# Logic Programming



Chapter 4
Companion slides from the book

## **Loops and Control Structures**

- Can use the backtracking of Prolog to perform loops and repetitive searches
  - Must force backtracking even when a solution is found by using the built-in predicate fail
- Example:

# Loops and Control Structures (cont'd.)

- Use this technique also to get repetitive computations
- Example: these clauses generate all integers greater than or equal to 0 as solutions to the goal num(X)

```
(1) num(0).
```

```
(2) \text{ num}(X) :- \text{num}(Y), X is Y + 1.
```

### Loops and Control Structures

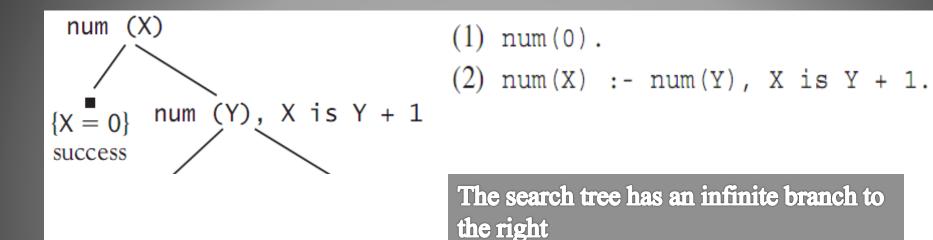


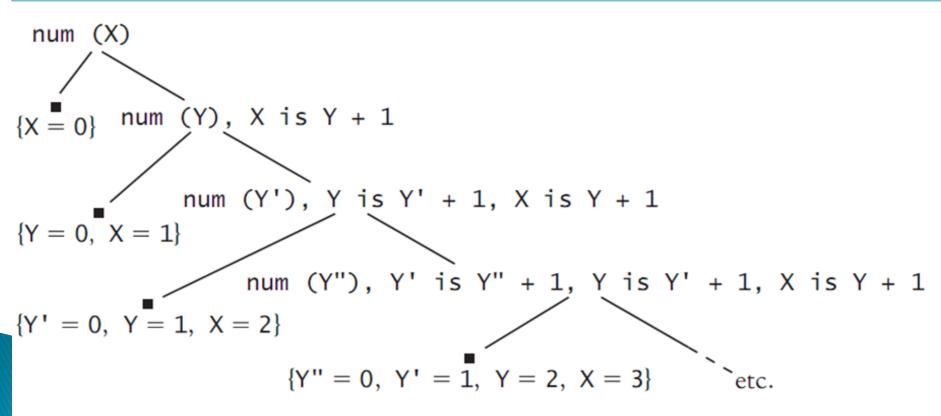
Figure 4.3 An infinite Prolog search tree showing repetitive computations

Example: trying to generate integers from 1 to 10

Causes an infinite loop after X = 10, even though X =< 10 will never succeed</p>

#### List of Numbers

```
\begin{aligned} &\text{num}(0)\,.\\ &\text{num}(X) := &\text{num}(Y)\,, & (X \text{ is } Y + 1)\,.\\ &\text{writeListwithCut}(I,J) := &\text{num}(X)\,, &\text{I}=&<&X, &\text{X}=&<&J, &\text{write}(X)\,, &\text{nl}, &\text{X}=&J, &\text{!}\,. \end{aligned}
```



## Max counting

Predicate max/3 which takes integers as arguments and succeeds if the third argument is the maximum of the first two.

```
▶ Imput
▶ ?- max(2,3,3)
▶ ?- max(3,2,3)
▶ ?- max(3,3,3)
▶ ?- max(2,3,5)
▶ ?- max(2,3,X)
```

output

```
1. \max(X, Y, Y) :- X =< Y.
```

2. 
$$\max(X, Y, X) :- X > Y$$
.

- There can never be any second solution. So, it should not backtrack.
- The two clauses are mutually exclusive!

1. 
$$\max(X, Y, Y) :- X =< Y, !$$
.

2. 
$$\max(X, Y, X) :- X > Y$$
.

Second clause will be evaluated only if first one does not satisfy. Once got passed the cut, control cannot backtrack!

**cut** operator (written as !) freezes a choice when it is encountered

Green Cuts:- Cuts like this, which doesn't change the meaning of a program

- 1.  $\max(X,Y,Y) :- X =< Y,!$
- 2.  $\max(X,Y,X)$ .
- ?- max(100,101,X). X=101, yes ?- max(3,2,X). X=3, yes ?- max(2,3,2).
- 1. max(X,Y,Z) :- X =< Y,!, Y = Z.
- 2. max(X,Y,X).

### If-thenelse

Can also use cut to imitate if-else constructs in imperative and functional languages, such as:

Prolog code:

```
D :- A, !, B.
D :- C.
```

 Could achieve almost same result without the cut, but A would be executed twice

```
D :- A, B.
D :- not(A), C.
```

### Loops and Control Structures

- If a cut is reached on backtracking, search of the subtrees of the parent node stops, and the search continues with the grandparent node
  - Cut prunes the search tree of all other siblings to the right of the node containing the cut
- Example:
- (1) ancestor(X, Y):-parent(X, Z), !, ancestor(Z, Y).
- (2) ancestor(X, X).
- (3) parent(amy, bob).

```
(1) ancestor(X, Y):-parent(X, Z), !, ancestor(Z, Y).
(2) ancestor(X, X).
(3) parent(amy, bob).
                                ancestor (X, bob)
           parent (X, Z), !, ancestor (Z, bob)
           Only X = amy will be found since the branch
           containing X = bob will be pruned
```

Figure 4.4 Consequences of the cut for the search tree of Figure 4.2

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# Loops and Control Structures (cont'd.)

