# Design and Analysis of Algorithms: Homework #2

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Suppose we are given an array A[1..n] with the special property that  $A[1] \ge A[2]$  and  $A[n-1] \le A[n]$ . We say that an element A[x] is a *local minimum* if it is less than or equal to both its neighbors, or more formally, if  $A[x-1] \ge A[x]$  and  $A[x] \le A[x+1]$ . For example, there are six local minima in the following array:



Table 1: Example array

We can obviously find a local minimum in O(n) time by scanning through the array. Describe and analyze an algorithm that finds a local minimum in  $O(\log n)$  time. [Hint: With the given boundary conditions, the array **must** have at least one local minimum. Why?]

# **Solution**

## Algorithm 1 Algorithm for finding a local minimum

```
1: function FINDLOCALMINIMUM(A[1..n])
      median \leftarrow n/2
      if A[median] > A[median - 1] then
3:
          return FINDLOCALMINIMUM(A[1..n/2])
4:
      else if A[median] > A[median + 1] then
5:
          return FINDLOCALMINIMUM(A[n/2..n])
6:
       else
7:
8:
          return median
       end if
9:
10: end function
```

Given the boundary conditions, the array **must** have at least one local minimum. To prove this, we can assume that the array has no local minimum. This means that the array must be either always increase or always decrease throughout the array; formally,  $\forall x \in \{1, \dots, n\}, A[x] > A[x-1]$  or  $\forall x \in \{1, \dots, n\}, A[x] > A[x+1]$ . However since  $A[1] \geq A[2]$  and  $A[n-1] \leq A[n]$ , this cannot be true; specifically it must *start* by decreasing such that  $A[x-1] \geq A[x]$  and then, at some point, start increasing, such that  $A[x] \leq A[x+1]$ . This point is the local minimum, since  $A[x-1] \geq A[x] \leq A[x+1]$ .

Given some median point, m, we can detect whether our array is increasing or decreasing at that point by examining the neighboring points. If the array is increasing,  $A[m] \ge A[m-1]$ . We know that the array starts by decreasing, so it must have started increasing since then; thus we can narrow our search for the local minimum to the first half of the array.

If the array is decreasing,  $A[m] \ge A[m+1]$ . Since the array ends with an increase, we know it must start increasing at some point after the median; thus we can narrow our search to the last half of the array.

If neither of these options is true, we must be at either a local maximum or minimum. If we are at a local maximum, then  $A[m] \ge A[m-1]$ , so we simply search the first half of the array; if we are at a local minimum,  $A[m] \ne A[m+1]$  and  $A[m] \ne A[m-1]$ , so we reach our final branch and simply return m.

Suppose we are given two sorted arrays A[1..n] and B[1..n] and an integer k. Describe an algorithm to find the kth smallest element in the union of A and B in  $\Theta(\log n)$  time. For example, if k=1, your algorithm should return the smallest element of  $A \cup B$ ; if k=n, your algorithm should return the median of  $A \cup B$ . You can assume that the arrays contain no duplicate elements. [Hint: First solve the special case k=n.]

## **Solution**

### **Algorithm 2** Algorithm for finding the *k*th smallest element in a union

```
1: function FINDKSMALLEST(A[1..m], B[1..n], k)
       if k = 1 then
           if m = 0 then
3:
               return B[1]
           else if n = 0 then
               return A[1]
6:
7:
           else
               return min(A[1], B[1])
8:
           end if
9:
       else
10:
           mid \leftarrow \left| \frac{k}{2} \right|
11:
           if mid \ge m + 1 then
12:
               FINDKSMALLEST(A, B[mid + 1..n], k - mid)
13:
           else if mid > n + 1 then
14:
               FINDKSMALLEST(A[mid + 1..m], B, k - mid)
15:
           else if A[mid] < B[mid] then
16:
               FINDKSMALLEST(A[mid + 1..m], B, k - mid)
17:
           else
18:
               FINDKSMALLEST(A, B[mid + 1..n], k - mid)
19:
           end if
20:
       end if
22: end function
```

As an example, we will run through the algorithm with  $A = \{1, 3, 5, 7\}$  and  $B = \{2, 4, 6, 8\}$ , with k = 4.

