

## Minimal Polynomial of Block Matrices

Theorem 2.6 Let  $f(t) \in K[t]$ . Suppose  $f(A) = 0$ . Then minimal polynomial  $m(t)$  of  $A$  divides  $f(t)$ . In particular,  $m(t)$  divides characteristic polynomial  $\Delta(t)$  of  $A$ .

Proof (of 2.6) By division algorithm,  $\exists$  polynomials  $q(t)$  and  $r(t)$  for which

$$f(t) = m(t)q(t) + r(t)$$

and  $r(t) = 0$  or  $\deg r(t) < \deg m(t)$

substituting  $t = A$  we get  $f(A) = m(A)q(A) + r(A)$

so  $r(A) = 0$ , another polynomial (which kills  $A$ )

but  $\deg r(t) < \deg m(t)$ .

by def. of  $m(t)$ ,  $r(t) \equiv 0 \Rightarrow f(t) = m(t)q(t)$

so  $m(t) \mid f(t)$

Theorem 2.7 The char. pol.  $\Delta(t)$  and min. pol.  $m(t)$  of a matrix  $A$  have the same irreducible factors. In particular, they have the same roots

Corollary 2.8 let  $\lambda \in K$ . TFAE (the following are equiv.)

- (1)  $\lambda$  is an eigenvalue of  $A$
- (2)  $\lambda$  is a root of the characteristic polynomial of  $A$ .
- (3)  $\lambda$  is a root of the minimal polynomial of  $A$ .

Corollary 2.9 Suppose

$$\Delta_A(t) = (t - \lambda_1)^{n_1} \cdots (t - \lambda_q)^{n_q}$$

where  $\lambda_1, \dots, \lambda_q$  are distinct roots of  $\Delta_A(t)$  and  $n_1, \dots, n_q$  are their alg. multiplicity then

$$m_A(t) = (t - \lambda_1)^{m_1} \cdots (t - \lambda_q)^{m_q}$$

where  $m_1, \dots, m_q$  are the smallest integers s.t.  $1 \leq m_i \leq n_i \forall i$   
and  $m_A(t) = 0$

Example minimal polynomial  $m(t)$  of  $A = \begin{bmatrix} 2 & 2 & -5 \\ 3 & 7 & -15 \\ 1 & 2 & -4 \end{bmatrix}$

set:  $\Delta(t) = \det(tI_3 - A) = t^3 - 5t^2 + 7t - 3$   
 $= (t-1)^2(t-3)$

$$m_1(t) = (t-1)(t-3) \text{ or } m_2(t) = (t-1)^2(t-3)$$

start with the smallest one and check whether  $m_i(A) = 0$

$$m_1(A) = (A - I_3)(A - 3I_3) = \begin{bmatrix} 1 & 2 & -5 \\ 3 & 6 & -15 \\ 1 & 2 & -5 \end{bmatrix} \cdot \begin{bmatrix} -1 & 2 & -5 \\ 3 & 4 & -15 \\ 1 & 2 & -7 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

so  $m(t) = (t-1)(t-3)$

### Example 2.13

$$J_r(\lambda) = \begin{bmatrix} \lambda & 1 & & 0 \\ & \lambda & \ddots & \\ 0 & & \ddots & 1 \\ & 0 & & \lambda \end{bmatrix} \quad \begin{array}{l} \text{(jordan block)} \\ \lambda \in K \end{array}$$

can show that  $m(t) = \Delta(t) = (t - \lambda)^r$  for  $J_r(\lambda)$

Remark 2.14 The characteristic polynomial of a linear operator  $T: V \rightarrow V$  are defined as those of  $[T]_S$  (the matrix of  $T$  in any basis  $S$  of  $V$ ). Check it doesn't depend on  $S$ .

$$A = P^{-1}BP$$

$$\det A = \det P^{-1} \det B \det P = \det B$$

$$[T]_{S'} = P^{-1} [T]_S P$$

↑  
similar

### 3. Characteristic and Minimal Polynomial of Block Matrices.

$$\text{block triangular matrix } M = \begin{bmatrix} A_1 & B \\ 0 & A_2 \end{bmatrix} \quad \begin{array}{l} A_1 \text{ \& } A_2 \text{ are square} \\ \text{matrices} \end{array}$$

$$\begin{aligned} \Delta_M(t) &= \det(tI - M) = \det \begin{bmatrix} tI - A_1 & -B \\ 0 & tI - A_2 \end{bmatrix} \\ &= \det(tI - A_1) \times \det(tI - A_2) \\ &= \Delta_{A_1}(t) \Delta_{A_2}(t) \end{aligned}$$

Theorem 3.1 If  $M$  is on the diag is a block triangular matrix with blocks  $A_1, \dots, A_r$   
then  $\Delta_M(t) = \Delta_{A_1}(t) \Delta_{A_2}(t) \Delta_{A_3}(t) \dots \Delta_{A_r}(t)$

Theorem 3.2 Suppose  $M$  is a block diagonal matrix with diagonal blocks  $A_1, A_2, \dots, A_r$ . Minimal polynomial of  $M$  is

$$m_M(t) = \text{LCM}(m_{A_1}(t), m_{A_2}(t), \dots, m_{A_r}(t))$$

Example 3.4  $\Delta(t)$  &  $m(t)$ ?  $7 \times 7$  matrix

$$M = \text{diag}(A_1, A_2, A_3) \text{ with } A_1 = \begin{bmatrix} 2 & 5 \\ 0 & 2 \end{bmatrix}$$

$$A_2 = \begin{bmatrix} 4 & 2 \\ 3 & 5 \end{bmatrix}$$

$$A_3 = \begin{bmatrix} 7 & 0 \\ 0 & 7 \end{bmatrix}$$

$$\begin{array}{ll} \Delta_1(t) \text{ of } A_1 & (t-2)^2 \\ \Delta_2(t) \text{ of } A_2 & (t-7)(t-2) \\ \Delta_3(t) \text{ of } A_3 & (t-7)^3 \end{array}$$

$$\Delta(t) = (t-2)^3 (t-7)^4$$

$$(\deg(\Delta(t)) = 7)$$

$$m_1(t) = (t-2)^2$$

$$m_2(t) = (t-2)(t-7)$$

$$m_3(t) = (t-7)$$

$$m(t) = \text{LCM}((t-2)^2, (t-2)(t-7), (t-7))$$

$$= (t-7)(t-2)^2$$