Determinant

- A determinant of a square matrix A is denoted by det.A or |A|.
- A determinant of order 1 x 1 matrix $A = [a_{11}]_{\mathbb{H}^1}$ is given by $|a_{11}| = a_{11}$
- A determinant of order of 2 x 2 matrix A ^a11 ^a12 is given by

$$|A| = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} = a_{11} a_{22} - a_{12} a_{21}$$

• A determinant of order 3 x 3 matrix A a_1 b_1 c_1 a_2 b_2 c_2 is given by (expanding along (a_3 b_3 c_3

$$R_{1} \mid A \mid = \begin{vmatrix} a_{1} & b_{1} & c_{1} \\ a_{2} & b_{2} & c_{2} \\ a_{3} & b_{3} & c_{3} \end{vmatrix} = a_{1} \begin{vmatrix} b_{2} & c_{2} \\ b_{3} & c_{3} \end{vmatrix} - b_{1} \begin{vmatrix} a_{2} & c_{2} \\ a_{3} & c_{3} \end{vmatrix} + c_{1} \begin{vmatrix} a_{2} & b_{2} \\ a_{3} & b_{3} \end{vmatrix}$$

- We can find the value of a a determinant by expanding along any one of the three rows (or columns) and the value remains same.
- Generally, we find the value of a determinant by expanding along a row or column which has maximum number of zeroes.
- For any square matrix A, the |A| satisfy following properties.
- 1. |A'| = |A|, where A' = transpose of A.
- 2. If we interchange any two rows (or columns), then sign of determinant changes.
- 3. If any two rows or any two columns are identical or proportional, then value of determinant is zero.
- 4. If we multiply each element of a row or a column of a determinant by constant k, then value of determinant is multiplied by k.
- 5. Multiplying a determinant by k means multiply elements of only one row (or one column) by k.
- 6. If $A = \left[a_{ij} \right]_{3\times3}$, then $|k, A| = k^3 |A|$

- If elements of a row or a column in a determinant can be expressed as sum of two or more elements, then the given determinant can be expressed as sum of two or more determinants.
- 8. If to each element of a row or a column of a determinant the equimultiples of corresponding elements of other rows or columns are added, then value of determinant remains same.
 - If A is skew symmetric matrix of odd order, then |A| = 0.
 - Area of a triangle with vertices $(x_1, y_1), (x_2, y_2)$ and (x_3, y_3) is given by

$$\Delta = \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix}$$

- **Minors**: Minor of an element a_{ij} of the determinant of matrix A is the determinant obtained by deleting i^{th} row and i^{th} column and denoted by M_{ii}
- Confactors: Cofactor of a_{ij} of given by $A_{ij} = (-1)i + j M_{ij}$.
- Value of determinant of a matrix A is obtained by sum of product of elements of a row (or a column) with corresponding cofactors. For example,

$$|A| = a_{11} A_{11} + a_{12} A_{12} + a_{13} A_{13}.$$

• If elements of one row (or column) are multiplied with cofactors of elements of any other row (or column), then their sum is zero. For example,

$$a_{11}A_{21} + a_{12}A_{22} + a_{13}A_{23} = 0$$

- Adjoint of a matrix: $A \left(adj A\right) = \left(adj A\right) A = \left|A\right| I$, where A is square matrix of order n.
- Singular Matrix: A square matrix A is said to be singular or non-singular according as |A| = 0 or $|A| \neq 0$.
- Inverse of a square matrix: If AB = BA = I, where B is square matrix, then B is called inverse of A. Also $A^{-1} = B$ or $B^{-1} = A$ and hence $\left(A^{-1}\right)^{-1} = A$
- A square matrix A has inverse if and only if A is non-singular.

•
$$A^{-1} = \frac{1}{|A|} (adj A)$$

• If
$$a_1x + b_1y + c_1z = d_1$$

$$a_2x + b_2y + c_2z = d_2$$

$$a_3x + b_3y + c_3z = d_3$$

then these equations can be written as AX = B, where

$$\cdot A = \begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = X \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$
 and
$$B = \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix}$$

- Unique solution of equation AX = B is given by $X = A^{-1}B$, where $|A| = 0 \neq 0$.
- A system of equation is consistent or inconsistent according as its solution exists or not.
- For a square matrix A in matrix equation AX = B
- $\cdot \mid A \mid \neq 0$, there exists unique solution
- |A| = 0 and (adj A) B $\neq 0$, then there exists no solution
- $\cdot |A| = 0$ and (adj A) B = 0, then system may or may not be consistent and has infinite solutions.