

**本科实验报告**

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2020年 3月25日

Lab 4 – IP Core Design CPU/IP2CPU

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**Course:** Computer Organization

**Date:** 2020-03-25 **Instructor:** 洪奇军

1. **Method and Experimental Steps**

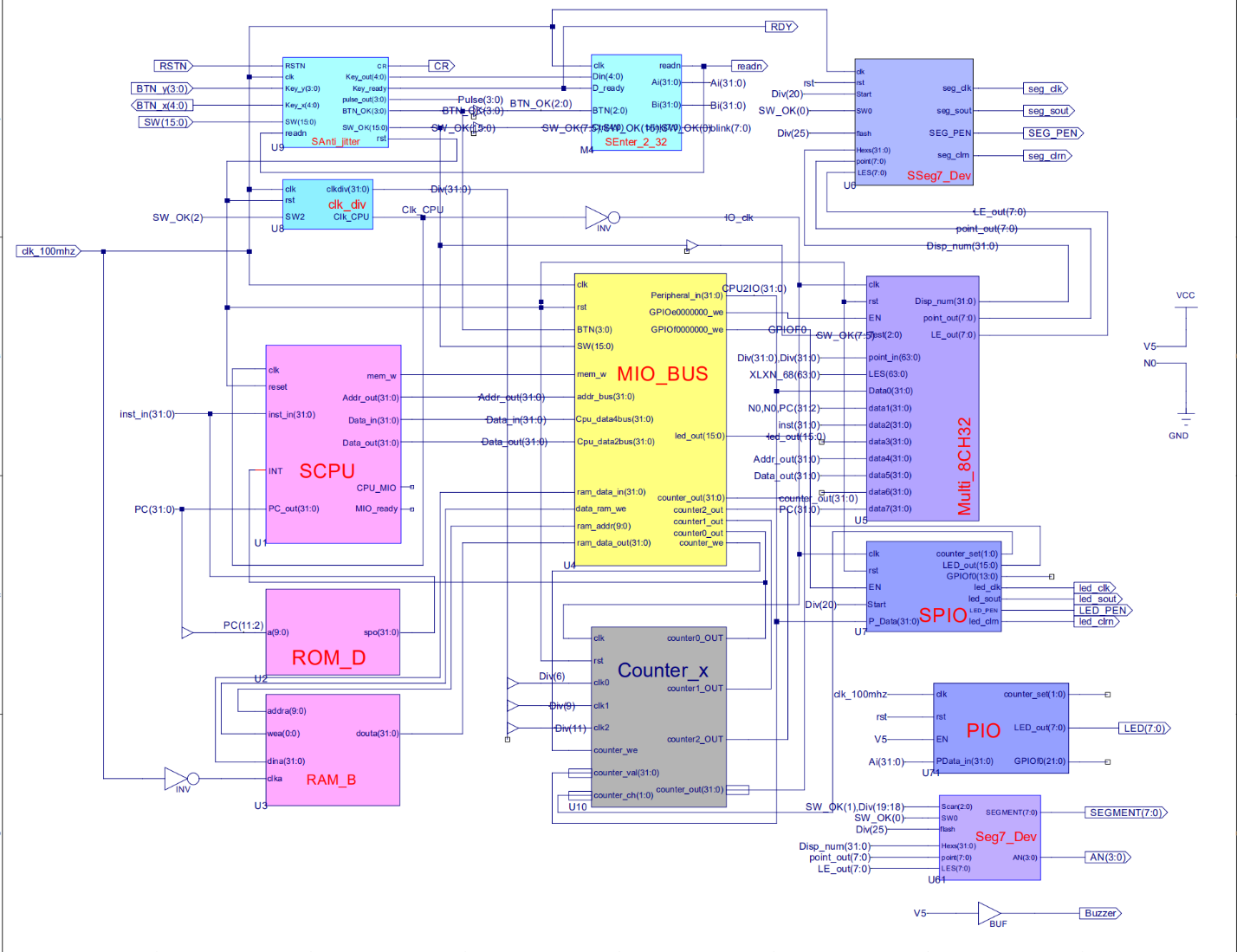


Figure 1 - topMod.sch

This depicts the completion of lab 4. I made two separate projects for this lab, with one being a CPU and the other being an ALU. The CPU is like the one that was built in lab 3, but with modifications to the SCPU module. Here, the CPU consists of the control unit and the data path. The data path is responsible for handling ALU operations, such as calculations, register maintenance and counting. The control unit decodes instructions sent from input and handles any external and internal signals. These topics were briefly examined in the Digital Logic Design course, but will be explored to a further extent here. The .ucf for this program came from the provided courseware, and is linked to topMod.sch. Synthesis had minimal warnings, and implementation was successful. A programmable file has been generated and is ready for testing on the SWORD board.

