

The Adaptive Radix Tree: ARTful Indexing for Main-Memory Databases

Jonas Fritsch

Technische Universität München

Department of Informatics

Chair for database systems

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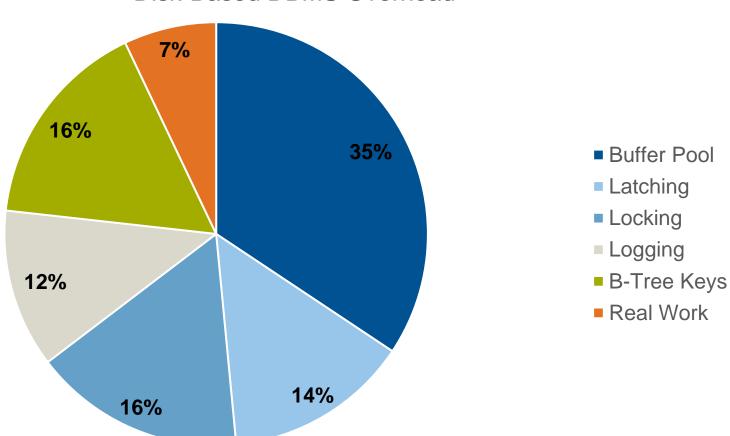
Overview

- Disk-Based vs. Main-Memory DBMS
- Index-Structures in DBMS
- From Tries to ART
- Key Transformations for Bitwise Comparisons
- Benchmarks
- Summary & Conclusion



Disk-Based vs Main-Memory DBMS





Source: OLTP through the looking glass, and what we found there. SIGMOD, 2008



Index-Structures in DBMS

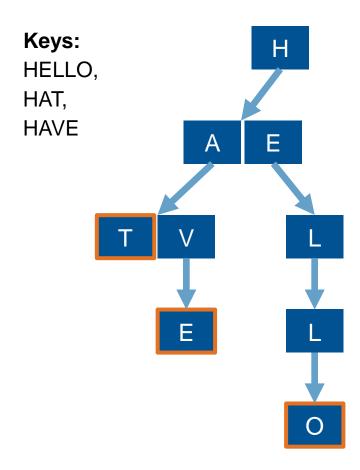
Data structures used to quickly find data in table via a key

2 Index-Types:

- Order Preserving Indexes (Maintains keys in sorted order)
- Hashing Indexes (Associative array mapping hash of key to data record. Only supports equality predicates!)

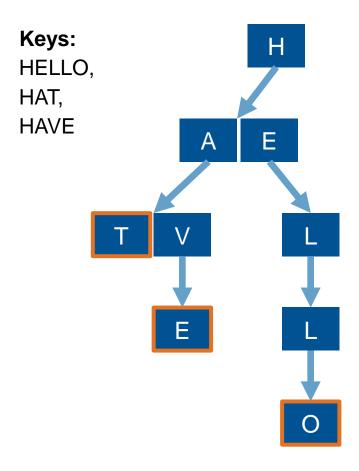


Tries





Tries – Properties

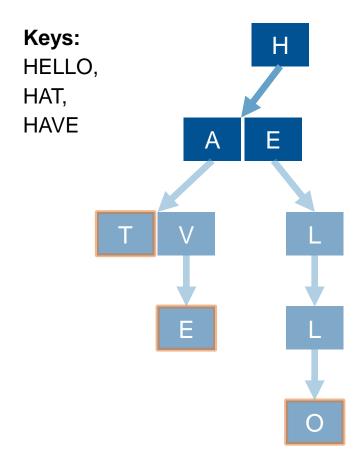


Properties:

- Height/complexity depends on key length k instead of number of elements
- Require no rebalancing
- All insertion orders results in same tree
- Keys stored in lexicographic order
- Keys are stored implicitly along paths



