

MA11114 22/2/22

Multiplication of Matrices is Composition of Linear Maps ; linear is  $\Leftrightarrow$  invertible

$T: V \rightarrow W$ , linear is

$$V = \langle \mathcal{B} \rangle \quad W = \langle \mathcal{e} \rangle$$

$$\begin{array}{ccc} V & \xrightarrow{\quad} & W \\ \downarrow \epsilon & \downarrow \downarrow & \downarrow \downarrow \epsilon' \\ \mathbb{R}^n & \xrightarrow{\quad} & \mathbb{R}^n \\ & & \downarrow \\ & & \mathcal{B} \end{array}$$

$[v]_{\mathcal{B}}$        $[w]_{\mathcal{B}}$

$$\mathcal{B} = \{v_1, v_2, \dots, v_n\}$$

$$A = {}_e[T]_{\mathcal{B}} = [ [T(v_1)]_e \quad [T(v_2)]_e \quad \dots \quad [T(v_n)]_e ]$$

$$A[v]_{\mathcal{B}} = [T(v)]_e$$

Example

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$
$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{pmatrix} x_1 + x_2 \\ -2x_1 + 4x_2 \end{pmatrix}$$

$$V = \mathbb{R}^2 \quad W = \mathbb{R}^2 \quad ; \quad \mathcal{B} = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\} \quad \mathcal{e} = \left\{ \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$$

$$T\left(\begin{pmatrix} 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ -2 \end{pmatrix}, \quad T\left(\begin{pmatrix} 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$\left. \begin{array}{l} [T(\begin{pmatrix} 1 \\ 0 \end{pmatrix})]_{\mathcal{e}} = \begin{pmatrix} 1 \\ -2 \end{pmatrix} = 1\begin{pmatrix} 1 \\ 0 \end{pmatrix} - 2\begin{pmatrix} 0 \\ 1 \end{pmatrix} \\ [T(\begin{pmatrix} 0 \\ 1 \end{pmatrix})]_{\mathcal{e}} = \begin{pmatrix} 1 \\ 4 \end{pmatrix} = 1\begin{pmatrix} 1 \\ 0 \end{pmatrix} + 4\begin{pmatrix} 0 \\ 1 \end{pmatrix} \end{array} \right\} \Rightarrow A = \begin{bmatrix} 1 & 1 \\ -2 & 4 \end{bmatrix} \text{ Does it work?}$$

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}_B = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$A = \begin{bmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \end{bmatrix}_B = \begin{pmatrix} 1 & 1 \\ -2 & 4 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} x_1 + x_2 \\ -2x_1 + 4x_2 \end{pmatrix} = [T(v)]_e$$

Difference Bases,  $e = B = \left\{ \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right\}$   
 $= \{v_1, v_2\}$

$$[T(v_1)]_e \quad [T(v_2)]_e ?$$

$$T(v_1) = \begin{pmatrix} 2 \\ 2 \end{pmatrix} = 2v_1 + 0v_2 \Rightarrow [T(v_1)]_e = \begin{pmatrix} 2 \\ 0 \end{pmatrix}$$

$$T(v_2) = \begin{pmatrix} 3 \\ 6 \end{pmatrix} = 0v_1 + 3v_2 \Rightarrow [T(v_2)]_e = \begin{pmatrix} 0 \\ 3 \end{pmatrix}$$

diff matrix  $A = \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix}$

Example

$$T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix} \mapsto \begin{pmatrix} x_1 + x_2 \\ x_1 - x_3 \end{pmatrix}$$

$$\mathbb{R}^3 = \langle B \rangle$$

$$\mathbb{R}^2 = \langle e \rangle$$

$$B = \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix} \right\} \quad e = \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 3 \\ 1 \end{pmatrix} \right\}$$

calculator  $A = [T]_B$

$$T\left(\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ 0 \end{pmatrix} = -2/5 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 4/5 \begin{pmatrix} 3 \\ 1 \end{pmatrix} \Rightarrow [T\left(\begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}\right)]_e = \begin{pmatrix} -2/5 \\ 4/5 \end{pmatrix}$$