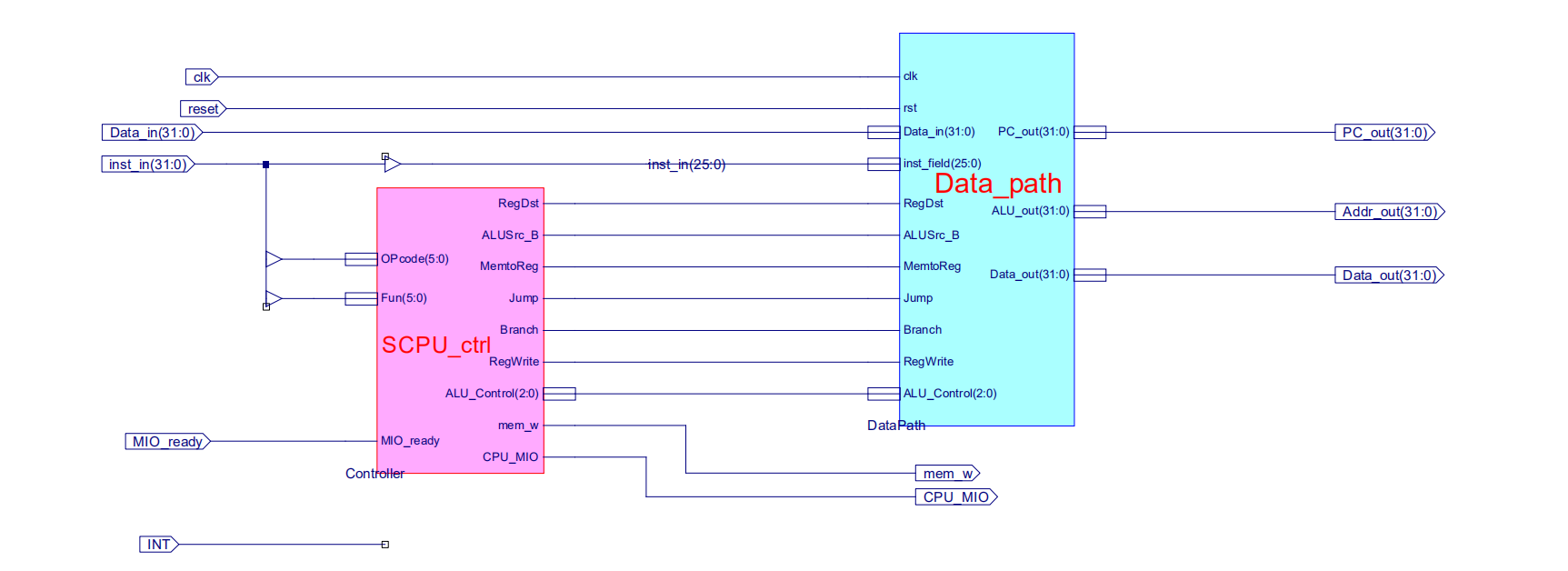


Figure 2 – U1 SCPU Module Schematic

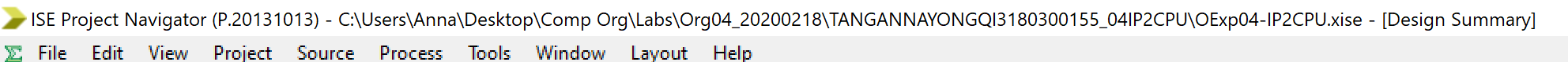


Figure 3 - TANGANNAYONGQI3180300155\_04IP2CPU

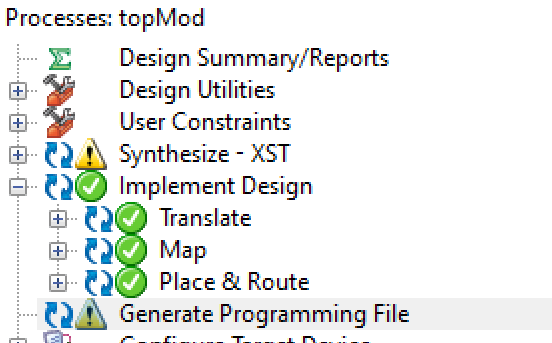
 

Figure 4 - .bit file generation Figure 5 - .bit file generated in directory