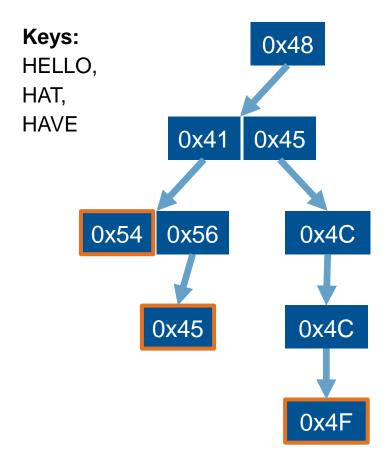
Tries – Implementation



```
class Node {
    bool is_leaf;
    // 'A' to 'Z'
    Node* children[26];
     Н
```



Tries – Key Span, Fanout and Height



Key Span s:

Number of bits each partial key represents (e.g. char is 8 bit span)

Fanout:

Number of children for a node

Determined by specific implementation but in general is 2\sigmas

Height:

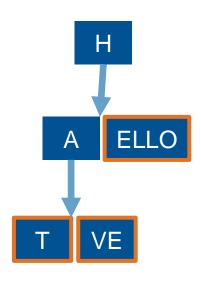
Max Height for k bit keys: ceil(k/s)

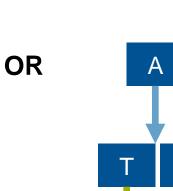


Radix Trees

Keys:

HELLO, HAT, HAVE



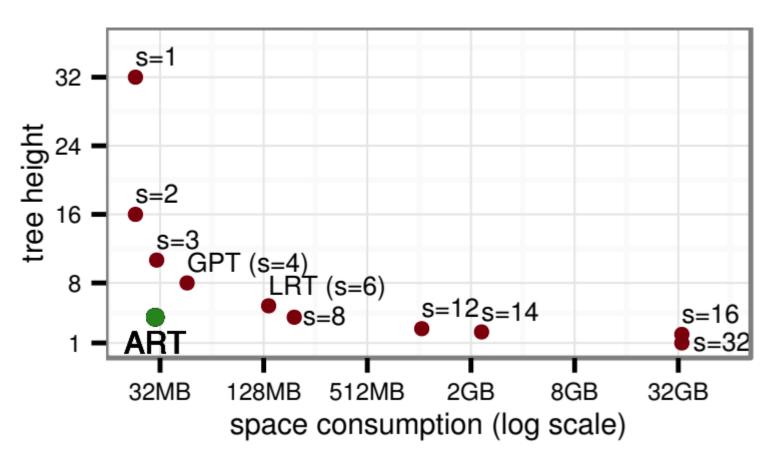




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Height vs. Space Tradeoff

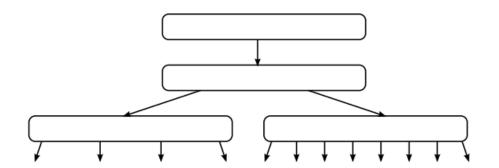


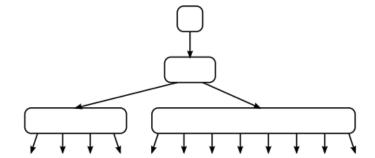


Adaptive Nodes

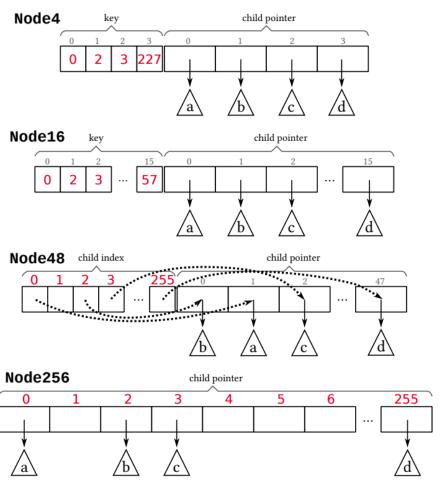
Main Idea:

Use different node types with different fanout based on number of non-null children.

