



MITx 6.86x

**Machine Learning with Python-From Linear Models to Deep Learning**[Course](#)[Progress](#)[Dates](#)[Discussion](#)[Resources](#)[Course](#) / [Unit 4. Unsupervised Learning...](#) / [Project 4: Collaborative Filtering vi](#)[< Previous](#)

## 7. Implementing EM for matrix completion

[Bookmark this page](#)

Project due Apr 26, 2023 08:59 -03 Completed

We need to update our EM algorithm a bit to deal with the fact that the observations are vectors. We use Bayes' rule to find an updated expression for the posterior probability

$$p(j|u) = P(y = j | x_{C_u}^{(u)}):$$

$$p(j|u) = \frac{p(u|j) \cdot p(j)}{p(u)} = \frac{p(u|j) \cdot p(j)}{\sum_{j=1}^K p(u|j) \cdot p(j)} = \frac{\pi_j N(x_{C_u}^{(u)}; \mu_{C_u}^{(j)}, \sigma_j^2 I_{C_u \times C_u})}{\sum_{j=1}^K \pi_j N(x_{C_u}^{(u)}; \mu_{C_u}^{(j)}, \sigma_j^2 I_{C_u \times C_u})}$$

This is the soft assignment of cluster  $j$  to data point  $u$ .

To minimize numerical instability, you will be re-implementing the E-step in the log-domain. You will calculate the values for the log of the posterior probability,  $\ell(j, u) = \log(p(j|u))$  (the log-likelihood of your E-step should include the non-log posterior).

Let  $f(u, i) = \log(\pi_i) + \log(N(x_{C_u}^{(u)}; \mu_{C_u}^{(i)}, \sigma_i^2 I_{C_u \times C_u}))$ . Then, in terms of  $f$ , the log

$$\begin{aligned} \ell(j|u) &= \log(p(j|u)) = \log\left(\frac{\pi_j N(x_{C_u}^{(u)}; \mu_{C_u}^{(j)}, \sigma_j^2 I_{C_u \times C_u})}{\sum_{j=1}^K \pi_j N(x_{C_u}^{(u)}; \mu_{C_u}^{(j)}, \sigma_j^2 I_{C_u \times C_u})}\right) \\ &= \log(\pi_j N(x_{C_u}^{(u)}; \mu_{C_u}^{(j)}, \sigma_j^2 I_{C_u \times C_u})) - \log\left(\sum_{j=1}^K \pi_j N(x_{C_u}^{(u)}; \mu_{C_u}^{(j)}, \sigma_j^2 I_{C_u \times C_u})\right) \\ &= \log(\pi_j) + \log(N(x_{C_u}^{(u)}; \mu_{C_u}^{(j)}, \sigma_j^2 I_{C_u \times C_u})) - \log\left(\sum_{j=1}^K \exp(\log(\pi_j N(x_{C_u}^{(u)}; \mu_{C_u}^{(j)}, \sigma_j^2 I_{C_u \times C_u})))\right) \\ &= f(u, j) - \log\left(\sum_{j=1}^K \exp(f(u, j))\right) \end{aligned}$$

Once we have evaluated  $p(j|u)$  in the E-step, we can proceed to the M-step. We wish to find  $\pi, \mu$ , and  $\sigma$  that maximize  $\ell(X; \theta)$ ,

First, note that, by decomposing the multivariate spherical Gaussians into univariate spherical Gaussians, before, we can write, if  $l \in C_u$ :

$$\frac{\partial}{\partial \mu_l^{(k)}} N(x^{(u)}; \mu^{(k)}, \sigma^2 I_{C_u \times C_u}) = N(x^{(u)}; \mu^{(k)}, \sigma^2 I_{C_u \times C_u}) \frac{\partial}{\partial \mu_l^{(k)}} \left( \frac{1}{\sqrt{2\pi}\sigma_{l,(k)}} \exp\left(-\frac{1}{2\sigma_{l,(k)}^2} (x_l^{(u)} - \mu_l^{(k)})^2\right) \right)$$

Following the EM algorithm's approach of maximizing a proxy likelihood function consider the following function:

where  $L(\theta)$  is the likelihood of  $\mathbf{X}$  generated by cluster  $k$  and  $\pi_k$  is the probability that a data point belongs to cluster  $k$ . The values  $\pi_k$  are the ones as we computed in the E step and they are constrained to sum to 1.

We now take the derivative of  $L(\theta)$  with respect to  $\mu_k$  to find the optimal value of  $\mu_k$ .

where  $\frac{\partial L(\theta)}{\partial \mu_k} = 0$  if  $\pi_k > 0$  and  $\frac{\partial L(\theta)}{\partial \mu_k} < 0$  if  $\pi_k = 0$ .

Setting the partial derivative equal to zero, we obtain that

We leave it as an exercise to the reader to obtain the estimates of  $\mu_k$  and  $\sigma_k^2$  for

**Implementation guidelines:**

- To debug your EM implementation, you may use the data files `test_incomplete.txt` and `test_complete.txt`. Compare your results to ours from `test_solutions.txt`.