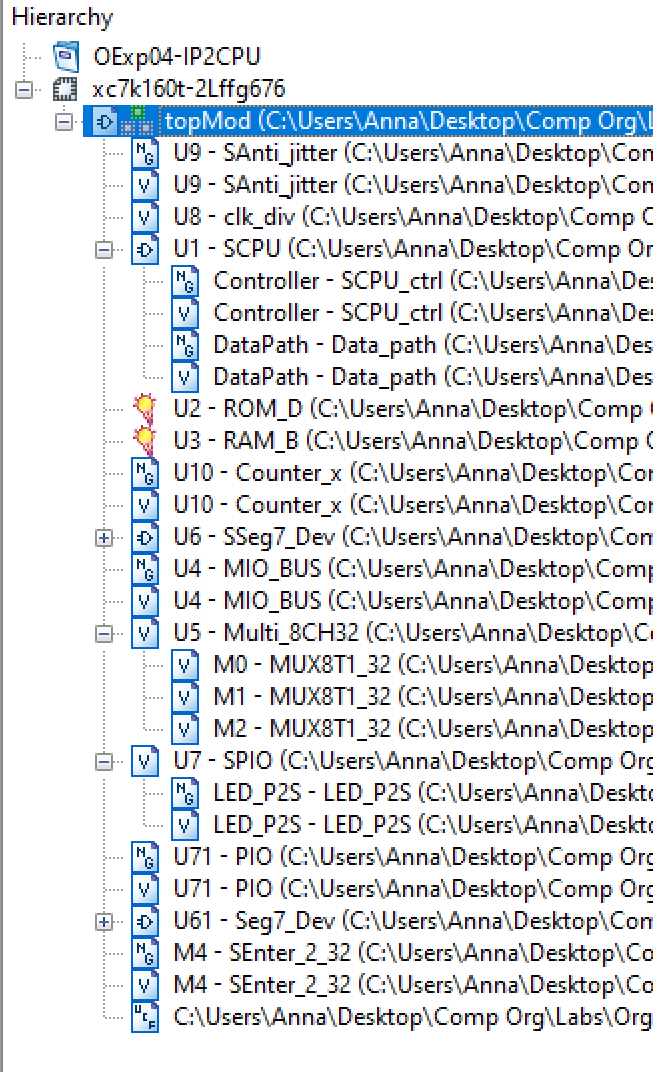


Figure 6 - file hierarchy

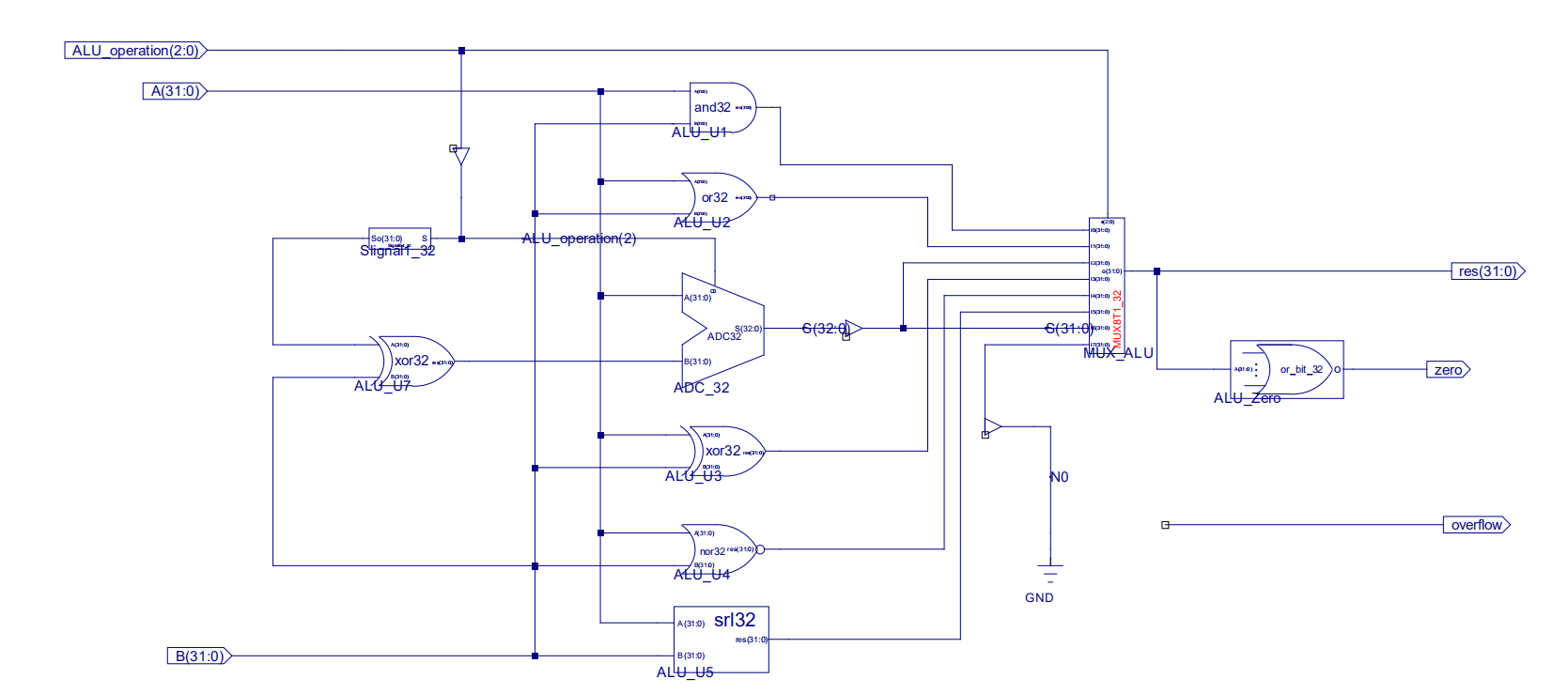


Figure 7 – ALU.sch

The schematic above is the second project of lab 4; the ALU. The ALU is capable of performing logical, arithmetic and shift operations. Examples include add, subtract, AND, OR, NOR, and so on. It takes three inputs A, B, and ALU\_Operation which are signal lines that specify the type of operation to perform. It has three outputs res, zero and overflow. This ALU module was based off of the one that was designed in the Digital Logic Design course.

