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Machine Learning with Python-From Linear Models to Deep Learning

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Course / Unit 5. Reinforcement Learning (2 we... / Lecture 17. Reinforcement



6. Bellman Equations

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Exercises due May 3, 2023 08:59 -03 Completed

Bellman Equations



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Recall from lecture the **Bellman Equations** are

$$V^{st}\left(s
ight) \ \ = \ \ \max_{a}Q^{st}\left(s,a
ight)$$

$$Q^{st}\left(s,a
ight) \;\;=\;\; \sum_{s^{\prime}}T\left(s,a,s^{\prime}
ight)\left(R\left(s,a,s^{\prime}
ight)+\gamma V^{st}\left(s^{\prime}
ight)
ight)$$

where

- ullet the **value function** $V^{st}\left(s
 ight)$ is the expected reward from starting at state s and acting
- the **Q-function** Q^* (s,a) is the expected reward from starting at state s, then acting acting optimally afterwards.

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You have used 1 of 2 attempts

Bellman Equation for Q Function

1/1 point (graded)

As above, let there be possible actions,

from a given state wth

Let be a state that can be reached from by taking the action . Let

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