problem of finding the LIS is now the problem of finding the longest path on this graph. Apply DAG.

Max Flows and Min Cuts



Blind Guess

1: **function** GuessMinCut(G)

Repeated Guessing

```
1: function KargerMinCut(G)
        mink \leftarrow \infty
 3:
        for i \leftarrow 1. N do
 4:
            X \leftarrow \text{GuessMinCut}(G)
            if |X| < mink then
 5:
 6:
                mink \leftarrow |X|
                minX \leftarrow X
 7:
            end if
 8:
        end for
 9:
10:
        return minX
11: end function
```

Set $N=c\binom{n}{2}\ln n$ for some constant c. $P(n)\geq 1-\frac{1}{n^c}.$ KargerminCut computes the min cut of any n-node graph with high probability in $O(n^4\log n)$ time.

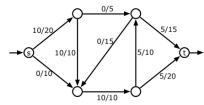
Not-So-Blindly Guessing

```
1: function Contract(G, m)
         for i \leftarrow n, m do
             pick a random edge e in G
  3:
             G \leftarrow G/e
         end for
  5:
  6: end function
  7: function BetterGuess(G)
         if G has more than 8 vertices then
  8:
             G_1 \leftarrow \text{Contract}(G, n/\sqrt{2} + 1)
  9:
             G_2 \leftarrow \text{Contract}(G, n/\sqrt{2} + 1)
 10:
             X_1 \leftarrow \text{BetterGuess}(G_1)
 11:
             X_2 \leftarrow \text{BetterGuess}(G_2)
 12:
             return min(X_1, X_2)
 13:
         else
 14:
             use brute force
 15:
         end if
 17: end function
P(n) \ge 1/\log n. The running time is O(n^2 \log n).
```

Flows

A flow is a function f that satisfies the conservation constraint at every vertex v: the total flow into v is equal to the total flow out of v.

A flow f is feasible if $f(e) \le c(e)$ for each edge e. A flow saturates edge e if f(e) = f(c), and avoids edge e if f(e) = 0.

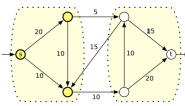


An (s, t)-flow with value 10. Each edge is labeled with its flow/capacity.

Cuts

A *cut* is a partition of the vertices into disjoint subsets S and T - meaning $S \cup T = V$ and $S \cap T = \emptyset$ - where $s \in S$ and $t \in T$.

If we have a capacity function c, the capacity of a cut is the sum of the capacities of the edges that start in S and end in T. The definition is asymmetric; edges that start in T and end in S are unimportant. The min-cut problem is to compute a cut whose capacity is as large as possible.

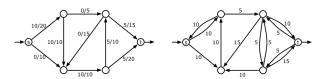


An (s, t)-cut with capacity 15. Each edge is labeled with its capacity.

Theorem 1 (Maxflow Mincut Theorem) In any flow network, the value of the maximum flow is equal to the capacity of the minimum cut.

Residual Capacity

$$c_f(u \to v) = \begin{cases} c(u \to v) - f(u \to v) & \text{if } u \to v \in E \\ f(v \to u) & \text{if } v \to u \in E \\ 0 & \text{otherwise} \end{cases}$$



A flow f in a weighted graph G and the corresponding residual graph G_f .

Augmenting Paths

Suppose there is a path $s=v_0\to v_1\to\cdots\to v_r$ in the residual graph G_f . This is an augmenting path. Let $F=\min_i c_f(v_i\to v_{i+1})$ denote the maximum amount of flow that we can push through the augmenting path in G_f . We can augment the flow into a new flow function f':

$$f'(u \to v) = \begin{cases} f(u \to v) + F & \text{if } u \to v \in s \\ f(u \to v) - F & \text{if } v \to u \in s \\ f(u \to v) & \text{otherwise} \end{cases}$$

Ford-Fulkerson

Starting with the zero flow, repeatedly augment the flow along any path from s to t in the residual graph, until there is no such path.

Further Work

The fastest known maximum flow algorithm, announced by James Orlin in 2012, runs in O(VE) time.

Flow/Cut Applications Edge-Disjoint Paths

A set of paths in G is edge-disjoint if each edge in G appears in at most one of the paths; several edge-disjoint paths may pass through the same vertex, however. Assign each edge capacity 1. The number of edge-disjoint paths is exactly equal to the value of the flow. Using Orlin's algorithm is overkill; the the maximum flow has value at most V-1, so Ford-Fulkerson's original augmenting path algorithm also runs in $O(|f^*|E) = O(VE)$ time.