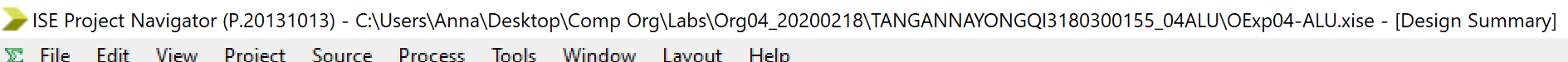


Figure 8 - TANGANNAYONGQI3180300155\_04ALU

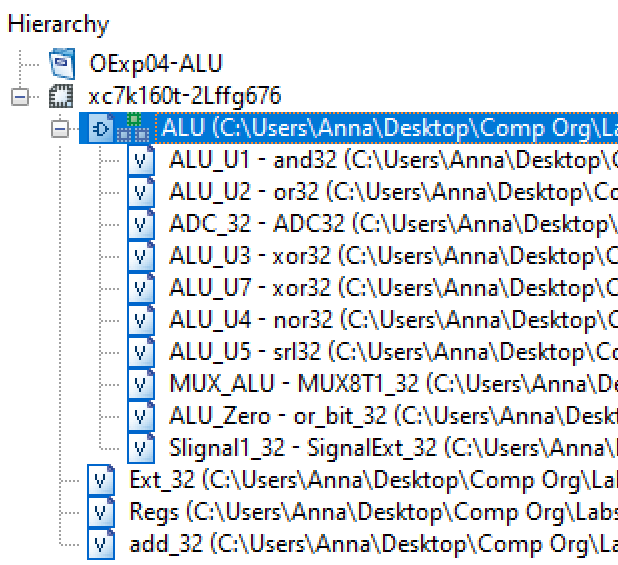


Figure 9 - file hierarchy

1. **Simulations and Observations**

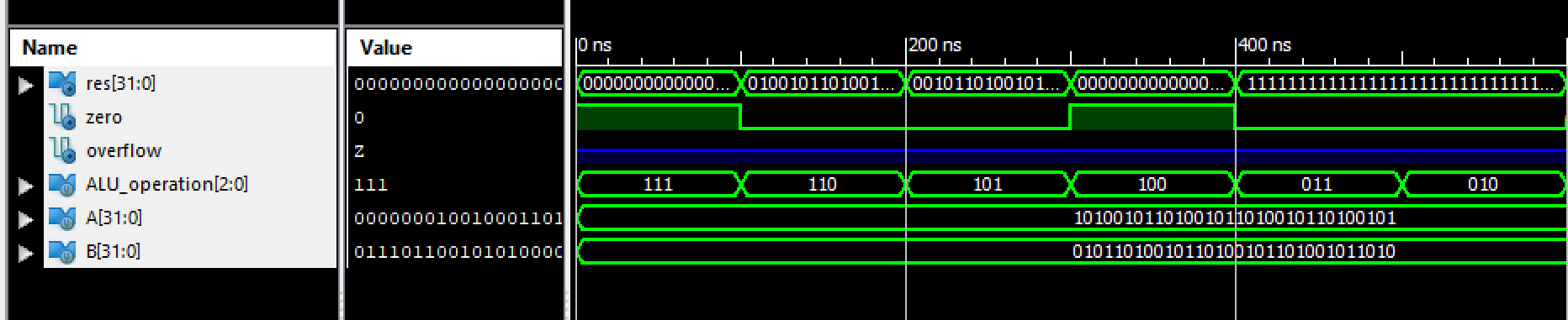


Figure 10 – ALU Simulation

Simulation parameters were taken from the lab PowerPoint. Some of the outcomes differed from the one presented in the slides, and I was unable to track down the issue that caused the difference.

*ALU Simulation*

module ALU\_ALU\_sch\_tb();

// Inputs

reg [2:0] ALU\_operation;

reg [31:0] A;

reg [31:0] B;

// Output

wire [31:0] res;

wire zero;

wire overflow;

// Bidirs

// Instantiate the UUT

ALU UUT (

.ALU\_operation(ALU\_operation),

.res(res),

.zero(zero),

.overflow(overflow),

.A(A),

.B(B)

);

// Initialize Inputs

initial begin

A = 0;

B = 0;

ALU\_operation = 0;

A=32'hA5A5A5A5;

B=32'h5A5A5A5A;

ALU\_operation =3'b111;

#100;

ALU\_operation =3'b110;

#100;

ALU\_operation =3'b101;

#100;

ALU\_operation =3'b100;

#100;

ALU\_operation =3'b011;

#100;

ALU\_operation =3'b010;

#100;

ALU\_operation =3'b001;

#100;

ALU\_operation =3'b000;

#100;

A=32'h01234567;

B=32'h76543210;

ALU\_operation =3'b111;

