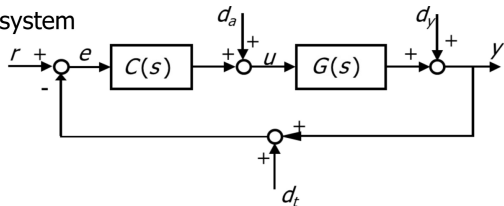


Consider the feedback control system



where

$$G(s) = \frac{2}{(1 + 0.2s)(1 + 0.1s)}, d_a(t) = \delta_a \varepsilon(t), |\delta_a| \leq 0.2$$

design the cascade controller $C(s)$ to satisfy the following requirements.

$$\begin{cases} |e_r^\infty| \leq 0.1, r(t) = t \varepsilon(t) \\ |y_{d_s}^\infty| = 0 \end{cases}$$

$$\hat{s} \leq 30\%$$

$$t_r \leq 0.3s$$

