Design and Analysis of Algorithms: Homework #2

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Problem 1

Suppose we are given an array A[1..n] with the special property that $A[1] \ge A[2]$ and $A[n-1] \le A[n]$. We say that an element A[x] is a *local minimum* if it is less than or equal to both its neighbors, or more formally, if $A[x-1] \ge A[x]$ and $A[x] \le A[x+1]$. For example, there are six local minima in the following array:

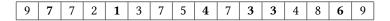


Table 1: Example array

We can obviously find a local minimum in O(n) time by scanning through the array. Describe and analyze an algorithm that finds a local minimum in $O(\log n)$ time. [Hint: With the given boundary conditions, the array **must** have at least one local minimum. Why?]

Solution

Algorithm 1 Algorithm for finding a local minimum

```
1: function FINDLOCALMINIMUM(A[1..n])
      median \leftarrow n/2
      if A[median] > A[median - 1] then
3:
          return FINDLOCALMINIMUM(A[1..n/2])
4:
      else if A[median] > A[median + 1] then
5:
          return FINDLOCALMINIMUM(A[n/2..n])
6:
       else
7:
8:
          return median
       end if
9:
10: end function
```

Given the boundary conditions, the array **must** have at least one local minimum. To prove this, we can assume that the array has no local minimum. This means that the array must be either always increase or always decrease throughout the array; formally, $\forall x \in \{1, \ldots, n\}, A[x] > A[x-1]$ or $\forall x \in \{1, \ldots, n\}, A[x] > A[x+1]$. However since $A[1] \geq A[2]$ and $A[n-1] \leq A[n]$, this cannot be true; specifically it must *start* by decreasing such that $A[x-1] \geq A[x]$ and then, at some point, stop decreasing, such that $A[x] \leq A[x+1]$. This point is the local minimum, since $A[x-1] \geq A[x] \leq A[x+1]$.

Given some median point, m, we can detect whether our array is increasing or decreasing at that point by examining the neighboring points. If the array is increasing, $A[m] \ge A[m-1]$. We know that the array starts by decreasing, so it must have started increasing since then; thus we can narrow our search for the local minimum to the first half of the array.

If the array is decreasing, $A[m] \ge A[m+1]$. Since the array ends with an increase, we know it must start increasing at some point after the median; thus we can narrow our search to the last half of the array.

If neither of these options is true, we must be at either a local maximum or minimum. If we are at a local maximum, then $A[m] \ge A[m-1]$, so we simply search the first half of the array; if we are at a local minimum, $A[m] \ne A[m+1]$ and $A[m] \ne A[m-1]$, so we reach our final branch and simply return m.

Problem 2

Suppose we are given two sorted arrays A[1..n] and B[1..n] and an integer k. Describe an algorithm to find the kth smallest element in the union of A and B in $\Theta(\log n)$ time. For example, if k=1, your algorithm should return the smallest element of $A \cup B$; if k=n, your algorithm should return the median of $A \cup B$. You can assume that the arrays contain no duplicate elements. [Hint: First solve the special case k=n.]

Solution

Algorithm 2 Algorithm for finding the *k*th smallest element in a union

```
1: function FINDKSMALLEST(A[1..m], B[1..n], k)
       if k = 1 then
           if m = 0 then
3:
               return B[1]
           else if n = 0 then
               return A[1]
6:
7:
           else
               return min(A[1], B[1])
8:
           end if
9:
       else
10:
           mid \leftarrow \left| \frac{k}{2} \right|
11:
           if mid \ge m + 1 then
12:
               FINDKSMALLEST(A, B[mid + 1..n], k - mid)
13:
           else if mid > n + 1 then
14:
               FINDKSMALLEST(A[mid + 1..m], B, k - mid)
15:
           else if A[mid] < B[mid] then
16:
               FINDKSMALLEST(A[mid + 1..m], B, k - mid)
17:
           else
18:
               FINDKSMALLEST(A, B[mid + 1..n], k - mid)
19:
           end if
20:
       end if
22: end function
```

As an example, we will run through the algorithm with $A = \{1, 3, 5, 7\}$ and $B = \{2, 4, 6, 8\}$, with k = 4.

