

Total Derivative:

Another notion of derivative for a vector field is the **total derivative**.

Let $\underline{F} = (F_1, F_2, F_3)$ be a (differential) vector field with variables x, y and z . The total derivative is then defined as the matrix

$$\frac{\partial (F_1, F_2, F_3)}{\partial (x, y, z)} = \begin{pmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} & \frac{\partial F_1}{\partial z} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} & \frac{\partial F_2}{\partial z} \\ \frac{\partial F_3}{\partial x} & \frac{\partial F_3}{\partial y} & \frac{\partial F_3}{\partial z} \end{pmatrix}$$

the total derivative contains a complete information concerning the rate of change of the vector field \underline{F}

Reminder:

matrix and vector **product** (matrix times vector = vector)

$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} A \\ B \end{pmatrix} = \begin{pmatrix} aA & bB \\ cA & dB \end{pmatrix}$$

Total differential of a **function**:

$$df(x_0, y_0) = \frac{\partial f(x_0, y_0)}{\partial x} dx + \frac{\partial f(x_0, y_0)}{\partial y} dy$$

Total **derivative** of a **vector function**:

$$d\vec{F} = \begin{pmatrix} dF_1 \\ dF_2 \end{pmatrix} = \begin{pmatrix} \frac{\partial F_1}{\partial x} dx + \frac{\partial F_1}{\partial y} dy \\ \frac{\partial F_2}{\partial x} dx + \frac{\partial F_2}{\partial y} dy \end{pmatrix} = \begin{pmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix}$$

Jacobian:

We also define the the **Jacobian** of the vector field \underline{F} as the **determinant of the total derivative**.

$$J = \left| \frac{\partial (F_1, F_2, F_3)}{\partial (x, y, z)} \right| = \begin{vmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial y} & \frac{\partial F_1}{\partial z} \\ \frac{\partial F_2}{\partial x} & \frac{\partial F_2}{\partial y} & \frac{\partial F_2}{\partial z} \\ \frac{\partial F_3}{\partial x} & \frac{\partial F_3}{\partial y} & \frac{\partial F_3}{\partial z} \end{vmatrix}$$

similarly for 2 dimensions

Jacobian - Polar Coordinates:

we want to make the following change of variables:

$$(x, y) \longrightarrow (r, \theta)$$

what is the Jacobian of this change of variables?

The Jacobian reads

$$\left| \frac{\partial(x, y)}{\partial(r, \theta)} \right| = \begin{vmatrix} x_r & x_\theta \\ y_r & y_\theta \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r \cos^2 \theta + r \sin^2 \theta = r$$

Jacobian - Spherical Coordinates:

for the following change of variables

$$x, y, z \rightarrow r, \theta, \varphi$$

the Jacobian reads:

$$\frac{\partial(x, y, z)}{\partial(r, \theta, \varphi)} = \begin{vmatrix} x_r & x_\theta & x_\varphi \\ y_r & y_\theta & y_\varphi \\ z_r & z_\theta & z_\varphi \end{vmatrix} = \begin{vmatrix} \sin \theta \cos \varphi & r \cos \theta \cos \varphi & -r \sin \theta \sin \varphi \\ \sin \theta \sin \varphi & r \cos \theta \sin \varphi & r \sin \theta \cos \varphi \\ \cos \theta & -r \sin \theta & 0 \end{vmatrix}$$

$$= r^2 \sin \theta$$

Change of Variables in the Laplacian

Example (polar coordinates)

$$x = r \cos \varphi \quad y = r \sin \varphi \quad u(x, y) \leftrightarrow g(r, \theta)$$

find $\frac{\partial u}{\partial x}$ and $\frac{\partial u}{\partial y}$ functions of $\frac{\partial g}{\partial r}$ and $\frac{\partial g}{\partial \varphi}$

the solution is

$$\frac{\partial u}{\partial x} = \frac{\partial g}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial g}{\partial \varphi} \frac{\partial \varphi}{\partial x} \quad \text{and} \quad \frac{\partial u}{\partial y} = \frac{\partial g}{\partial r} \frac{\partial r}{\partial y} + \frac{\partial g}{\partial \varphi} \frac{\partial \varphi}{\partial y}$$

$$r = \sqrt{x^2 + y^2} \quad ; \quad \varphi = \arctan\left(\frac{y}{x}\right)$$

the derivatives are:

$$\frac{\partial r}{\partial x} = \cos \theta \quad \frac{\partial \varphi}{\partial y} = -\sin \varphi / r \quad \frac{\partial r}{\partial y} = \sin \varphi \quad \frac{\partial \varphi}{\partial x} = \cos \varphi / r$$

$$\text{thus } \boxed{\frac{\partial u}{\partial x} = \frac{\partial g}{\partial r} \cos \varphi + \frac{\partial g}{\partial \varphi} (-\sin \varphi / r) \quad \frac{\partial u}{\partial y} = \frac{\partial g}{\partial r} \sin \varphi + \frac{\partial g}{\partial \varphi} \cos \varphi / r}$$

The Laplacian in Polar Coordinates:

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 g}{\partial r^2} + \frac{\partial g}{\partial r} \frac{1}{r} + \frac{\partial^2 g}{\partial \varphi^2} \frac{1}{r^2}$$

The Laplacian in Cylindrical Coordinates:

$$= \frac{\partial^2 g}{\partial r^2} + \frac{1}{r} \frac{\partial g}{\partial r} + \frac{1}{r^2} \frac{\partial^2 g}{\partial \varphi^2} + \frac{\partial^2 g}{\partial z^2}$$