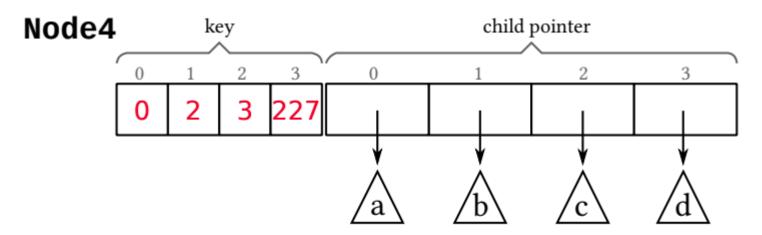


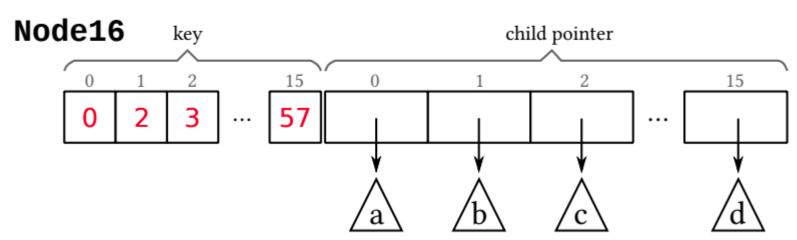




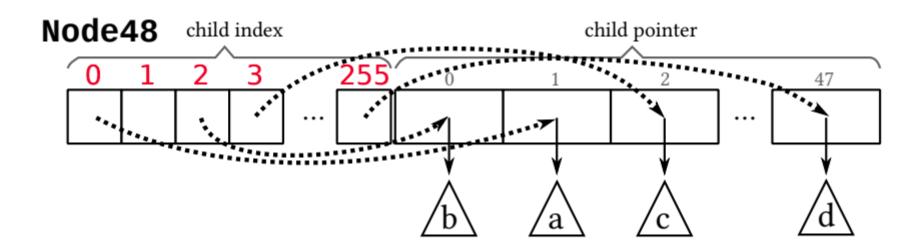




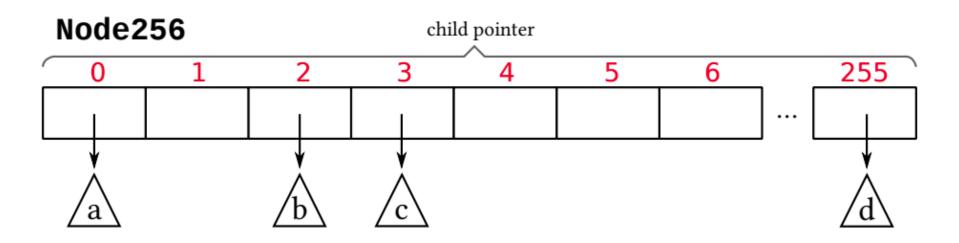






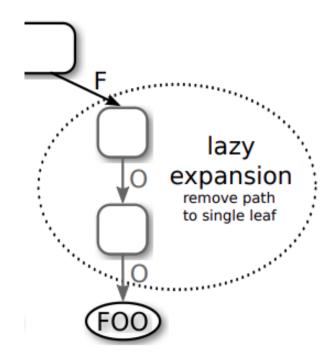






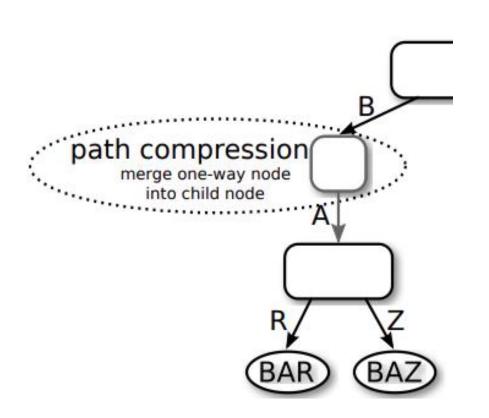


ART – Lazy Expansion





ART – Path Compression



How to handle omitted partial key?

- Pessimistic: store omitted partial key at parent node
- Optimistic:
 only store count of omitted nodes
 and skip over equivalent key part
 (compare full key when reaching
 leaf)

Hybrid approach in ART:

Use pessimistic for size of up to 8 bytes for partial key. Then use optimistic.



