



Object diagram



c:Clock

now=UInteger(1524199495,0.1)

d:Drone

width=UReal(0.5,0.01)
angle=UReal(0.78,0.02)
speed=UReal(20.0,0.1)

object

currentPosition

c1:Coordinate

x=UReal(0.0,0.01)
y=UReal(0.0,0.01)

o:UnidentifiedObject

confidence=0.98
width=UReal(0.7,0.1)
angle=UReal(3.92,0.07)
speed=UReal(15.0,0.2)

object

currentPosition

c2:Coordinate

x=UReal(150.0,0.1)
y=UReal(0.0,0.01)