Procedural 3D Audio for AR Applications

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Abstract

This is the first paragraph

THis is the second

THird paragraph of abstract

Four paragraphs is enough I guess

Acknowledgements

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Contents

Abbreviations

ASW Apparent Source Width.

AVIL Audio Visual Immersion Lab.

BRIR Binaural Room Impulse Response.

CS Compressive Sensing.

DOA Direction of Arrival.

ERB Equivalent Rectangular Band.

HATS Head And Torso Simulator.

HOA Higher Order Ambisonics.

HRTF Head-Related Transfer Function.

IACC Inter-Aural Cross Coherence.

ILD Inter-Aural Level Difference.

ITD Inter-Aural Time Difference.

STFT Short-Time Fourier Transform.

WFS Wave Field Synthesis.

Nomenclature

$\mathbf{\Omega}_{LS}$ Vector containing directions of Loudspeakers in reproduction.

$\mathbf{\Omega}_L$ Grid of directions used for the CS algorithm.

$\mathbf{\Omega}_s$ Subvector of $\mathbf{\Omega}_L$ containing only the prominent directions after CS processing.

$\breve{\mathbf{H}}$ Combined transfer matrix for mixed-norm problem.

$\breve{\mathbf{p}}$ Combined measurement pressure vector for mixed-norm problem.

$\mathbf{x}$ Combined amplitude.

ℓ_p Norm-p.

$\mathbf{H}$ Transfer Matrix for plane waves impinging on rigid sphere.

$\mathbf{p}$ Measurement vector for the pressure on the spherical array.

$\mathbf{x}$ Amplitude vector for plane waves impinging on the sphere.

$\widetilde{\mathbf{p}}$ Pressure vector reconstructed from prominent plane waves.

B_n^m Ambisonics coefficients.

L Number of plane waves in a discrete grid of directions.

LS Number of Loudspeakers in reproduction.

N Truncation order for the spherical Harmonic Functions.

P_n^m The associated Legendre polynomials of the first kind.

Q Number of sampling points on the spherical microphone array.

R_0 Radius of reproduction area.

Y_n^m Spherical harmonic Functions.

Ω Angular Dependency on both azimuth and inclination angle.

λ Regularization factor for natural field HOA processing.

$\mathbf{B}_N$ Ambisonics coefficients vector truncated at order N.

$\mathbf{S}$ Loudspeaker signals resulting from HOA decoding.

$\mathbf{W}$ Vector containing radial functions W_n.

$\mathbf{Y}_N(\mathbf{\Omega}_L)$ Spherical harmonics vector truncated at order N for all measurement angles in vector $\mathbf{\Omega}_L$.

$\mathbf{p}'$ Residual pressure.

ε Noise parameter for Compressive Sensing Algorithm.

a Radius of microphone array.

"w/ Residual" Exploiting the residual pressure (full implementation of signal path in Figure **??**).

"w/o Residual" Residual pressure is neglected (only upper path in Figure **??**).

Chapter 1

Introduction

This is the introduction.

Another pragraph of the introduction...

Chapter 2

Theoretical Background

This is a way to link to explanations Direction of Arrival (DOA)

THis is a todo:

THis is smth done:

2.1 State-Of-The-Art

2.2 Modal Analysis

$$\frac{1}{r^2}\frac{\partial}{\partial r}(r^2\frac{\partial p}{\partial r}) + \frac{1}{r^2 \mathrm{sin}\theta}\frac{\partial}{\partial \theta}(\mathrm{sin}\theta\frac{\partial p}{\partial \theta}) + \frac{1}{r^2 \mathrm{sin}^2\theta}\frac{\partial^2 p}{\partial \phi^2} - \frac{1}{c^2}\frac{\partial^2 p}{\partial t^2} = 0. \tag{2.1}$$

[43].

2.2.1 Features Extraction

2.3 Modal Synthesis

2.3.1 John's way

2.3.2 Angeliki's way

CHAPTER 3

Method

A combination of the methods described in Chapter 2 is proposed in the present study.

3.1 Chuck language

Modal features extraction code

3.2 PureData

3.3 Heavy Compiler

3.4 Unity

3.5 Overview

Chapter 4

Measurements

Here we can describe the audio recordings if we do any

Chapter 5

Implementation

Here we can put pictures and codes snippets

5.1 Impact Sounds

5.1.1 Additive synthesis

5.1.2 Filter-based additive synthesis

5.2 Rolling Sounds

5.3 Scratching Sounds

Chapter 6

Results & Discussion

Chapter 7

Conclusion

This is the conclusion
4-5 paragraph approx

Appendix A

Results of tests to users

Appendix B

Some other stuff in the appendix

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