MALLY 12/10/21

Mabrices

Definition 1.32

A m×n mobile A is an m×n rectangular array

$$A = \begin{cases} a_{11} & a_{12} & a_{13} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{m_1} & a_{m_2} & a_{m_3} & \dots & a_{m_n} \\ \vdots & & & \vdots & & \ddots \\ \end{cases}$$
** Yours

a; ER for all 1sism, 1sijen

If m=n say A is square

Escamples

- (1,0) is a 1 x 2 matrix a,= 1 a,= 0

$$\begin{pmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \end{pmatrix}$$
 is a 2×3 mobilise

a column vectors on R" is a nx1 matrix

Definition 1.35

Two matrix A. B are equal if they have the same size and entries

$$lr(A)$$
 "the trace of A "
$$= \sum_{i=1}^{n} A_{ii}$$

Definition 1.41

16; EM 18; EN

Isiam ReR Kjan

Escareple

$$\begin{pmatrix} 3 & 1 \\ 2 & 9 \end{pmatrix} + \begin{pmatrix} 7 & 2 \\ 8 & 3 \end{pmatrix} = \begin{pmatrix} 10 & 3 \\ 10 & 12 \end{pmatrix}$$

$$2 \cdot \begin{pmatrix} 3 & 1 \\ 4 & 2 \end{pmatrix} = \begin{pmatrix} 6 & 2 \\ 8 & 4 \end{pmatrix}$$

Proposition 1.44

The set of all mxn matrices $M_{m,n} = \{(A) \mid A \text{ is a } n \times n \text{ matrix}\}$ forms a vector space.

Proof

dosed under addition / closed under scalar multiple /

Definition 1.45

A e Mmin (A wa mrn mabie)

(A^r);; = A;;

$$\begin{pmatrix} 1 & 3 & 2 \\ q & 2 & -1 \end{pmatrix}^{T} = \begin{pmatrix} 1 & q \\ 3 & 2 \\ 2 & -1 \end{pmatrix}$$

$$\begin{pmatrix} 2 & 3 \\ 1 & \delta \end{pmatrix}^{\mathsf{T}} = \begin{pmatrix} 2 & 1 \\ 3 & \delta \end{pmatrix}$$

Definition 1.39

The mxn matrix In is the matrix whose diagonal entries are 1 and the rust are 0.

$$\prod_{2} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \prod_{3} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Proposition 1.47 branspose properties

A, BEMmn. RER

(i)
$$(A^{\mathsf{T}})^{\mathsf{T}} = A$$

(ii)
$$(A+B)^T = A^T + B^T$$

$$(iii) (\lambda A)^T = \lambda \cdot A^T$$

Proof

First notice that the matrices on either side of the equations have the some size

$$(i) (A^{\tau})_{ij}^{\tau} = (A_{ji})^{\tau} = A_{\bar{j}}$$

$$(iii)((\lambda A)^{T})_{ij} = (\lambda A)_{ji} = \lambda \cdot A_{ji} = \lambda (A^{T})_{ij}$$