Key Transformations for Bitwise Comparisons

How to translate attribute types to make them binary comparible?

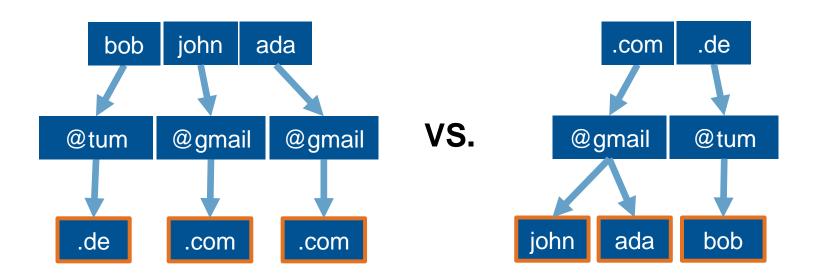
$$a < b \Leftrightarrow bin(a) < bin(b)$$
 (same for > and =)

- Unsigned Integers: Flip byte order for little endian machines
- **Signed Integers:** Flip sign bit (so negative values come before positive ones), store as unsigned integer
- Floats: Classify into group (neg vs. Pos, normalized vs. denomarlized, NaN, ∞, 0), store as unsigned integer
- Strings: Library functions for Unicode Strings
- Null: Identify special value
- Compound Type: Transform each attribute separately, concatenate results



Store Attributes in Context Sensitive Way

Example: E-Mails from back to front for best compression





ART – Implementation Specifics

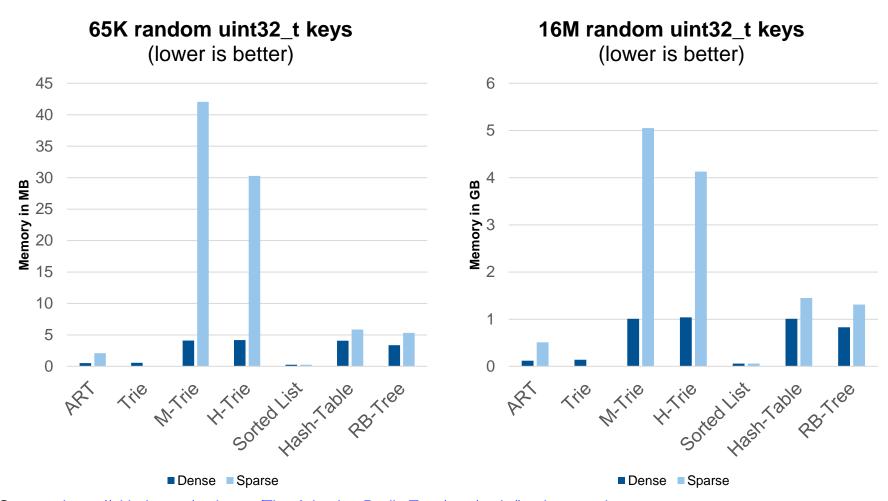
ART implementation for storing 32 bit keys (no path compression)

Important Points:

- No recursion! (self explanatory)
- Careful with polymorphie! (C++ utilizes vtables for dynamic dispatch → performance + memory overhead)
- Memory management! (<u>malloc vs. TCMalloc vs. jemalloc</u> vs. custom memory arenas/pools)
- Node16 search SIMD comparison: used x86-64 SSE2
- Combined value/pointer slots: Pointer Tagging using 3 low bits on 64 bit architecture (pointers are 8-byte aligned)