Vertex Capacities and Vertex-Disjoint Paths

If we require the total flow into (and out of) any vertex v other than s and t is at most some value c(v), we transform the input into a new graph. We replace each vertex v with two vertices v_{in} and v_{out} , connected by an edge $v_{in} \rightarrow v_{out}$ with capacity c(v), and then replace

every directed edge $u \to v$ with the edge $u_{out} \to v_{in}$ (keeping the same capacity).

Computing the maximum number of *vertex-disjoint* paths from s to t in any directed graph simply involves giving every vertex capacity 1, and computing a maximum flow. SATandCNFSAT

NP-Hardness

Definition 2 P is the set of decision problems that can be solved in polynomial time. Intuitively, P is the set of problems that can be solved quickly.

Definition 3 NP is the set of decision problems with the following property: if the answer is Yes, then there is a proof of this fact that can be checked in polynomial time. Intuitively, NP is the set of decision problems where we can verify a Yes answer quickly if we have the solution in front of us.

Definition 4 co-NP is essentially the opposite of NP. If the answer to a problem in co-NP is No, then there is a proof of this fact that can be checked in polynomial time.

Every decision problem in P is also in NP and also in co-NP.

Definition 5 A problem Π is NP-hard if a polynomial-time algorithm for Π would imply a polynomial-time algorithm for every problem in NP.

Definition 6 A problem Π is NP-complete if it is both NP-hard and an element of NP.

Theorem 7 (Cook-Levin Theorem) *Circuit satisfiability is NP-complete.*

To prove that problem A is NP-hard, reduce a known NP-hard problem to A.

Definition 8 A many-one reduction from one language $L' \subseteq \Sigma^*$ is a function $f: \Sigma^* \to \Sigma^*$ such that $x \in L'$ iff $f(x) \in L$. A language L is NP-hard iff, for any language $L' \in NP$, there is a many-one reduction from L' to L that can be computed in polynomial time.

NP-Hard Problems

- SAT
- 3SAT
- Maximum Independent Set: find the size of the largest subset of the vertices of a graph with no edges between them
- Clique: Compute the number of nodes in its largest complete subgraph
- Vertex Cover: Smallest set of vertices that touch every edge in the graph
- Graph Coloring: Find the smallest possible number of colors in a legal coloring such that every edge has two different colors at its endpoints
- Hamiltonian Cycle: find a cycle that visits each vertex in a graph exactly once
- Subset Sum: Given a set X of positive integers and an integer t, determine whether X has a subset whose elements sum to t
- Planar Circuit SAT: Given a boolean circuit that can be embedded in the plane so that no two wires cross, is there an input that makes the circuit output True
- Not All Equal 3SAT: Given a 3CNF formula, is there an assignment of values to the variables so

- that every clause contains at least one True literal *and* at least one False literal?
- Exact 3-Dimensional Matching: Given a set S and a collection of three-element subsets of S, called *triples*, is there a sub-collection of disjoint triples that exactly cover S?
- Partition: Given a set S of n integers, are there subsets A and B such that A ∪ B = S, A ∩ B = ∅, and ∑_{a∈A} a = ∑_{b∈B} b?
 3Partition: Given a set S of 3n integers, can it be
- 3Partition: Given a set *S* of 3n integers, can it be partitioned into *n* disjoint three-element subsets, such that every subset has exactly the same sum?
- Set Cover: Given a collection of sets $\mathcal{S} = \{S_1, S_2, \dots, S_m\}, \text{ find the smallest}$ sub-collection of S_i 's that contains all the elements of $\bigcup_i S_i$
- Hitting Set: Given a collection of sets $S = \{S_1, S_2, \dots, S_m\}$, find the minimum number of elements of $\bigcup_i S_i$ that hit every set in S
- Hamiltonian Path: Given a graph G, is there a path in G that visits every vertex exactly once?
- Longest Path: Given a non-negatively weighted graph G and two vertices u and v, what is the longest simple path from u to v in the graph? A path is simple if it visits each vertex at most once.
- Steiner Tree: Given a weighted, undirected graph G with some of the vertices marked, what is the minimum-weight subtree of G that contains every marked vertex?