## Implementing E-step (2)

1.0/1.0 point (graded)

In `em.py`, fill in the `estep` function so that it works with partially observed vectors `w` indicated with zeros, and perform the computations in the log domain to help with numerical

**Available Functions:** You have access to the NumPy python library as `np`, to the `Gaussian` class and to typing annotation `typing.Tuple` as `Tuple`. You also have access to `scipy.special` and `logsumexp`.

**Hint:** For this function, you will want to use `log(mixture.p[j] + 1e-16)` instead of `log(mixture.p[j])` to avoid numerical underflow

```
1 def log_gaussian(x: np.ndarray, mean: np.ndarray, var: float) -> float:
2     """Computes the log probability of vector x under a normal distribution
3     Args:
4         x: (d, ) array holding the vector's coordinates
5         mean: (d, ) mean of the gaussian
6         var: variance of the gaussian
7     Returns:
8         float: the log probability
9     """
10    d = len(x)
11    log_prob = -d / 2.0 * np.log(2 * np.pi * var)
12    log_prob -= 0.5 * ((x - mean) ** 2).sum() / var
13    return log_prob
14
15
```

Press ESC then TAB or click outside of the code editor to exit

Correct

## Test results

CORRECT

Submit

You have used 8 of 50 attempts

```
12
13     Returns:
14         GaussianMixture: the new gaussian mixture
15     """
```

Press ESC then TAB or click outside of the code editor to exit

Correct

## Test results

CORRECT

Submit

You have used 6 of 50 attempts

## Implementing run

1.0/1.0 point (graded)

In `em.py`, fill in the `run` function so that it runs the EM algorithm. As before, the convergence criterion you should use is that the improvement in the log-likelihood is less than or equal to a small absolute value. Note: do not alter data 'X' in place. Deep copy the data and return new values.

**Available Functions:** You have access to the NumPy python library as `np`, to the `GaussianMixture` class and to typing annotation `typing.Tuple` as `Tuple`. You also have access to the `estimate` and `compute_log_likelihood` functions you have just implemented

```
1 def run(X: np.ndarray, mixture: GaussianMixture,
2         post: np.ndarray) -> Tuple[GaussianMixture, np.ndarray, float]:
3     """Runs the mixture model
4
5     Args:
6         X: (n, d) array holding the data
7         post: (n, K) array holding the soft counts
8              for all components for all examples
9
10    Returns:
11        GaussianMixture: the new gaussian mixture
12        np.ndarray: (n, K) array holding the soft counts
13                   for all components for all examples
14        float: log-likelihood of the current assignment
15    """
```

Press ESC then TAB or click outside of the code editor to exit

Show all posts ▾

- ? Why is  $\log(\text{mixture.p}[j] + 1e-16)$  useful to avoid numerical underflow ?  
This is about the hint on "Implementing E-step (2)" > Hint: For this function, you will want to use  $\log(\text{mixture.p}[j] + 1e-16)$ .
- ? M-step - the condition for updating the mean (Implementation guidelines #2)  
If I understand the condition properly - it says: update the mean if  $n_{\text{hat}} > 1$  (by  $n_{\text{hat}}$  I mean the denominator).
- 💬 Efficient code in e-step with different sizes of input vectors?  
Hi, to describe the issue I will use the example from my previous post: We have an array of input vectors  $5 \times 1$ .
- ? Don't we lose too much after the observations are no longer complete vectors?  
Hi, I have a problem with catching the idea of shrinking the input vectors to only non-zero values. It reduces the dimensionality.
- 💬 Derivation of  $d/du(N, x, \sigma^2)$
- ? Partial grade on E-step?  
Does anyone got a partial grade for E-step? I got all the answer correct except the first log likelihood. I have a partial grade.
- ? How to write code for normal pdf with only observed values?
- ? Grader Issue  
Hi Staff, I'm wondering if the grader is just malfunctioning for my answer for Implementing M-step (2) question.
- ? [STAFF]: Why doesn't the Grader's "See full output" for the M-step show the input mean for e  
It would help if the Grader's "See full output" showed the input mean. I could then copy the input data into the output.
- ? Staff: Grader error?  
In m-step for the case of:  $X: \begin{bmatrix} 0.0 & 0.0 & 0.0 \\ 0.0 & 0.0 & 0.0 \\ 0.0 & 0.0 & 0.0 \\ 0.0 & 0.0 & 0.0 \\ 0.0 & 0.0 & 0.0 \\ 0.0 & 0.0 & 0.0 \end{bmatrix}$   $\begin{bmatrix} 0.13471579 & 0.0 & 0.0 \end{bmatrix}$   $\begin{bmatrix} 0.0 & 0.0 & 0.0 \end{bmatrix}$ .
- 💬 M-step: Shallow or deepcopy the mean (mixture.mu)? What about the variance?  
Shall we also deepcopy the mean in the M-step or just do shallow .copy(), i.e.  $\mu = \text{mixture.mu.copy}()$  ? Do you have any other suggestions?
- 💬 dimension and number of samples

# edX

[About](#)
[Affiliates](#)
[edX for Business](#)
[Open edX](#)
[Careers](#)
[News](#)

# Legal

# Connect

[Blog](#)

[Contact Us](#)

[Help Center](#)

[Security](#)

[Media Kit](#)



© 2023 edX LLC. All rights reserved.

深圳市恒宇博科技有限公司 [粤ICP备17044299号-2](#)