Since  $k \neq 1$ , we determine a middle element,  $mid = \left\lfloor \frac{k}{2} \right\rfloor = 2$ . Since mid < m+1 and mid < n+1, we compare the second element of each array. A has a smaller element, since A[2] = 3 < B[2] = 4, so we recurse with a new  $A = \{5, 7\}$ , B remaining the same, and k = k - mid = 4 - 2 = 2.

k is still not 1, so we determine our middle element,  $mid = \left\lfloor \frac{k}{2} \right\rfloor = 1$ . Since mid < m+1 and mid < n+1, we compare the first element of each array. B has a smaller element, since B[1] = 2, so we recurse with a new  $B = \{4, 6, 8\}$ , A remaining the same, and k = k - mid = 2 - 1 = 1.

Now, k = 1. Since neither A nor B are empty, we simply find the minimum of their first elements; B[1] = 4 and A[1] = 5, so we return 4, as expected.

In general, we can divide the two arrays into four sections:  $A_1$ ,  $A_2$ ,  $B_1$ , and  $B_2$ , such that  $A_1$  and  $B_1$  have length  $\frac{k}{2}$ . Since we are looking for the kth smallest element, there are k-1 smaller elements we wish to discard. Let us define  $A_{1_M}$  to be the largest element in  $A_1$  and  $A_1$  to be the largest element in  $A_1$ .

Let us first suppose that the kth smallest element is in either  $A_1$  or  $B_1$ ; without loss of generality, suppose it is in  $A_1$ . Then, since  $|A_1 \cup B_1| = k$ , we know that up to  $\frac{k}{2} - 1$  of the k - 1 smaller elements are also in  $A_1$ . Therefore, there must be at least  $\frac{k}{2}$  of the k - 1 smaller elements in  $B_1$ . By definition, the kth smallest element will be larger than any of the k - 1 smaller elements, so  $A_{1_M} > B_{1_M}$ , and our algorithm can safely remove  $B_1$ , as we know it contains only elements that are smaller than the kth smallest element.

Alternatively, we can suppose that the kth smallest element is in either  $A_2$  or  $B_2$ ; without loss of generality, suppose it is in  $A_2$ . Then,  $A_1$  must contain  $\frac{k}{2}$  of the k-1 smaller elements, since  $A_1$  and  $B_1$  contain  $\frac{k}{2}$  elements. The opposite array  $(B_1)$  must therefore contain fewer than  $\frac{k}{2}$  of the k-1 smaller elements, and will therefore have its largest element  $B_{1_M}$  be greater than  $A_{1_M}$ ; our algorithm then safely removes  $A_1$ , as we know it contains only elements that are smaller than the kth smallest element.

Since we have discarded elements smaller than the kth smallest, we update our value of k, removing the number of elements we discarded -  $\frac{k}{2}$ . We continue in this manner, discarding elements when possible, until we have reached our trivial base case, where k=1 and we can simply find the minimal element of  $A \cup B$ .

For this problem, a *subtree* of a binary tree means any connected subgraph. A binary tree is *complete* if every internal node has two children, and every leaf has exactly the same depth. Describe and analyze a recursive algorithm to compute the *largest complete subtree* of a given binary tree. Your algorithm should return the root and the depth of this subtree.

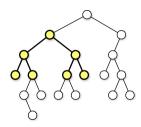


Figure 1: The largest complete subtree of this binary tree has depth 2.

#### Solution

## Algorithm 3 Algorithm for finding the largest complete subtree

```
1: function LargestCompleteSubtreeAt(node)
2:
       if node.left exists and node.right exists then
           childDepth \leftarrow \text{the minimum of LargestCompleteSubtreeAt}(node.left) and LargestCompleteSub-
3:
   TREEAt(node.right)
           return 1 + childDepth
4:
       else
5:
           return 0
6:
       end if
7:
8: end function
   function Largest Complete Subtree At(root)
       rootDepth \leftarrow LargestCompleteSubtreeAt(root)
10:
       if node.left exists then
11:
12:
           leftDepth, leftNode \leftarrow \texttt{LargestCompleteSubtree}(node.left)
       end if
13:
       if node.right exists then
14:
           rightDepth, rightNode \leftarrow \texttt{LargestCompleteSubtree}(node.left)
15:
16:
       end if
       maxDepth \leftarrow \text{the maximum of } rootDepth, leftDepth, \text{ and } rightDepth
17:
       if maxDepth = rootDepth then
18:
           return maxDepth, root
19:
       else if maxDepth = leftDepth then
20:
           return \ maxDepth, leftNode
21:
       else
22:
           return maxDepth, rightNode
23:
       end if
25: end function
```

Our first function exists to determine the largest complete subtree beginning at a particular node. This way, we can separate our concerns to aid with recursion. Our second function repeatedly calls the first function to determine

the largest complete subtree at any position in the tree; we do this by recursing through it and finding the largest complete subtree starting from every node in the tree.

