

MA1114 21/2/22

Matrix Representation of Linear Map.

Reminder

linear map $T: V \rightarrow V$

Theorem

Any real/complex vector space V of dimension n is isos to $\mathbb{R}^n/\mathbb{C}^n$

(isos $\Leftrightarrow \exists$ a linear map $E: V \rightarrow \mathbb{R}^n/\mathbb{C}^n$ which is a bijection)

what is E ?

E sends a vector to its coordinate vector with respect to a basis i.e. $v \in V$ and V has basis

$$B = \{v_1, \dots, v_n\} \Rightarrow v = \sum_{i=1}^n \lambda_i v_i$$

$$\text{so } E(v) = \begin{pmatrix} \lambda_1 \\ \lambda_2 \\ \vdots \\ \lambda_n \end{pmatrix} = [v]_B$$

$$\text{so } \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \\ \frac{x-y}{2} \end{pmatrix}$$

now suppose V, W real vector spaces and $T: V \rightarrow W$ is a linear isos, suppose $V = \langle B \rangle$ and $W = \langle C \rangle$

we have two maps $E: V \rightarrow \mathbb{R}^n$
 $v \mapsto [v]_B$

and $E': W \rightarrow \mathbb{R}^n$

$$v \mapsto [w]_e$$

so we have a picture

$$\begin{array}{ccc} V & \xrightarrow{T} & W \\ E \downarrow & & \downarrow E' \\ \mathbb{R}^n & \xrightarrow{\quad} & \mathbb{R}^n \end{array}$$

goal find a matrix $A \in M_n(\mathbb{R})$

$$\text{s.t. } [T(v)]_e = A[v]_B \quad (\text{for } v \in V)$$

lemma A exists!

Proof suppose $B = \{v_1, \dots, v_n\}$

$$A = ([T(v_1)]_e, \dots, [T(v_n)]_e)$$

suppose $v \in V$

$$v = \sum_{i=1}^n \lambda_i v_i, \quad \text{want to show } [T(v)]_e = A[v]_B$$

$$E(v) = [v]_B = \begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{pmatrix}$$

$$A[v]_B = \lambda_1 [T(v_1)]_e + \lambda_2 [T(v_2)]_e + \dots + \lambda_n [T(v_n)]_e$$

since $E: v \mapsto [v]_B$ is linear

this becomes $[\lambda_1 T(v_1) + \dots + \lambda_n T(v_n)]_e$ since T is linear

$$[T(\lambda_1 v_1 + \dots + \lambda_n v_n)]_e = [T(v)]_e = [T(v)]_e$$

Examples

(a) $\text{id}: V \rightarrow V$ $V = [B]$
 $v \mapsto v$

$$\begin{array}{ccc} \begin{pmatrix} \lambda_1 \\ \vdots \\ \lambda_n \end{pmatrix} = \begin{array}{c} V \\ \downarrow \\ [v]_B \end{array} & \begin{array}{c} V \\ \downarrow \\ \mathbb{R}^n \end{array} & \begin{array}{c} \xrightarrow{\quad} \\ \downarrow \\ \mathbb{R}^n \end{array} \begin{array}{c} V \\ \downarrow \\ [v]_B \end{array} \end{array}$$

so $[T(V)]_B = T_n.$

(b) $0: V \rightarrow W$
 $v \mapsto \underline{0}$

is represented by $\dim(W) \times \dim(V)$ all 0 matrix

$$\begin{pmatrix} 0 & 0 & \dots & 0 \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{pmatrix} \begin{matrix} \dim(W) \\ \\ \\ \dim(V) \end{matrix}$$

$T: \mathbb{R}^n \rightarrow \mathbb{R}^n$

$v \mapsto rv$ $r \neq 0$
 represented by?

$B = \{e_1, \dots, e_n\}$ $e_i = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix}$ \leftarrow i th position

$T(e_i) = r e_i = \begin{pmatrix} 0 \\ \vdots \\ r \\ \vdots \\ 0 \end{pmatrix}$ \leftarrow i th position

$$\text{so } A = \begin{bmatrix} r & 0 & \dots & 0 \\ 0 & r & & \\ \vdots & & \ddots & \\ 0 & \dots & & r \end{bmatrix} = [T(e_1) \quad T(e_2) \quad \dots \quad T(e_n)]$$

$$(c) \quad P: P_{n+1} \rightarrow P_n$$

$$p(x) \mapsto \frac{d}{dx}(p(x))$$

$$P_n = \{ \text{polynomial of degree at most } n \}$$

$$p \text{ is linear} \quad p(x) = \sum_{i=0}^{n+1} a_i x^i$$

$$q(x) = \sum_{i=0}^n b_i x^i$$

$$\begin{aligned} P(p(x) + q(x)) &= P\left(\sum_{i=0}^{n+1} a_i x^i + \sum_{i=0}^n b_i x^i\right) \\ &= \sum_{i=0}^{n+1} i(a_i + b_i) x^{i-1} = \sum_{i=0}^{n+1} i a_i x^{i-1} + \dots \\ &= \sum_{i=0}^{n+1} i a_i x^{i-1} + \sum_{i=0}^n i b_i x^{i-1} \\ &= P(p(x)) + P(q(x)) \end{aligned}$$

$$\begin{aligned} P(\lambda p(x)) &= P\left(\sum_{i=0}^{n+1} \lambda a_i x^i\right) \\ &= \sum_{i=0}^{n+1} \lambda a_i i x^{i-1} \\ &= \lambda P(p(x)) \end{aligned}$$

with respect to the standard basis $\{1, x, x^2, x^3, \dots, x^n\}$

D is represented by

$$\begin{array}{c}
 \begin{array}{c} 1 \\ x^2 \\ x^3 \\ \vdots \\ x^{n+1} \end{array}
 \left[\begin{array}{ccccccc}
 1 & x & x^2 & x^3 & \dots & x^n \\
 0 & 1 & 0 & & & 0 \\
 \vdots & & 2 & & & \vdots \\
 & & & 3 & & & \\
 & & & & \ddots & & \\
 0 & \dots & \dots & \dots & \dots & \dots & n+1
 \end{array} \right]
 \begin{array}{c} \uparrow \\ = kx^{k-1} \\ \downarrow \end{array}
 \end{array}$$

$\xleftarrow{\hspace{10em}} n+1$

To work out a matrix, A , representing a linear map:

$$T: V \rightarrow W \quad \text{where } V = \langle B \rangle \\ W = \langle C \rangle$$

① calculating images of vectors $T(v_1), T(v_2), \dots, T(v_n)$

where $B = \{v_1, \dots, v_n\}$

② calculating coefficients $[T(v_i)]_C$ for each i

$$\textcircled{3} \quad A = \begin{bmatrix} [T(v_1)]_C & [T(v_2)]_C & \dots & [T(v_n)]_C \end{bmatrix}$$

(this is an $m \times n$ matrix where $\dim(V) = n$
 $\dim(W) = m$)

good since $[v]_B$

so $A[v]_B$ make sense \therefore

Calculate the matrix corresponding to $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$
(w.r.t the standard basis) $\begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mapsto \begin{pmatrix} x_1 + x_2 \\ 3x_1 + 4x_2 \end{pmatrix}$

$$\text{so } e = \{e_1, e_2\}$$

$$v_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad T(v_1) = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$$

$$v_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \quad T(v_2) = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$$

$$A = [T(v_1) \ T(v_2)]$$

$$A = \begin{bmatrix} 1 & 1 \\ 3 & 4 \end{bmatrix}$$