$$T\left(\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}\right) = \begin{pmatrix} 2 \\ 1 \end{pmatrix} = 1/5 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 3/5 \begin{pmatrix} 3 \\ 1 \end{pmatrix} \Rightarrow [T\left(\begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix}\right)]_e = \begin{pmatrix} 1/5 \\ 3/5 \end{pmatrix}$$

$$T\left(\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}\right) = \begin{pmatrix} 1 \\ 1 \end{pmatrix} = 3/5 \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 1/5 \begin{pmatrix} 3 \\ 1 \end{pmatrix} = [T\left(\begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}\right)]_e = \begin{pmatrix} 3/5 \\ 1/5 \end{pmatrix} \quad e [T]_B = \begin{pmatrix} -2/5 & 1/5 & 3/5 \\ 4/5 & 3/5 & 1/5 \end{pmatrix}$$

### Proposition 8.47

if  $T: U \rightarrow V$  and  $S: V \rightarrow W$

and  $u = \langle B_1 \rangle$ ,  $v = \langle B_2 \rangle$ ,  $w = \langle B_3 \rangle$

$$B_3 [S \circ T]_{B_1} = B_3 [S]_{B_2} B_2 [T]_{B_1}$$

Proof ("see notes")

### Proposition 8.48

let  $v = \langle B \rangle$ ,  $w = \langle e \rangle$

and  $T: V \rightarrow W$  is a linear map

$T$  is an isom  $\Leftrightarrow e [T]_B$  is invertible

Proof

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ E_1 \downarrow & & \downarrow E_2 \\ \mathbb{R}^n & \xrightarrow{T_A} & \mathbb{R}^1 \end{array}$$

$$A = e [T]_B \quad T_A = E_2 \circ T \circ E_1^{-1}$$

$$\overline{T_A(v) = Av}$$

If  $T$  is an isom then

$T^{-1}: W \rightarrow V$  is an isom and is represented by matrix  $C$

where  $T_C = E_1 T E_2^{-1}$   
similarly  $T_A = \text{id}_{\mathbb{R}^n}$

$$T_C T_A = E_1 T^{-1} E_2^{-1} E_2 T E_1^{-1} = \text{id}_n$$

$$AeV = v = eAV \text{ for all } v \in \mathbb{R}^n$$

$$\Rightarrow Ae = eA = I_n$$

$\Rightarrow$  invertible

Conversely if  $A$  is invertible

then  $s = E_1^{-1} \cdot T_A \cdot E_2$  is the inverse of  $T$  since

$$T = E_2^{-1} T_A E_1$$

$$\Rightarrow s \circ T = E_1^{-1} T_A^{-1} E_2 E_2^{-1} T_A E_1 = \text{id}_V$$

similarly  $T \circ s = \text{id}_W \Rightarrow s$  is inverse of  $T \Rightarrow T$  is isomorphic

Example

$$B = e = \{e_1, e_2\}$$

$$T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{pmatrix} x_1 + x_2 \\ -2x_1 + 4x_2 \end{pmatrix}$$

$$c[A]_B = \begin{pmatrix} 1 & 1 \\ -2 & 4 \end{pmatrix}$$

$\therefore$  invertible since  $\det \neq 0$

$$\ker(T) = \{v \in \mathbb{R}^2 \mid T(v) = \underline{0}\}$$

$$\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \in \ker(T) \iff \begin{pmatrix} x_1 + x_2 \\ -2x_1 + 4x_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$\Rightarrow x_1 = -x_2$$

$$\Rightarrow 2x_1 = 4x_2$$

$$\Rightarrow -2x_1 = 4x_2$$

$$\Rightarrow x_2 = 0 \Rightarrow x_1 = 0$$

so  $\ker(T) = \left\{ \begin{pmatrix} 0 \\ 0 \end{pmatrix} \right\} \Rightarrow T$  is injective  $\Rightarrow T$  is ~~iso~~ by COGOF for <sup>iso</sup>