end

endmodule

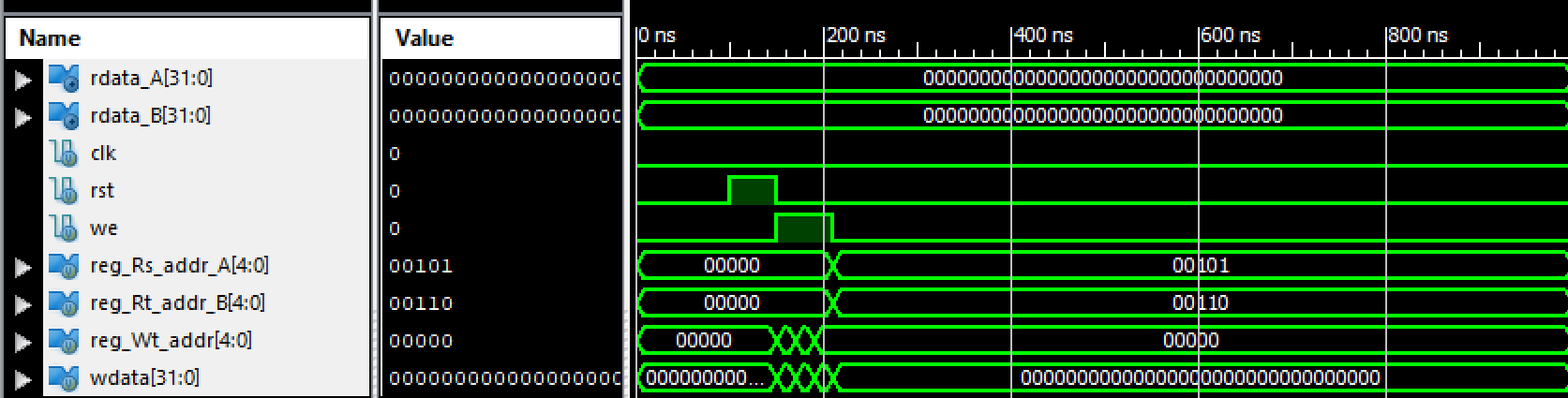


Figure 11 – Regs Simulation

Simulation parameters were taken from the lab PowerPoint. They were consisted with the one presented in the slides.

*ALU Regs Simulation*

module RegsSim;

// Inputs

reg clk;

reg rst;

reg we;

reg [4:0] reg\_Rs\_addr\_A;

reg [4:0] reg\_Rt\_addr\_B;

reg [4:0] reg\_Wt\_addr;

reg [31:0] wdata;

// Outputs

wire [31:0] rdata\_A;

wire [31:0] rdata\_B;

// Instantiate the Unit Under Test (UUT)

Regs uut (

.clk(clk),

.rst(rst),

.we(we),

.reg\_Rs\_addr\_A(reg\_Rs\_addr\_A),

.reg\_Rt\_addr\_B(reg\_Rt\_addr\_B),

.reg\_Wt\_addr(reg\_Wt\_addr),

.wdata(wdata),

.rdata\_A(rdata\_A),

.rdata\_B(rdata\_B)

);

initial begin

// Initialize Inputs

clk = 0;

rst = 0;

we = 0;

reg\_Rs\_addr\_A = 0;

reg\_Rt\_addr\_B = 0;

reg\_Wt\_addr = 0;

wdata = 0;

// Wait 100 ns for global reset to finish

#100;

// Add stimulus here

rst = 1;

#50;

rst = 0;

we = 1;

reg\_Rs\_addr\_A = 0;

reg\_Rt\_addr\_B = 0;

reg\_Wt\_addr = 5;

wdata = 32'hA5A5A5A5;

#20;

we = 1;

reg\_Rs\_addr\_A = 0;

reg\_Rt\_addr\_B = 0;

reg\_Wt\_addr = 6;

wdata = 32'h55AA55AA;

#20;

we = 1;

reg\_Rs\_addr\_A = 0;

reg\_Rt\_addr\_B = 0;

reg\_Wt\_addr = 0;

wdata = 32'hAAAA5555;

#20;

we = 0;

reg\_Rs\_addr\_A = 5;

reg\_Rt\_addr\_B = 6;

reg\_Wt\_addr = 0;

wdata = 0;

#20;