The run-time of Largest Complete Subtree At has a recurrence of  $T_1(n) = 2T_1(\frac{n}{2}) + 1$ . Using the Master Theorem, we can solve this recurrence:

$$a = 2$$

$$f(\frac{n}{b}) = 1$$

$$f(n) = 1$$

$$af(\frac{n}{b}) = Kf(n)$$

$$2 \times 1 = K \times 1$$

$$K = 2$$

$$(1)$$

Since K > 1, the Master Theorem states that  $T_1(n) = \Theta(n^{\log_b a})$ ; with b = 2 and a = 2, we get  $T_1(n) = \Theta(n^{\log_2 2})$ , which trivially reduces to  $T_1(n) = \Theta(n^1) = \Theta(n)$ .

The unoptimized run-time of Largest Complete Subtree has a recurrence of  $T_2(n) = 2T_2(\frac{n}{2}) + T_1(n)$ . Using the Master Theorem, we get:

$$a = 2$$

$$f(\frac{n}{b}) = \frac{n}{2}$$

$$f(n) = n$$

$$af(\frac{n}{b}) = Kf(n)$$

$$2\frac{n}{2} = K \times n$$

$$K = 1$$
(2)

Since K=1, the Master Theorem states that  $T_2(n)=\Theta(f(n)\log_b n)$ , so  $T_2(n)=\Theta(n\log_2 n)$ .

This could easily be optimized with memoization; we can cache the results of Largest Complete Subtree At. In this case, no repeated calculations of Largest Complete Subtree At occur, so rather than running in  $\Theta(n \log_2 n)$ , it would run in  $\Theta(n)$ .

- (a) Let A[1..m] and B[1..n] be two arbitrary arrays. A common subsequence of A and B is both a subsequence of A and a subsequence of B. Give a simple recursive definition for the function lcs(A,B), which gives the length of the *longest* common subsequence of A and B.
- (b) Call a sequence X[1..n] oscillating if X[i] < X[i+1] for all even i, and X[i] > X[i+1] for all odd i. Give a simple recursive definition for the function los(A), which gives the length of the longest oscillating subsequence of an arbitrary array A of integers.
- (c) Call a sequence X[1..n] accelerating if  $2 \times X[i] < X[i-1] + X[i+1]$  for all i. Give a simple recursive definition for the function lxs(A), which gives the length of the longest accelerating subsequence of an arbitrary array A of integers.

#### Solution

#### Part A

# Algorithm 4 Algorithm for finding the length of the longest common subsequence

```
1: function LCS(A[1..m], B[1..n])
        if m = 0 or n = 0 then
            return 0
 3:
        else if A[1] \neq B[1] then
 4:
            a \leftarrow LCS(A, B[2..n])
 5:
 6:
       else
 7:
            while a < m and a < n and A[a] = B[a] do
 8:
                a \leftarrow a + 1
 9:
10:
            end while
            a \leftarrow the maximum of a and LCS(A, B[a..n])
11:
        end if
12:
        b \leftarrow \mathsf{LCS}(A[2..m], B)
13:
        return the maximum of a and b
15: end function
```

## Part B

Algorithm 5 Algorithm for finding the length of the longest oscillating subsequence

```
1: function LOS(X[1..n])
       if n \leq 1 then
           return n
3:
       else
4:
           i \leftarrow 1
5:
           while i + 1 < n do
               if i is even then
7:
                   if X[i] \geq X[i+1] then
8:
                       break
9:
                   end if
10:
               else
11:
                   if X[i] \leq X[i+1] then
12:
                       break
13:
                   end if
14:
               end if
15:
               i \leftarrow i+1
16:
           end while
17:
           return the max of i and LOS(X[2..n])
18:
       end if
19:
20: end function
```

# Part C

Algorithm 6 Algorithm for finding the length of the longest accelerating subsequence

```
1: function LXS(X[1..n])
       if n \leq 2 then
2:
           return n
3:
       else
4:
           i \leftarrow 2
5:
           while i < n do
6:
               if 2 \times X[i] \ge X[i-1] + X[i+1] then
7:
                   break
8:
               end if
9:
               i \leftarrow i + 1
10:
           end while
11:
           return the max of i and LXS(X[2..n])
12:
       end if
14: end function
```