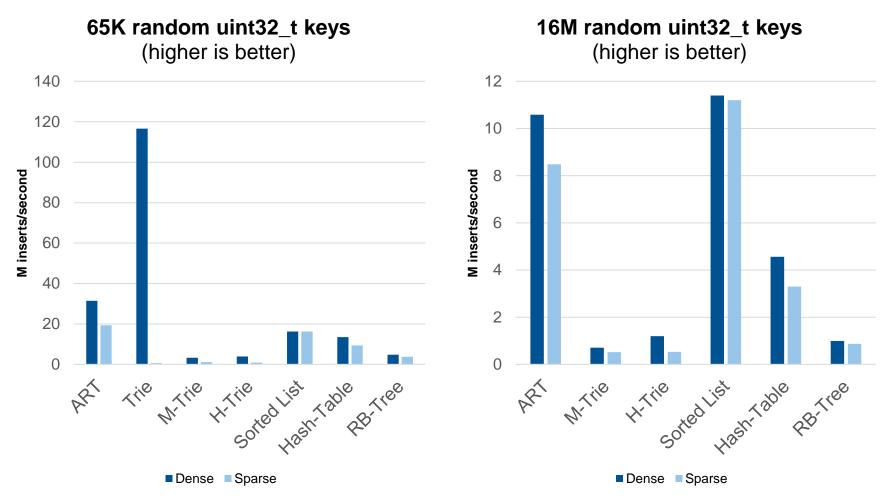
Memory Benchmark



Source: https://github.com/atalantus/The-Adaptive-Radix-Tree/tree/main/Implementation



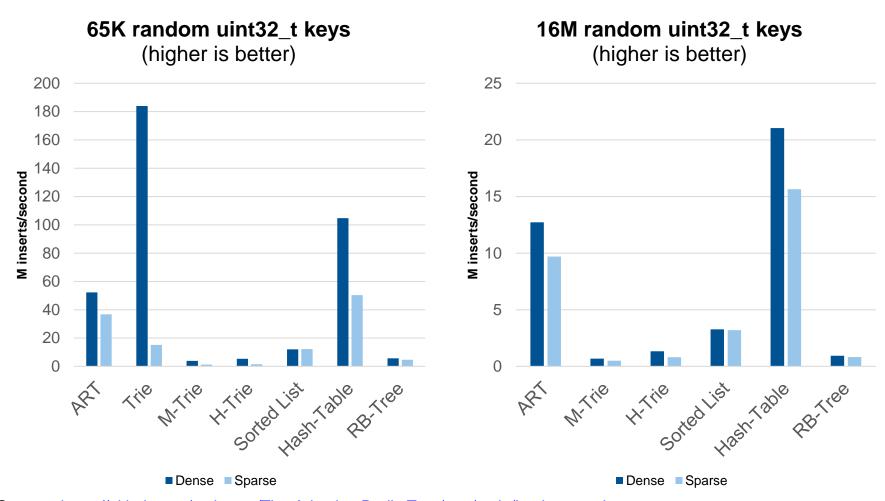
Performance Benchmark (insert)



Source: https://github.com/atalantus/The-Adaptive-Radix-Tree/tree/main/Implementation



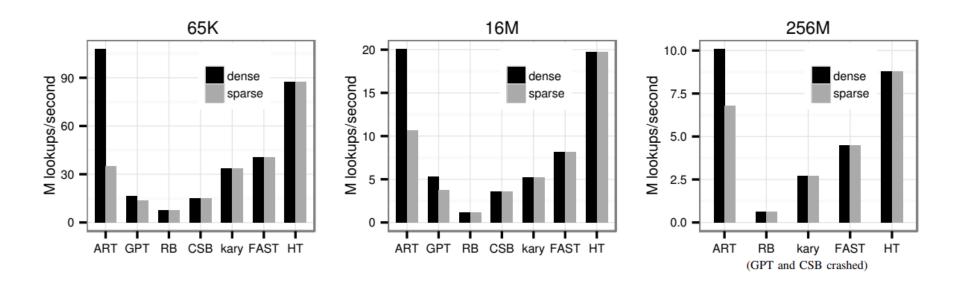
Performance Benchmark (search)



Source: https://github.com/atalantus/The-Adaptive-Radix-Tree/tree/main/Implementation