Rewriting this example:

```
(1) ancestor(X, Y) :- !, parent(X, Z), ancestor(Z, Y).
```

- (2) ancestor(X, X).
- (3) parent(amy, bob).

#### Loops and Control Structures (cont'd.)

Rewriting again:

```
(1) ancestor(X, Y) : - parent(X, Z), ancestor(Z, Y).
```

- (2) ancestor(X, X) : !.
- (3) parent(amy, bob).

- Cut can be used to reduce the number of branches in the subtree that need to be followed
- Also solves the problem of the infinite loop in the program to print numbers between  ${\tt I}$  and  ${\tt J}$  shown earlier

### Summation of a list

- ▶ Sum(1,1):-!.
- ▶ Sum(N,R):-

```
N1 is N-1, Sum(N1,R1),
Res is R1+N.
```

- insert(X,[],[X]).
- insert(X,[H|Tail],[X,H|Tail]):- X = < H.
- insert(X,[H|Tail],[H|NewTail]):- X > H, insert(X,Tail,NewTail).
- isort([],[]).
- isort([X|Tail],SList):- isort(Tail,STail), insert(X,STail,SList).

#### **Problems with Logic Programming**

- Original goal of logic programming was to make programming a specification activity
  - Allow the programmer to specify only the properties of a solution and let the language implementation provide the actual method for computing the solution
- Declarative programming: program describes what a solution to a given problem is, not how the problem is solved
- Logic programming languages, especially Prolog, have only partially met this goal

#### Problems with Logic Programming (cont'd.)

- The programmer must be aware of the pitfalls in the nature of the algorithms used by logic programming systems
- The programmer must sometimes take an even lower-level perspective of a program, such as exploiting the underlying backtrack mechanism to implement a cut/fail loop

#### The Occur-Check Problem in Unification

- Occur-check problem: when unifying a variable with a term, Prolog does not check whether the variable itself occurs in the term it is being instantiated to
- Example: is\_own\_successor :- X = successor(X).
- ightharpoonup This will be true if there exists an x for which x is its own successor
- But even in the absence of any other clauses for successor, Prolog answers yes

#### The Occur-Check Problem in Unification (cont'd.)

This becomes apparent if we make Prolog try to print such an X:

```
is_{own}_{successor}(X) :- X = successor(X).
```

- $\circ$  Prolog responds with an infinite loop because unification has constructed X as a circular structure
- What should be logically false now becomes a programming error

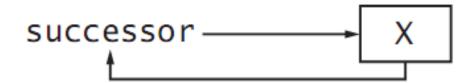


Figure 4-7: Circular structure created by unification

#### Negation as Failure

- Closed-world assumption: something that cannot be proved to be true is assumed to be false
  - Is a basic property of all logic programming systems
- Negation as failure: the goal not (X) succeeds whenever the goal X fails
- Example: program with one clause: parent(amy, bob).
- - The answer is yes since the system has no knowledge of mother
  - If we add facts about mother, this would no longer be true

#### Negation as Failure (cont'd.)

- Nonmonotonic reasoning: the property that adding information to a system can reduce the number of things that can be proved
  - This is a consequence of the closed-world assumption
- A related problem is that failure causes instantiation of variables to be released by backtracking
  - A variable may no longer have an appropriate value after failure

#### Negation as Failure (cont'd.)

Example: assumes the fact human(bob)

```
?- human(X).
X = bob
?- not(not(human(X))).
X = _23
```

The goal not (not (human (X))) succeeds because not (human (X)) fails, but the instantiation of X to bob is released

#### Negation as Failure (cont'd.)

Example:

```
?- X = 0, not(X = 1).

X = 0

?- not(X = 1), X = 0.
```

- The second pair of goals fails because X is instantiated to 1 to make X = 1 succeed, and then not(X=1) fails
- $\circ$  The goal X = 0 is never reached

#### Horn Clauses Do Not Express All of Logic

- Not every logical statement can be turned into Horn clauses
  - Statements with quantifiers may be problematic
- Example:

```
p(a) and (there exists x, not(p(x))).
```

Attempting to use Prolog, we might write:

```
p(a).
not(p(b)).
```

Causes an error: trying to redefine the not operator

#### Horn Clauses Do Not Express All of Logic (cont'd.)

- A better approximation would be simply p(a)
  - Closed-world assumption will force not(p(X)) to be true for all X not equal to a
  - But this is really the logical equivalent of:

$$p(a)$$
 and (for all  $x$ , not( $x = a$ )  $\rightarrow$  not( $p(a)$ )).

This is not the same as the original statement

#### Control Information in Logic Programming

- Because of its depth-first search strategy and linear processing of goals and statements, Prolog programs also contain implicit information on control that can cause programs to fail
  - Changing the order of the right-hand side of a clause may cause an infinite loop
  - Changing the order of clauses may find all solutions but still go into an infinite loop searching for further (nonexistent) solutions

#### Control Information in Logic Programming

- One would want a logic programming system to accept a mathematical definition and find an efficient algorithm to compute it
- Instead, we must specify actual steps in the algorithm to get a reasonable efficient sort
- In logic programming system, we not only provide specifications in our programs, but we must also provide algorithmic control information