Since $k \neq 1$, we determine a middle element, $mid = \left\lfloor \frac{k}{2} \right\rfloor = 2$. Since mid < m+1 and mid < n+1, we compare the second element of each array. A has a smaller element, since A[2] = 3 < B[2] = 4, so we recurse with a new $A = \{5, 7\}$, B remaining the same, and k = k - mid = 4 - 2 = 2.

k is still not 1, so we determine our middle element, $mid = \left\lfloor \frac{k}{2} \right\rfloor = 1$. Since mid < m+1 and mid < n+1, we compare the first element of each array. B has a smaller element, since B[1] = 2, so we recurse with a new $B = \{4, 6, 8\}$, A remaining the same, and k = k - mid = 2 - 1 = 1.

Now, k = 1. Since neither A nor B are empty, we simply find the minimum of their first elements; B[1] = 4 and A[1] = 5, so we return 4, as expected.

In general, we can divide the two arrays into four sections: A_1 , A_2 , B_1 , and B_2 , such that A_1 and B_1 have length $\frac{k}{2}$. Since we are looking for the kth smallest element, there are k-1 smaller elements we wish to discard. Let us define A_{1_M} to be the largest element in A_1 and A_1 to be the largest element in A_1 .

Let us first suppose that the kth smallest element is in either A_1 or B_1 ; without loss of generality, suppose it is in A_1 . Then, since $|A_1 \cup B_1| = k$, we know that up to $\frac{k}{2} - 1$ of the k - 1 smaller elements are also in A_1 . Therefore, there must be at least $\frac{k}{2}$ of the k - 1 smaller elements in B_1 . By definition, the kth smallest element will be larger than any of the k - 1 smaller elements, so $A_{1_M} > B_{1_M}$, and our algorithm can safely remove B_1 , as we know it contains only elements that are smaller than the kth smallest element.

Alternatively, we can suppose that the kth smallest element is in either A_2 or B_2 ; without loss of generality, suppose it is in A_2 . Then, A_1 must contain $\frac{k}{2}$ of the k-1 smaller elements, since A_1 and B_1 contain $\frac{k}{2}$ elements. The opposite array (B_1) must therefore contain fewer than $\frac{k}{2}$ of the k-1 smaller elements, and will therefore have its largest element B_{1_M} be greater than A_{1_M} ; our algorithm then safely removes A_1 , as we know it contains only elements that are smaller than the kth smallest element.

Since we have discarded elements smaller than the kth smallest, we update our value of k, removing the number of elements we discarded - $\frac{k}{2}$. We continue in this manner, discarding elements when possible, until we have reached our trivial base case, where k=1 and we can simply find the minimal element of $A \cup B$.

Problem 3

For this problem, a *subtree* of a binary tree means any connected subgraph. A binary tree is *complete* if every internal node has two children, and every leaf has exactly the same depth. Describe and analyze a recursive algorithm to compute the *largest complete subtree* of a given binary tree. Your algorithm should return the root and the depth of this subtree.

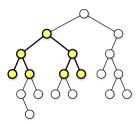


Figure 1: The largest complete subtree of this binary tree has depth 2.

Solution

Algorithm 3 Algorithm for finding the largest complete subtree

- 1: **function** LargestCompleteSubtree(root)
- 2: end function

Problem 4

- (a) Let A[1..m] and B[1..n] be two arbitrary arrays. A common subsequence of A and B is both a subsequence of A and a subsequence of B. Give a simple recursive definition for the function lcs(A,B), which gives the length of the *longest* common subsequence of A and B.
- (b) Call a sequence X[1..n] oscillating if X[i] < X[i+1] for all even i, and X[i] > X[i+1] for all odd i. Give a simple recursive definition for the function los(A), which gives the length of the longest oscillating subsequence of an arbitrary array A of integers.

(c) Call a sequence X[1..n] accelerating if $2 \times X[i] < X[i-1] + X[i+1]$ for all i. Give a simple recursive definition for the function lxs(A), which gives the length of the longest accelerating subsequence of an arbitrary array A of integers.

Solution