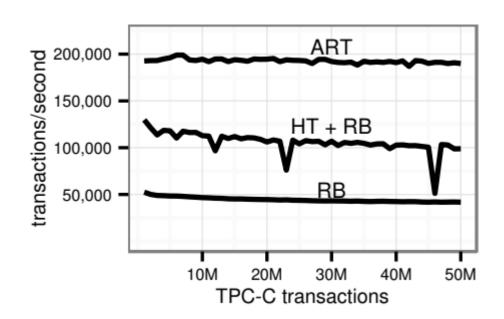


Performance Benchmark (search)





TPC-C Benchmark





Other Benchmarks: Memory Usage

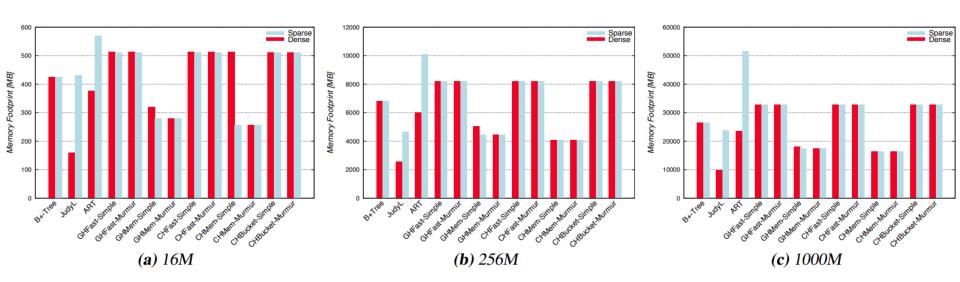


Figure 9: Memory footprint in MB (covering). Lower is better.



Other Benchmarks: Insert

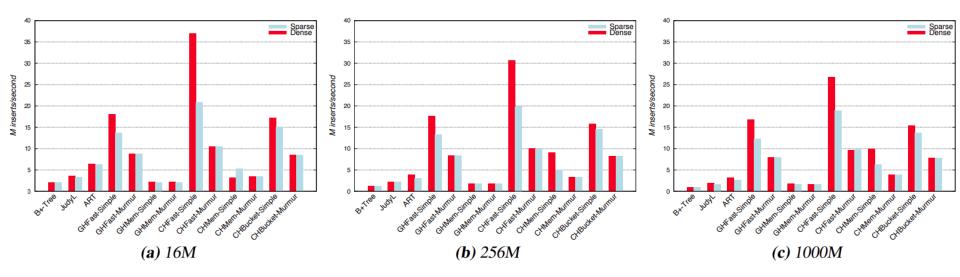


Figure 7: Insertion throughput (covering). Higher is better.



Other Benchmarks: Search

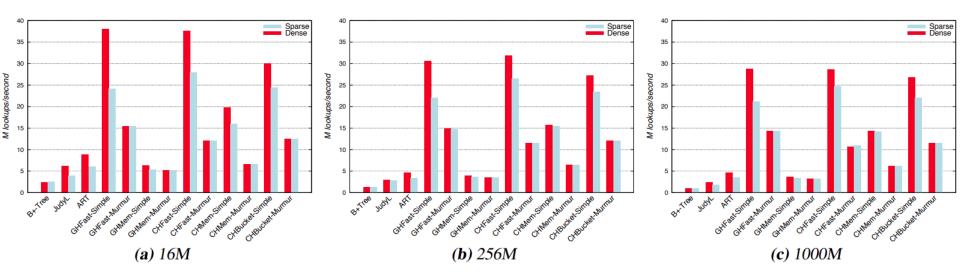
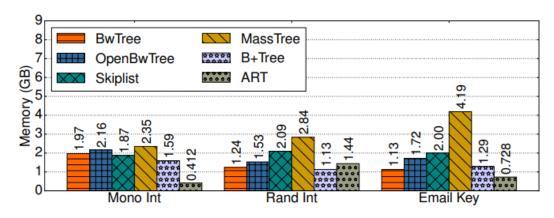


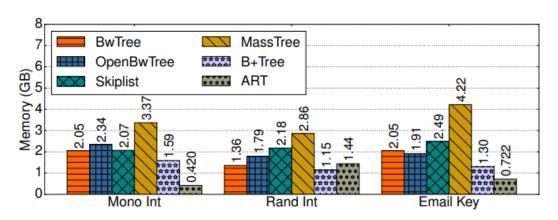
Figure 8: Lookup throughput (covering). Higher is better.