end

endmodule

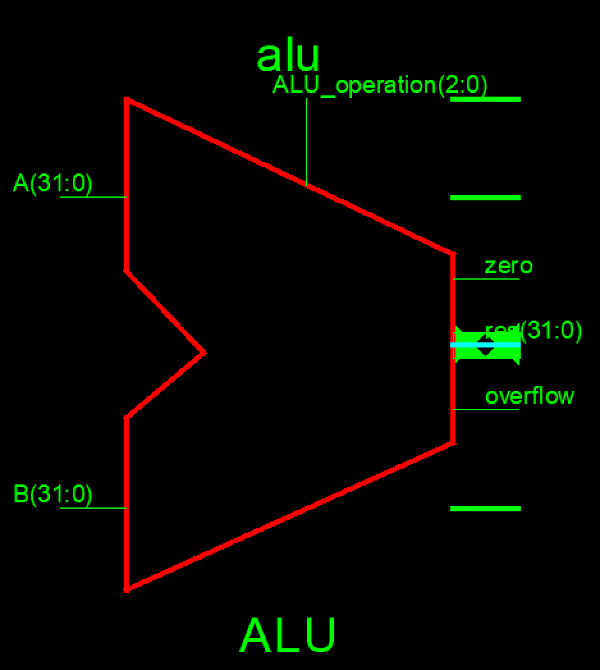
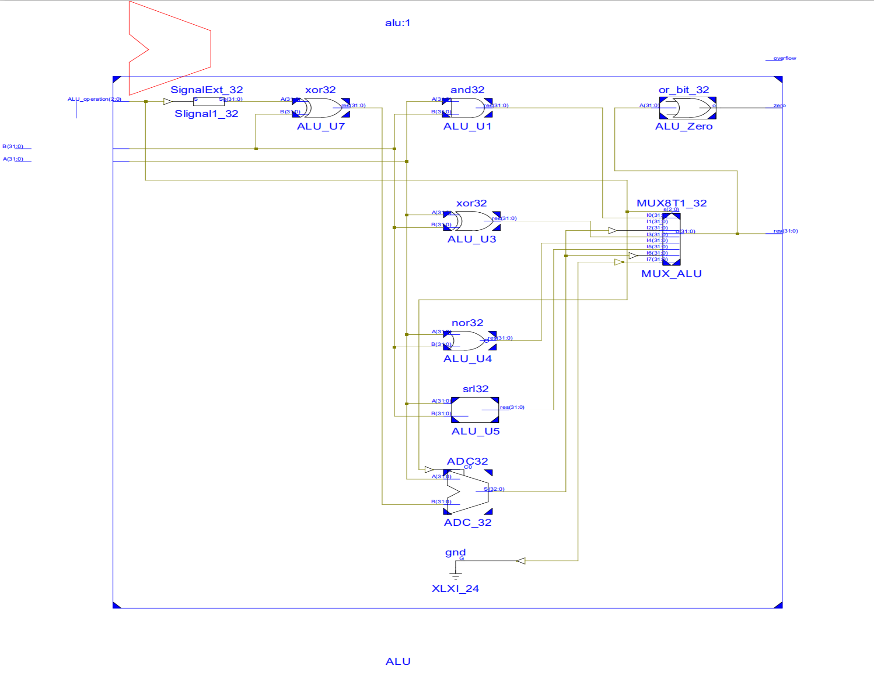
 

Figure 12 – ALU RTL symbol Figure 13 – ALU RTL

RTL schematic of the ALU. Here, we see the ALU as a module symbol and its digital logic structure.

**3. Conclusion**

In this week’s lab, I was mostly interested in the CPU module. We haven’t really gotten the chance to explore the data path and control unit in the theoretical section of this course, so I’m looking forward to that. I think the purpose of making the ALU in this lab is to prepare for the next experiments, where we focus on building the processor of the CPU. Overall, I found this lab to be very straightforward and simple to implement.

1. **Source Code**

All modules and components were either retrieved from lab 1, lab 2 or directly taken from the given files.

*ALU Regs*

module Regs(input clk, rst, we,

input [4:0] reg\_Rs\_addr\_A, reg\_Rt\_addr\_B, reg\_Wt\_addr,

input [31:0] wdata,

output [31:0] rdata\_A, rdata\_B

);

reg [31:0] register [1:31]; // r1 - r31

integer i;

assign rdata\_A = (reg\_Rs\_addr\_A == 0) ? 0 : register[reg\_Rs\_addr\_A]; // read

assign rdata\_B = (reg\_Rt\_addr\_B == 0) ? 0 : register[reg\_Rt\_addr\_B]; // read

always @(posedge clk or posedge rst) begin

if (rst == 1) begin

for (i=1; i<32; i=i+1) begin

register[i] <= 0; // reset

end

end else if ((reg\_Wt\_addr != 0) && (we == 1)) begin

register[reg\_Wt\_addr] <= wdata; // write

end

end

endmodule