Other Benchmarks: Memory Usage



(a) Single-Threaded – Read/Update



(b) Multi-Threaded – Read/Update

Source: Building a Bw-Tree Takes More Than Just Buzz Words. SIGMOD, 2018



Other Benchmarks: Performance

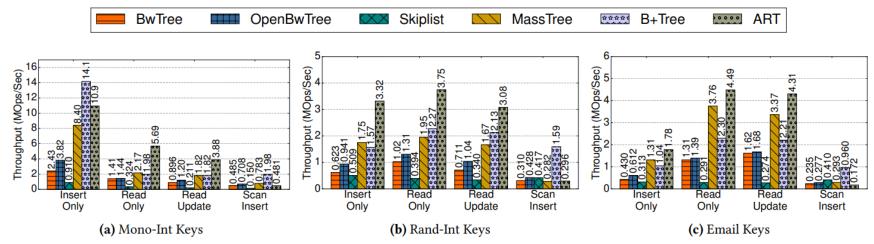


Figure 13: In-Memory Index Comparison (Single-Threaded) - The worker thread is pinned to NUMA node 0.

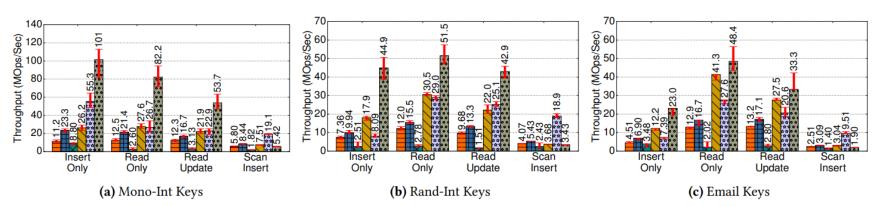


Figure 14: In-Memory Index Comparison (Multi-Threaded) - 20 worker threads. All worker threads are pinned to NUMA node 0.

Source: Building a Bw-Tree Takes More Than Just Buzz Words. SIGMOD, 2018



Summary & Conclusion

ART as (synchronized) order preserving index structure is

- space efficient
- outperforms other op-index structures in insert, search and update performance
- usable for typical data types
- used as default index in (at least) HyPer and DuckDB

	Range Support	Memory Efficiency	Performance	Researched
B+-Tree	+	-	 (best for range)	+
ART	+	~	~	~
Judy-Array	+	+	_	_
Hash-Table	_	+	++	~



Summary & Conclusion

Further research being done:

The ART of practical synchronization (DaMoN, 2016)

sychronize ART for multithreading using combination of OLP and ROWEX

HOT: A Height Optimized Trie Index for Main-Memory Database Systems (SIGMOD, 2018)

- ART performs worse on string (more random binary distribution) due to low fanout in lower tree levels
- Idea: Achieve consistently high fanout by adapting the span at each node

<u>START – Self-Tuning Adaptive Radix Tree</u> (IEEE, 2020)

- Learned indexes outperforming ART in read-mostly benchmark due to hierarchical structure of nodes
- Idea: Optimize lower level nodes using cost model and optimizer

(Judy Arrays patent expired this year)

- even better cache efficiency, complex node transitions (~20k LoC
- Judy-Pointers



Benchmark Specs

Intel Core i5-8400 CPU @ 2.80GHz

L1 Instruction Cache: 6 x 32 KB

• L1 Data Cache: 6 x 32 KB

• L2 Cache: 6 x 256 KB

• L3 Cache: 9 MB

16 GB DDR4 RAM

Windows 10 Pro (10.0.19044 Build 19044)



ART - Search

```
search (node, key, depth)
if node==NULL
return NULL
if isLeaf(node)
if leafMatches(node, key, depth)
return node
return NULL
if checkPrefix(node, key, depth)!=node.prefixLen
return NULL
depth=depth+node.prefixLen
next=findChild(node, key[depth])
return search(next, key, depth+1)
```



ART - Search

```
findChild (node, byte)
   if node.type==Node4 // simple loop
     for (i=0; i<node.count; i=i+1)</pre>
2
        if node.key[i] == byte
3
          return node.child[i]
4
     return NULL
5
   if node.type==Node16 // SSE comparison
     key=_mm_set1_epi8(byte)
7
     cmp=_mm_cmpeq_epi8(key, node.key)
     mask=(1 < node.count)-1
    bitfield=_mm_movemask_epi8(cmp)&mask
10
    if bitfield
11
        return node.child[ctz(bitfield)]
12
     else
13
       return NULL
14
   if node.type==Node48 // two array lookups
     if node.childIndex[byte]!=EMPTY
16
        return node.child[node.childIndex[byte]]
17
     else
       return NULL
   if node.type==Node256 // one array lookup
     return node.child[byte]
21
```



ART – Insert

```
insert (node, key, leaf, depth)
i if node==NULL // handle empty tree
     replace (node, leaf)
2
     return
   if isLeaf(node) // expand node
     newNode=makeNode4()
5
   key2=loadKey(node)
     for (i=depth; key[i]==key2[i]; i=i+1)
       newNode.prefix[i-depth]=key[i]
     newNode.prefixLen=i-depth
     depth=depth+newNode.prefixLen
10
     addChild(newNode, key[depth], leaf)
11
     addChild(newNode, key2[depth], node)
12
     replace (node, newNode)
13
     return
p=checkPrefix(node, key, depth)
```



ART – Insert

```
if p!=node.prefixLen // prefix mismatch
     newNode=makeNode4()
17
     addChild(newNode, key[depth+p], leaf)
18
     addChild(newNode, node.prefix[p], node)
19
     newNode.prefixLen=p
20
     memcpy(newNode.prefix, node.prefix, p)
21
     node.prefixLen=node.prefixLen-(p+1)
22
     memmove (node.prefix, node.prefix+p+1, node.prefixLen)
23
     replace (node, newNode)
24
     return
25
   depth=depth+node.prefixLen
   next=findChild(node, key[depth])
   if next // recurse
     insert (next, key, leaf, depth+1)
29
   else // add to inner node
     if isFull(node)
31
       grow(node)
32
     addChild(node, key[depth], leaf)
33
```



ART – Space Consumption

TABLE I SUMMARY OF THE NODE TYPES (16 BYTE HEADER, 64 BIT POINTERS).

Type	Children	Space (bytes)
Node4	2-4	$16 + 4 + 4 \cdot 8 = 52$
Node16	5-16	$16 + 16 + 16 \cdot 8 = 160$
Node48	17-48	$16 + 256 + 48 \cdot 8 = 656$
Node256	49-256	$16 + 256 \cdot 8 = 2064$

TABLE II
WORST-CASE SPACE CONSUMPTION PER KEY (IN BYTES) FOR DIFFERENT RADIX TREE VARIANTS WITH 64 BIT POINTERS.

	k = 32	$k \to \infty$
ART	43	52
GPT	256	∞
LRT	2048	∞
KISS	>4096	NA.



Performance-Benchmark (search)

TABLE III
PERFORMANCE COUNTERS PER LOOKUP.

	65K			16M		
	ART (d./s.)	FAST	HT	ART (d./s.)	FAST	HT
Cycles	40/105	94	44	188/352	461	191
Instructions	85/127	75	26	88/99	110	26
Misp. Branches	0.0/0.85	0.0	0.26	0.0/0.84	0.0	0.25
L3 Hits	0.65/1.9	4.7	2.2	2.6/3.0	2.5	2.1
L3 Misses	0.0/0.0	0.0	0.0	1.2/2.6	2.4	2.4